

# MONITOUCH S8 series

*Connection Manual*



**Record of Revisions**

Reference numbers are shown at the bottom left corner on the back cover of each manual.

Printing Date	Reference No.	Revised Contents
July, 2009	2202NE0	First edition
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# Preface

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Thank you for selecting the MONITOUCH S8 series.

For correct set-up of the S8 series, you are requested to read through this manual to understand more about the product.

For more information about the S8 series, refer to the following related manuals.

Manual Name	Contents	Reference No.
S8 series Reference Manual	The functions and instructions of the S8 series are explained.	1201NE
V Series Macro Reference	An overview of macros of V-SFT version 5 as well as macro editor operations and macro command description are explained.	1056NE
V8 Series Operation Manual	The information related to the operations of V-SFT version 5, such as software composition, editing procedure or limitations, is explained in detail.	1058NE
S8 Series Hardware Specifications	Notes on usage and hardware specifications for the S8 series are explained.	2020NE

For further details about PLCs, inverters, or temperature controllers, refer to the manual attached to each controller.

**Notes:**

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5. This manual is intended to give accurate information about MONITOUCH hardware. If you have any questions, please contact your local distributor.



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# Notes on Safe Usage of MONITOUCH

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In this manual, you will find various notes categorized under the following two levels with the signal words “Danger” and “Caution”.




## DANGER

Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.



## CAUTION

Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury and could cause property damage.

Note that there is a possibility that the item listed with  **CAUTION** may have serious ramifications.



## DANGER

- Never use the output signal of MONITOUCH for operations that may threaten human life or damage the system, such as signals used in case of emergency. Please design the system so that it can cope with the malfunctions of a touch switch. A malfunction of a touch switch will result in machine accident or damage.
- Turn off the power supply when you set up the unit, connect new cables, or perform maintenance or inspections. Otherwise, electrical shock or damage may occur.
- Never touch any terminals while the power is on. Otherwise, electric shock may occur.
- You must put a cover on the terminals on the unit when you turn the power on and operate the unit. Without the terminal cover in place, electric shock may occur.
- The liquid crystal in the LCD panel is a hazardous substance. If the LCD panel is damaged, do not ingest the leaked liquid crystal. If the liquid crystal spills on skin or clothing, use soap and wash off thoroughly.
- Never disassemble, recharge, deform by pressure, short-circuit, reverse the polarity of the lithium battery, nor dispose of the lithium battery in fire. Failure to follow these conditions will lead to explosion or ignition.
- Never use a lithium battery that is deformed, leaks, or shows any other signs of abnormality. Failure to follow these conditions will lead to explosion or fire.



## CAUTION

- Check the appearance of MONITOUCH when it is unpacked. Do not use the unit if any damage or deformation is found. Failure to do so may lead to fire, damage or malfunction.
- For use in a facility or for a system related to nuclear energy, aerospace, medical, traffic equipment, or mobile installations, please consult your local distributor.
- Operate (or store) MONITOUCH under the conditions indicated in this manual and related manuals. Failure to do so could cause fire, malfunction, physical damage or deterioration.
- Understand the following environmental limits for use and storage of MONITOUCH. Otherwise, fire or damage to the unit may result.
  - Avoid locations where there is a possibility that water, corrosive gas, flammable gas, solvents, grinding fluids or cutting oil can come into contact with the unit.
  - Avoid high temperature, high humidity, and outside weather conditions, such as wind, rain or direct sunlight.
  - Avoid locations where excessive dust, salt, and metallic particles are present.
  - Avoid installing the unit in a location where vibration or physical shock may be transmitted.
- Equipment must be correctly mounted so that the main terminal of MONITOUCH will not be touched inadvertently. Otherwise, an accident or electric shock may occur.
- Tighten the fixtures of MONITOUCH with a torque in the specified range. Excessive tightening may distort the panel surface. Loose tightening may cause MONITOUCH to come off, malfunction or be short-circuited.
- Tighten terminal screws on the power supply terminal block equally with a torque in the specified range. Improper tightening of screws may result in fire, malfunction, or trouble, so check periodically that terminal screws on the power supply terminal block and fixtures are firmly tightened.
- MONITOUCH has a glass screen. Do not drop or give physical shock to the unit. Otherwise, the screen may be damaged.
- Connect the cables correctly to the terminals of MONITOUCH in accordance with the specified voltage and wattage. Over-voltage, over-wattage, or incorrect cable connection could cause fire, malfunction or damage to the unit.
- Be sure to establish a ground of MONITOUCH. Ground FG terminal which must be used for the unit. Otherwise, electric shock or a fire may occur.
- Prevent any conductive particles from entering into MONITOUCH. Failure to do so may lead to fire, damage, or malfunction.
- Do not attempt to repair MONITOUCH at your site. Ask HAKKO Electronics or the designated contractor for repair.
- Do not repair, disassemble or modify MONITOUCH. HAKKO Electronics Co., Ltd. is not responsible for any damages resulting from repair, disassembly or modification of MONITOUCH that was performed by an unauthorized person.
- Do not use a sharp-pointed tool when pressing a touch switch. Doing so may damage the display unit.
- Only experts are authorized to set up the unit, connect the cables or perform maintenance and inspection.
- Lithium batteries contain combustible material such as lithium or organic solvent. Mishandling may cause heat, explosion or ignition resulting in fire or injury. Read related manuals carefully and handle the lithium battery correctly as instructed.
- Do not press two or more points on the screen at the same time. If two or more positions are pressed at the same time, the switch located between the pressed positions activates.

 **CAUTION**

- Take safety precautions during such operations as setting change during running, forced output, start, and stop. Any misoperation may cause unexpected machine motions, resulting in machine accident or damage.
- In facilities where a failure of MONITOUCH could lead to accident threatening human life or other serious damage, be sure that the facilities are equipped with adequate safeguards.
- At the time of disposal, MONITOUCH must be treated as industrial waste.
- Before touching MONITOUCH, discharge static electricity from your body by touching grounded metal. Excessive static electricity may cause malfunction or trouble.

[General Notes]

- Never bundle control cables nor input/output cables with high-voltage and large-current carrying cables such as power supply cables. Keep these cables at least 200 mm away from the high-voltage and large-current carrying cables. Otherwise, malfunction may occur due to noise.
- When using MONITOUCH in an environment where a source of high-frequency noise is present, it is recommended that the FG shielded cable (communication cable) be grounded at its ends. However, the cable may be grounded only at one end if this is necessary due to unstable communication conditions or for any other reason.
- Plug connectors or sockets of MONITOUCH in the correct orientation. Failure to do so may lead to malfunction.
- Do not use thinners for cleaning because they may discolor the MONITOUCH surface. Use alcohol or benzine commercially available.
- If a data receive error occurs when MONITOUCH and the counterpart (PLC, temperature controller, etc.) are started at the same time, read the manual for the counterpart unit and remove the error correctly.
- Avoid discharging static electricity on the mounting panel of MONITOUCH. Static charges can damage the unit and cause malfunctions. Otherwise, malfunction may occur due to noise.
- Avoid prolonged display of any fixed pattern. Due to the characteristics of the liquid crystal display, an afterimage may occur. If a prolonged display of a fixed pattern is expected, use the auto OFF function of the backlight.

[General Notes]

Note that the following conditions may occur under normal circumstances.

- The response time, brightness and colors of the S8 series may be affected by the ambient temperature.
- Tiny spots (dark or luminescent) may appear on the display due to the liquid crystal characteristics.
- There are variations in brightness and colors on each unit.
- Cold cathode tubes are incorporated into the S808's LCD display for backlights. Optical properties (brightness, irregular colors, etc.) may change in a low-temperature environment or over time of operation.

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## Connection Compatibility List



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# 1. Overview

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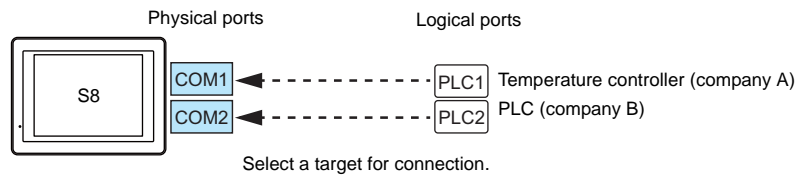
- 1.1 2-way Communication
- 1.2 Connection Modes
- 1.3 Physical Port
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# 1.1 2-way Communication

## 1.1.1 Overview

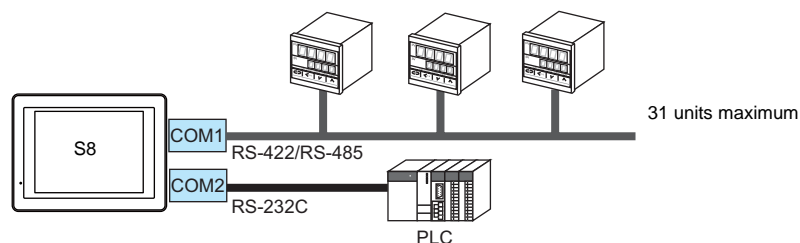
The S8 series is equipped with two serial ports for RS-232C and RS-422/485 communication. You can connect two different models of devices and allow the S8 series to communicate with them at the same time. This is called the 2-way communication.



Physical Ports		No. of Ports	Applicable Devices
Serial	COM1 (RS-422/RS-485)	1	PLC/temperature controller/servo/inverter
	COM2 (RS-232C)	1	PLC/temperature controller/servo/inverter/barcode reader/V-Link/slave communication (Modbus RTU)

- Only the logical port PLC1 can be selected for the following devices and functions. Thus, they cannot be connected at the same time.
  - Devices  
Universal serial connection, without PLC connection, AB Control Logix, Siemens S7-200 PPI, Siemens S7-300/400MPI
  - Functions  
Multi-link2, multi-link, ladder transfer, Micrex SX variable name cooperation function

### System Composition



## 1.2 Connection Modes

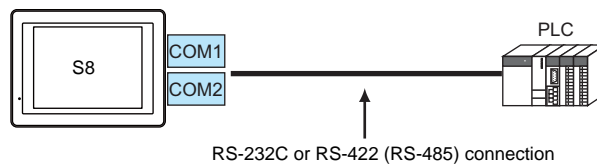
### 1.2.1 PLC Connection

There are four connection modes below to establish serial communication.

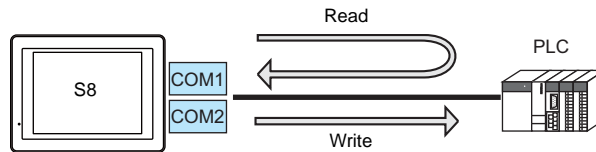
#### 1 : 1 Connection

##### Overview

- One set of the S8 is connected to one PLC (1 : 1 connection).
- You can make settings for 1 : 1 communication in the [Communication Setting] tab window for the logical ports PLC1 and PLC2. A communication port is selectable from COM1 and COM2.



- The S8 (master station) communicates with a PLC under the PLC's protocol. Therefore, there is no need to prepare a communication program for the PLC (slave station).
- The S8 reads the PLC memory for screen display. It is also possible to write switch data or numerical data entered through the keypad directly to the PLC memory.



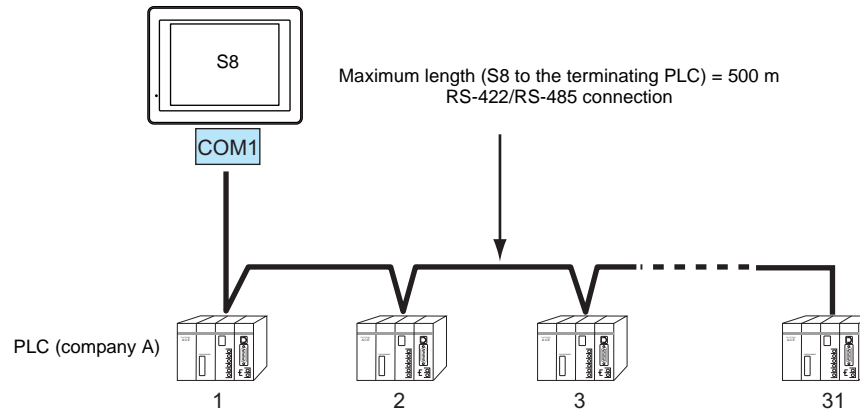
##### Connection

For more information on connection, see "1.4 Wiring" on page 1-10, "1.5 Settings for the Connected Device" on page 1-13, or the chapters on individual manufacturers.

## 1 : n Connection (Multi-drop)

### Overview

- Multi-drop connection connects one S8 unit to multiple PLCs of the same model as 1 : n connection. (Maximum connectable PLCs: 31)
- You can make settings for 1 : n communication in the [Communication Setting] tab window for the logical ports PLC1 and PLC2. COM1 is used as a communication port.



- For models that support multi-drop connection, refer to the list provided at the end of this manual or the chapters on individual manufacturers.

### Connection

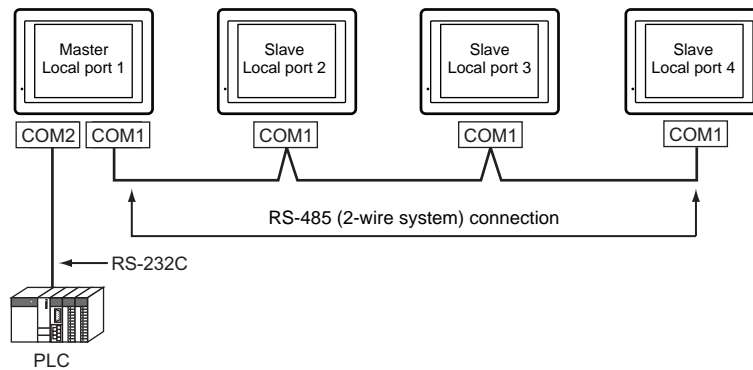
For more information on connection, see “1.4 Wiring” on page 1-10, “1.5 Settings for the Connected Device” on page 1-13, or the chapters on individual manufacturers.

For description of connecting the PLCs, refer to the manual for the corresponding PLC model.

## n : 1 Connection (Multi-link2)

### Overview

- One PLC is connected to a maximum of four\* S8/V8 units. The S8 series cannot be connected with the V7 and V6 series as multi-link2.
  - \* The terminating resistance of COM1 on S806M10D is always set to ON. If you use S806M10D in multi-link2 connection, S806M10D is available only in the termination of multi-link2 (master and slave). So, a maximum of two S806M10D units is available.
- Multi-link2 enables you to establish an original network consisting of a master S8 of local port No. 1 and slave S8 units of local port Nos. 2, 3, and 4. The master S8 communicates with the PLC directly, and the slave S8 units communicate with the PLC through the master.



- You can make settings for multi-link2 in the [Communication Setting] tab window for the logical port PLC1.
- Multi-link2 enables PLC1 memory data to be shared among the S8 units.
- Communication speed between the master station and the PLC depend on the setting made on the PLC. The maximum communication speed between S8 units is 115 kbps, which is higher than the one available with multi-link connection described in "n : 1 Connection (Multi-link)".
- For PLCs that support multi-link2 connection, refer to the list provided at the end of this manual or the chapters on individual manufacturers.  
The COM2 port (RS-232C) must be used for PLC connection (1:1 connection). The COM1 port (RS-485, 2-wire system) must be used for connection between S8 units.

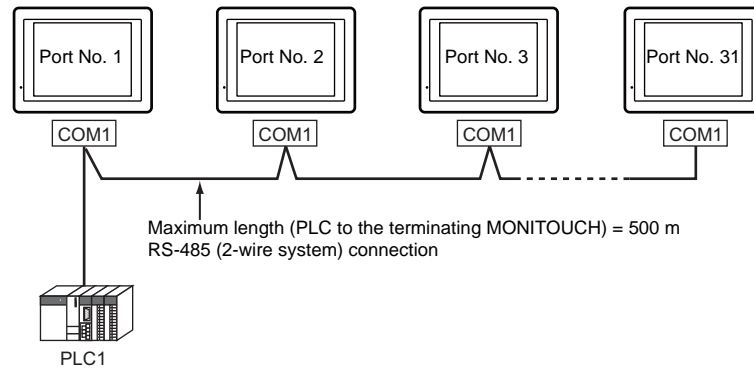
### Connection

For more information, see "Appendix 3.1 Multi-link2".

## n : 1 Connection (Multi-link)

### Overview

- One PLC is connected to a maximum of 31\* S8 units. The S8, V8, V7, and V6 series can be used together.
  - \* The terminating resistance of COM1 on S806M10D is always set to ON. So, S806M10D is available only in the termination of multi-link.
- Connection Example



- You can make settings for multi-link in the [Communication Setting] tab window for the logical port PLC1. For the S8, COM1 is available for a communication port. For the V8, however, a communication port is selectable from CN1, MJ1, and MJ2. For the V7 or V6, CN1 is only available.
- Only a PLC for the signal level RS422/RS485 and with a port number is available. For PLCs that support multi-link connection, refer to the list provided at the end of this manual or the chapters on individual manufacturers.
- Wiring type is RS-485 (2-wire system).

### Connection

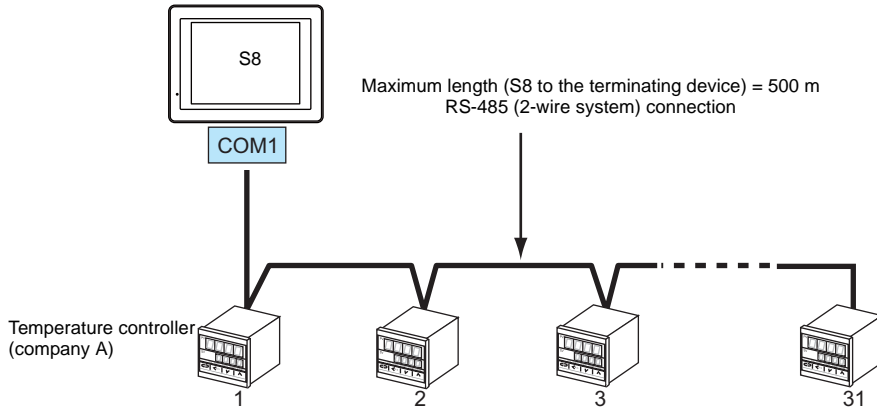
For more information, see "Appendix 3.2 Multi-link".



## 1.2.2 Temperature Controller/Servo/Inverter Connection

### Overview

- The S8 series is connected to temperature controllers, servos, or inverters via serial communication.
- You can make settings for temperature controller/servo/inverter communication in the [Communication Setting] tab window for the logical ports PLC1 - PLC2.
- The S8 series can be connected to multiple temperature controllers, servos, or inverters of the same model as 1 : n connection with COM1 port (RS-422/485). (Maximum connectable units: 31)



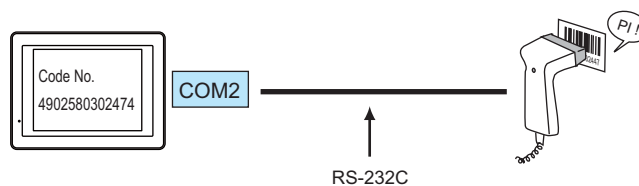
### Connection

For more information on connection, see "1.4 Wiring" on page 1-10, "1.5 Settings for the Connected Device" on page 1-13, or the chapters on individual manufacturers.

## 1.2.3 Barcode Reader Connection

### Overview

- The S8 series is connected to a barcode reader as 1 : 1 connection (RS-232C).
- You can make settings for barcode reader communication in the [Communication Setting] tab window for the logical ports PLC2. COM2 is only available for a communication port.



### Connection

For more information on connection, see "21.1 Barcode Reader Connection".

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## 1.2.4 Slave Communication

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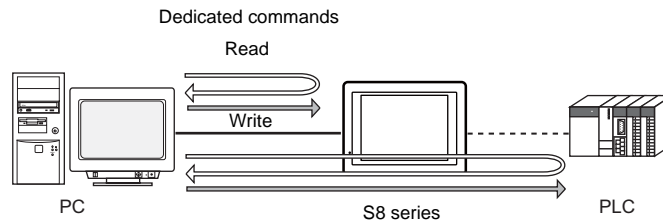
Connecting via V-Link, or Modbus RTU is applicable to slave communication using the S8.

---

### V-Link

---

- “V-Link” is the network where the computer reads from and writes to the internal memory of the S8 series, or PLC1 memory using a dedicated protocol.



- You can make settings for V-Link in the [Communication Setting] tab window for the logical ports PLC2. A communication port is selectable from COM1 and COM2.
- For more information, see “22.1 V-Link”.

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### Modbus RTU

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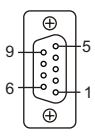
- The S8 series is connected to a Modbus RTU master via serial connection.
- The Modbus slave communication memory table is prepared for the S8. The master is allowed to gain access to the memory table and read/write the PLC1 data.
- For more information, refer to the Modbus Slave Communication manual separately provided.

## 1.3 Physical Port

### 1.3.1 COM1

The COM1 port supports communication via RS-422 (4-wire system), and RS-485 (2-wire system).

#### Pin Arrangement

COM1 D-sub 9-pin, Female	No.	RS-422/RS-485	
		Signal	Contents
	1	+RD	Receive data (+)
	2	-RD	Receive data (-)
	3	-SD	Send data (-)
	4	+SD	Send data (+)
	5	0 V	Signal ground
	6	NC	Not used
	7		
	8		
	9	+5 V / +3.3 V	Terminating resistance <sup>*</sup>

\* +5 V (S808) or +3.3 V (S806) is output from pin No. 9.

It is used as the power supply for the external terminating resistance. It cannot be used as an external power supply.

#### Recommended Connector for Communication Cable

Recommended Connector	
DDK's 17JE-23090-02(D8C)-CG	D-sub 9-pin, male, inch screw thread, with hood, RoHS compliant

#### Applicable Devices

Applicable Devices
PLC, temperature controller, inverter, servo, V-Link, slave communication (Modbus RTU)

## 1.3.2 COM2

The COM2 port supports communication via RS-232C.

### Pin Arrangement

COM2 D-sub 9-pin, Male	No.	RS-232C	
		Signal	Contents
	1	NC	Not used
	2	RD	Receive data
	3	SD	Send data
	4	NC	Not used
	5	0V	Signal ground
	6	NC	Not used
	7	RS	RS request to send
	8	CS	CS clear to send
	9	NC	Not used

### Recommended Connector for Communication Cable

Recommended Connector	
DDK's 17JE-13090-02(D8C)-CG	D-sub 9-pin, female, inch screw thread, with hood, RoHS compliant

### Applicable Devices

Applicable Devices
PLC, temperature controller, inverter, servo, barcode reader, V-Link, slave communication (Modbus RTU)

## 1.4 Wiring

This section provides notes on configuring cables. For device wiring diagrams, refer to the chapters on individual manufacturers.

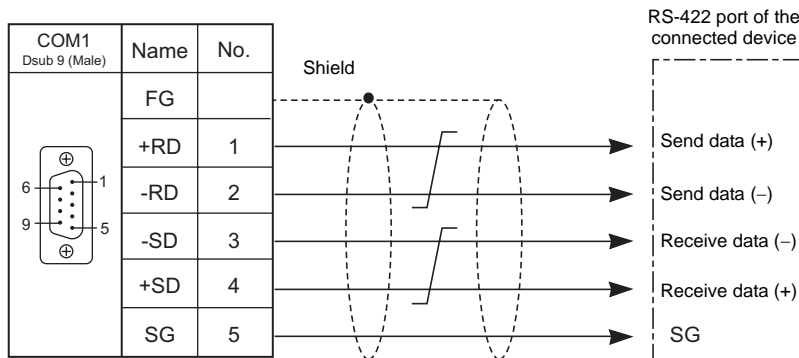


### DANGER

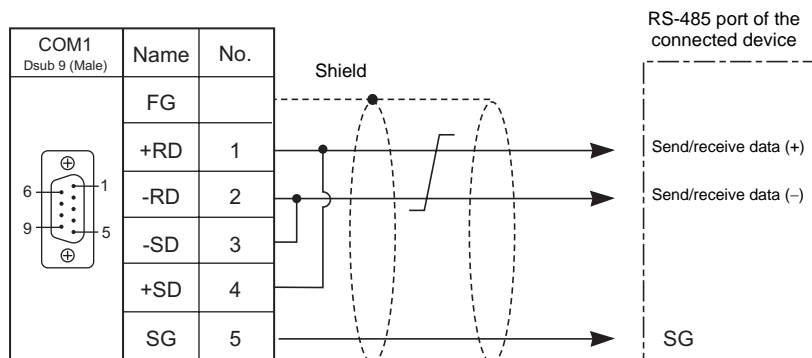
Be sure to turn off the power before connecting cables. Otherwise, electrical shock or damage may occur.

### 1.4.1 COM1 (RS-422/485) Connection

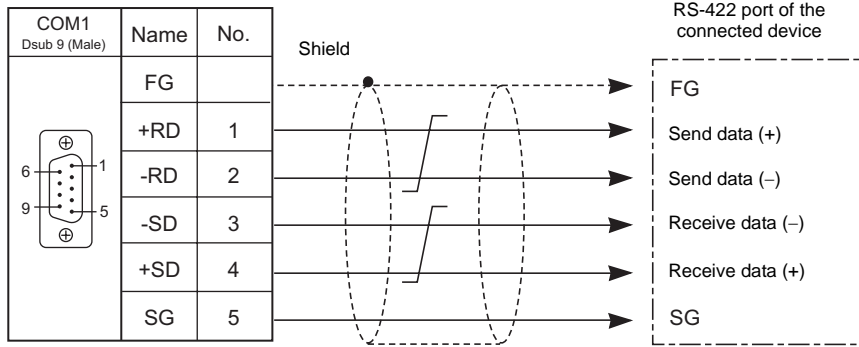
- Prepare a communication cable on your side. Twisted pairs of 0.3 mm sq. or above are recommended.
- Connect twisted pairs between +SD/-SD and +RD/-RD.
- If the PLC has the terminal for signal ground (SG), connect a wire.
- To use a terminal block for connecting to other device, use Hakko Electronics' "TC-D9" optionally available.
- The DIP switch on the back of the S8 unit excluding S806M10D is used to set the terminating resistance. For more information on the DIP switch, refer to the separate S8 Series Hardware Specifications manual.
  - \* S806M10D is not equipped with DIP switches. Therefore, the terminating resistance of COM1 is always set to ON. Note that there are some restrictions on the configuration including S806M10D when multiple units of S8 and V8 are connected via multi-link, multi-link2, V-Link and Modbus slave.
- Connect a shielded cable to either the S8 series or the connected device. The connection diagram shows the case where the shielded cable is connected on the S8 series side. Connect the cable to the FG terminal on the backside of MONITOUCH.
  - RS-422 (4-wire system)



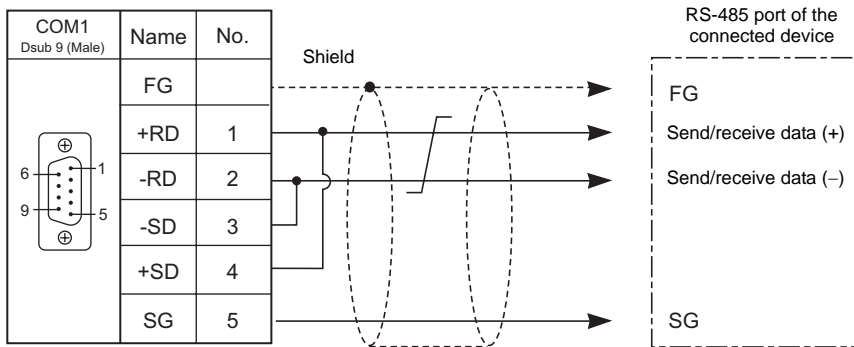
- RS-485 (2-wire system)



- If noise disturbs communications, connect a shielded cable to both the S8 series and the connected device.
  - RS-422 (4-wire system)



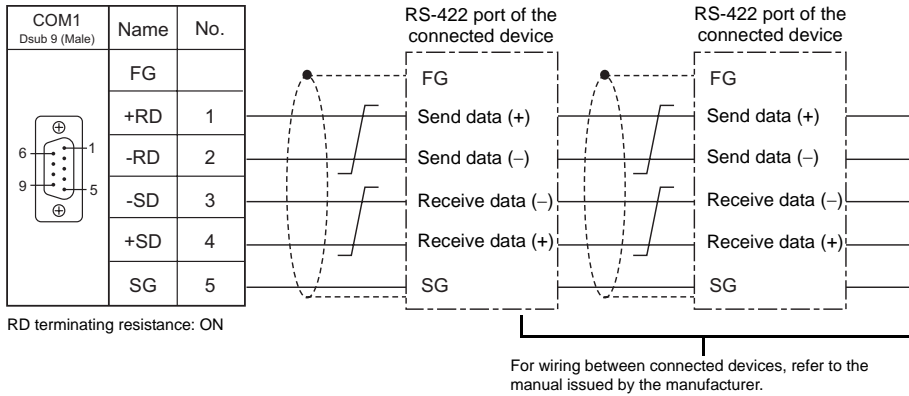
- RS-485 (2-wire system)



**Multi-drop connection (1 : n)**

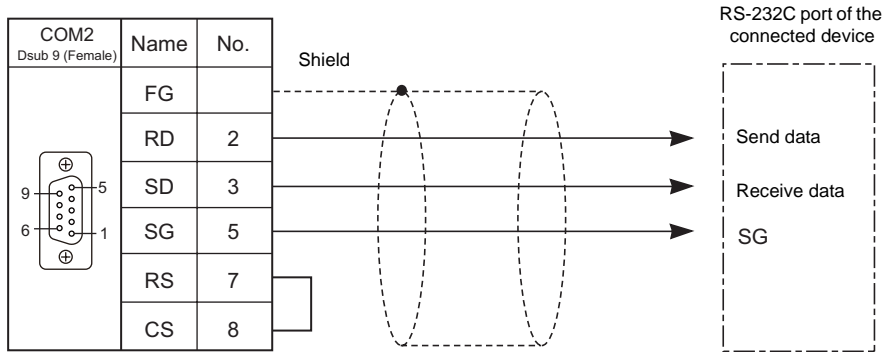
In the case of multi-drop connection, wiring between a S8 and a connected device is the same as that for 1 : 1 communication. Meanwhile, for description of wiring between connected devices, refer to the manual issued by the manufacturer.

- Connection example

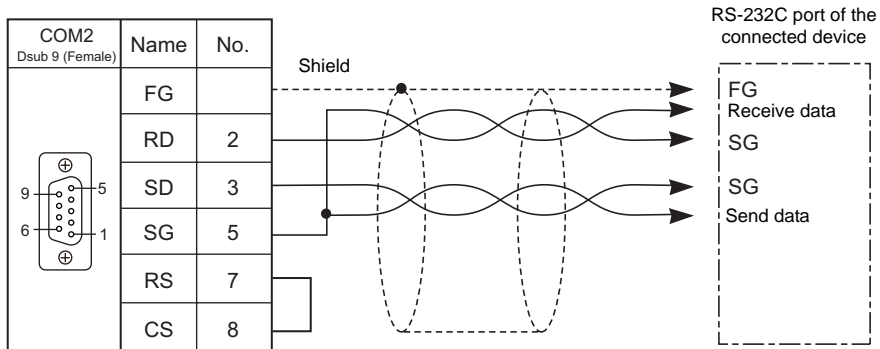


### 1.4.2 COM2 (RS-232C) Connection

- Prepare a communication cable on your side. Twisted pairs of 0.3 mm sq. or above are recommended.
- Connect a shielded cable to either the S8 series or the connected device. The connection diagram shows the case where the shielded cable is connected on the S8 series side. Connect the cable to the FG terminal on the backside of MONITOUCH.



- If noise disturbs communications, establish connections between SD and SG and between RD and SG as pairs respectively, and connect a shielded cable to both the S8 series and the connected device.



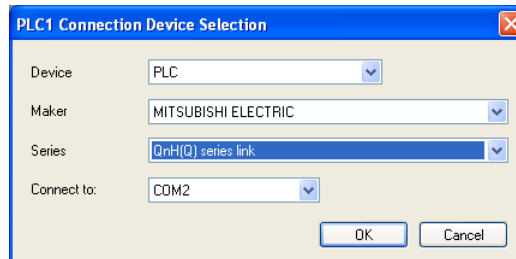
## 1.5 Settings for the Connected Device

### 1.5.1 PLC1 to PLC2

To enable communication with a PLC, a temperature controller, an inverter, etc., the following settings are required to be set on the editor. You can see the contents of these settings on the S8 Main Menu screen.

For the Main Menu screen, refer to the separate S8 Series Hardware Specifications manual.

#### Selecting a Device to be Connected

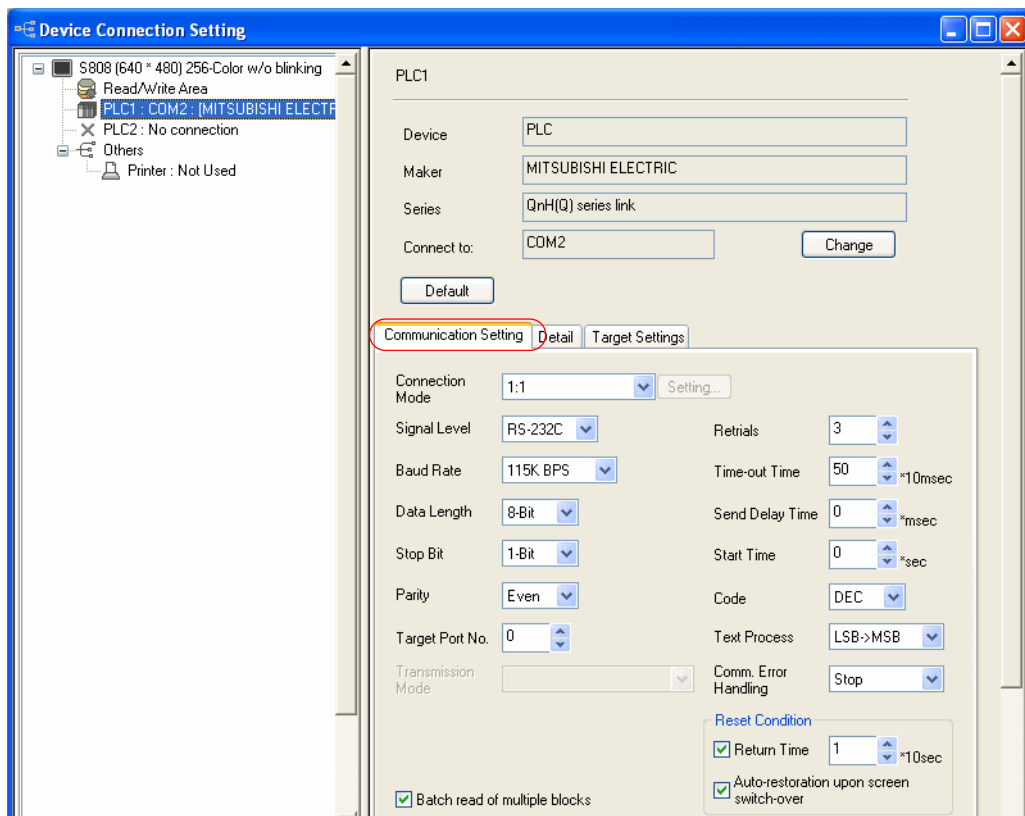


#### Note on Settings for the Connected Device

Only the logical port PLC1 can be selected for the following devices and functions. Thus, they cannot be connected at the same time.

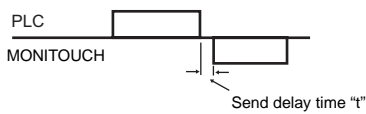
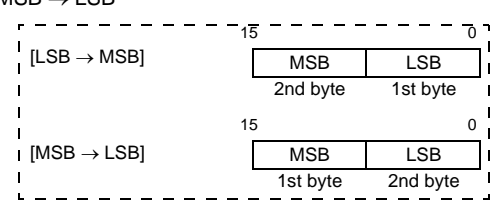
- Devices  
Universal serial connection, without PLC connection, AB Control Logix, Siemens S7-200PPI, Siemens S7-300/400MPI
- Functions  
Multi-link2, multi-link, ladder transfer, Micrex SX variable name cooperation function

#### Communication Setting



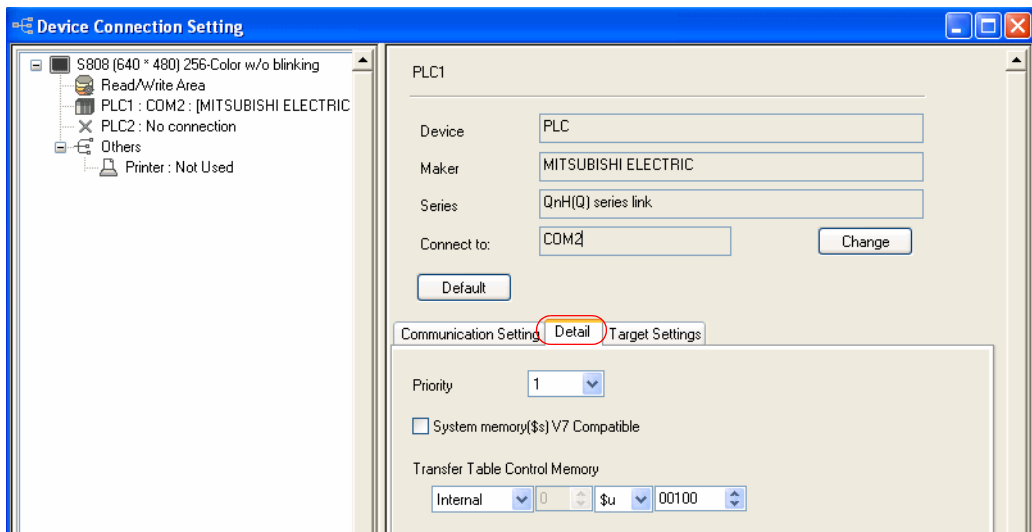
Connection Mode	Select a connection mode. 1 : 1 / 1 : n / Multi-link / Multi-link2 Available options vary, depending on which device is connected. See the list at the end of this manual.
Signal Level*1	Select a signal level. RS-232C / RS-422/485



Baud Rate* <sup>1</sup>	Select a baud rate. 4800 / 9600 / 19200 / 38400 / 57600 / 76800 / 115K BPS
Data Length* <sup>1</sup>	Select a data length. 7-Bit / 8-Bit
Stop Bit* <sup>1</sup>	Select a stop bit. 1-Bit / 2-Bit
Parity* <sup>1</sup>	Select an option for parity bit. None / Odd / Even
Target Port No. * <sup>1</sup>	Specify a port number of the connected device. 0 to 31 (Modbus RTU: 1 to 255)
Transmission Mode* <sup>1</sup>	Select a transmission mode for the connected device. This setting is required if a device of Mitsubishi, Omron, Yokogawa, or Yaskawa is in use.
Time-out Time	Specify a period of time allowed for S8 to monitor a response from its connected device. If S8 receives no response within the specified time, it retries to communicate with it. 0 to 999 (× 10 msec)
Retrials	Specify the number of retrials to be allowed in the event of a timeout during communication. If a timeout persists even after as many retrials as specified, an error handling routine will take place. 1 to 255
Send Delay Time	Specify a delay time that elapses before S8 sends the next command after receiving a response from its connected device. Normally use the default setting. 0 to 255 (× 1 msec)  
Start Time	Specify a delay time that elapses before S8 starts to send commands upon power-up. If S8 and its connected device are turned on at the same time and the device is slower to start up, set [Start Time]. 0 to 255 (× 1 sec)
Comm. Error Handling	Select an action to be taken in the event of a communication error. <ul style="list-style-type: none"> <li>• [Stop] Communication will be stopped entirely and the communication error screen will be displayed. The [RETRY] switch is available to retry the reestablishment of communication.</li> <li>• [Continue] The communication error message will be displayed in the top-left of the screen. The same communication will continue until restoration, and screen operation is not allowed then. When communication has been returned to a normal state, the message disappears and screen operation is allowed.</li> <li>• [Disconnect] No error message will appear and communication will proceed to the next. However, communication with the device, in which a timeout was detected, will be disconnected.</li> </ul>
Reset Condition	This setting is valid when [Disconnect] is selected for [Comm. Error Handling]. <ul style="list-style-type: none"> <li>• [<input type="checkbox"/> Return Time] 1 to 255 sec (× 10 sec) When the specified time has elapsed, S8 checks the restoration of the device which discontinued communicating.</li> <li>• [<input type="checkbox"/> Auto-restoration upon screen switch-over] When the screen is switched, S8 checks the restoration of the device which discontinued communicating.</li> </ul>
Code	Select a code for the connected device. The selected option is reflected through the data displayed on graphs or trending sampling parts. DEC/BCD
Text Process	Specify a byte order in text data. This setting is valid for macro commands that handle text. LSB → MSB / MSB → LSB  

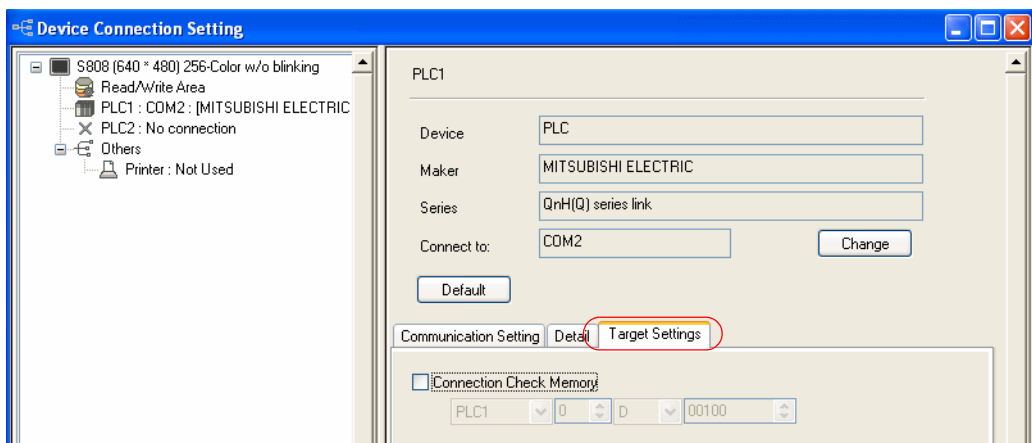
\*<sup>1</sup> Be sure to match the settings to those made on the connected device.

Detail



Priority	[1] (higher priority) - [2] (lower priority) Specify a priority taken during 2-way communication. If interrupts from two devices occur at the same time, communication with these devices will take place in order of priority.
<input type="checkbox"/> System memory (\$s) V7 Compatible (PLC1)	This box is checked if the V7-series screen data has been converted to the data for the S8 series. The system information relevant to 2-way communication will be stored in memory \$P1 and \$s. For more information, see "System Memory" (page App2-1).
<input type="checkbox"/> System memory (\$s) V7 Compatible (PLC2)	This box is checked if the V7-series screen data (including temperature control network/PLC2Way settings) has been converted to the data for the S8 series. <ul style="list-style-type: none"> <li>• Unchecked \$P2:493/494/495 is used as the transfer table control memory.</li> <li>• Checked \$s762/763/764 is used as the transfer table control memory.</li> </ul> For more information, see "System Memory" (page App2-1).
Transfer Table Control Memory	Specify the transfer table control memory for PLC1 - PLC2. The memory specified here is the same as [Control Memory] in the [Device Memory Map Setting] dialog ([System Setting] → [Device Memory Map] → [Device Memory Map Edit] window → [Device Memory Map Setting] dialog). For more information, see "Control Memory" (page App1-11).

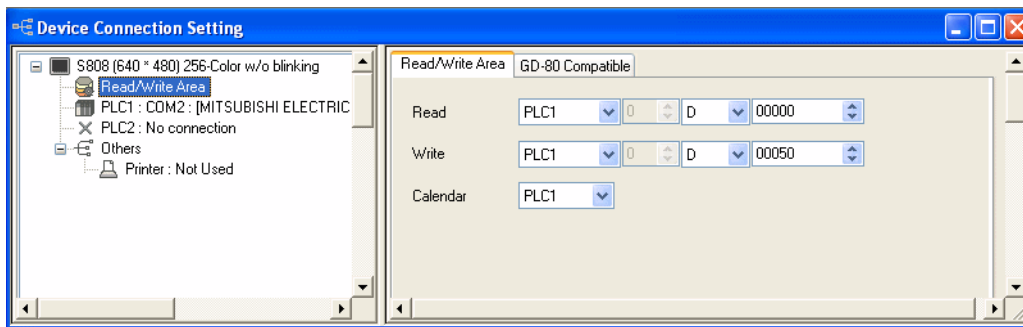
Target Settings



<input type="checkbox"/> Connection Check Memory	Specify a desired memory address used for connection confirmation when communication starts. This memory address will be used mainly during Modbus communication.
--	--

## 1.5.2 Read/Write Area

### Read/Write Area



Read Area	Specify a memory address used to give commands for display or operation from the PLC to MONITOUCH. Three words (at the minimum) <sup>*1</sup> of consecutive memory addresses are secured. For more information, see "Read area" (page 1-16).
Write area	This is the area, to which the screen numbers or overlaps displayed on MONITOUCH or a buzzer state will be written. Three words of consecutive memory addresses are secured. For more information, see "Write area" (page 1-20).
Calendar	This setting is valid when the S8's internal clock <sup>*2</sup> is not used. The setting allows the calendar data to be read from the device via the selected port at PLC1 - PLC2. The calendar data will be updated when: <ul style="list-style-type: none"> <li>• The power is turned on.</li> <li>• STOP → RUN</li> <li>• The date changes.</li> <li>• Bit 11 in the read area "n" is set (ON) (0 → 1 leading edge)</li> </ul>

\*1 More words are required if the sampling function is used:

sampling control memory (three words maximum), sampling data memory (variable depending on the setting)

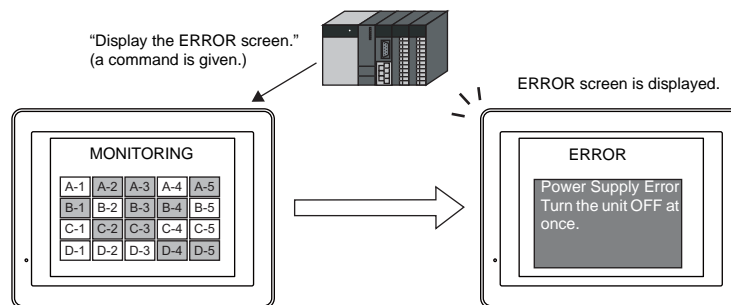
\*2 For more information on the internal clock, refer to the S8 Series Reference Manual.

### Read area

The read area is the area where the PLC gives commands for display or operation to MONITOUCH.

Three words (at the minimum) of consecutive memory addresses are secured.

MONITOUCH always reads data from these three words to display and operate according to the commands.



Memory addresses are allocated as shown below.

Address	Contents	Operation
n	Sub command/data	S8 series ← PLC
n + 1	Screen status command	
n + 2	Screen number command	

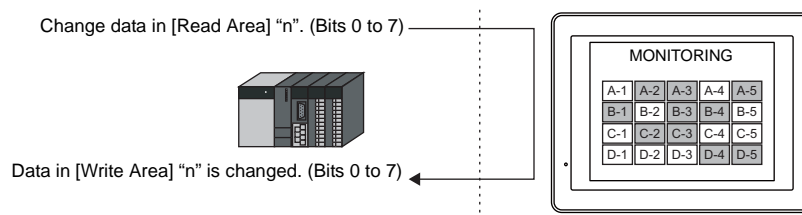
Read area =

\* Data in these memory addresses is saved at \$s460 to 462 of the S8 series internal memory. For more information on the internal memory (\$s), refer to the S8 Series Reference Manual.

Read area "n" (sub command/data)															
15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
0	0	0	0					0	0	0	0	0	0	0	0
(1) Free	When data is saved in this area, the same data is written to [Write Area] "n" after the screen has been displayed. Utilizing this operation, these bits can be used for watch dog monitoring <sup>*1</sup> or display scanning <sup>*2</sup> .														
(2) BZ0	A beep (peep) sounds at the leading edge [0 → 1].														
(3) BZ1	An error buzzer (peep-peep) sounds at the leading edge [0 → 1].														
(4) BZ2	A buzzer (feee) sounds continuously while the bit remains [1]. When setting this bit, check [Use Continuous Buzzer Sound] ([System Setting] → [Unit Setting] → [General Setting]).														
(5) Calendar setting <sup>*3</sup>	This bit is valid when the built-in clock is not used. This bit should be used differently depending on whether the connecting PLC is equipped with the calendar function.														
	When MONITOUCH is connected to a PLC with calendar function: When calendar data in the PLC is updated, it can forcibly be read by setting this bit (at the leading edge of [0 → 1]). In addition to calendar data update using this bit, calendar data in the PLC is automatically read and updated when: <ul style="list-style-type: none"> <li>• The power is turned on.</li> <li>• STOP → RUN</li> <li>• The date changes (AM 00:00:00).</li> </ul>														
	When MONITOUCH is connected to a PLC without calendar function: A virtual calendar area can be provided by setting [Calendar memory] in the [GD-80 Compatible] tab window ([Read/Write Area] → [GD-80 Compatible]). Then setting this bit (ON) updates the calendar data.														
(6) System reserved	This bit is reserved by the system. This bit must be "0".														

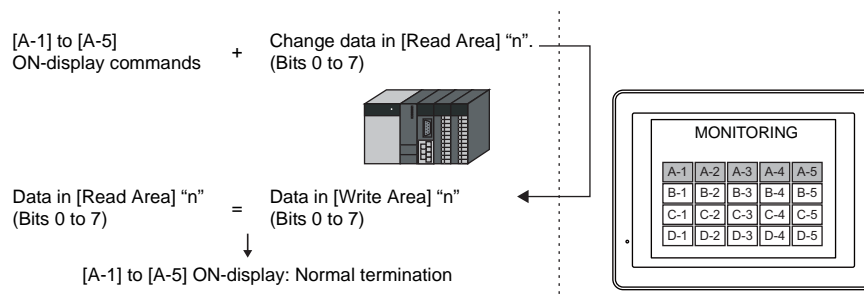
**\*1 Watchdog**

When the PLC is communicating with MONITOUCH, there is no means for the PLC to know whether or not MONITOUCH is doing operations correctly.  
To solve this one-way communication, change data in bits 0 to 7 in [Read Area] "n" and check that the same data is saved in bits 0 to 7 in [Write Area] "n". This proves that the S8 series is correctly doing operations through communications with the PLC. This verification is called "watchdog".



**\*2 Display scanning**

This operation can be utilized for display scanning. Change data in bits 0 to 7 in [Read Area] "n" when giving a graphic change command and check that the same data is saved in bits 0 to 7 in [Write Area] "n". This can prove that the graphic change command is received and executed correctly.



<sup>\*3</sup> If this bit is used during constant sampling, data sampling timing may be shifted. If this bit is set during constant sampling, we recommend you to reset the sampling as well.

Read area "n + 1" (screen status command)															
15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
			0					0	0	0	0	0			
(1) Overlap 0 (2) Overlap 1 (3) Overlap 2	<p>These bits are used for controlling show/hide operations of overlaps.</p> <ul style="list-style-type: none"> <li>Normal overlap or call-overlap [0 → 1] (leading edge<sup>*1</sup>): Show [1 → 0] (falling edge<sup>*1</sup>): Hide</li> <li>Multi-overlap [0] (level<sup>*2</sup>): Hide [1] (level<sup>*2</sup>): Show</li> </ul> <p>It is necessary to specify library No. 0 to 1023 for [Overlap Library Number] for multi-overlap.</p>														
(4) System reserved	This bit is reserved by the system. This bit must be "0".														
(5) Global macro execution	<p>The macro set for [Macro Block] is executed once at [0 → 1] (leading edge). The macro block number should be specified for [Global Macro Memory] in the dialog that is displayed by selecting [System Setting] → [Macro Setting]. For more information, refer to the Macro Reference manual provided separately.</p>														
(6) Data sheet output	<p>The data sheet is printed out at [0 → 1] (leading edge). This bit becomes valid when the data sheet function is set.</p>														
(7) Screen hard copy	<p>The S8 series screen image is printed out at [0 → 1] (leading edge). This bit becomes valid when a printer is connected. It is also possible to make a screen hard copy using an internal switch [Function: Hard Copy].</p>														
(8) Backlight	<p>This bit becomes valid when an option other than [Always ON] is selected in the [Backlight] tab window that is displayed by selecting [System Setting] → [Unit Setting]. [0] (level): OFF when the conditions are satisfied [1] (level): ON</p>														
(9) Screen internal switching	<p>This bit controls screen switching by internal switches. [0]: Screen switching by internal switches is enabled. [1]: Screen switching by internal switches is disabled. * An "internal switch" means a switch you can create for internal processing within MONITOUCH by selecting [Screen] or [Return] for [Function:] of the switch.</p>														
(10) Screen forced switching	This bit is used for switching the screen using the read area "n + 2" when the required screen number has already been specified in "n + 2". <sup>*3</sup>														
(11) Data read refresh	All the data display items on the screen are refreshed at [0 → 1] (leading edge). This is applied to every data display item regardless of the setting for [Process Cycle].														

\*1 It is possible to make this function work with the bit in the level. For more information, refer to the S8 Series Reference Manual provided separately.

\*2 As an exception, a multi-overlap may appear/disappear at the edge. For more information, refer to the S8 Series Reference Manual provided separately.

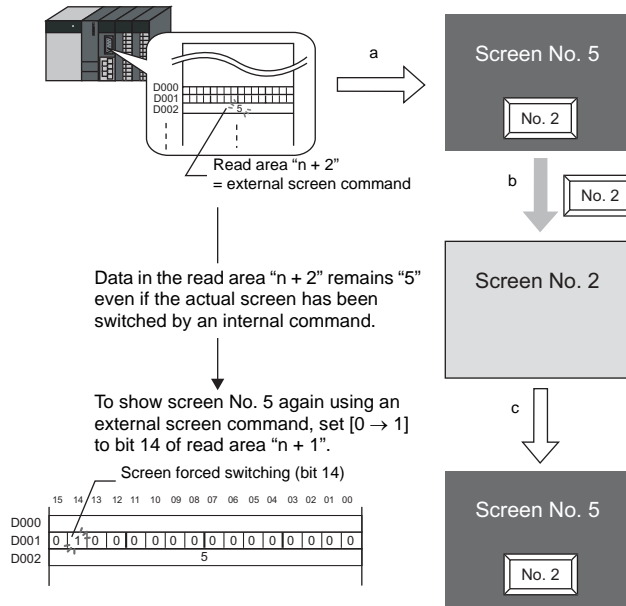
\*3 Usage Example

Step a: Screen change according to read area "n + 2"

Step b: Screen change with an internal switch

Step c: Screen change to the same screen number as step 1 according to read area "n + 2"

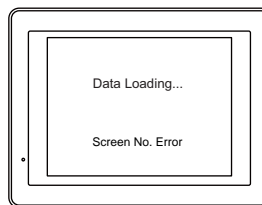
In this case, however, the same value is stored in read area "n + 2" so the command is not valid. In such a case, it is possible to forcibly switch the screen to the screen number contained in read area "n + 2" at the leading edge [0 → 1] of bit 14.



Read area "n + 2" (screen number command)															
15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
└── (1) Screen number															
(1) Screen number command *1		0 to 9999 These bits are used for switching the screen by an external command. When a screen number is specified in these bits, the screen is displayed. Even if the screen has been switched using an internal switch, it is possible to switch the screen using an external command from the PLC. External commands have priority over internal switches.													

\*1 Screen No. Error

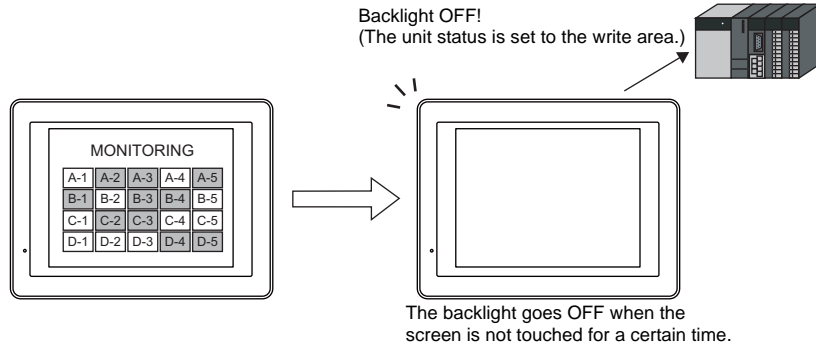
When MONITOUCH has started communications with the PLC, the screen of the screen number specified in read area "n + 2" is displayed. If the screen number specified in read area "n + 2" does not exist in the screen data, "Screen No. Error" is displayed on MONITOUCH.



Before starting communications with the PLC, check the data in [Read Area] "n + 2" and confirm that the screen number to be displayed at first is specified.

**Write area**

This is the area where data is written from [Read Area], such as the displayed screen number, overlap display status, buzzer sounding status, etc. Three words of consecutive memory addresses are secured. MONITOUCH writes information to these three words during communications with the PLC. When the S8 series has completed a display operation, sub command/data in [Read Area] "n" is written.



Memory addresses are allocated as shown below.

Address	Contents	Operation
n	Same as data in read area "n"	S8 series → PLC
n + 1	Screen status	
n + 2	Displayed screen number	

\* Data in these memory addresses is saved at \$s464 to 466 of the S8 series internal memory. For more information on the internal memory (\$s), refer to the S8 Series Reference Manual.

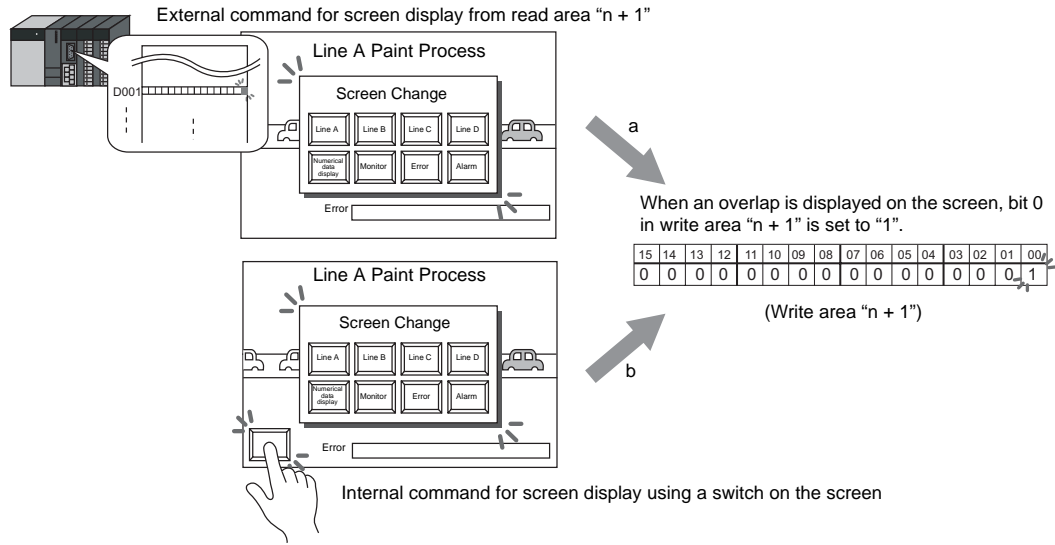
Write Area "n" (output of read area "n")															
15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
0	0	0	0					0	0	0	0	0	0	0	0
(1) Free	These bits reflect the data in read area "n" at the time MONITOUCH has been finished with processing.														
(2) BZ0															
(3) BZ1															
(4) BZ2															
(5) Calendar setting															
(6) System reserved	Always "0"														

Write area "n + 1" (screen status)															
15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
			0					0	0	0	0	0			
											(1) Overlap 0				
											(2) Overlap 1				
											(3) Overlap 2				
											(4) System reserved				
											(5) Global macro execution				
											(6) Printer busy				
											(7) Print data transferring				
											(8) Backlight				
											(9) Screen internal switching				
											(10) Screen forced switching				
											(11) Data read refresh				
(1) Overlap 0 (2) Overlap 1 (3) Overlap 2			Overlap status *1 [0]: Hide [1]: Show												
(4) System reserved			Always "0"												
(5) Global macro execution			This bit reflects the data in bit 8 of read area "n + 1".												
(6) Printer busy			Printer status *2 [0]: Not busy [1]: Busy												
(7) Print data transferring			Print data transferring status when a print command (hard copy, sample print or data sheet) is executed *2 [0 → 1]: Print data transferring start [1 → 0]: Print data transferring end												
(8) Backlight			Backlight ON/OFF status *3 [0]: OFF [1]: ON * Even if bit 11 (backlight) in read area "n + 1" is reset (0: OFF), this bit shows "1" if the backlight is on.												
(9) Screen internal switching			This bit reflects the data in bit 13 of read area "n + 1".												
(10) Screen forced switching			This bit reflects the data in bit 14 of read area "n + 1".												
(11) Data read refresh			This bit reflects the data in bit 15 of read area "n + 1".												



\*1 Example:

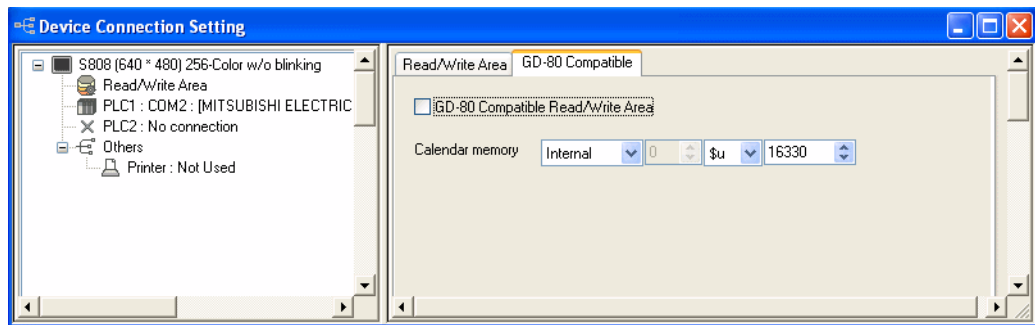
- a. Display overlap No. 0 from read area (n + 1) using an external command.
  - b. Display overlap No. 0 internally using the [Function: Overlap = ON] switch.
- In either case (a or b), bit 0 of write area "n + 1" is set (ON).  
 In the case of b, the bit in read area "n + 1" remains "0".



- \*2 Data of bits 9 and 10 is output to internal memory address \$s16. For more information on the internal memory (\$s), refer to the S8 Series Reference Manual.
- \*3 Data of bit 11 is output to internal memory address \$s17. For more information on the internal memory (\$s), refer to the S8 Series Reference Manual.

Write area "n + 2" (displayed screen number)															
15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
└─ (1) Screen number															
(1) Screen number	0 to 9999 Screen number currently displayed														

## GD-80 Compatible



<input type="checkbox"/> GD-80 Compatible Read/Write Area	<p>When converting screen data files created on the MONITOUCH GD-80/81S series into those of the S8 series, this option is automatically checked.</p> <ul style="list-style-type: none"> <li>• Unchecked: The memory addresses allocated to the S8 series are applied to the read and write areas. (See page 1-16.)</li> <li>• Checked: The memory addresses allocated to the GD-80/81S series are applied to the read and write areas. For more information on [Read Area] and [Write Area] of the GD-80/81S series, refer to the GD-80 User's Manual provided separately.</li> </ul>
Calendar memory	Use this memory area when the connected device is not equipped with the calendar function and the S8 series built-in clock * is not used.

### Calendar memory

Follow the steps below to set the calendar memory.

1. Specify the desired memory address for [Calendar memory]. Six words are occupied consecutively.
2. Save calendar data in the calendar memory addresses specified in step 1 in BCD notation.  
The allocation of calendar memory is shown below.

Memory	Contents
n	Year (BCD 0 to 99)
n + 1	Month (BCD 1 to 12)
n + 2	Day (BCD 1 to 31)
n + 3	Hour (BCD 0 to 23)
n + 4	Minute(s) (BCD 0 to 59)
n + 5	Second(s) (BCD 0 to 59)

The day of the week is automatically recognized from the above data. It is not necessary to input any data.

3. Set bit 11 (calendar setting) of read area "n". At the leading edge of this bit (0 → 1), data in calendar memory is set for calendar data.
  - \*1 Calendar data is cleared when the power is turned off. When the power is turned on, set calendar data according to the procedure mentioned above.
  - \*2 When using the calendar memory, automatic reading of calendar data at the time of PLC connection as well as once-a-day automatic correction is not performed. Consequently, some errors may be introduced. Perform the procedure described above at regular intervals.

## 1.5.3 Others

### Printer

Select when you connect PictBridge printer to the USB-B port of S8 series.  
For more information, refer to the separate S8 Series Reference manual.



# 2. ALLEN BRADLEY

---

## 2.1 PLC Connection



## 2.1 PLC Connection

### Serial Connection

PLC Selection on the Editor	CPU	Unit/Port	Signal Level	Connection		Ladder Transfer <sup>*2</sup>
				COM1	COM2	
Control Logix / Compact Logix	1756 Control Logix	Logix 5550	RS-232C	-	Wiring diagram 1 - COM2 <sup>*1</sup>	×
	1769 Compact Logix	Channel 0				
SLC500	SLC5/03 and later	Channel 0	RS-232C	-	Wiring diagram 2 - COM2	
		1747-KE DF1	RS-232C			
			RS-422	Wiring diagram 1 - COM1	-	
MicroLogix	MicroLogix 1000	Channel 0	RS-232C	-	AB's "1761-CBL-PM02"	
	MicroLogix 1100					

\*1 Can be connected using the AB's "1756-CP3" cable.

\*2 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".

## 2.1.1 Control Logix / Compact Logix

The logical port PLC1 can only be selected because the tag table is used.

### Communication Setting

#### Editor

#### Communication setting

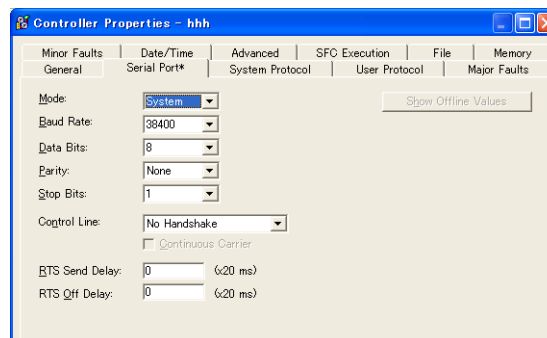
(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> : 1 / Multi-link2	For multi-link2, be sure to use the same tag table.
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 / 57600 115k bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	<u>None</u> / Odd / Even	
Target Port No.	<u>0</u> to 31	

#### PLC

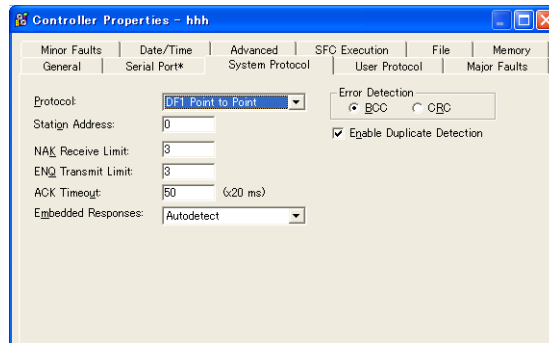
#### Control Logix

#### Serial port



Item	Setting	Remarks
MODE	System	
Baud Rate	38400	
Data Bits	8	
Parity	None	
Stop Bits	1	
Control Line	No Handshake	

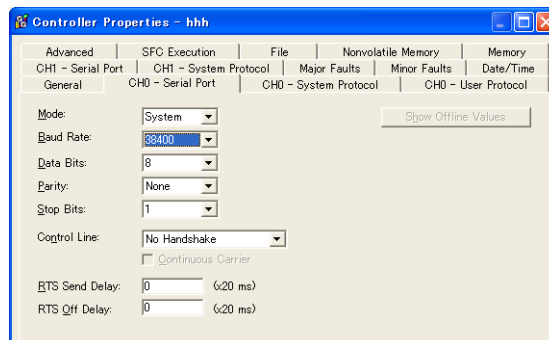
## System protocol



Item	Setting	Remarks
Protocol	DF1 Point to Point	
Station Address	0	
NAK Receive Limit	3	
ENQ Transmit Limit	3	
ACK Timeout	50	
Embedded Responses	Autodetect	
Error Detection	BCC	
Enable Duplicate Detection	Checked	

## Compact Logix

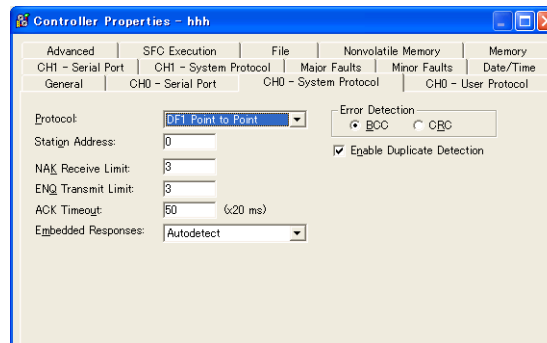
### CH0 - serial port



Item	Setting	Remarks
MODE	System	
Baud Rate	38400	
Data Bits	8	
Parity	None	
Stop Bits	1	
Control Line	No Handshake	



## CH0 - system protocol



Item	Setting	Remarks
Protocol	DF1 Point to Point	
Station Address	0	
NAK Receive Limit	3	
ENQ Transmit Limit	3	
ACK Timeout	50	
Embedded Responses	Autodetect	
Error Detection	BCC	
Enable Duplicate Detection	Checked	

## Available Memory

Create a CSV file by exporting "tag" created by using the ladder tool of the PLC. Then import the CSV file into the editor to set the PLC memory.

For more information on importing, exporting and creating a tag, refer to "Connection with A•B Control Logix" provided separately.

## 2.1.2 SLC500

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> :1 / 1 : n / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Even</u>	
Target Port No.	<u>0</u> to 31	

#### PLC

#### Channel 0



#### Channel configuration (chan. 0 - system)

The screenshot shows the 'Channel Configuration' dialog box with the 'Chan. 0 - System' tab selected. The settings are as follows:

- Driver: DF1 Full Duplex
- Baud: 19200
- Parity: NONE
- Stop Bits: 1
- Source ID: 9 (decimal)
- Control Line: No Handshaking
- Error Detection: BCC
- Embedded Responses: Auto Detect
- Duplicate Packet Detect
- ACK Timeout (x20 ms): 50
- NAK Retries: 3
- ENQ Retries: 3

Item	Setting	Remarks
Driver	<b>DF1 Full Duplex</b>	
Baud	9600 / 19200 / 38400	
Parity	<u>None</u> / Even	
Stop Bits	<u>1</u> / 2	
Control Line	<b>No Handshaking</b>	
Error Detection	<b>BCC</b>	
Embedded Responses	<b>Auto Detect</b>	

**1747-KE****Jumper JW2**

Item	Setting	Remarks
RS-232		
RS-422		

**DF1 port setup menu**

Item	Setting	Remarks
Baudrate	19200	
Bits Per Character	8	
Parity	Even	
Stop Bits	1	

**DF1 full-duplex setup menu**

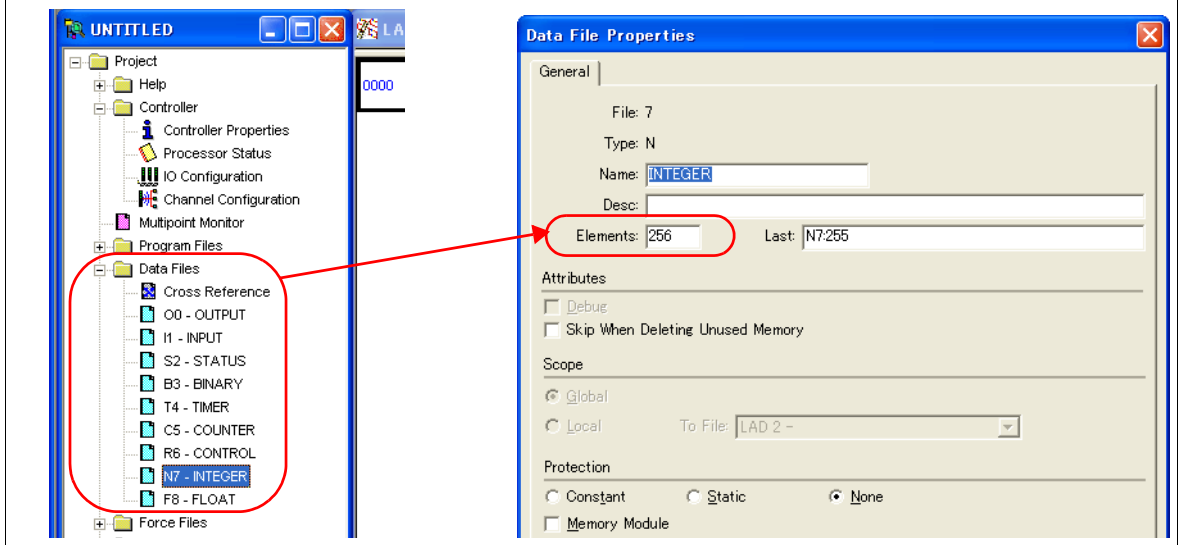
Item	Setting	Remarks
Duplicate Packet Detection	Enabled	
Checksum	BCC	
Constant Carrier Detect	Disabled	
Message Timeout	400	
Hardware Handshaking	Disabled	
Embedded Response Detect	Auto Detect	
ACK Timeout (× 5 ms)	90	
ENQuery Retries	3	
NAK Received Retries	3	

## Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
N (integer)	00H	
B (bit)	01H	
T. ACC (timer/current value)	02H	
T. PRE (timer/set value)	03H	
C. ACC (counter/current value)	04H	
C. PRE (counter/set value)	05H	
I (input)	06H	
O (output)	07H	
S (status)	08H	
T (timer/control)	09H	
C (counter/control)	0AH	
R (control)	0BH	
R. LEN (control/data length)	0CH	
R. POS (control/data position)	0DH	
D (BCD)	0EH	
A (ASCII)	0FH	
F (FLOAT)	10H	Double-word
ST (STRING)	11H	

Make settings for "Data Files" using the ladder tool. Otherwise, "Error Code 10 00" is displayed on MONITOUCH. For more information, refer to the PLC manual issued by the manufacturer.



## 2.1.3 Micro Logix

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> :1 / 1:n / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	<u>None</u> / Even	
Target Port No.	<u>0</u> to 31	

#### PLC

#### Channel Configuration

#### Channel 0 - system

Channel Configuration

General Channel 0 Channel 1

Driver: DF1 Full Duplex Source ID: 1 (decimal)

Baud: 19200

Parity: NONE

Protocol Control:

Control Line: No Handshaking ACK Timeout (x20 ms): 50

Error Detection: CRC

Embedded Responses: Auto Detect

Duplicate Packet Detect

NAK Retries: 3

ENQ Retries: 3

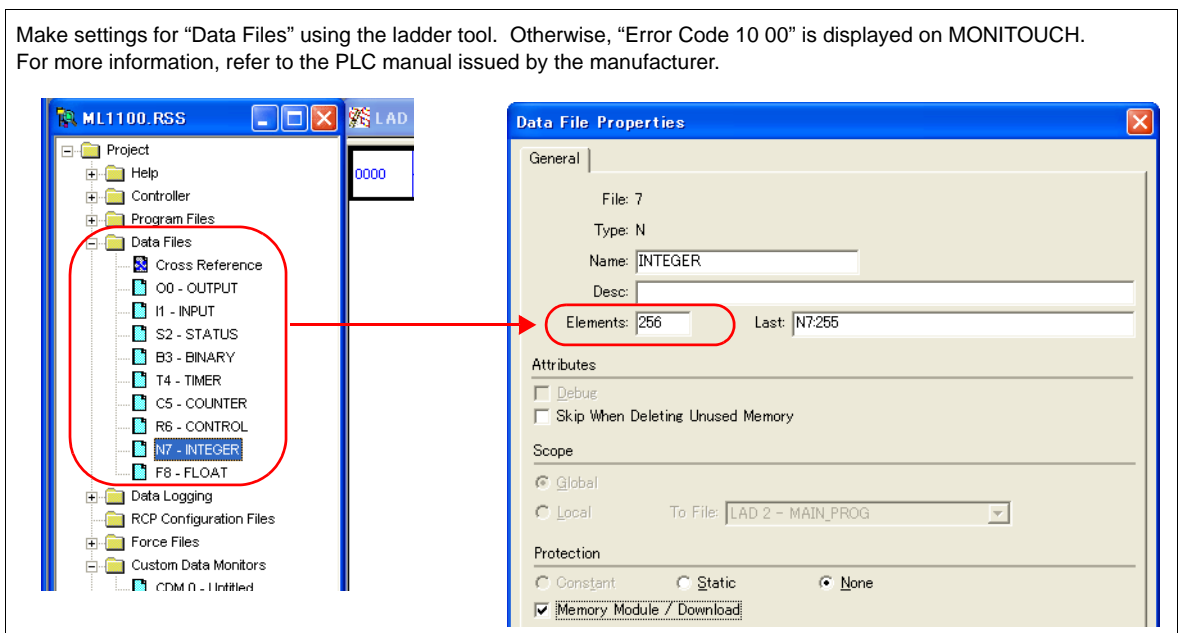
Item	Setting	Remarks
Driver	DF1 Full Duplex	
Baud	4800 / 9600 / <u>19200</u> / 38.4K	
Parity	<u>None</u> / Even	
Control Line	No Handshaking	
Error Detection	CRC / BCC	
Embedded Responses	Auto Detect	

## Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
N (integer)	00H	
B (bit)	01H	
T. ACC (timer/current value)	02H	
T. PRE (timer/set value)	03H	
C. ACC (counter/current value)	04H	
C. PRE (counter/set value)	05H	
I (input)	06H	
O (output)	07H	
S (status)	08H	
T (timer/control)	09H	
C (counter/control)	0AH	
R (control)	0BH	
R. LEN (control/data length)	0CH	
R. POS (control/data position)	0DH	
D (BCD)	0EH	
A (ASCII)	0FH	
F (FLOAT)	10H	Double-word
ST (STRING)	11H	
L (LONG)	12H	Double-word

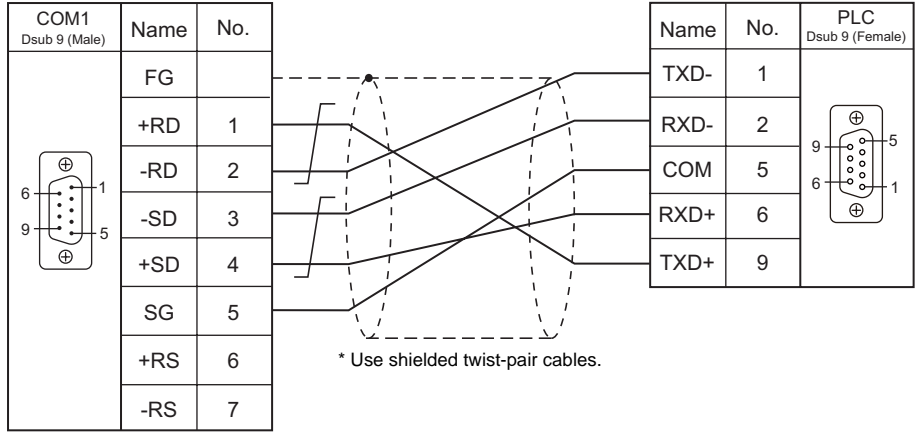
Make settings for "Data Files" using the ladder tool. Otherwise, "Error Code 10 00" is displayed on MONITOUCH. For more information, refer to the PLC manual issued by the manufacturer.



## 2.1.4 Wiring Diagrams

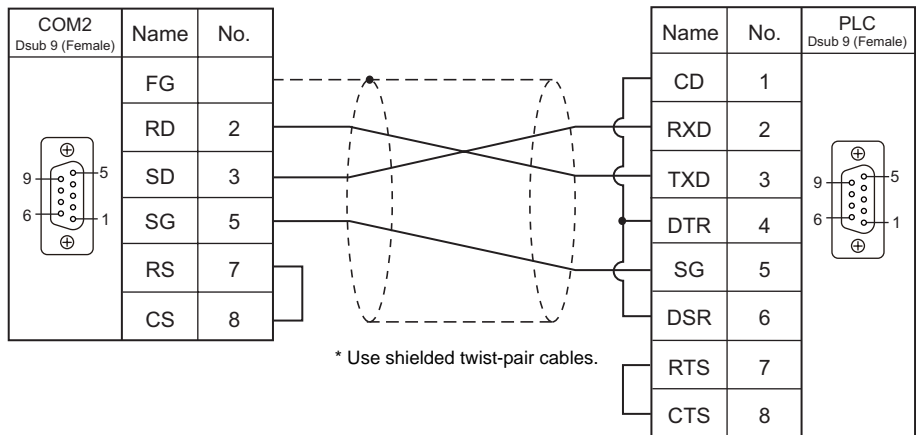
### When Connected at COM1 (RS-422 / RS-485):

Wiring diagram 1 - COM1

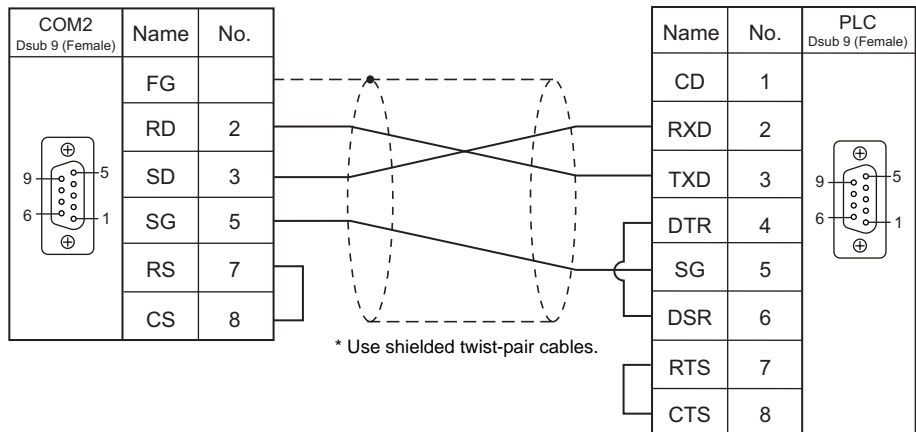


### When Connected at COM2 (RS-232C):

Wiring diagram 1 - COM2



Wiring diagram 2 - COM2



# 3. Automation Direct

---

## 3.1 PLC Connection





## 3.1 PLC Connection

### Serial Connection

PLC Selection on the Editor	PLC	Port	Signal Level	Connection		Ladder Transfer *1
				COM1	COM2	
Direct LOGIC (K-Sequence)	D4-430 D4-440	Port 0	RS-232C	-	Wiring diagram 4 - COM2	×
		Port 1	RS-232C	-	Wiring diagram 1 - COM2	
			RS-422	Wiring diagram 1 - COM1	-	
	D4-450	Port 0	RS-232C	-	Wiring diagram 4 - COM2	
		Port 1	RS-232C	-	Wiring diagram 1 - COM2	
			RS-422	Wiring diagram 1 - COM1	-	
		Port 2	RS-232C	-	Wiring diagram 3 - COM2	
		Port 3	RS-422	Wiring diagram 2 - COM1	-	
	D2-230	PORT1	RS-232C	-	Wiring diagram 3 - COM2	
	D2-240 DL05	PORT1				
		PORT2				
	D2-250-1 D2-260 DL06	PORT1	RS-232C	-	Wiring diagram 2 - COM2	
PORT2		RS-422	Wiring diagram 3 - COM1	-		
Direct LOGIC (MODBUS RTU)	D4-450	Port 1	RS-232C	-	Wiring diagram 1 - COM2	
			RS-422	Wiring diagram 1 - COM1	-	
		Port 3	RS-422	Wiring diagram 2 - COM1	-	
	D2-250-1 D2-260	PORT2	RS-232C	-	Wiring diagram 2 - COM2	
			RS-422	Wiring diagram 3 - COM1	-	

\*1 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".

### 3.1.1 Direct LOGIC (K-Sequence)

#### Communication Setting

##### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> :1 / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Odd</u> / Even	
Target Port No.	0 to 31	

##### D4-450

##### PORT0

No particular setting is necessary on the PLC. The PLC always performs communication functions using the following parameters. Set the following parameters on the [Communication Setting] tab window of the editor.

Item	Setting	Remarks
Baud Rate	9600 bps	
Parity	Odd	
Data Length	8	
Stop Bit	1	
Data Type	HEX	

##### PORT1

Set parameters into the special register "R772, 773", then set "AA5A" (HEX) into the setting complete register "R767". When the set value at R767 is changed to "AAAA" (HEX), it is regarded as normal; if it is changed to "AAEA" (HEX), it is regarded as erroneous.

##### Parameter setting register

Register	Setting	Setting Example
R772	<p>0 0 E 0</p> <p>Communication protocol 80: K-Sequence E0: Automatic recognition (Modbus, CCM, K-Sequence)</p> <p>Communication timeout 0: 800 ms</p> <p>Response delay time 0: 0 ms</p>	<p>00E0H</p> <p>K-Sequence</p>

Register	Setting	Setting Example
R773	<p>Station number 01 to 1F (HEX)</p> <p>Baud rate 4: 4800 bps 5: 9600 bps <u>6: 19200 bps</u> 7: 38400 bps</p> <p>Parity stop bit 0: Without parity, stop bit 1 2: Without parity, stop bit 2 <u>8: Odd parity, stop bit 1</u> A: Odd parity, stop bit 2 C: Even parity, stop bit 1 E: Even parity, stop bit 2</p>	<p>8701H</p> <p>38400 bps Odd parity Stop bit 1 Station number 01</p>

## PORT2

Set parameters into the special register "R774, 775", then set "A5AA" (HEX) into the setting complete register "R767". When the set value at R767 is changed to "AAAA" (HEX), it is regarded as normal; if it is changed to "AEEA" (HEX), it is regarded as erroneous.

### Parameter setting register

Register	Setting	Setting Example
R774	Same as the setting register R772 for PORT1	00E0H
R775	Same as the setting register R773 for PORT1	8701H

## PORT3

Set parameters into the special register "R776, 777", then set "5AAA" (HEX) into the setting complete register "R767". When the set value at R767 is changed to "AAAA" (HEX), it is regarded as normal; if it is changed to "EAAA" (HEX), it is regarded as erroneous.

### Parameter setting register

Register	Setting	Setting Example
R776	Same as the setting register R772 for PORT1	00E0H
R777	Same as the setting register R773 for PORT1	8701H

**D2-240/D2-250-1****PORT1 / PORT2**

No particular setting is necessary on the PLC. The PLC performs communication functions using the following parameters. Set the following parameters on the [Communication Setting] tab window of S8.

Item	Setting	Remarks
Baud Rate	9600 bps	For PORT2: 19200 bps can be set in the special register.
Parity	Odd	
Data Length	8	
Stop Bit	1	
Data Type	HEX	

**Available Memory**

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
V (data register)	00H	
X (input)	01H	
Y (output)	02H	
C (internal relay)	03H	
S (stage)	04H	
GX (transmission relay for all stations)	05H	
GY (transmission relay for specified station)	06H	
T (timer/contact)	07H	
CT (counter/contact)	08H	

## 3.1.2 Direct LOGIC (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> : 1 / 1 : n / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 bps	
Data Length	8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / Even	
Target Port No.	1	

#### D4-450

#### PORT1

Set parameters into the special register "R772, 773", then set "AA5A" (HEX) into the setting complete register "R767". When the set value at R767 is changed to "AAAA" (HEX), it is regarded as normal; if it is changed to "AAEA" (HEX), it is regarded as erroneous.

#### Parameter setting register

Register	Setting	Setting Example
R772	<p>0 0 E 0</p> <ul style="list-style-type: none"> <li>Communication protocol 20: MODBUS RTU <u>E</u>: Automatic recognition (Modbus, CCM, K-Sequence)</li> <li>Communication timeout 0: 800 ms</li> <li>Response delay time 0: 0 ms</li> </ul>	00E0H
R773	<p>8 6 0 1</p> <ul style="list-style-type: none"> <li>Station number 01 to 1F (HEX)</li> <li>Baud rate 4: 4800 bps 5: 9600 bps <u>6</u>: 19200 bps 7: 38400 bps</li> <li>Parity stop bit 0: Without parity, stop bit 1 2: Without parity, stop bit 2 <u>8</u>: Odd parity, stop bit 1 A: Odd parity, stop bit 2 C: Even parity, stop bit 1 E: Even parity, stop bit 2</li> </ul>	8701H 38400 bps Odd parity Stop bit 1 Station number 01

## PORT3

Set parameters into the special register "R776, 777", then set "5AAA" (HEX) into the setting complete register "R767". When the set value at R767 is changed to "AAAA" (HEX), it is regarded as normal; if it is changed to "EAAA" (HEX), it is regarded as erroneous.

### Parameter setting register

Register	Setting	Setting Example
R776	Same as the setting register R772 for PORT1	00E0H
R777	Same as the setting register R773 for PORT1	8701H

## D2-250-1

## PORT2

Set parameters into the special register "R7655, 7656", then set "0500" (HEX) into the setting complete register "R7657". When the set value at R7657 is changed to "0A00" (HEX), it is regarded as normal; if it is changed to "0E00" (HEX), it is regarded as erroneous.

### Parameter setting register

Register	Setting	Setting Example
R7655	<p>0 0 2 0</p> <ul style="list-style-type: none"> <li>Communication protocol 20: MODBUS RTU</li> <li>Communication timeout 0: Specified time</li> <li>Response delay time 0: 0 ms</li> </ul>	0020H
R7656	<p>8 7 0 1</p> <ul style="list-style-type: none"> <li>Station number 01 to 7A (HEX)</li> <li>Baud rate 4: 4800 bps 5: 9600 bps 6: 19200 bps 7: 38400 bps</li> <li>Parity stop bit 0: Without parity, stop bit 1 2: Without parity, stop bit 2 8: <u>Odd parity, stop bit 1</u> A: Odd parity, stop bit 2 C: Even parity, stop bit 1 E: Even parity, stop bit 2</li> </ul>	8701H 38400 bps Odd parity Stop bit 1 Station number 01

## Available Memory

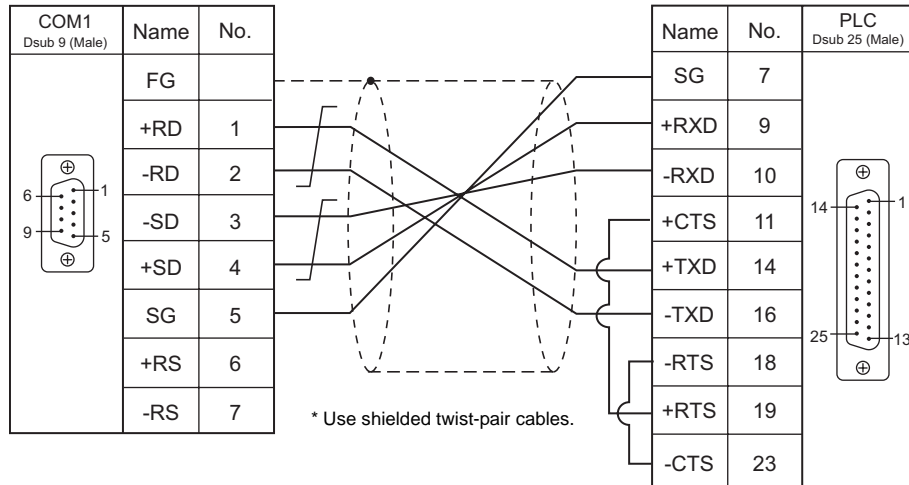
The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
V (data register)	00H	
X (input)	01H	
Y (output)	02H	
C (internal relay)	03H	
S (stage)	04H	
GX (transmission relay for all stations)	05H	
GY (transmission relay for specified station)	06H	
T (timer/contact)	07H	
CT (counter/contact)	08H	

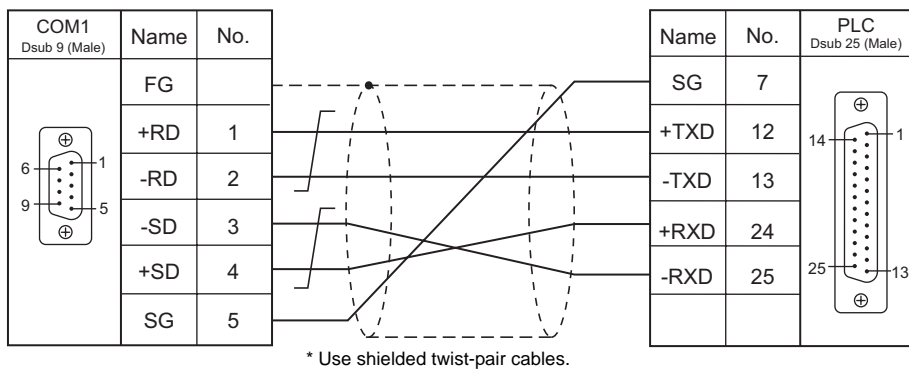
### 3.1.3 Wiring Diagrams

#### When Connected at COM1 (RS-422 / RS-485):

**Wiring diagram 1 - COM1**

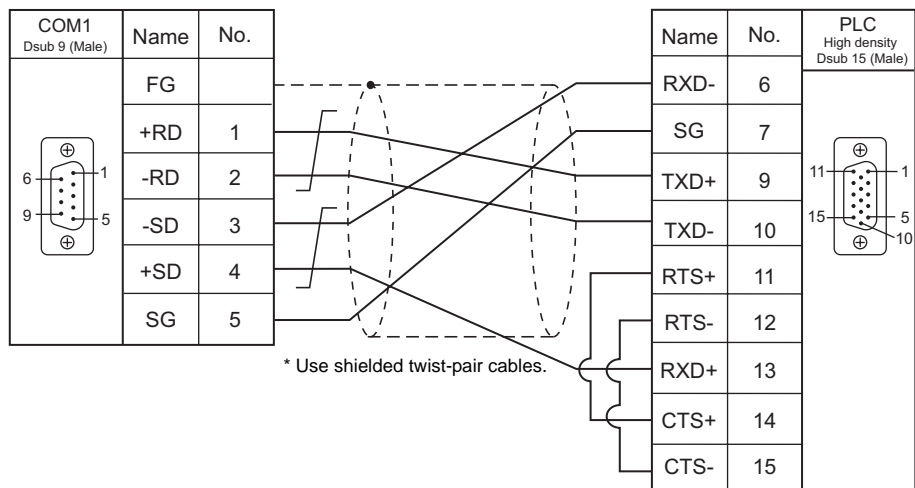


**Wiring diagram 2 - COM1**



\* SU-6M: Terminal block connectable

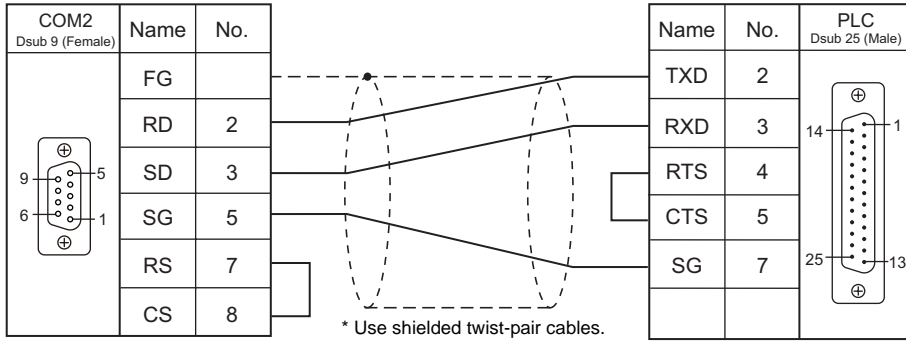
**Wiring diagram 3 - COM1**



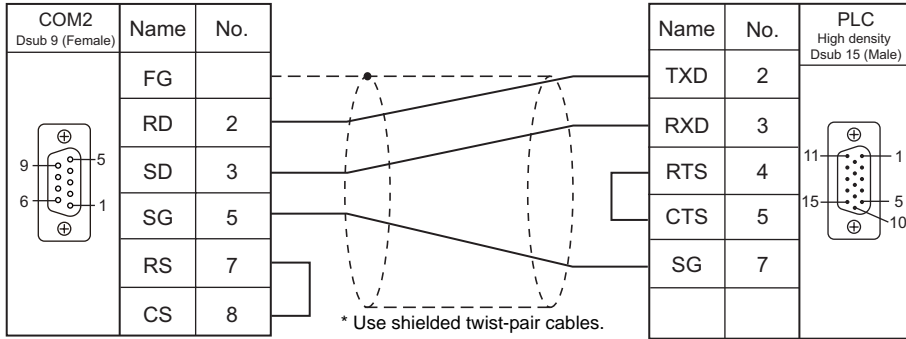


**When Connected at COM2 (RS-232C):**

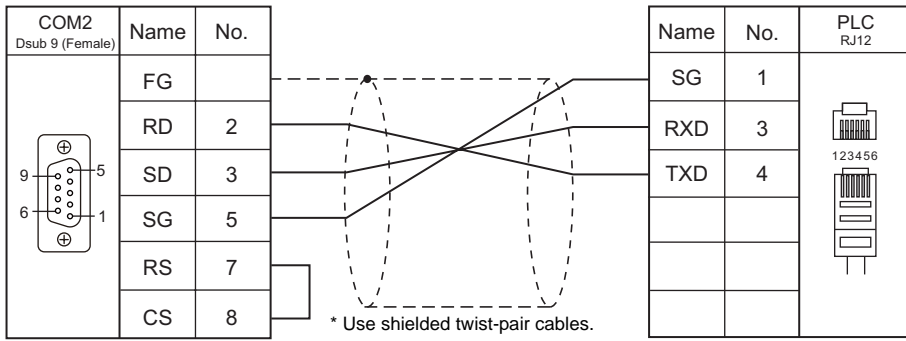
**Wiring diagram 1 - COM2**



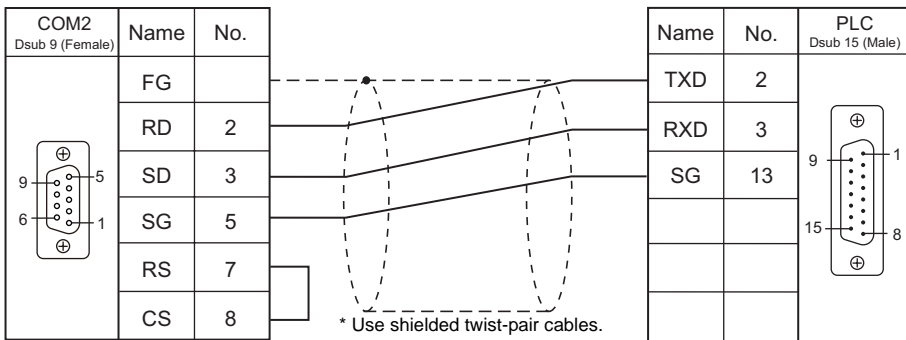
**Wiring diagram 2 - COM2**



**Wiring diagram 3 - COM2**



**Wiring diagram 4 - COM2**



# 4. EATON Cutler-Hammer

---

## 4.1 PLC Connection



## 4.1 PLC Connection

The PLC models shown below can be connected.

### Serial Connection

PLC Selection on the Editor	CPU	Unit/Port	Signal Level	Connection		Ladder Transfer *1
				COM1	COM2	
ELC	ELC-PA10 ELC-PC12 ELC-PH12 ELC-PB14	Programming port on the CPU unit (COM1)	RS-232C	-	Wiring diagram 1 - COM2	×
		Communication port on the CPU unit (COM2)	RS-485	Wiring diagram 1 - COM1	-	

\*1 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".

## 4.1.1 ELC

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> :1 / 1:n / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 / 115200 bps	
Data Length	<u>Z</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bit	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>1</u> to 31	

#### PLC

Make the PLC setting using the data register memory "D". For more information, refer to the PLC manual issued by the manufacturer.

### Available Memory

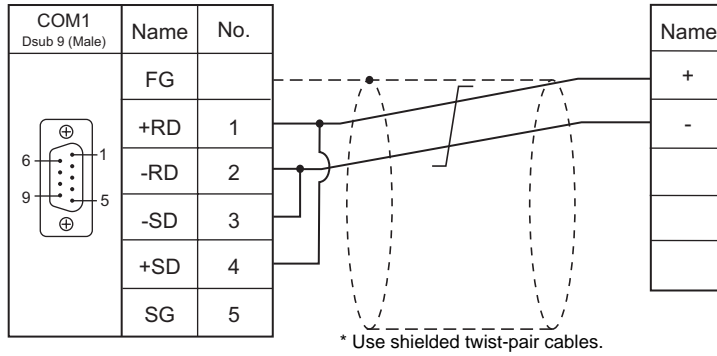
The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

	Memory	TYPE	Remarks
D	(data register)	00H	
X	(input)	01H	Read only
Y	(output)	02H	
M	(auxiliary relay)	03H	
S	(step point)	04H	
T	(timer)	05H	
C	(counter)	06H	
32C	(high-speed counter)	07H	Double-word

## 4.1.2 Wiring Diagrams

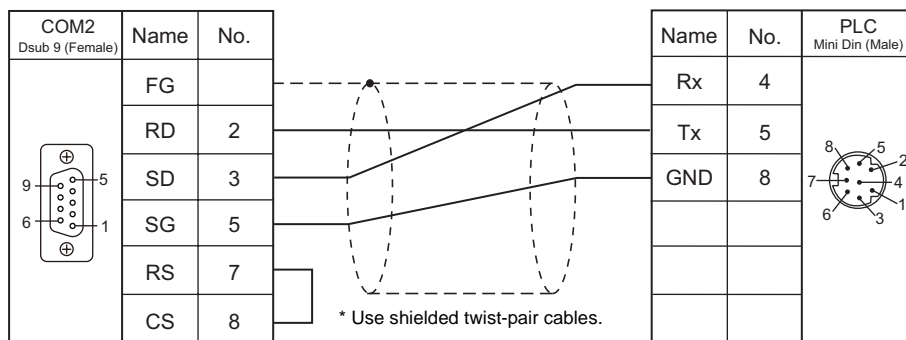
### When Connected at COM1 (RS-422 / RS-485):

Wiring diagram 1 - COM1



### When Connected at COM2 (RS-232C):

Wiring diagram 1 - COM2



# MEMO

Please use this page freely.

# 5.FANUC

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## 5.1 PLC Connection





## 5.1 PLC Connection

### Serial Connection

PLC Selection on the Editor	CPU	Unit/Port	Signal Level	Connection		Ladder Transfer *1
				COM1	COM2	
Power Mate	Power Mate Model H/D	JD14	RS-422	Wiring diagram 1 - COM1	-	×
	Power Mate i Model H/D	JD40	RS-422	Wiring diagram 2 - COM1	-	
		JD42	RS-232C	-	Wiring diagram 1 - COM2	
	16-Model C	JD5B	RS-232C	-	Wiring diagram 2 - COM2	
	16i-Model A 16i-Model B 18i-Model A 18i-Model B 18-Model C 21i-Model A 21i-Model B	JD36B	RS-232C	-		
	30i-Model A 31i-Model A 32i-Model A	JD36A		-		
		JD54		-	Wiring diagram 3 - COM2	

\*1 For the ladder transfer function, see "Appendix 5 Ladder Transfer Function".

## 5.1.1 Power Mate

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / Multi-link2	
Signal Level	RS-232C / RS-422/RS-485	
Baud Rate	19200 bps (fixed)	
Data Length	8 bits (fixed)	
Stop Bit	1 bits (fixed)	
Parity	Even (fixed)	

### Available Memory

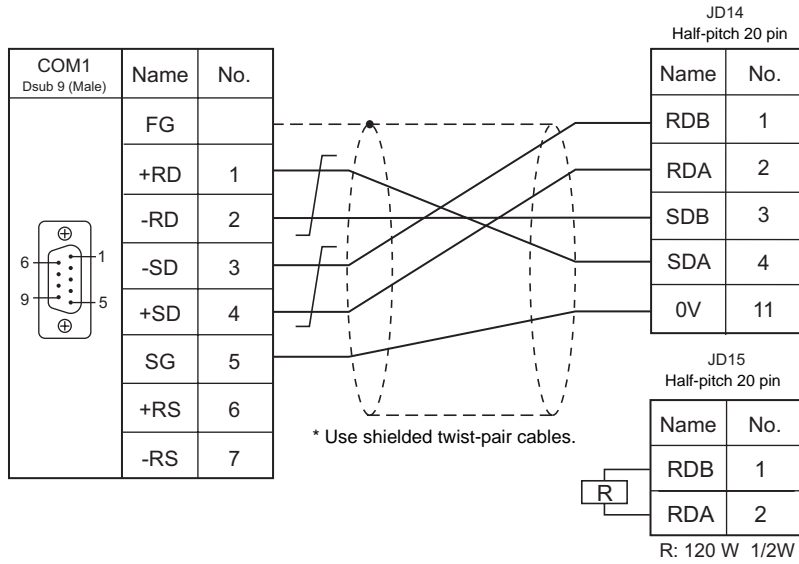
The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
D (data table)	00H	
X input relay	01H	WX as word device
Y output relay	02H	WY as word device
R internal relay	03H	WR as word device
K keep relay	04H	WK as word device
T timer	05H	
C counter	06H	
E extensional relay	07H	WE as word device

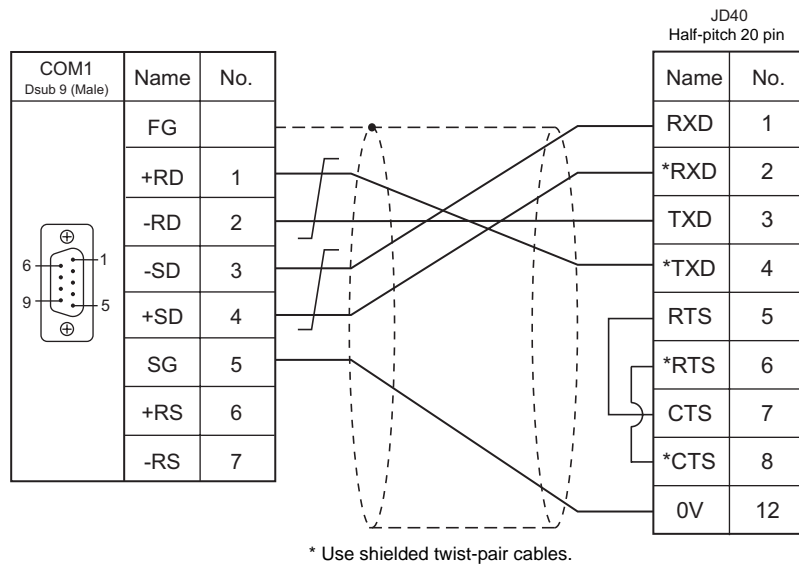
## 5.1.2 Wiring Diagrams

### When Connected at COM1 (RS-422 / RS-485):

Wiring diagram 1 - COM1

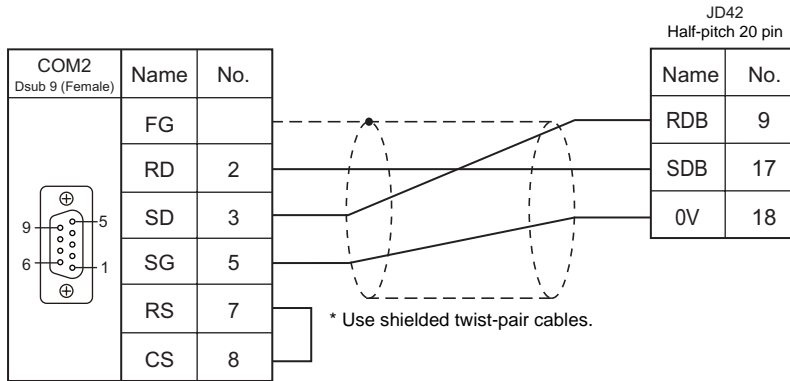


Wiring diagram 2 - COM1

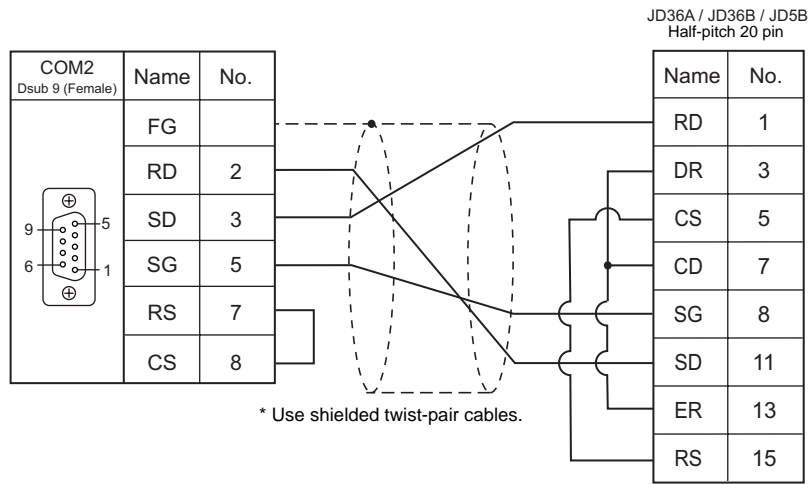


**When Connected at COM2 (RS-232C):**

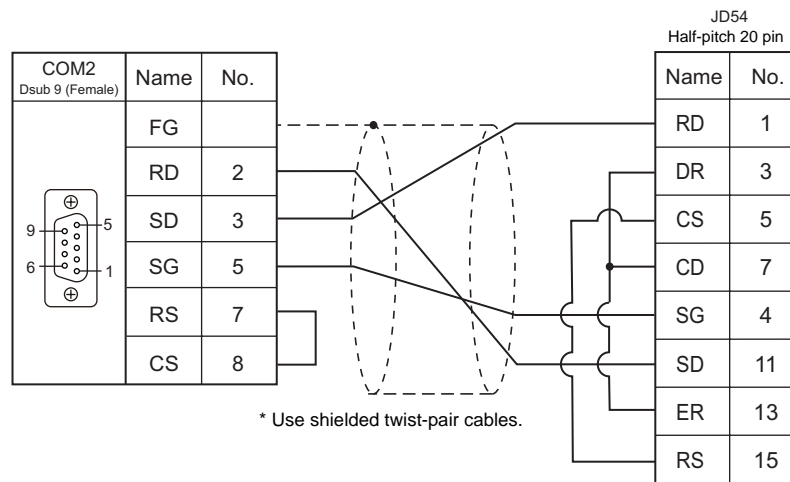
**Wiring diagram 1 - COM2**



**Wiring diagram 2 - COM2**



**Wiring diagram 3 - COM2**



# 6. FATEK AUTOMATION

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## 6.1 PLC Connection



## 6.1 PLC Connection

The PLC models shown below can be connected.

### Serial Connection

PLC Selection on the Editor	CPU	Unit/Port	Signal Level	Connection		Ladder Transfer *1	
				COM1	COM2		
FACON FB series	FBE-20MC FBE-28MC FBE-40MC	Programming port on the CPU unit		RS-232C	-	Wiring diagram 1 - COM2	×
				RS-485	Wiring diagram 1 - COM1	-	
		FB-DTBR	Port1 (Dsub 15 pin)	RS-232C	-	Wiring diagram 1 - COM2	
			Port1 (Dsub 9 pin)	RS-232C	-	Wiring diagram 2 - COM2	
			Port2 (Terminal block)	RS-485	Wiring diagram 2 - COM1	-	

\*1 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".



## 6.1.1 FACON FB series

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> : 1 / 1 : n / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 bps	
Data Length	<u>Z</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bit	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>1</u> to 31	

#### PLC

Make the PLC setting using the configuration tool "PRO\_LADDER". For more information, refer to the PLC manual issued by the manufacturer.

### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

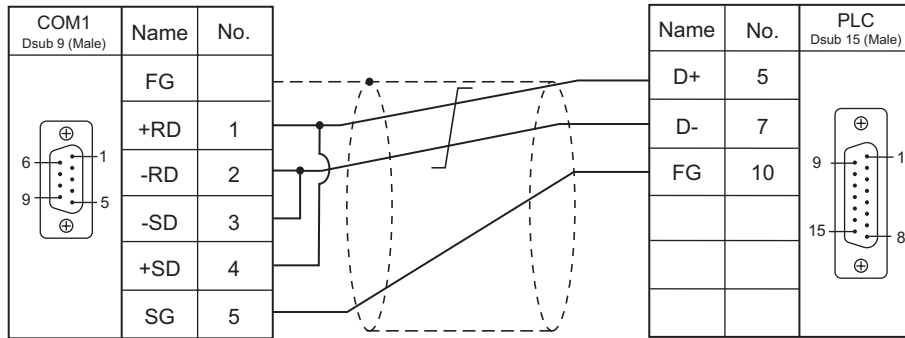
Memory	TYPE	Remarks
HR (data register)	00H	
DR (data register)	01H	
X (input relay)	02H	WX as word device
Y (output relay)	03H	WY as word device
M (internal relay)	04H	WM as word device
S (step relay)	05H	WS as word device
T (timer/contact)	06H	WT as word device
C (counter/contact)	07H	WC as word device
RT (timer/current value)	08H	
RC (counter/current value)	09H	
DRC (32-bit counter/current value)	10H	*1

- \*1 For items where double-words can be used (Num. Display, Graph, Sampling), data is processed as double-words.  
 For those where bits or words can be used, data is processed as words consisting of lower 16 bits.  
 For input: Upper 16 bits are ignored.  
 For output: "0" is written for upper 16 bits.

## 6.1.2 Wiring Diagrams

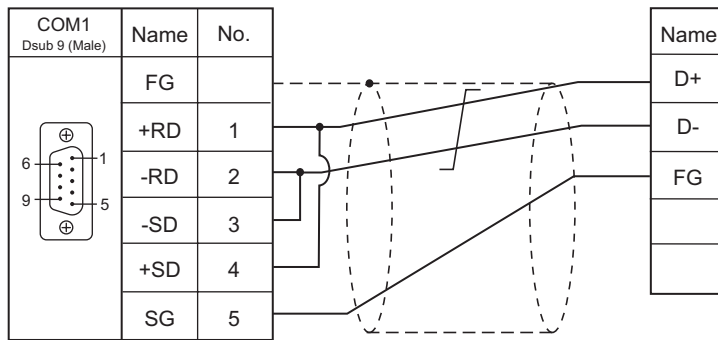
### When Connected at COM1 (RS-422 / RS-485):

Wiring diagram 1 - COM1



\* Use shielded twist-pair cables.

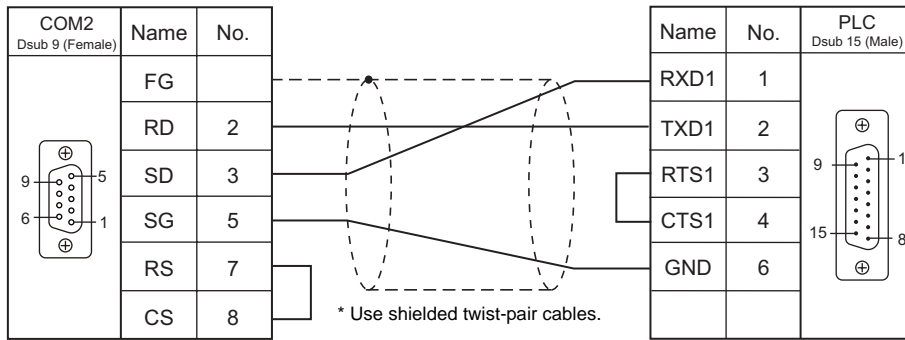
Wiring diagram 2 - COM1



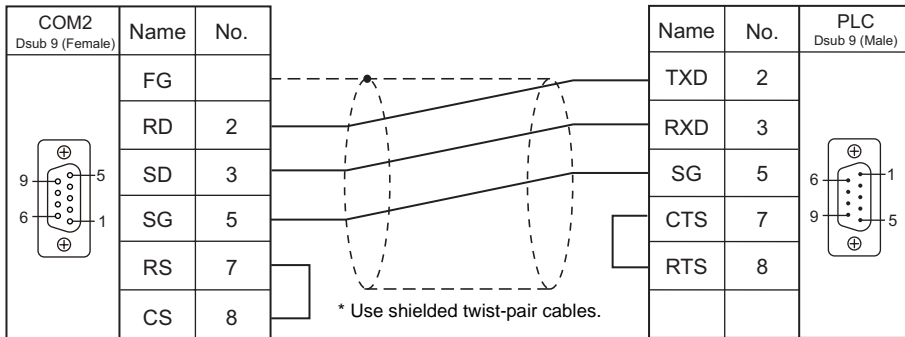
\* Use shielded twist-pair cables.

## When Connected at COM2 (RS-232C):

### Wiring diagram 1 - COM2



### Wiring diagram 2 - COM2



# 7. Fuji Electric

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7.1 PLC Connection

7.2 Temperature Controller/Servo/Inverter Connection



## 7.1 PLC Connection

The PLC models shown below can be connected.

### Serial Connection

#### MICREX-F Series

PLC Selection on the Editor	CPU	Unit/Port	Signal Level	Connection		Ladder Transfer *1
				COM1	COM2	
MICREX-F series	NV1P-x (F55)	NV1L-RS2	RS-232C	-	Wiring diagram 1 - COM2	×
	NC1P-E (F70) NC1P-S (F70S)	NC1L-RS2	RS-232C	-	Wiring diagram 1 - COM2	
		NC1L-RS4	RS-485	Wiring diagram 1 - COM1	-	
	FPU080H (F80H) FPU120H (F120H) FPU120S (F120S) FPU140S (F140S) FPU15xS (F15xS)	FFU120B	RS-232C	-	Wiring diagram 1 - COM2	
		FFK120A	RS-485	Wiring diagram 1 - COM1	-	

\*1 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".

#### SPB (N Mode), FLEX-PC

PLC Selection on the Editor	CPU	Unit/Port	Signal Level	Connection		Ladder Transfer *1
				COM1	COM2	
SPB (N mode) & FLEX-PC series	NS-CPU-xx	NS-RS1	RS-232C	-	Wiring diagram 1 - COM2	×
			RS-485	Wiring diagram 1 - COM1	-	
	NJ-CPU-xx	NJ-RS2	RS-232C	-	Wiring diagram 1 - COM2	
			NJ-RS4	RS-485	Wiring diagram 1 - COM1	
	NBxx	NB-RS1	RS-232C	-	Wiring diagram 1 - COM2	
			RS-485	Wiring diagram 1 - COM1	-	
	NW0Pxx (SPB)	NW0LA-RS2	RS-232C	-	Wiring diagram 3 - COM2	
			NW0LA-RS4	RS-485 (4-wire)	Wiring diagram 1 - COM1	
RS-485 (2-wire)				Wiring diagram 2 - COM1	-	
SPB (N Mode) & FLEX-PC CPU	NS-CPU-xx NJ-CPU-xx NBxx NW0Pxx (SPB)	CPU port	RS-485	Hakko Electronics' cable "D9-FU-SPBCPU" *2	-	×
	NJ-CPU-B16	RS-232C port	RS-232C	-	Wiring diagram 2 - COM2	×

\*1 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".

\*2 Cable length: XXX-FU-SPBCPU-□M (□= 2, 3, 5 m)

## MICREX-SX, SPB (IEC Mode)

PLC Selection on the Editor	CPU	Unit/Port	Signal Level	Connection		Ladder Transfer <sup>*1</sup>
				COM1	COM2	
MICREX-SX SPH/SPB series	NP1Px-xx (SPH)	NP1L-RS1	RS-232C	-	Wiring diagram 4 - COM2	×
			RS-485	Wiring diagram 3 - COM1	-	
		NP1L-RS2, NP1L-RS3	RS-232C	-	Wiring diagram 4 - COM2	
			RS-485	Wiring diagram 3 - COM1	-	
	NW0Pxx (SPB)	NW0LA-RS2	RS-232C	-	Wiring diagram 3 - COM2	
			RS-485	Wiring diagram 3 - COM1	-	
MICREX-SX SPH/SPB CPU	NP1Px-xx (SPH)	CPU port	RS-485	Hakko Electronics' cable "D9-FU-SPHCPU" <sup>*2</sup>	-	○
	NW0Pxx (SPB)	CPU port	RS-485	Hakko Electronics' cable "D9-FU-SPBCPU" <sup>*2</sup>	-	

\*1 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".

\*2 Cable length: XXX-FU-SPHCPU-□M, XXX-FU-SPBCPU-□M (□ = 2, 3, 5 m)

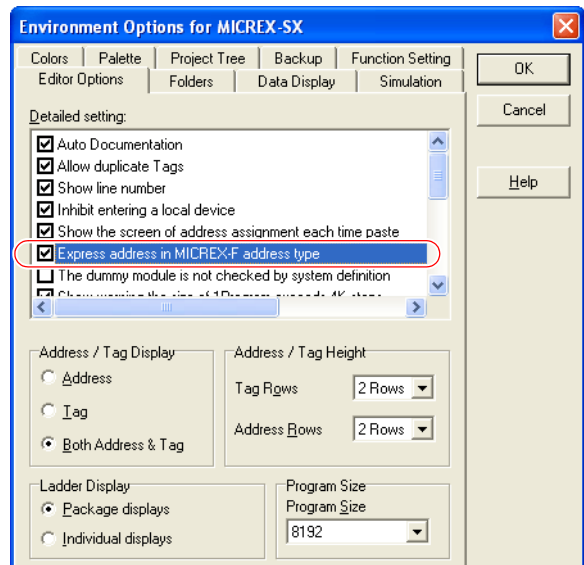
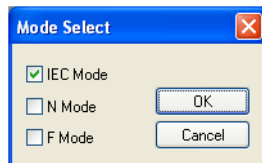
## MICREX-SX Model Selection

When the MICREX-SX SPH or SPB series is connected, a mode selection may be required on the S8 editor depending on the programming tool used on the PLC or the setting on the programming tool.

PLC	PLC Programming Tool			Setting on the S8 Editor	
		Environment Options for MICREX-SX		PLC Selection	Mode Selection <sup>*2</sup>
SPH series	SX-Programmer Expert (D300win)			MICREX-SX SPH / SPB series MICREX-SX SPH / SPB CPU	IEC Mode
	SX-Programmer Standard	Unchecked <sup>*1</sup>		MICREX-SX T-Link MICREX-SX OPCN-1 MICREX-SX Ethernet	N Mode
Checked <sup>*1</sup>				F Mode	
SPB Series	SX-Programmer Expert (D300win)			MICREX-SX SPH / SPB series MICREX-SX SPH / SPB CPU	IEC Mode
	SX-Programmer Standard	SX-MODE	Unchecked <sup>*1</sup>		N Mode
			Checked <sup>*1</sup>	F Mode	
	N-MODE		-	SPB (N mode) & FLEX-PC series SPB (N mode) & FLEX-PC CPU	-
FLEX-PC Programmer			-	-	

\*1 Check or uncheck the box for [Express address in MICREX-F address type] on the [Editor Options] tab window in the [Environment Options for MICREX-SX] dialog ([Options] → [MICREX-SX Environment]) on the SX-Programmer Standard tool.

\*2



## 7.1.1 MICREX-F Series

### Communication Setting

#### Editor

#### Communication setting


(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> : 1 / 1 : n / Multi-link / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>1920Q</u> bps	
Data Length	<u>Z</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>Q</u> to 31	

#### PLC

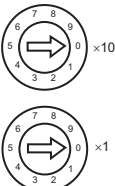
Be sure to match the settings to those made on the [Communication Setting] tab window of the editor.

#### Mode setting

MODE	Setting	Contents	
	1	RS-232C	Command-defined asynchronous communication (non-procedure)
	3	RS-485	Command-defined asynchronous communication (non-procedure)

\* The mode setting switch is common to NV1L-RS2, NC1L-RS2, NC1L-RS4, FFU120B and FFK120A.

#### Station number setting

ADDRESS	Setting	Contents
	0 to 31	Station number ×10: the tens place ×1: the ones place

\* The station number setting switch is common to NC1L-RS4, FFU120B and FFK120A. It is not provided on NV1L-RS2 nor NC1L-RS2.



## Transmission setting

### NV1L-RS2, NC1L-RS2, NC1L-RS4, FFU120B

Switch	Contents	ON	OFF	E.g.) Editor Default Setting
8	Initializing method	Switch	Initial file	
7	Parity	Provided	Not provided	
6	Parity bit	Even	Odd	
5	Data bit length	7 bits	8 bits	
4	Stop bit length	1 bit	2 bits	
		19200	9600	
3	Baud rate	ON	ON	
2		ON	OFF	
1		OFF	ON	

### FFK120A

- Character switches

Switch	Contents	ON	OFF	E.g.) Editor Default Setting
8	Initializing method	Switch	Initial file	
7	Parity	Provided	Not provided	
6	Parity bit	Even	Odd	
5	Data bit length	7 bits	8 bits	
4	Stop bit length	2 bits	1 bit	
3	Not used	-	OFF	
2		-	OFF	
1		-	OFF	

- Baud rate setting switches  
Set a switch to the ON position.

Switch	Contents	Example: 19,200 bps
8	Not used	
7	19,200 bps	
6	9,600 bps	
5	4,800 bps	
4	2,400 bps	
3	1,200 bps	
2	600 bps	
1	300 bps	

## Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
M (auxiliary relay)	00H	WM as word device
K (keep relay)	01H	WK as word device
B (input/output relay)	02H	WB as word device
L (link relay)	09H	WL as word device
F (special relay)	0AH	WF as word device
TS (timer/set value)	0BH	*1
TR (timer/current value)	0CH	*1
W9 (0.1-sec timer/current value)	0DH	*1
CS (counter/set value)	0EH	*1
CR (counter/current value)	0FH	*1
BD (data memory)	10H	*1
WS (step relay)	11H	*2
Wn (file memory)	12H	*3, *4

\*1 For items where double-words can be used (Num. Display, Graph, Sampling), data is processed as double-words. For those where bits or words can be used, data is processed as words consisting of lower 16 bits.

For input: Upper 16 bits are ignored.

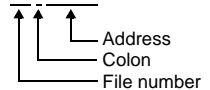
For output: "0" is written for upper 16 bits.

\*2 Byte device such as step relay is processed as described below.

For input: Upper 8 bits are "0".

For output: Lower 8 bits are written.

\*3 To set up the file memory on the editor, enter "file number" + ":" (colon) + "address" in order. Example: W30 : 00002



\*4 Define the file area as "SI".

## 7.1.2 SPB (N Mode) & FLEX-PC Series

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)


Item	Setting	Remarks
Connection Mode	<u>1</u> : 1 / 1 : n / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 bps	
Data Length	<u>Z</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>Q</u> to 31	

#### PLC

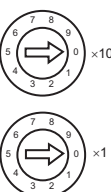
Be sure to match the settings to those made on the [Communication Setting] tab window of the editor.

#### NS-RS1, NJ-RS2, NJ-RS4, NB-RS1

#### Mode setting

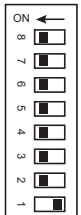
MODE	Setting	Contents	
	1	RS-232C	Command-defined asynchronous communication (non-procedure)
	3	RS-485	Command-defined asynchronous communication (non-procedure)

#### Station number setting

ADDRESS	Setting	Contents
	0 to 31	Station number ×10: the tens place ×1: the ones place

\* The station number setting switch is not provided on NJ-RS2.

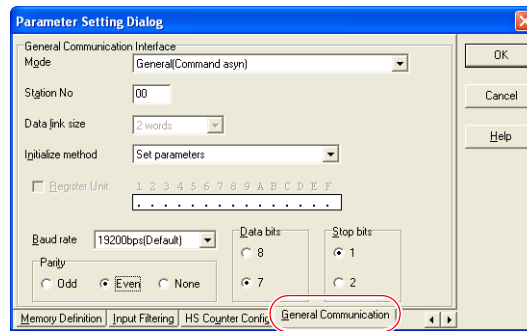
#### Transmission setting

Switch	Contents	ON	OFF	E.g.) Editor Default Setting
8	Initializing method	Switch	Initial file	
7	Parity	Provided	Not provided	
6	Parity bit	Even	Odd	
5	Data bit length	7 bits	8 bits	
4	Stop bit length	1 bit	2 bits	
3	Baud rate	19200	9600	
2		ON	ON	
1		ON	OFF	
1		OFF	ON	

## NW0LA-RS2, NW0LA-RS4 (Parameter Setting)

On the PLC loader, set parameters for general communications.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor.



Item	Setting	Remarks
Mode	General (Command asyn)	These settings can also be specified for the parameter area. For more information, refer to the MICREX-SX SPB Series User's Manual <Communication Adapter> (FEH405).
Station No.	RS-232C: 0, RS-485: 0 to 31	
Initialize method	Set parameters	
Baud rate	4800 / 9600 / 19200 / 38400	
Parity	Odd / Even / None	
Data bits	8 / 7	
Stop bits	1 / 2	

### Notes on use of 2-wire connection with NW0LA-RS4

The settings show above are not enough to establish a 2-wire connection with NW0LA-RS4.

To establish a connection, select [Initial file transfer] for [Initial Setting Mode] on the PLC loader, and select 2-wire connection for [485 mode] in the initial setting file.

For more information, refer to the MICREX-SX SPB Series User's Manual <Communication Adapter> (FEH405).

## Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Standard Memory	TYPE	Remarks
D (data register)	00H	
W (link register)	01H	
M (internal relay)	02H	WM as word device
L (latch relay)	03H	WL as word device
X (input relay)	04H	WX as word device
Y (output relay)	05H	WY as word device
R (file register)	06H	
TN (timer/current value)	07H	
CN (counter/current value)	08H	
T (timer/contact)	09H	
C (counter/contact)	0AH	
WS (step relay)	0BH	

## 7.1.3 SPB (N Mode) & FLEX-PC CPU

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	When connecting MONITOUCH to the RS-232C port on NJ-CPU-B16, select [RS-232C]. In other cases, select [RS-485].
Baud Rate	<u>19200</u> bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> bit	
Parity	<u>Odd</u>	
Target Port No.	<u>0</u>	

#### PLC

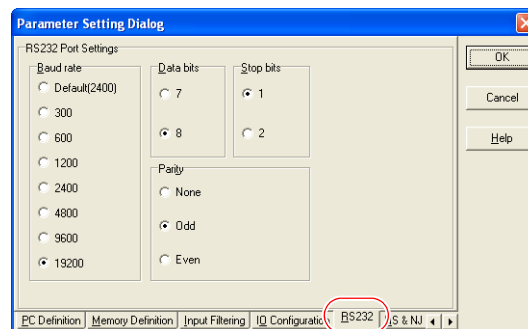
#### SPB, FLEX-PC CPU Port

No particular setting is necessary on the PLC.

#### Built-in RS-232C Port on NJ-CPU-B16

On the PLC loader, set parameters for the built-in RS-232C port.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor.



#### Available Memory

The available memory is the same as the one described in "7.1.2 SPB (N Mode) & FLEX-PC Series".

## 7.1.4 MICREX-SX SPH/SPB Series (IEC Mode)

### Communication Setting

#### Editor

#### Communication setting

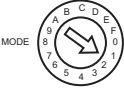
(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> :1 / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / 19200 / <u>38400</u> bps	For the SPH series: Do not change the default setting.
Data Length	8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>0</u> to 31	

#### PLC

#### NP1L-RS1 , NP1L-RS2 , NP1L-RS3 , NP1L-RS4 , NP1L-RS5

#### Mode setting

MODE	Setting	RS1, 2, 4	RS-232C Port	RS-485 Port	Remarks	
		RS3, 5	CH1	CH2		
	0		General equipment	General equipment		
	1		Loader	General equipment		
	2		General equipment	Loader		
	3		Loader	Loader		
	4		General equipment	General equipment	RS3 and 5 are not used.	
	5		Not used			
	6		Modem loader 19200 bps		General equipment	
	7		Self-diagnosis mode 1			
	8		Self-diagnosis mode 2			
	9		Modem loader 19200 bps		Loader	
	A		Modem loader 9600 bps		General equipment	
	B		Modem loader 9600 bps		Loader	
	C		Modem loader 38400 bps		General equipment	
	D		Modem loader 38400 bps		Loader	
	E		Modem loader 76800 bps		General equipment	
	F		Modem loader 115200 bps		Modem loader 115200 bps	

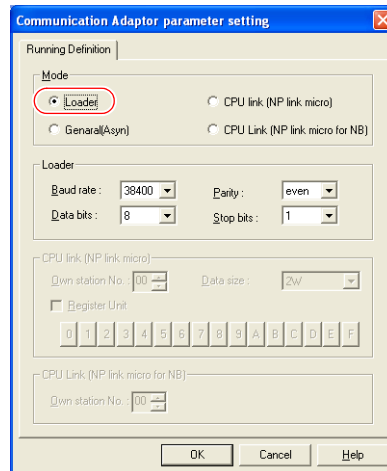
\* Set the port (or CH No.) where the S8 is connected to "loader".  
Communication parameters are fixed to 38400 bps (baud rate), 8 bits (data length), 1 bit (stop bit), and even (parity).

\* When the PLC is connected with the S8, the station number setting switch for RS-485 is not used.

## NW0LA-RS2, NW0LA-RS4 (Parameter Setting)

On the PLC loader, set parameters for general communications.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor.



Item	Setting	Remarks
Mode	Loader	
Baud rate	4800 / 9600 / 19200 / 38400	
Parity	Odd / Even / None	
Data bits	8	
Stop bits	1 / 2	

## Available Memory

### Variable name cooperation function

The variable name cooperation function can be used only for PLC1. For memory assignment, basically use the variable name cooperation function. **We recommend you to define the area (variable) that is used for communications with the S8 as "AT".**

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
%IX (input memory) *1	-	%IW as word device, %ID as double-word device
%QX (output memory) *1	-	%QW as word device, %QD as double-word device
%MX1. (standard memory)	02H	%MW1. as word device, %MD1. as double-word device
%MX3. (retain memory)	04H	%MW3. as word device, %MD3. as double-word device
%MX10. (system memory)	08H	%MW10. as word device, %MD10. as double-word device

\*1 For the input/output memory, the variable name cooperation function of the PLC1 must be used. Indirect designation is not available with the input/output memory.

## Indirect Memory Designation

Specify the CPU number in the expansion code.

## 7.1.5 MICREX-SX SPH/SPB Series (N Mode / F Mode)

### Communication Setting

The communication setting is the same as the one described in “7.1.4 MICREX-SX SPH/SPB Series (IEC Mode)”.

### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
X (input memory) *1	-	X as bit device, WX as word device, DX as double-word device
Y (output memory) *1	-	Y as bit device, WY as word device, DY as double-word device
M (standard memory)	02H	M as bit device, WM as word device, DM as double-word device
L (retain memory)	04H	L as bit device, WL as word device, DL as double-word device
SM (system memory)	08H	SM as bit device, WSM as word device, DSM as double-word device

\*1 Input/output memory does not operate normally unless you import the “\*.ini” file created using [Export Device Information] in the PLC programming tool. Indirect designation is not available with the input/output memory.

### Indirect Memory Designation

Specify the CPU number in the expansion code.

## 7.1.6 MICREX-SX SPH/SPB CPU (IEC Mode)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> : 1 / Multi-link2	Do not change the setting from default.
Signal Level	RS-422/485	
Baud Rate	38400 bps	
Data Length	8 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	<u>0</u> to 31	

#### PLC

No particular setting is necessary on the PLC.

Communication parameters are fixed to 38400 bps (baud rate), RS-422/485 (signal level), 8 bits (data length), 1 bit (stop bit), and even (parity).

### Available Memory

The available memory is the same as the one described in “7.1.4 MICREX-SX SPH/SPB Series (IEC Mode)”.



## **7.1.7 MICREX-SX SPH/SPB CPU (N Mode / F Mode)**

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### **Communication Setting**

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The communication setting is the same as the one described in "7.1.6 MICREX-SX SPH/SPB CPU (IEC Mode)".

### **Available Memory**

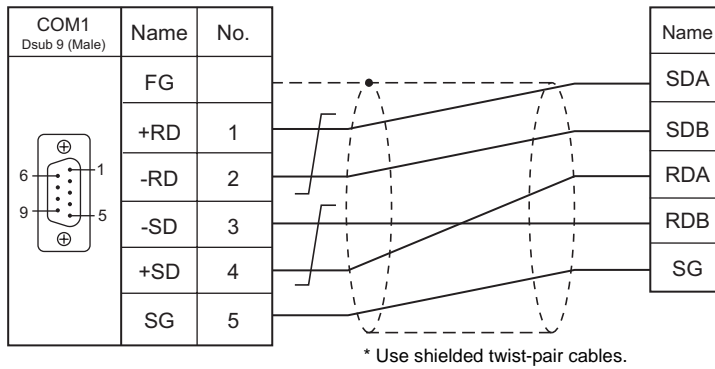
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The available memory is the same as the one described in "7.1.5 MICREX-SX SPH/SPB Series (N Mode / F Mode)".

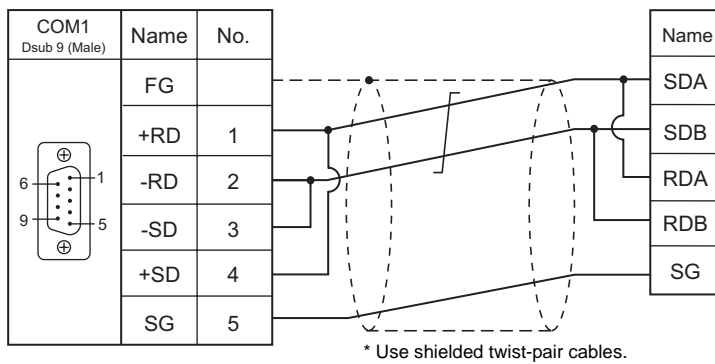
## 7.1.8 Wiring Diagrams

### When Connected at COM1 (RS-422 / RS-485):

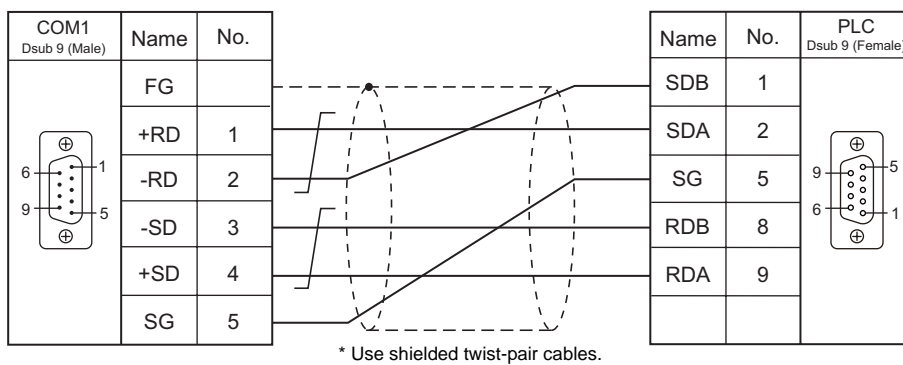
Wiring diagram 1 - COM1



Wiring diagram 2 - COM1

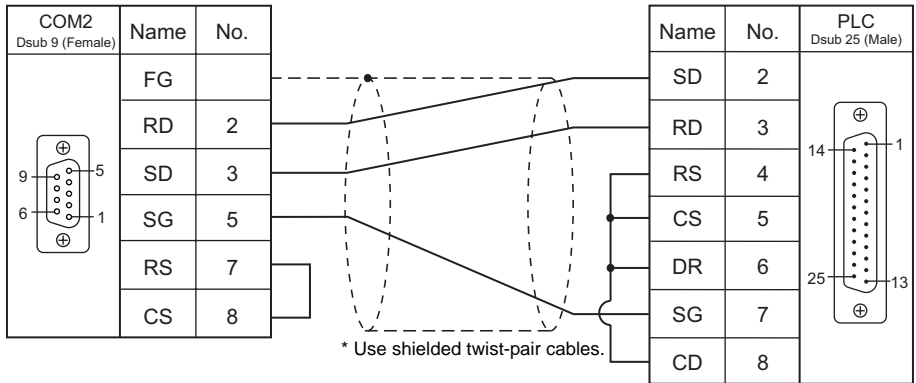


Wiring diagram 3 - COM1

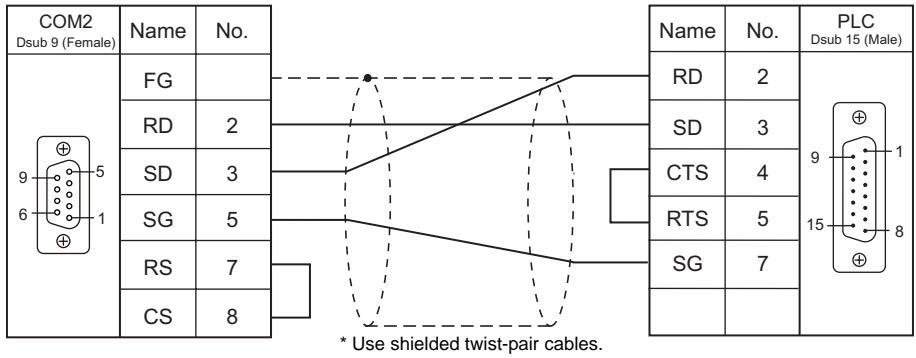


**When Connected at COM2 (RS-232C):**

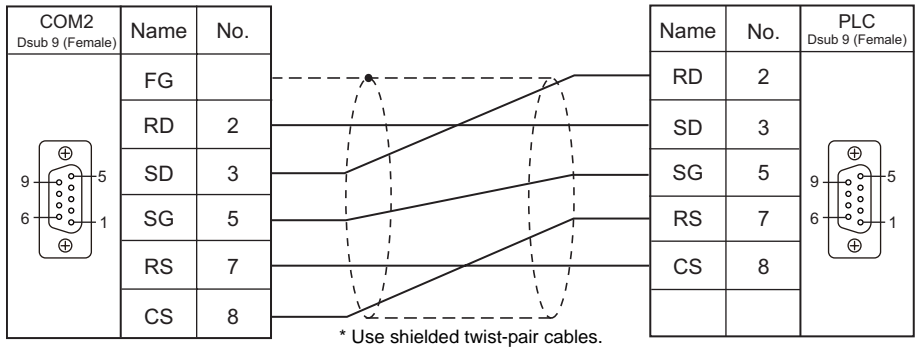
**Wiring diagram 1 - COM2**



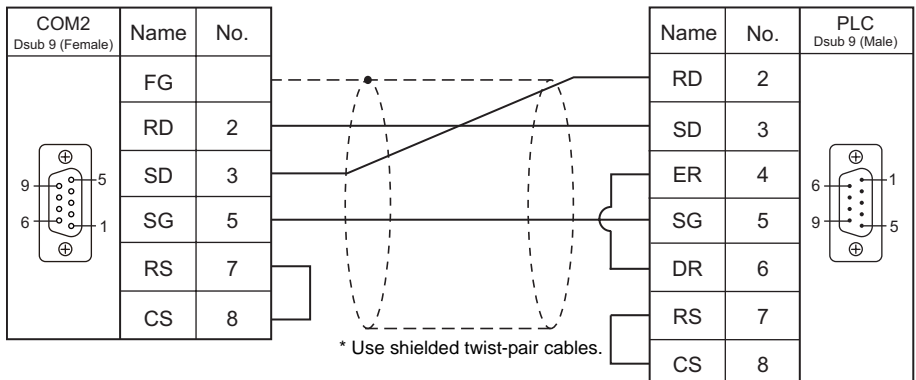
**Wiring diagram 2 - COM2**



**Wiring diagram 3 - COM2**



**Wiring diagram 4 - COM2**



## 7.2 Temperature Controller/Servo/Inverter Connection

The controllers shown below can be connected.

### Temperature Controller

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
PYX (MODBUS RTU)	PYX4xx PYX5xx PYX9xx *1	Terminal block	RS-485	Wiring diagram 1 - COM1	-	PYX.Lst
PXR (MODBUS RTU)	PXR3xx PXR4xx PXR5xx PXR7xx PXR9xx *1	Terminal block	RS-485	Wiring diagram 1 - COM1	-	PXR.Lst
PXG (MODBUS RTU)	PXG4xx PXG5xx PXG9xx *1	Terminal block	RS-485	Wiring diagram 1 - COM1	-	F_PXG.Lst
PXH (MODBUS RTU)	PXH9xx *1	Terminal block	RS-485	Wiring diagram 2 - COM1	-	F_PXH.Lst
PUM (MODBUS RTU)	PUMxx	Terminal block (base)	RS-485	Wiring diagram 2 - COM1	-	F_PUMA_B.Lst F_PUME.Lst

\*1 Select a model on which Modbus communication is available.

### Power Monitor Unit

PLC Selection on the Editor	Series Name	Model	Port	Signal Level	Connection		Lst File
					COM1	COM2	
F-MPC04P (loader)	F-MPC04P	UM02-AR2 UM02-AR3 UM02-AR4	RS-485 connector	RS-485	Wiring diagram 3 - COM1	-	F-MPC04P.Lst
F-MPC series / FePSU	F-MPC04	UM01-ARxx	Terminal block	RS-485	Wiring diagram 4 - COM1	-	UM01_ARA4.Lst
	F-MPC04P	UM02-AR2	Terminal block	RS-485	Wiring diagram 4 - COM1	-	UM02_AR2.Lst
		UM02-AR3					UM02_AR3.Lst
		UM02-AR4					UM02_AR4.Lst
	F-MPC04S	UM03-AR3x	Terminal block	RS-485	Wiring diagram 4 - COM1	-	UM03_ARA3G.L st
	F-MPC30	UM5ACxx *1	Terminal block	RS-485	Wiring diagram 4 - COM1	-	UM5A.Lst
		UM45xx *1					
	F-MPC50	UM50xx *1	Terminal block	RS-485	Wiring diagram 4 - COM1	-	UM50.Lst
	F-MPC55	UM55V	Terminal block	RS-485	Wiring diagram 4 - COM1	-	UM55V.Lst
	F-MPC60B	UM4Bxx *1	Terminal block	RS-485	Wiring diagram 4 - COM1	-	UM4_UM42_UM 43.Lst
		UM42Cxx *1					
		UM42Fxx *1					
		UM43FDxx *1					
UM43FGxx *1							
UM44Bxx *1							
UM44CDxx *1							
UM44FGxx *1	UM44.Lst						
FePSU	EAx EGxx SAXX SGxx	Terminal block	RS-485	Wiring diagram 5 - COM1	-	FePSU.Lst	

\*1 Select a model on which RS-485 communication is available.

## Inverter

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
FVR-E11S (MODBUS RTU)	FVRxxE11S-x	Touch panel connector	RS-485	Wiring diagram 6 - COM1	-	FVR-E11S(Mobus).Lst
FVR-C11S (MODBUS RTU)	FVRxxC11S-x	OPC-C11S-RSx	RS-485	Wiring diagram 7 - COM1	-	FVR-C11S(Mobus).Lst
FRENIC5000G11S / P11S (MODBUS RTU)	FRNxxG11S-x FRNxxP11S-x	Terminal block	RS-485	Wiring diagram 8 - COM1	-	FRENIC5000G11S_P11S(Modbus).Lst
FRENIC5000VG7 (MODBUS RTU)	FRNxxVG7S-x	RS-485 connector	RS-485	Wiring diagram 9 - COM1	-	FRENIC5000VG7S(Modbus).Lst
		OPC-VG7-RS (communication board)		Wiring diagram 8 - COM1	-	
FRENIC-Mini (MODBUS RTU)	FRNxxC1S-x	OPC-C1-RS (communication board)	RS-485	Wiring diagram 10 - COM1	-	F-Mini.Lst
FRENIC-Eco (MODBUS RTU)	FRNxxF1S-x	Touch panel connector	RS-485	Wiring diagram 10 - COM1	-	F-Eco(Modbus).Lst
		OPC-F1-RS (communication board)		Wiring diagram 8 - COM1	-	
FRENIC-Multi (MODBUS RTU)	FRNxxE1S-x	Touch panel connector	RS-485	Wiring diagram 10 - COM1	-	F-Multi.Lst
		OPC-E1-RS (communication board)		Wiring diagram 10 - COM1	-	
FRENIC-MEGA (MODBUS RTU)	FRNxxxG1x-xx	Touch panel connector	RS-485	Wiring diagram 10 - COM1	-	FRENIC-MEGA(Modbus).Lst
		Terminal block on control circuit		Wiring diagram 8 - COM1	-	

## IH Inverter

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
HFR-C9K	HFR030C9Kxx HFR050C9Kxx	HFR-OPC01 (communication board)	RS-485	Wiring diagram 13 - COM1	-	F_HFR.Lst
HFR-C11K	HFR3.0C11Kxx HFR5.0C11Kxx HFR7.0C11Kxx	Terminal block	RS-485	Wiring diagram 8 - COM1	-	HFR-C11K.Lst

## AC Power Monitor

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
PPMC (MODBUS RTU)	PPMCxx *1	Terminal block	RS-232C	-	Wiring diagram 1 - COM2	F-PPMC.Lst
			RS-485	Wiring diagram 1 - COM1	-	

\*1 Select a model on which RS-485 or RS-232C communication is available.

## Servo Amplifier

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
FALDIC-a series	RYSxx *1	CN3	RS-485	Wiring diagram 12 - COM1	-	F_FAL-A.Lst
ALPHA5 (MODBUS RTU)	RYTxxx5-VVx	CN3A	RS-485	Wiring diagram 14 - COM1	-	ALPHA5.Lst

\*1 Select a model on which host interface: universal communication (RS-485) is available.

## Recorder

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
PHR (MODBUS RTU)	PHRxx	Terminal block	RS-485	Wiring diagram 2 - COM1	-	F_PHR.Lst

## Digital Panel Meter

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
WA5000	WA5xx *1	Modular Jack	RS-232C	-	Wiring diagram 2 - COM2	WA5000.Lst
			RS-485	Wiring diagram 11 - COM1	-	

\*1 Select a model on which RS-485 or RS-232C communication is available.

## AC Power Regulator

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
APR-N (MODBUS RTU)	RPNExxx-xx-ZAM-xx/xx	RPN003-AM (communication board)	RS-485	Wiring diagram 4 - COM1	-	F_APR-N.Lst

## Electronic Multimeter

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
WE1MA (MODBUS RTU)	WE1MA-AFxxx-Mxx	Terminal block	RS-485	Wiring diagram 15 - COM1	-	F_WE1MA.Lst
	WE1MA-AGxxx-Mxx					F_WE1MA_1P.Lst *1
	WE1MA-A1xxx-Mxx					F_WE1MA_1P3L.Lst *1
	WE1MA-A5xxx-Mxx					F_WE1MA_3P3L.Lst *1
	WE1MA-A2xxx-Mxx					F_WE1MA_3P4L.Lst *1
	WE1MA-A6xxx-Mxx					
	WE1MA-A7xxx-Mxx					
	WE1MA-A4xxx-Mxx					

\*1 The file of "F\_WE1MA.Lst" can be browsed by pressing the [Refer] button by default. It is possible to set the memory with this list file.

## 7.2.1 PYX (MODBUS RTU)

### Communication Setting

#### Editor

##### Communication setting


(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-422/485</u>	Do not change the default settings because these settings on the temperature controller cannot be changed.
Baud Rate	<u>9600</u> bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> bit	
Parity	<u>Odd</u>	
Target Port No.	1 to 31	

#### Temperature Controller

The communication parameter can be set using keys attached to the front of the temperature controller.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Parameter	Item	Setting	Example
	Digital transmission function (station number)	<u>1</u> to 31	1

\* The communication function of the temperature controller can be selected from Fuji protocol or Modbus protocol at the time of purchase. For communication with a S8, select a model on which the Modbus protocol is available.

\* Digital transmission settings other than the station number are fixed as shown below.

Transmission signal: RS-485  
 Baud rate: 9600 bps  
 Data length: 8 bits  
 Parity: odd parity  
 Stop bit: 1 bit

#### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
0	00H	
1	01H	Read only
4	02H	
3	03H	Read only

## 7.2.2 PXR (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-422/485</u>	Do not change the default settings because these settings on the temperature controller cannot be changed.
Baud Rate	<u>9600</u> bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> bit	
Parity	None / Even / <u>Odd</u>	
Target Port No.	1 to 31	

#### Temperature Controller

The communication parameter can be set using keys attached to the front of the temperature controller. Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Parameter	Display	Item	Setting	Example	
Third block parameter	<u>STno</u>	STno	Station number	<u>1</u> - 31	1
	<u>CoM</u>	CoM	Parity	<u>0: Odd</u> 1: Even 2: None	0
	<u>PCoL</u>	PCoL	Communication protocol	1: Modbus <sup>*1</sup> 2: Z-ASCII	1

\*1 The communication function of the temperature controller can be selected at the time of purchase. Select a model on which RS-485 (Modbus) communication is available.

### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
0	00H	
1	01H	Read only
4	02H	
3	03H	Read only



## 7.2.3 PXG (MODBUS RTU)

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-422/485</u>	Do not change the default settings of the signal level, data length and stop bit because these settings on the temperature controller cannot be changed.
Baud Rate	<u>9600</u> / 19200 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> bit	
Parity	None / Even / <u>Odd</u>	
Target Port No.	1 to 31	

#### Temperature Controller

The communication parameter can be set using keys attached to the front of the temperature controller.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Channel	Parameter Display	Item	Setting	Example	
"CoM Ch9" Communication (Ch9)	"STno"	STno	Station number	<u>1</u> to 31	1
	"CoM"	CoM	Parity	<u>96od</u> (9600 bps / odd parity) 96Ev (9600 bps / even parity) 96no (9600 bps / without parity) 19od (19200 bps / odd parity) 19Ev (19200 bps / even parity) 19no (19200 bps / without parity)	96od
	"SCC"	SCC	Communication authority	r (Read only) <u>rW</u> (Read/write allowed)	rW

\* The communication function of the temperature controller can be selected at the time of purchase. Select a model on which RS-485 (Modbus) communication is available.

#### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
1 (input relay)	01H	
4 (holding register)	02H	
3 (input register)	03H	

## 7.2.4 PXH (MODBUS RTU)

### Communication Setting

#### Editor




#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-422/485</u>	Do not change the default settings of the signal level, data length and stop bit because these settings on the temperature controller cannot be changed.
Baud Rate	9600 / 19200 / <u>38400</u> bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> bit	
Parity	None / Even / <u>Odd</u>	
Target Port No.	1 to 31	

#### Temperature Controller

The communication parameter can be set using keys attached to the front of the temperature controller. Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Channel	Parameter Display	Item	Setting	Example
Communication (Ch B)	 STn4	RS-485 station No.	<u>1</u> to 31	1
	 SPd4	RS-485 baud rate	96: 9600 bps 192: 19200 bps <u>384: 38400 bps</u>	384
	 biT4	RS-485 bit format	8n: Data length 8 bits, without parity <u>8o: Data length 8 bits, odd parity</u> 8E: Data length 8 bits, even parity	8o

\* The communication function of the temperature controller can be selected at the time of purchase. Select a model on which RS-485 (Modbus) communication is available.

#### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
4 (holding register)	02H	
3 (input register)	03H	

## 7.2.5 PUM (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting


(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-422/485</u>	Do not change the default settings of the signal level, data length and stop bit because these settings on the temperature controller cannot be changed.
Baud Rate	9600 / <u>19200</u> / 38400 / 115200 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> bit	
Parity	<u>None</u> / Even / Odd	
Target Port No.	1 to 15 [DEC]	

#### Temperature Controller

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

#### Station number setting

STATION	Setting	Example
	0 to F [HEX]	0: Station number 1 F: Station number 16

#### Communication setting

On the temperature controller loader, set communication parameters.

Item	Setting	Example	Remarks
RS-485 parity setting	0: <u>None</u> 1: Odd 2: Even	0	
RS-485 baud rate setting	0: 9600 1: <u>19200</u> 2: 38400 4: 115200 kbps	1	
RS-485 communication authority setting	0: Read only 1: <u>Read/write allowed</u>	1	
RS-485 response interval setting	0 to 25 (default: 1)	1	Response interval = setting value × 20 ms
Extensional communication module (PUMC) connection	0: <u>Without PUMC (RS-485 valid)</u> 1: With PUMC (RS-485 invalid)	0	When using RS-485 communication, set "0".

## Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
4 (holding register)	02H	
3 (input register)	03H	

### Note on Setting the Memory

In accordance with the connected PUM model, set the "List" file name to be browsed by pressing the [Refer] button.

Model	List File Name
PUMAx	F_PUMA_B.Lst
PUMBx	
PUMEx	F_PUME.Lst

"F\_PUMA\_B.Lst" is set as default.

## 7.2.6 F-MPC04P (Loader)

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

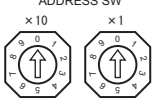
Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-422/485</u>	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	1 bit	Do not change the default setting because the setting on the power monitor unit cannot be changed.
Parity	None / <u>Odd</u> / Even	
Target Port No.	1 to 99 <sup>*1</sup>	

\*1 To use port No. 32 to 99, use the station number table.

#### Power Monitor Unit

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

##### Station number setting

Station	Setting	Example	Remarks
	01 to 99 [DEC] (default: <u>0</u> )	1	

##### Communication setting

The communication parameter can be set using keys attached to the front of the power monitor unit.

Circuit No.	Setting Code	Item	Setting	Example
C	L1-□□	Baud rate	00: 4800 bps 01: 9600 bps <u>02: 19200 bps</u>	02
	L2-□□	Parity	00: None 01: Even <u>02: Odd</u>	02
	L3-□□	Data length	<u>00: 7 bits</u> 01: 8 bits	00

### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

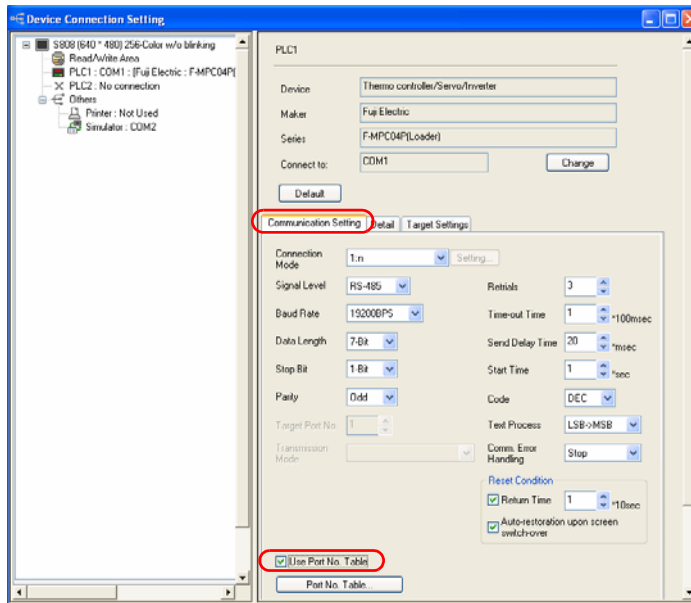
Memory	TYPE	Remarks
---	00H	Double-word

## Station Number Table

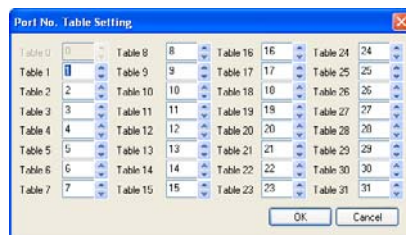
- A maximum of 31 units can be connected via serial communication. Port numbers from 0 to 31 can be set on the [Memory Setting] dialog of the editor; however, depending on the controller, port numbers exceeding 32 may be available. In such a case, use the station number table to enable communications with devices of port No. 32 or greater.
- It is easier to specify port numbers for each network in the field by making the screen for setting the port number when creating screen data. In this case, it is not necessary to transfer screen data again.

### Setting the Station Number Table

1. Click [System Setting] → [Device Connection Setting]. On the [Communication Setting] tab window, check  Use Port No. Table].



2. Click the [Port No. Table] button. The [Port No. Table Setting] dialog is displayed.
3. Specify port numbers of the temperature controllers for "Table 0" to "31".



## Macro

To rewrite the station number table on the S8 series screen, use macro commands [FROM\_WR] and [RESTART].

### FROM\_WR

#### FROM\_WR F0 F1

- Function: Writing to FROM  
As many words as specified for F1 from the memory address set for F0 is written in the FP-ROM.
- Available memory

	Internal Memory	PLC n Memory	Memory Card	Constant
F0	⊙	⊙	⊙	
F1				○

○: Setting enabled (indirect designation disabled)  
⊙: Setting enabled (indirect designation enabled)

- Data range

	Setting	Remarks
F0	Top memory address of the source	32 words from the specified top memory address are used. Set port numbers from 0 to 31 for the memory addresses. For the station number table not used, set [-1].
F1	Number of transmission words: 32	If any other value than "32" is set, the write error (\$s728 = 1) occurs.

- Notes
  - The maximum possible number of write operations to the FP-ROM is 100,000 times. This is not related to the number of words that are written.
  - Do not include the FROM\_WR command in a cycle macro or an event timer macro.
  - Writing to FP-ROM takes a longer time.
  - When the station number table has been rewritten using the [FROM\_WR] command, be sure to execute the [RESTART] command.
  - When the station number table is used, it is not possible to set  Use Internal Flash ROM as Back-up Area on the [General Settings] tab window that is displayed by selecting [System Setting] → [Unit Setting] → [General Settings]. Be sure to leave this box unchecked.

### RESTART

When the station number table has been rewritten using the [FROM\_WR] command, be sure to execute this command.

#### SYS (RESTART) F0

- Function: Reconnection  
This macro command reconnects the controller when the time specified for F1 has elapsed.
- Available memory

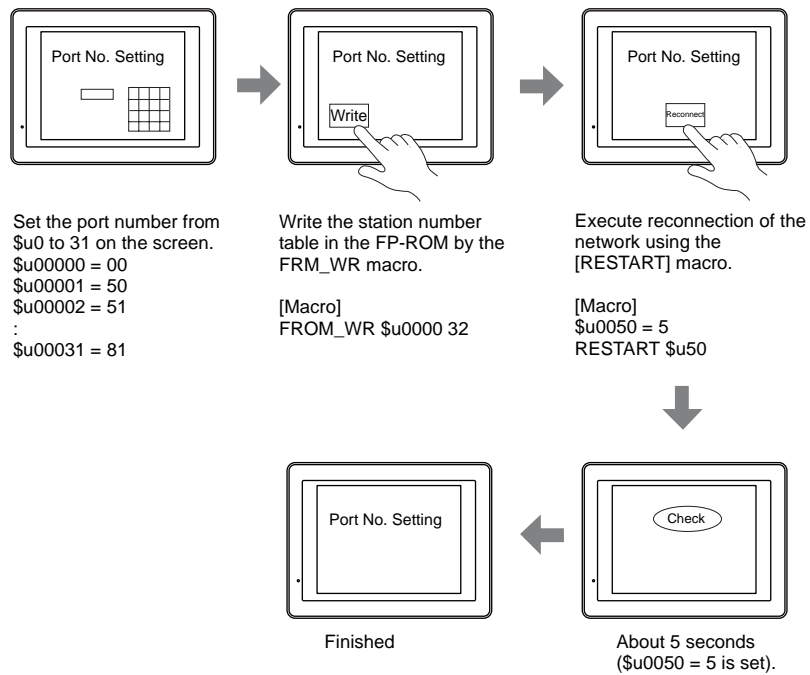
	Internal Memory	PLC n Memory	Memory Card	Constant
F1	⊙			

○: Setting enabled (indirect designation disabled)  
⊙: Setting enabled (indirect designation enabled)

- Data range

	Setting
F0	RESTART
F1	Time: 0 to 60 s

### Example of Procedure for Rewriting the Station Number Table



### System Memory

The result of [FROM\_WR] macro execution is stored in \$s728.

- [0]: Normal
- [1]: Error



## 7.2.7 F-MPC Series / FePSU

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-422/485</u>	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	1 bit	Do not change the default setting because the setting on the power monitor unit cannot be changed.
Parity	None / <u>Odd</u> / Even	
Target Port No.	1 to 99*1	

\*1 To use port numbers 32 to 99, use the station number table. For the station number table, see "Station Number Table" (page 7-25).

#### F-MPC04

#### Communication setting

The communication parameters can be set using keys attached to the front of the power monitor unit.

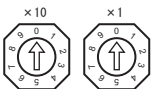
Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Circuit No.	Setting Code	Item	Setting	Example
C	4-0	RS-485 address	<u>Loc: Communication not used</u> 01 to 99	01
	4-1	RS-485 baud rate setting	4.8: 4800 bps 9.6: 9600 bps <u>19.2: 19200 bps</u>	19.2
	4-2	RS-485 data length	<u>7: 7 bits</u> 8: 8 bits	7
	4-3	RS-485 Parity	00: None 01: Even <u>02: Odd</u>	02

#### F-MPC04P

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

#### Station number setting

Station	Setting	Example	Remarks
ADDRESS SW × 10      × 1 	01 to 99 [DEC] (default: <u>0</u> )	1	

#### Communication setting

The communication parameters can be set using keys attached to the front of the power monitor unit.

Circuit No.	Setting Code	Item	Setting	Example
C	L1-□□	Baud rate	00: 4800 bps 01: 9600 bps <u>02: 19200 bps</u>	02
	L2-□□	Parity	00: None 01: Even <u>02: Odd</u>	02
	L3-□□	Data length	<u>00: 7 bits</u> 01: 8 bits	00

## F-MPC04S

### Communication setting

The communication parameters can be set using keys attached to the front of the power monitor unit. Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Setting Code	Item	Setting	Example
L-□□	Baud rate	4.8: 4800 bps 9.6: 9600 bps <u>19.2: 19200 bps</u>	19.2
L2-□□	Data length and parity	8n: Data length 8 bits, without parity 8E: Data length 8 bits, even parity 8o: Data length 8 bits, odd parity 7n: Data length 7 bits, without parity 7E: Data length 7 bits, even parity <u>7o: Data length 7 bits, odd parity</u>	7o
LA-□□	Address (Transmission station number)	<u>Loc: Station number not set</u> 01 to 99	01
Lt-□□	Communication model mode	<u>04: F-MPC04 mode</u> *1 PP: PPM (B) mode	04

\*1 The communication function of F-MPC04 can be selected at the time of purchase. Select a model on which "F-MPC04 mode" is available.

## F-MPC30

### Communication setting

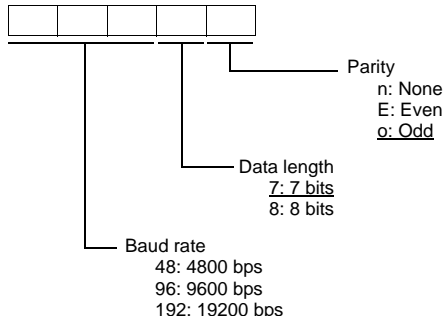
The communication parameters can be set using keys attached to the front of the power monitor unit. Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Setting Code	Item	Setting	Example
90	RS-485 address setting	<u>Loc: Communication not used</u> 01 to 99	01
91	RS-485 transmission specification	<p>7SEG LED</p> <p>Parity n: None E: Even o: Odd</p> <p>Data length 7: 7 bits 8: 8 bits</p> <p>Baud rate 48: 4800 bps 96: 9600 bps 192: 19200 bps</p> <p>* "<u>b192E</u>" is set as default.</p>	1927o

## F-MPC50/F-MPC55/F-MPC60B (UM4Bx, UM42xx, UM43xx)

### Communication setting

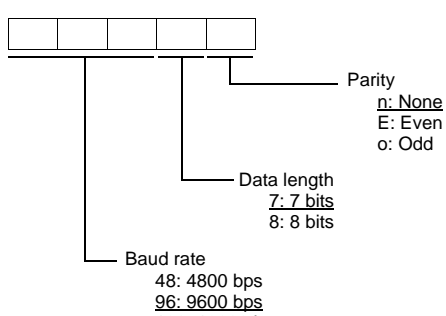
The communication parameters can be set using keys attached to the front of the power monitor unit. Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Setting Code	Item	Setting	Example
90	RS-485 address setting	<u>Loc: communication not used</u> 01 to 99	01
91	RS-485 transmission specification	7SEG LED  Parity n: None E: Even <u>o: Odd</u> Data length <u>7: 7 bits</u> 8: 8 bits Baud rate 48: 4800 bps 96: 9600 bps <u>192: 19200 bps</u>	1927o

## F-MPC60B (UM44xx)

### Communication setting

The communication parameters can be set using keys attached to the front of the power monitor unit. Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Setting Code	Item	Setting	Example
90	RS-485 address setting	<u>Loc: communication not used</u> 01 to 99	01
91	RS-485 transmission specification	7SEG LED  Parity n: None E: Even o: Odd Data length <u>7: 7 bits</u> 8: 8 bits Baud rate 48: 4800 bps <u>96: 9600 bps</u> 192: 19200 bps	1927o

## FePSU

### Communication setting

The communication parameters can be set using keys attached to the front of the power monitor unit. Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Type	Parameter Display	Item	Setting	Example
SEL-c	Adr. □ □	Communicating station number	<u>Loc: Communication not used</u> 01 to 99	01
	bud □ □	Baud rate	4.8: 4800 bps 9.6: 9600 bps <u>19.2: 19200 bps</u>	19.2
	cbit. □ □	Data length, parity	8n: Data length 8 bits, without parity 8E: Data length 8 bits, even parity 8o: Data length 8 bits, odd parity 7n: Data length 7 bits, without parity 7E: Data length 7 bits, even parity <u>7o: Data length 7 bits, odd parity</u>	7o
	LtY. □ □	Communication Mode	<u>Psu: FePSU mode</u> <sup>*1</sup> _PP: PPM(B) mode	Psu

\*1 The communication function of FePSU can be selected at the time of purchase. Select a model on which "FePSU mode" is available.

## Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
00 (data request of circuit No. 1 to 4) *1	00H	Double-word, read only
01 (data request of circuit No. 5 to 8) *1	01H	Double-word, read only
02 (data request of circuit No. 9, 10 or E) *1	02H	Double-word, read only
03 (Data request of the minimum/maximum voltage, power factor of circuit 1 to 10, and invalid power) *1 *2	03H	Double-word, read only
09 (model code)	09H	Read only
10 (operation status)	0AH	Read only
11 (pre-alarm value) *1	0BH	Double-word, read only
12 (current value measurement data) *1 *2	0CH	Double-word, read only
13 (integrated value data) *1 *2	0DH	Double-word, read only
14 (demand measurement data) *1 *2	0EH	Double-word, read only
15 (data of a maximum value of demand measurement) *1 *2	0FH	Double-word, read only
16 (historical data 1) *1 *2	10H	Double-word, read only
17 (historical data 2)	11H	Double-word, read only
18 (setting data) *3	12H	Double-word

\*1 When a memory other than status is used, set the decimal point of the numerical display part to "3".

\*2 "0" is stored in the address for which "(Blank)" is indicated in the table below.

\*3 For setting data, see "Memory: 18 (Setting Data)" described below.

### Memory: 18 (Setting Data)

Address	F-MPC04/F-MPC04P/F-MPC04S	FePSU	F-MPC30/F-MPC50/F-MPC55V/F-MPC60B
00zz	Wiring method (voltage measured)	(Blank)	CT primary rated current
01zz	Ratio of VT 1 (primary voltage) *1	(Blank)	Ratio of VT (primary voltage)
02zz	Ratio of VT 1 (secondary voltage) *1	(Blank)	Ratio of VT (secondary voltage)
03zz	Demand average time	Demand average time	Rated frequency
04zz	Frequency	(Blank)	Protective INST (current setting) *2
05zz	Number of applicable circuits	(Blank)	Protective INST (output setting)
06zz	Pulse multiplying factor	(Blank)	Protective DT (current setting) *2
07zz	Ratio of VT 2 (primary voltage) *1	(Blank)	Protective DT (operation time) *2
08zz	Ratio of VT 2 (secondary voltage) *1	(Blank)	Protective DT (output setting) *2
09zz	Number of turns for CT2 secondary line	(Blank)	Protective OC (current setting)
10zz	CT primary current *1	(Blank)	Protective OC (characteristic)
11zz	OCG sensitivity current	(Blank)	Protective OC (time magnification) *2
12zz	OCG operation time *2	(Blank)	Protective OC (output setting)
13zz	Load pre-alarm sensitivity current	(Blank)	Protective OCA overcurrent pre-alarm (current setting)
14zz	Load pre-alarm operation time	(Blank)	Protective OCA overcurrent pre-alarm (operation time)
15zz	Automatic display circuit register	(Blank)	Protective OCA overcurrent pre-alarm (output setting)
16zz	ZCT select	(Blank)	Protective OCG (51G) (current setting) *3
17zz	VT select	(Blank)	Protective OCG (51G) (characteristic)
18zz	(Blank)	(Blank)	Protective OCG (51G) (time magnification) *2
19zz	(Blank)	(Blank)	Protective OCG (51G) (output setting)

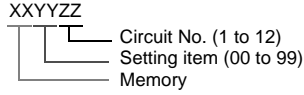
Address	F-MPC04/F-MPC04P/F-MPC04S	FePSU	F-MPC30/F-MPC50/F-MPC55V/F-MPC60B
20zz	Phase selection	(Blank)	Protective OCG (50G) (current setting) <sup>*2</sup>
21zz	Power alarm upper limit	Power alarm upper limit	Protective OCG (50G) (operation time) <sup>*2</sup>
22zz	Integral power pulse multiplying factor <sup>*4</sup>	Pulse multiplying factor <sup>*4</sup>	Protective OCG (50G) (output setting)
23zz	Load pre-alarm operation value	Load pre-alarm operation value	Protective DG (DG/OCG) (current setting) <sup>*3</sup>
24zz	Load pre-alarm operation time	(Blank)	Protective DG (DG/OCG) (operation time) <sup>*3</sup>
25zz	Leak pre-alarm sensitivity current	Leak pre-alarm sensitivity current	Protect DG (DG/OCG) (output setting)
26zz	Leak pre-alarm operation time <sup>*2</sup>	Leak pre-alarm operation time <sup>*2</sup>	Protective DG (DG/OCG) (maximum sensitivity phase angle)
27zz	OCG sensitivity current	Leak alarm sensitivity current	Protective DG (DG/OCG) (voltage setting) <sup>*2</sup>
28zz	OCG operation time <sup>*2</sup>	Leak alarm operation time <sup>*2</sup>	Protective DG (DG/OCG) (selected from DG or OCG)
29zz	Operation type for power	Operation type for power	Protective 0 V (voltage setting)
30zz	(Blank)	Phase R input position	Protective 0 V (operation time) <sup>*2</sup>
31zz	(Blank)	History of turning breaker ON	Protective 0 V (output setting)
32zz	(Blank)	Show/hide cause of trouble	Protective UV (voltage setting)
33zz	(Blank)	Phase interruption alarm of neutral line	Protective UV (operation time) <sup>*2</sup>
34zz	(Blank)	Alarm output 1	Protective UV (output setting)
35zz	(Blank)	Alarm output 2	Protective UV2 (voltage setting)
36zz	(Blank)	Contact input 1	Protective UV2 (operation time) <sup>*2</sup>
37zz	(Blank)	Contact input 2	Protective UV2 (output setting)
38zz	(Blank)	(Blank)	Protective UV operation setting
39zz	(Blank)	Rated current (IN)	Voltage establishment VR (voltage setting)
40zz	(Blank)	Current demand time	Voltage establishment VR (operation time) <sup>*2</sup>
41zz	(Blank)	Voltage demand time	Voltage establishment VR (output setting)
42zz	(Blank)	Power demand time	Protective OVG (voltage setting) <sup>*2</sup>
43zz	(Blank)	Leak demand time	Protective OVG (operation time)
44zz	(Blank)	(Blank)	Protective OVG (output setting)
45zz	(Blank)	(Blank)	ZPD/EVT selection
46zz	(Blank)	(Blank)	Phase interruption relay
47zz	(Blank)	(Blank)	Reverse phase relay
48zz	(Blank)	(Blank)	Demand average time
49zz	(Blank)	Year setting	CB opening jam monitoring time <sup>*3</sup>
50zz	(Blank)	Month setting	CB closing jam monitoring time <sup>*3</sup>
51zz	(Blank)	Date setting	Monitoring trip coil TC disconnection, OFF expedited, function application setting
52zz	(Blank)	Hour setting	kWh pulse constant <sup>*5</sup>
53zz	(Blank)	Minute setting	kvarh pulse constant <sup>*5</sup>
54zz	(Blank)	(Blank)	Selective input 1 function setting

Address	F-MPC04/F-MPC04P/F-MPC04S	FePSU	F-MPC30/F-MPC50/F-MPC55V/F-MPC60B
55zz	(Blank)	(Blank)	Selective input 2 function setting
56zz	(Blank)	(Blank)	Selective input 3 function setting
57zz	(Blank)	(Blank)	Selective input 4 function setting
58zz	(Blank)	(Blank)	Selective input 5 function setting
59zz	(Blank)	(Blank)	Selective input 6 function setting
60zz	(Blank)	(Blank)	Selective input 7 function setting
61zz	(Blank)	(Blank)	Selective input 8 function setting
62zz	(Blank)	(Blank)	Device fault detection function setting
63zz	(Blank)	(Blank)	Fault pick-up output setting
64zz	(Blank)	(Blank)	Transmission component 1 output setting
65zz	(Blank)	(Blank)	Transmission component 2 output setting
66zz	(Blank)	(Blank)	Distant/direct state output setting
67zz	(Blank)	(Blank)	Transducer output current phase setting
68zz	(Blank)	(Blank)	Transducer output voltage phase setting
69zz	(Blank)	(Blank)	Residue/CT 3rd selection (zero-phase current)
70zz	(Blank)	(Blank)	Protective INST (phase N) (current setting) <sup>*2</sup>
71zz	(Blank)	(Blank)	Protective INST (phase N) (output setting)
72zz	(Blank)	(Blank)	Protective OC (phase N) (current setting)
73zz	(Blank)	(Blank)	Protective OC (phase N) (characteristic)
74zz	(Blank)	(Blank)	Protective OC (phase-N) (time magnification) <sup>*2</sup>
75zz	(Blank)	(Blank)	Protective OC (phase N) (output setting)
76zz	(Blank)	(Blank)	Protective OCA overcurrent pre-alarm (phase N) (current setting)
77zz	(Blank)	(Blank)	Protective OCA overcurrent pre-alarm (phase N) (operation time)
78zz	(Blank)	(Blank)	Protective OCA overcurrent pre-alarm (phase N) (output setting)
79zz	(Blank)	(Blank)	Protective OCGA pre-alarm (current setting)
80zz	(Blank)	(Blank)	Protective OCGA pre-alarm (operation time)
81zz	(Blank)	(Blank)	Protective OCGA pre-alarm (output setting)
82zz	(Blank)	(Blank)	Protective DT2 (current setting)
83zz	(Blank)	(Blank)	Protective DT2 (operation time) <sup>*2</sup>
84zz	(Blank)	(Blank)	Protective DT2 (output setting)
85zz	(Blank)	(Blank)	Transducer output CH1 setting
86zz	(Blank)	(Blank)	Transducer output CH2 setting
87zz	(Blank)	(Blank)	Transducer output CH3 setting
88zz	(Blank)	(Blank)	Transducer output CH4 setting
89zz	(Blank)	(Blank)	Transducer output CH5 setting
90zz	(Blank)	(Blank)	Transducer output CH6 setting
91zz	(Blank)	(Blank)	External change-over function setting of transducer output
92zz	(Blank)	(Blank)	Display mode selection

- \*1 When using a direct value, set [DEC (with sign)] for [Display Type] on the [Num. Display] dialog.
- \*2 Specify "1" for [Decimal Point] on the [Num. Display] dialog.
- \*3 Specify "2" for [Decimal Point] on the [Num. Display] dialog.
- \*4 Specify the multiplying factor in the range of -3 to 2.
- \*5 Specify the pulse constant in the range of -2 to 4 or F.

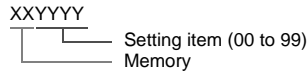
Address denotations:

- For the memory for which the circuit number is set (00 to 02, 12 to 18):



- \* For circuit No. E, specify "11" for the circuit number.

- For the memory for which the circuit number is not set (03, 09 to 11):



#### Note on Setting the Memory

Only the "List" file of "F-MPC04S" can be browsed by pressing the [Refer] button by default.

If any power monitor unit other than above is used, refer to each "List" file by pressing the [Refer] button and set the memory.

## PLC\_CTL

Content	F0	F1 (= \$u n)		F2
kWh integrated value reset	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 0	
Max. kW (amount of power) reset	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 1	
Operation control *1	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 2	
		n + 2	0: Turning ON the input/output 1: Turning ON the output of Power OFF 2: Turning OFF the output of power ON/OFF	
Reset all of the demand maximum values *2	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 3	
Alarm reset *2	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 4	
Time setting *2	1 - 2 (PLC1 - 2)	n	Station number *3	9
		n + 1	Command: 5	
		n + 2	0: Specific station number 1: Broadcast	
		n + 3	Year	
		n + 4	Month	
		n + 5	Day	
		n + 6	Hour	
		n + 7	Minute	
n + 8	Second *4			

\*1 Available only with F-MPC60B.

\*2 Available only with FePSU.

\*3 Select station No. 0 for a broadcast command.

\*4 Can be set only for a broadcast command.

## 7.2.8 FVR-E11S (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	<u>None</u> / Odd / Even	
Target Port No.	<u>1</u> to 31	

#### Inverter

Be sure to match the communication settings of the inverter to those made on the editor.  
For details on communication parameters of the inverter, contact your local distributor.

### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
4	02H	



## 7.2.9 FVR-C11S (MODBUS RTU)

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	<u>8</u> bits	
Stop Bit	1 / <u>2</u> bits	
Parity	<u>None</u> / Odd / Even	
Target Port No.	<u>1</u> to 31	

#### Inverter

Be sure to match the communication settings of the inverter to those made on the editor.  
For details on communication parameters of the inverter, contact your local distributor.

### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
4	02H	

## 7.2.10 FRENIC5000 G11S / P11S (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	<u>8</u> bits	
Stop Bit	1 / <u>2</u> bits	
Parity	<u>None</u> / Odd / Even	
Target Port No.	<u>1</u> to 31	

#### Inverter

Set communication parameters.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Function Code	Item	Setting	Example																				
H30	Link function *1	<table border="1"> <thead> <tr> <th></th> <th>Writing of Monitor/function Data</th> <th>Frequency Setting</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>○</td> <td>X</td> <td>X</td> </tr> <tr> <td>1</td> <td>○</td> <td>○</td> <td>X</td> </tr> <tr> <td>2</td> <td>○</td> <td>X</td> <td>○</td> </tr> <tr> <td>3</td> <td>○</td> <td>○</td> <td>○</td> </tr> </tbody> </table>		Writing of Monitor/function Data	Frequency Setting	Operation Command	<u>0</u>	○	X	X	1	○	○	X	2	○	X	○	3	○	○	○	3
			Writing of Monitor/function Data	Frequency Setting	Operation Command																		
		<u>0</u>	○	X	X																		
		1	○	○	X																		
		2	○	X	○																		
3	○	○	○																				
H31	Station address	<u>1</u> to 31	1																				
H34	Baud rate	0: 19200 bps <u>1: 9600 bps</u> 2: 4800 bps	1																				
H35	Data length	<u>0: 8 bits</u> 1: 7 bits	0																				
H36	Parity bit	<u>0: None</u> 1: Even 2: Odd	0																				
H37	Stop bit	<u>0: 2 bits</u> 1: 1 bit	0																				
U49	Communication protocol*2	<u>0: FGI-bus</u> 1: Modbus RTU	1																				

\*1 Available when the communication is enabled by digital input.

Example: To make the communication enabled when digital input terminal X1 is turned ON; Set "24 (link operation)" for function code E01 and turn on the digital input terminal X1 externally. Terminals from X2 to X9 can also be used. Set the function code corresponding to the digital input terminal to use.

\*2 When "FRENIC5000G11S/P11S (MODBUS RTU)" is selected for model selection on the editor, select "Modbus RTU" for the communication protocol on the inverter.

### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
4	02H	

## 7.2.11 FRENIC5000 VG7S (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / 19200 / <u>38400</u> bps	
Data Length	<u>8</u> bits	Do not change the default setting because the setting on the inverter cannot be changed.
Stop Bit	<u>1</u> / 2 bits*1	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>1</u> to 31	

\*1 When no parity setting is made, set "2 bits" for stop bit.  
When a parity setting (even or odd) is made, set "1 bit" for stop bit.

#### When Connecting to the Built-in RS-485 Port on the Inverter:

Set communication parameters.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Function Code	Item	Setting	Example																				
H30	Link function *1	<table border="1"> <thead> <tr> <th></th> <th>Writing of Monitor/function Data</th> <th>Frequency Setting</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>○</td> <td>X</td> <td>X</td> </tr> <tr> <td>1</td> <td>○</td> <td>○</td> <td>X</td> </tr> <tr> <td>2</td> <td>○</td> <td>X</td> <td>○</td> </tr> <tr> <td>3</td> <td>○</td> <td>○</td> <td>○</td> </tr> </tbody> </table>		Writing of Monitor/function Data	Frequency Setting	Operation Command	<u>0</u>	○	X	X	1	○	○	X	2	○	X	○	3	○	○	○	3
			Writing of Monitor/function Data	Frequency Setting	Operation Command																		
		<u>0</u>	○	X	X																		
		1	○	○	X																		
		2	○	X	○																		
3	○	○	○																				
H31	Station address	<u>1</u> to 31	1																				
H34	Baud rate	<u>0: 38400 bps</u> 1: 19200 bps 2: 9600 bps 3: 4800 bps	0																				
H36	Parity bit	0: None <u>1: Even</u> 2: Odd	1																				
H37	Stop bit	For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting.  When no parity setting is made, "2 bits" is set for stop bit. When a parity setting (even or odd) is made, "1 bit" is set for stop bit.	1																				
H40	Communication protocol*2	0: FGI-bus <u>1: SX (loader) protocol</u> 2: Modbus RTU	2																				

## When Connecting to the Terminal Block on “OPC-VG7-RS” (Optional Communication Board):

### Communication setting

Set communication parameters.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Function Code	Item	Setting	Example																				
H30	Link function *1	<table border="1"> <thead> <tr> <th></th> <th>Writing of Monitor/function Data</th> <th>Frequency Setting</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>○</td> <td>X</td> <td>X</td> </tr> <tr> <td>1</td> <td>○</td> <td>○</td> <td>X</td> </tr> <tr> <td>2</td> <td>○</td> <td>X</td> <td>○</td> </tr> <tr> <td>3</td> <td>○</td> <td>○</td> <td>○</td> </tr> </tbody> </table>		Writing of Monitor/function Data	Frequency Setting	Operation Command	<u>0</u>	○	X	X	1	○	○	X	2	○	X	○	3	○	○	○	3
	Writing of Monitor/function Data	Frequency Setting	Operation Command																				
<u>0</u>	○	X	X																				
1	○	○	X																				
2	○	X	○																				
3	○	○	○																				
H31	Station address	<u>1</u> to 31	1																				
o37	Communication definition setting	<p>Baud rate  <u>0</u>: 38400 bps            1: 19200 bps            2: 9600 bps            3: 4800 bps</p> <p>Parity            0: None (stop bit: 2 bits)  <u>1</u>: Even (stop bit: 1 bit)            2: Odd (stop bit: 1 bit)</p>	10																				
H40	Communication protocol *2	0: FGI-bus <u>1</u> : SX (loader) protocol 2: Modbus RTU	2																				

\*1 Available when the communication is enabled by digital input.

Example: To make the communication enabled when digital input terminal X1 is turned ON;

Set “24 (link operation)” for function code E01 and turn on the digital input terminal X1 externally.

Terminals from X2 to X9 can also be used. Set the function code corresponding to the digital input terminal to use.

\*2 When “FRENIC5000G11S/P11S (MODBUS RTU)” is selected for model selection on the editor, select “Modbus RTU” for the communication protocol on the inverter.

### Notes on Using “OPC-VG7-RS” (Optional Communication Board)

Set the DIPSW2 on the optional communication board “OPC-VG7-RS” as shown below when connecting the S8 and the terminal block of the board.

The underlined settings are set as default.

SW2	SW2-1 Setting	SW2-2 Setting	Function	Remarks
	OFF	OFF	-	-
	ON	OFF		-
	<u>OFF</u>	<u>ON</u>	Optional communication board enabled	Do not change the default setting when connecting with the S8.
	ON	ON	-	-

## Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
4	02H	

## 7.2.12 FRENIC-Mini (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Data Length	<u>8</u> bits	Do not change the default setting because the setting on the inverter cannot be changed.
Stop bit	1 / <u>2</u> bits <sup>*1</sup>	
Parity	<u>None</u> / Odd / Even	
Target Port No.	<u>1</u> to 31	

\*1 When no parity setting is made, "2 bits" is set for stop bit.  
When a parity setting (even or odd) is made, "1 bit" is set for stop bit.

#### Inverter

Set communication parameters.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Function Code	Item	Setting	Example															
y01	Station address	<u>1</u> to 31	1															
y04	Baud rate	1: 4800 bps 2: 9600 bps <u>3: 19200 bps</u>	3															
y06	Parity bit	<u>0: None</u> 1: Even 2: Odd	0															
y07	Stop bit	For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting.  When no parity setting is made, "2 bits" is set for stop bit. When a parity setting (even or odd) is made, "1 bit" is set for stop bit.	-															
y10	Communication protocol <sup>*1</sup>	0: Modbus RTU <u>1: SX (loader) protocol</u> 2: FGI-bus	0															
y99	Support link function	<table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>Function code H30</td> <td>Function code H30</td> </tr> <tr> <td>1</td> <td>Commanded from RS-485</td> <td>Function code H30</td> </tr> <tr> <td>2</td> <td>Function code H30</td> <td>Commanded from RS-485</td> </tr> <tr> <td>3</td> <td>Commanded from RS-485</td> <td>Commanded from RS-485</td> </tr> </tbody> </table>		Frequency	Operation Command	<u>0</u>	Function code H30	Function code H30	1	Commanded from RS-485	Function code H30	2	Function code H30	Commanded from RS-485	3	Commanded from RS-485	Commanded from RS-485	0
	Frequency	Operation Command																
<u>0</u>	Function code H30	Function code H30																
1	Commanded from RS-485	Function code H30																
2	Function code H30	Commanded from RS-485																
3	Commanded from RS-485	Commanded from RS-485																
H30	Link function <sup>*2</sup>	<table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>Inverter</td> <td>Inverter</td> </tr> <tr> <td>1</td> <td>RS-485 communication</td> <td>Inverter</td> </tr> <tr> <td>2</td> <td>Inverter</td> <td>RS-485 communication</td> </tr> <tr> <td>3</td> <td>RS-485 communication</td> <td>RS-485 communication</td> </tr> </tbody> </table>		Frequency	Operation Command	<u>0</u>	Inverter	Inverter	1	RS-485 communication	Inverter	2	Inverter	RS-485 communication	3	RS-485 communication	RS-485 communication	3
	Frequency	Operation Command																
<u>0</u>	Inverter	Inverter																
1	RS-485 communication	Inverter																
2	Inverter	RS-485 communication																
3	RS-485 communication	RS-485 communication																

\*1 Select "Modbus RTU" for the communication protocol on the inverter when connecting with the S8.

\*2 When "0" is specified for y99 (support link function), command from function code H30 is valid for the frequency setting and operation command.

## Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
---	02H	

Address denotations XYY

Function code identification number  
 Function code group

Group	Code	Name
F	00H	Basic function
E	01H	Terminal function
C	02H	Control function
P	03H	Motor parameter
H	04H	High level function
S	07H	Command/function data
M	08H	Monitor data
J	0DH	Application function
y	0EH	Link function
W	0FH	Monitor 2
X	10H	Alarm 1
Z	11H	Alarm 2

## 7.2.13 FRENIC-Eco (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 bps	
Data Length	<u>8</u> bits	Do not change the default setting because the setting on the inverter cannot be changed.
Stop Bit	1 / <u>2 bits</u>	When no parity setting is made, "2 bits" is set for stop bit.
Parity	<u>None</u> / Odd / Even	When a parity setting is made, "1 bit" is set for stop bit.
Target Port No.	<u>1</u> to 31	

#### Inverter

Set communication parameters.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Function Code	Item	Setting	Example															
y01	Station address	<u>1</u> to 31	1															
y04	Baud rate	1: 4800 bps 2: 9600 bps <u>3: 19200 bps</u> 4: 38400 bps	3															
y06	Parity bit	<u>0: None</u> 1: Even 2: Odd	0															
y07	Stop bit	For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting.  When no parity setting is made, "2 bits" is set for stop bit. When a parity setting (even or odd) is made, "1 bit" is set for stop bit.	-															
y10	Communication protocol <sup>*1</sup>	0: Modbus RTU <u>1: SX (loader) protocol</u> 2: FGI-bus	0															
y11	Station address	<u>1</u> to 31	1															
y14	Baud rate	1: 4800 bps 2: 9600 bps <u>3: 19200 bps</u> 4: 38400 bps	3															
y16	Parity bit	<u>0: None</u> 1: Even 2: Odd	0															
y17	Stop bit	For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting.  When no parity setting is made, "2 bits" is set for stop bit. When a parity setting (even or odd) is made, "1 bit" is set for stop bit.	-															
y20	Communication protocol <sup>*1</sup>	<u>0: Modbus RTU</u> 2: FGI-bus	0															
y98	Bus function	<table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>Function code H30</td> <td>Function code H30</td> </tr> <tr> <td>1</td> <td>Commanded from the fieldbus</td> <td>Function code H30</td> </tr> <tr> <td>2</td> <td>Function code H30</td> <td>Commanded from the fieldbus</td> </tr> <tr> <td>3</td> <td>Commanded from the fieldbus</td> <td>Commanded from the fieldbus</td> </tr> </tbody> </table>		Frequency	Operation Command	<u>0</u>	Function code H30	Function code H30	1	Commanded from the fieldbus	Function code H30	2	Function code H30	Commanded from the fieldbus	3	Commanded from the fieldbus	Commanded from the fieldbus	0
	Frequency	Operation Command																
<u>0</u>	Function code H30	Function code H30																
1	Commanded from the fieldbus	Function code H30																
2	Function code H30	Commanded from the fieldbus																
3	Commanded from the fieldbus	Commanded from the fieldbus																
y99	Support link function	<table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>Function code H30, y98</td> <td>Function code H30, y98</td> </tr> <tr> <td>1</td> <td>Commanded from RS-485</td> <td>Function code H30, y98</td> </tr> <tr> <td>2</td> <td>Function code H30, y98</td> <td>Commanded from RS-485</td> </tr> <tr> <td>3</td> <td>Commanded from RS-485</td> <td>Commanded from RS-485</td> </tr> </tbody> </table>		Frequency	Operation Command	<u>0</u>	Function code H30, y98	Function code H30, y98	1	Commanded from RS-485	Function code H30, y98	2	Function code H30, y98	Commanded from RS-485	3	Commanded from RS-485	Commanded from RS-485	0
	Frequency	Operation Command																
<u>0</u>	Function code H30, y98	Function code H30, y98																
1	Commanded from RS-485	Function code H30, y98																
2	Function code H30, y98	Commanded from RS-485																
3	Commanded from RS-485	Commanded from RS-485																

Function Code	Item	Setting		Example	
H30	Link function *2			3	
		0	Inverter		Inverter
		1	RS-485 communication		Inverter
		2	Inverter		RS-485 communication
		3	RS-485 communication		RS-485 communication
		4	RS-485 communication (optional)		Inverter
		5	RS-485 communication (optional)		RS-485 communication
		6	Inverter		RS-485 communication (optional)
7	RS-485 communication	RS-485 communication (optional)			
8	RS-485 communication (optional)	RS-485 communication (optional)			

\*1 Select "Modbus RTU" for the communication protocol on the inverter when connecting with the S8.

\*2 When "0" is specified for y98 (bus function) as well as y99 (support link function), the frequency and operation command can be set on the S8.  
When making the frequency and operation command settings on the S8 connected to the connector for the touch panel, specify "3" for function code H30. When making those settings on the S8 connected to the optional communication board, specify "8" for function code H30.

## Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
4	02H	



## 7.2.14 FRENIC-Multi (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 bps	
Data Length	<u>8</u> bits	Do not change the default setting because the setting on the inverter cannot be changed.
Stop Bit	1 / <u>2</u> bits	On the inverter: 2 bits when "0" is specified for y06 or y16 1 bit when "1", "2" or "3" is specified for y06 or y16
Parity	<u>None</u> / Odd / Even	
Target Port No.	<u>1</u> to 31	

#### Inverter

Set communication parameters.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Function Code	Item	Setting	Example															
y01	Station address	<u>1</u> to 31	1															
y04	Baud rate	1: 4800 bps 2: 9600 bps 3: <u>19200 bps</u> 4: 38400 bps	3															
y06	Parity bit	0: <u>None</u> 1: Even 2: Odd 3: None	0															
y07	Stop bit	For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting.  When "0" is specified for y06, "2 bits" is set for stop bit. When "1", "2", or "3" is specified for y06, "1 bit" is set for stop bit.	-															
y10	Communication protocol <sup>*1</sup>	0: Modbus RTU 1: <u>SX (loader) protocol</u> 2: FGI-bus	0															
y11	Station address	<u>1</u> to 31	1															
y14	Baud rate	1: 4800 bps 2: 9600 bps 3: <u>19200 bps</u> 4: 38400 bps	3															
y16	Parity bit	0: <u>None</u> 1: Even 2: Odd 3: None	0															
y17	Stop bit	For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting.  When "0" is specified for y16, "2 bits" is set for stop bit. When "1", "2", or "3" is specified for y16, "1 bit" is set for stop bit.	-															
y20	Communication protocol <sup>*1</sup>	0: <u>Modbus RTU</u> 2: FGI-bus	0															
y98	Bus function	<table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Function code H30</td> <td>Function code H30</td> </tr> <tr> <td>1</td> <td>Commanded from the fieldbus</td> <td>Function code H30</td> </tr> <tr> <td>2</td> <td>Function code H30</td> <td>Commanded from the fieldbus</td> </tr> <tr> <td>3</td> <td>Commanded from the fieldbus</td> <td>Commanded from the fieldbus</td> </tr> </tbody> </table>		Frequency	Operation Command	0	Function code H30	Function code H30	1	Commanded from the fieldbus	Function code H30	2	Function code H30	Commanded from the fieldbus	3	Commanded from the fieldbus	Commanded from the fieldbus	0
	Frequency	Operation Command																
0	Function code H30	Function code H30																
1	Commanded from the fieldbus	Function code H30																
2	Function code H30	Commanded from the fieldbus																
3	Commanded from the fieldbus	Commanded from the fieldbus																

Function Code	Item	Setting		Example	
y99	Support link function			0	
		0	Function code H30, y98		Function code H30, y98
		1	Commanded from RS-485		Function code H30, y98
		2	Function code H30, y98		Commanded from RS-485
H30	Link function *2			3	
		0	Inverter		Inverter
		1	RS-485 communication		Inverter
		2	Inverter		RS-485 communication
		3	RS-485 communication		RS-485 communication
		4	RS-485 communication (optional)		Inverter
		5	RS-485 communication (optional)		RS-485 communication
		6	Inverter		RS-485 communication (optional)
		7	RS-485 communication		RS-485 communication (optional)
8	RS-485 communication (optional)	RS-485 communication (optional)			

\*1 Select "Modbus RTU" for the communication protocol on the inverter when connecting with the S8.

\*2 When "0" is specified for y98 (bus function) as well as y99 (support link function), the frequency and operation command can be set on the S8.  
When making the frequency and operation command settings on the S8 connected to the connector for the touch panel, specify "3" for function code H30. When making those settings on the S8 connected to the optional communication board, specify "8" for function code H30.

## Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
4	02H	

## 7.2.15 FRENIC-MEGA (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 bps	
Data Length	<u>8</u> bits	Do not change the default setting because the setting on the inverter cannot be changed.
Stop Bit	1 / <u>2</u> bits	On the inverter: 2 bits when "0" is specified for y06 or y16 1 bit when "1", "2" or "3" is specified for y06 or y16
Parity	<u>None</u> / Odd / Even	
Target Port No.	<u>1</u> to 31	

#### Inverter

Set communication parameters.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Function Code	Item	Setting	Example															
y01	Station address	<u>1</u> to 31	1															
y04	Baud rate	1: 4800 bps 2: 9600 bps 3: <u>19200 bps</u> 4: 38400 bps	3															
y06	Parity bit	0: <u>None</u> 1: Even 2: Odd 3: None	0															
y07	Stop bit	For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting.  When "0" is specified for y06, "2 bits" is set for stop bit. When "1", "2", or "3" is specified for y06, "1 bit" is set for stop bit.	-															
y10	Communication protocol <sup>*1</sup>	0: Modbus RTU 1: <u>SX (loader) protocol</u> 2: FGI-bus	0															
y11	Station address	<u>1</u> to 31	1															
y14	Baud rate	1: 4800 bps 2: 9600 bps 3: <u>19200 bps</u> 4: 38400 bps	3															
y16	Parity bit	0: <u>None</u> 1: Even 2: Odd 3: None	0															
y17	Stop bit	For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting.  When "0" is specified for y16, "2 bits" is set for stop bit. When "1", "2", or "3" is specified for y16, "1 bit" is set for stop bit.	-															
y20	Communication protocol <sup>*1</sup>	0: <u>Modbus RTU</u> 2: FGI-bus	0															
y98	Bus function	<table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Function code H30</td> <td>Function code H30</td> </tr> <tr> <td>1</td> <td>Commanded from the fieldbus</td> <td>Function code H30</td> </tr> <tr> <td>2</td> <td>Function code H30</td> <td>Commanded from the fieldbus</td> </tr> <tr> <td>3</td> <td>Commanded from the fieldbus</td> <td>Commanded from the fieldbus</td> </tr> </tbody> </table>		Frequency	Operation Command	0	Function code H30	Function code H30	1	Commanded from the fieldbus	Function code H30	2	Function code H30	Commanded from the fieldbus	3	Commanded from the fieldbus	Commanded from the fieldbus	0
	Frequency	Operation Command																
0	Function code H30	Function code H30																
1	Commanded from the fieldbus	Function code H30																
2	Function code H30	Commanded from the fieldbus																
3	Commanded from the fieldbus	Commanded from the fieldbus																

Function Code	Item	Setting		Example	
y99	Support link function		Frequency	Operation Command	0
		0	Function code H30, y98	Function code H30, y98	
		1	Commanded from the loader	Function code H30, y98	
		2	Function code H30, y98	Commanded from the loader	
H30	Link function *2		Frequency	Operation Command	3
		0	Inverter	Inverter	
		1	RS-485 communication	Inverter	
		2	Inverter	RS-485 communication	
		3	RS-485 communication	RS-485 communication	
		4	RS-485 communication (control circuit)	Inverter	
		5	RS-485 communication (control circuit)	RS-485 communication	
		6	Inverter	RS-485 communication (control circuit)	
		7	RS-485 communication	RS-485 communication (control circuit)	
8	RS-485 communication (control circuit)	RS-485 communication (control circuit)			

\*1 Select "Modbus RTU" for the communication protocol on the inverter when connecting with the S8.

\*2 When "0" is specified for y98 (bus function) as well as y99 (support link function), the frequency and operation command can be set on the S8.  
When making the frequency and operation command settings on the S8 connected to the connector for the touch panel, specify "3" for function code H30. When making those settings on the S8 connected to the terminal block on control circuit, specify "8" for function code H30.

## Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
4	02H	

## 7.2.16 HFR-C9K

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	1 / <u>2</u> bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>1</u> to 31	

#### IH Inverter

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

#### SW1 setting (Station address / optional selection)

Switch	Contents	Example																																																												
1	<table border="1"> <thead> <tr> <th>Switch</th> <th>1</th> <th>2</th> <th>3</th> <th>4</th> <th>5</th> </tr> </thead> <tbody> <tr> <td>Address 0</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>1</td> <td>ON</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>2</td> <td>OFF</td> <td>ON</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>3</td> <td>ON</td> <td>ON</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>:</td> <td>:</td> <td>:</td> <td>:</td> <td>:</td> <td>:</td> </tr> <tr> <td>28</td> <td>OFF</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> <tr> <td>29</td> <td>ON</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> <tr> <td>30</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> <tr> <td>31</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> </tbody> </table>	Switch	1	2	3	4	5	Address 0	OFF	OFF	OFF	OFF	OFF	1	ON	OFF	OFF	OFF	OFF	2	OFF	ON	OFF	OFF	OFF	3	ON	ON	OFF	OFF	OFF	:	:	:	:	:	:	28	OFF	OFF	ON	ON	ON	29	ON	OFF	ON	ON	ON	30	OFF	ON	ON	ON	ON	31	ON	ON	ON	ON	ON	Station Address: 1 Optional Selection: Selection for Communication Operation (Start from LSB)
Switch		1	2	3	4	5																																																								
Address 0		OFF	OFF	OFF	OFF	OFF																																																								
1		ON	OFF	OFF	OFF	OFF																																																								
2		OFF	ON	OFF	OFF	OFF																																																								
3	ON	ON	OFF	OFF	OFF																																																									
:	:	:	:	:	:																																																									
28	OFF	OFF	ON	ON	ON																																																									
29	ON	OFF	ON	ON	ON																																																									
30	OFF	ON	ON	ON	ON																																																									
31	ON	ON	ON	ON	ON																																																									
2																																																														
3																																																														
4																																																														
5																																																														
6	<table border="1"> <thead> <tr> <th>Contents</th> <th>LSB</th> <th>MSB</th> </tr> </thead> <tbody> <tr> <td>Selection for Communication Operation (Start from LSB)</td> <td><u>ON</u></td> <td>OFF</td> </tr> <tr> <td>Selection for Communication Operation (Start from MSB)</td> <td>OFF</td> <td>ON</td> </tr> </tbody> </table>	Contents	LSB	MSB	Selection for Communication Operation (Start from LSB)	<u>ON</u>	OFF	Selection for Communication Operation (Start from MSB)	OFF	ON																																																				
Contents	LSB	MSB																																																												
Selection for Communication Operation (Start from LSB)	<u>ON</u>	OFF																																																												
Selection for Communication Operation (Start from MSB)	OFF	ON																																																												

\*1 For communication with S8, be sure to set the station address other than 0.

#### Communication setting

Set communication parameters.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Function Code	Item	Setting	Example
F16	Baud rate	4: 4800 bps 5: <u>9600 bps</u> 6: 19200 bps	5
F17	Data length	0: 7 bit 1: <u>8 bits</u>	1
F18	Parity bit	0: None 1: <u>Even</u> 2: Odd	1
F19	Stop bit	0: 1 bit 1: <u>2 bits</u>	1

---

## Available Memory

---

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
---	00H	

## 7.2.17 HFR-C11K

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>1</u> to 31	

#### IH Inverter

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

#### SW3 setting (Station address / Terminating resistance)

Switch	Contents	Example																																																												
1	<table border="1"> <thead> <tr> <th>Switch Address</th> <th>1</th> <th>2</th> <th>3</th> <th>4</th> <th>5</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>1</td> <td>ON</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>2</td> <td>OFF</td> <td>ON</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>3</td> <td>ON</td> <td>ON</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>:</td> <td>:</td> <td>:</td> <td>:</td> <td>:</td> <td>:</td> </tr> <tr> <td>28</td> <td>OFF</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> <tr> <td>29</td> <td>ON</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> <tr> <td>30</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> <tr> <td>31</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> </tbody> </table>	Switch Address	1	2	3	4	5	<u>0</u>	OFF	OFF	OFF	OFF	OFF	1	ON	OFF	OFF	OFF	OFF	2	OFF	ON	OFF	OFF	OFF	3	ON	ON	OFF	OFF	OFF	:	:	:	:	:	:	28	OFF	OFF	ON	ON	ON	29	ON	OFF	ON	ON	ON	30	OFF	ON	ON	ON	ON	31	ON	ON	ON	ON	ON	Example Station Address: 1 Terminating Resistance: none 
Switch Address		1	2	3	4	5																																																								
<u>0</u>		OFF	OFF	OFF	OFF	OFF																																																								
1		ON	OFF	OFF	OFF	OFF																																																								
2		OFF	ON	OFF	OFF	OFF																																																								
3	ON	ON	OFF	OFF	OFF																																																									
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28	OFF	OFF	ON	ON	ON																																																									
29	ON	OFF	ON	ON	ON																																																									
30	OFF	ON	ON	ON	ON																																																									
31	ON	ON	ON	ON	ON																																																									
2	Station Address*1																																																													
3																																																														
4																																																														
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6		Terminating Resistance	<table border="1"> <thead> <tr> <th>Contents</th> <th>OFF</th> <th>ON</th> </tr> </thead> <tbody> <tr> <td>Terminating resistance</td> <td><u>None</u></td> <td>Provided</td> </tr> </tbody> </table>	Contents	OFF	ON	Terminating resistance	<u>None</u>	Provided																																																					
Contents	OFF	ON																																																												
Terminating resistance	<u>None</u>	Provided																																																												

\*1 For communication with S8, be sure to set the station address other than 0.

#### Communication setting

Set communication parameters.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Function Code	Item	Setting	Example
r 04	Baud rate	2: 4800 bps <u>3: 9600 bps</u> 4: 19200 bps	3
r 05	Data length	0: 8 bit <u>1: 7 bits</u>	1
r 06	Parity bit	0: None <u>1: Even</u> 2: Odd	1
r 07	Stop bit	0: 2 bit <u>1: 1 bits</u>	1
r 10	Communication protocol*	<u>0: FGI-bus</u> 1: C9K mode	0

- \* RS-485 communication is available when the communication is enabled by digital input.  
 Example: To make the communication enabled when digital input terminal X1 is turned ON;  
 Set "11 (RS485 communication selection (RS))" for function code i01 and turn on the digital input terminal X1 externally.  
 Terminals from X2 to X5 can also be used. Set the function code corresponding to the digital input terminal to use.

## Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
S (command data)	00H	
M (monitor data)	01H	
F (basic function)	02H	
E (error display function)	03H	
C (control function)	04H	
P (optional function)	05H	
H (high level function)	06H	
o (output terminal function)	08H	
i (input terminal function)	0BH	
t (control function in the event of trip (alarm) occurrence)	0CH	
r (RS communication function)	0DH	
Pn (touch panel function)	0EH	

## PLC\_CTL

Content	F0	F1 (= \$u n)		F2
Reset command	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 0	



## 7.2.18 PPMC (MODBUS RTU)

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / 1 : n / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	<u>9600</u> / 19200 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> bit	Do not change the default setting because the setting on the AC power monitor cannot be changed.
Parity	<u>None</u> / Even / Odd	
Target Port No.	1 to 31	

#### AC Power Monitor

The communication parameters can be set using keys attached to the front of the AC power monitor.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Parameter	Item	Setting	Example	
Setting condition 2	Item number 2	ID number	1 to 31 (default: unit number*1)	1
	Item number 3	Communication protocol selection	<u>nor: Dedicated protocol</u> rtu: Modbus RTU protocol *2	rtu
	Item number 7	Baud rate	<u>9.6: 9600 bps</u> 19.2: 19200 bps 4.8: 4800 bps	9.6
	Item number 8	Data length, parity	<u>8n: Data length 8 bits, without parity</u> 8o: Data length 8 bits, odd parity 8E: Data length 8 bits, even parity	8n

\* The communication function of the AC power monitor can be selected at the time of purchase. Select a model on which RS-485/RS-232C communication is available.

\*1 The unit number is set for the ID number upon delivery. The unit number is indicated on the instruction plate attached to the side of the case.

\*2 Select "rtu (Modbus RTU)" for the communication protocol when communicating with the S8.

#### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
4 (holding register)	02H	
3 (input register)	03H	Read only

\* Remarks on data format for the following memory:

40022 (fixed voltage), 40028 (Ip fixed power factor): 6-byte character string

40046 (calendar): 14-byte character string

Measurement data: real type (Float)

40060 (alarm clear), 40062 (amount of power clear), 40064 (cumulative value of invalid power clear): write only

## 7.2.19 FALDIC- $\alpha$ Series

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-422/485</u>	Do not change the default setting other than baud rate because the setting on the servo amplifier cannot be changed.
Baud Rate	<u>9600</u> / 19200 / 38400 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> bit	
Parity	<u>Even</u>	
Target Port No.	1 to 31	

#### Servo Amplifier

Set the communication parameters using the touch panel mounted on the servo amplifier.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Parameter	Item	Setting	Example
<i>Pn002</i> <i>PP096</i> (No. 96)	Station number	<u>1</u> to 31	1
System parameter <i>PP097</i> (No. 97)	Baud rate	<u>0: 9600 bps</u> 1: 19200 bps 2: 38400 bps	0

\*1 The communication function of the servo amplifier can be selected at the time of purchase. Select a model on which host interface: universal communication (RS-485) is available.

### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
00 (monitor data)	00H	Double-word, read only
01 (data on positioning being executed)	01H	Double-word, read only
10 (sequence mode)	02H	Read only
11 (control input/output signal)	03H	Read only
12 (alarm detection log)	04H	Read only
13 (detected alarm contents)	05H	Read only
20 (standard parameter)	06H	Double-word <sup>*1</sup>
21 (system parameter)	07H	Double-word <sup>*1</sup>
30 (positioning data)	08H	Double-word <sup>*2</sup>
40 (control command)	09H	Double-word, write only

\*1 Input a parameter number by manual operation.

\*2 Address denotations XXYY

┌ Address  
└ Positioning data number (01H - 63H)

## PLC\_CTL

Contents	F0	F1 (= \$u n)		F2
Positioning data (immediate) setting	1 - 2 (PLC1 - 2)	n	Station number	6
		n + 1	Command: 9	
		n + 2	ABS/INC	
		n + 3	Speed selection	
		n + 4 to n + 5	Position data	
Automatic start (immediate)	1 - 2 (PLC1 - 2)	n	Station number	6
		n + 1	Command: 11	
		n + 2	ABS/INC	
		n + 3	Speed selection	
		n + 4 to n + 5	Position data	
Automatic start (positioning data number)	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 12	
		n + 2	Start number	
Override setting	1 - 2 (PLC1 - 2)	n	Station number	4
		n + 1	Command: 33	
		n + 2	Data type	
		n + 3	Setting	

## 7.2.20 PHR (MODBUS RTU)

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-422/485</u>	Do not change the default settings of the signal level, data length and stop bit because these settings on the recorder cannot be changed.
Baud Rate	9600 / <u>19200</u> bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> bit	
Parity	None / Even / <u>Odd</u>	
Target Port No.	1 to 31	

#### Recorder

The communication parameters can be set using keys attached to the front of the recorder.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Parameter	Setting	Example	Remarks
Modbus station No.	<u>1</u> to 31	1	
Modbus baud rate	9600 / <u>19200</u> bps	19200 bps	
Modbus parity	None / Even / <u>Odd</u>	Odd	
Front communication function	<u>ON</u> / OFF	ON	Be sure to set to "ON".

\* The communication function of the recorder can be selected at the time of purchase. Select a model on which RS-485 communication is available.

### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
4 (holding register)	02H	
3 (input register)	03H	

## 7.2.21 WA5000

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	1 / <u>2</u> bits	
Parity	None / <u>Even</u> / Odd	
CR / LF	<u>CR</u> / CR/LF	
Target Port No.	1 to 31	

#### Digital Panel Meter

The communication parameters can be set using keys attached to the front of the digital panel meter. Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Parameter	Item	Setting	Example	Remarks	
<b>BAUD</b>	BAUD	Baud rate setting	4800: 4800 <u>9600: 9600</u> 192: 19200 384: 38400	9600	
<b>DATA</b>	DATA	Data length setting	<u>7: 7 bits</u> 8: 8 bits	7 bits	
<b>P.BIT</b>	P.BIT	Parity bit setting	<u>E: Even</u> o: Odd n: None	E: Even	
<b>S.BIT</b>	S.BIT	Stop bit setting	<u>2: 2 bits</u> 1: 1 bit	2: 2 bits	
<b>T-</b>	T-	Delimiter setting	<u>cr.LF: CR/LF</u> cr: CR	cr.LF: CR/LF	
<b>ADR</b>	ADR	Unit ID setting	01 to 31 (default: <u>00</u> )	01	Specify a value when using RS-485 connection.

\* The communication function of the temperature controller can be selected with the output unit specified at the time of purchase. Select a model on which RS-485/RS-232C communication is available.

#### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
DSP (display)	00H	
CMP (comparator)	01H	
SCL (scaling)	02H	
CAL1 (calibration 1)**1	03H	
CAL2 (calibration 2)	04H	

\*\*1 To perform zero calibration (0000), specify a value other than 0.

## PLC\_CTL

Contents	F0	F1 (= \$u n)		F2
Hold remote control response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 0	
		n + 2	Hold status 0: OFF, 1: ON	
Hold terminal response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 1	
		n + 2	Hold status 0: OFF, 1: ON	
Hold remote control	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 2	
		n + 2	Hold status 0: OFF, 1: ON	
Trigger input	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 3	
		n + 2	Display type 0: Normal display 1: Over display 2: Peak hold display 3: Valley hold display 4: Peak valley hold display	
		n + 3	Measurement value	
		n + 4	Comparison result 0: OFF 1: HI 2: GO 3: LO	
Hold remote control cancel	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 4	
Peak hold remote control response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 5	
		n + 2	Peak hold type 0: Peak hold 1: Valley hold 2: Peak valley hold	
		n + 3	Peak hold status 0: OFF, 1: ON	
Peak hold terminal response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 6	
		n + 2	Peak hold status 0: OFF, 1: ON	
Peak hold type setting	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 7	
		n + 2	Peak hold type 0: Peak hold 1: Valley hold 2: Peak valley hold	
Peak hold remote control	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 8	
		n + 2	Peak hold remote 0: OFF, 1: ON	
Peak hold value response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 9	
		n + 2	Peak hold value	
		n + 3	Valley hold value	
Peak hold value clear	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 10	
		n + 2	Peak hold type 0: Peak hold 1: Valley hold 2: Peak valley hold	
		n + 3	Peak valley hold value	
Peak hold remote control cancel	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 11	

Contents	F0	F1 (= \$u n)		F2					
Digital zero remote control response	1 - 2 (PLC1 - 2)	n	Station number	2					
		n + 1	Command: 12						
		n + 2	Digital zero 0: OFF, 1: ON						
		n + 3	Displayed value						
Digital zero terminal response	1 - 2 (PLC1 - 2)	n	Station number	2					
		n + 1	Command: 13						
		n + 2	Digital zero 0: OFF, 1: ON						
Digital zero remote control	1 - 2 (PLC1 - 2)	n	Station number	4					
		n + 1	Command: 14						
		n + 2	Digital zero 0: OFF, 1: ON, 2: ON when the value reaches the set value						
		n + 3	Setting value						
Digital zero remote control cancel	1 - 2 (PLC1 - 2)	n	Station number	2					
		n + 1	Command: 15						
Comparison output remote control response	1 - 2 (PLC1 - 2)	n	Station number	2					
		n + 1	Command: 16						
		n + 2	Status 0: OFF 1: Set (ON) HI 2: Set (ON) GO 3: Set (ON) LO						
Comparison output remote control	1 - 2 (PLC1 - 2)	n	Station number	3					
		n + 1	Command: 17						
		n + 2	Status 0: OFF 1: Set (ON) HI 2: Set (ON) GO 3: Set (ON) LO						
Comparison output remote control cancel	1 - 2 (PLC1 - 2)	n	Station number	2					
		n + 1	Command: 18						
Remote control response	1 - 2 (PLC1 - 2)	n	Station number	2					
		n + 1	Command: 19						
		n + 2	Remote control status  Bit <table border="1" style="display: inline-table; vertical-align: middle;"> <tr> <td>-</td> <td>3</td> <td>2</td> <td>1</td> <td>0</td> </tr> </table> — Hold function — Peak hold — Digital zero — Comparison output  * No remote control is performed when all bits are reset (OFF).		-	3	2	1	0
		-	3		2	1	0		
Maximum / minimum / (maximum - minimum) response	1 - 2 (PLC1 - 2)	n	Station number	2					
		n + 1	Command: 20						
		n + 2	Maximum						
		n + 3	Minimum						
		n + 4	(Maximum - minimum)						
Maximum / minimum / (maximum - minimum) clear	1 - 2 (PLC1 - 2)	n	Station number	3					
		n + 1	Command: 21						
		n + 2	Maximum / minimum / (maximum - minimum) clear 0: Maximum 1: Minimum 2: Maximum - minimum						

Contents	F0	F1 (= \$u n)		F2
Range response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 22	
		n + 2	Range 0: No designation      12: J 1: Range 11            13: T 2: Range 12            14: R 3: Range 13            15: S 4: Range 14            16: B 5: Range 15            17: PA 6: Range 23            18: Pb 7: Range 24            19: JPA 8: Range 25            20: JPb 9: Range 26            21: 1V 10: KA                    22: 2A 11: KB	
Range setting	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 23	
		n + 2	Range 1: Range 11            12: J 2: Range 12            13: T 3: Range 13            14: R 4: Range 14            15: S 5: Range 15            16: B 6: Range 23            17: PA 7: Range 24            18: Pb 8: Range 25            19: JPA 9: Range 26            20: JPb 10: KA                    21: 1V 11: KB                    22: 2A	
Average number of responses	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 24	
		n + 2	Average number of times 1 / 2 / 4 / 8 / 10 / 20 / 40 / 80 (times)	
Setting for average number of times	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 25	
		n + 2	Average number of times 1 / 2 / 4 / 8 / 10 / 20 / 40 / 80 (times)	
Average number of movement times	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 26	
		n + 2	Average number of movement times 0 (OFF) / 2 / 4 / 8 / 16 / 32 (times)	
Setting for average number of movement times	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 27	
		n + 2	Average number of movement times 0 (OFF) / 2 / 4 / 8 / 16 / 32 (times)	
Step-wide response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 28	
		n + 2	Step wide 1:1, 2:2, 5:5, 0:10 (digit)	
Step-wide setting	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 29	
		n + 2	Step wide 1:1, 2:2, 5:5, 0:10 (digit)	
Communication function parameter response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 30	
		n + 2	Baud rate 0: 2400, 1: 4800, 2: 9600, 3: 19200, 4: 38400	
		n + 3	Data length 0: 7 bits, 1: 8 bits	
		n + 4	Parity 0: none, 1: odd, 2: even	
		n + 5	Stop bit 0: 1 bit, 1: 2 bits	
		n + 6	Delimiter 0: CR/LF, 1: CR	




Contents	F0	F1 (= \$u n)		F2
Communication function parameter setting	1 - 2 (PLC1 - 2)	n	Station number	7
		n + 1	Command: 31	
		n + 2	Baud rate 0: 2400, 1: 4800, 2: 9600, 3: 19200, 4: 38400	
		n + 3	Data length 0: 7 bits, 1: 8 bits	
		n + 4	Parity 0: none, 1: odd, 2: even	
		n + 5	Stop bit 0: 1 bit, 1: 2 bits	
		n + 6	Delimiter 0: CR/LF, 1: CR	
Unit ID response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 32	
		n + 2	Unit ID 1 to 99	
Unit ID setting	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 33	
		n + 2	Unit ID 1 to 99	
Analog output type response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 34	
		n + 2	Analog output type 0: Not provided 1: OFF 2: 0 - 1 (V) 3: 0 - 10 (V) 4: 1 - 5 (V) 5: 0 - 20 (mA) 6: 4 - 20 (mA)	
Analog output type setting	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 35	
		n + 2	Analog output type 1: OFF 2: 0 - 1 (V) 3: 0 - 10 (V) 4: 1 - 5 (V) 5: 0 - 20 (mA) 6: 4 - 20 (mA)	
Digital zero backup status response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 36	
		n + 2	Digital zero backup status 0: OFF 1: ON	
Digital zero backup control	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 37	
		n + 2	Digital zero backup status 0: OFF 1: ON	
Digital zero data save command	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 38	
Input change response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 39	
		n + 2	Input change 0: Not provided 1: Open collector 2: Logic 3: Magnetic	
Input change setting	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 40	
		n + 2	Input change 1: Open collector 2: Logic 3: Magnetic	

Contents	F0	F1 (= \$u n)		F2
Tracking zero response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 41	
		n + 2	Tracking zero time 0 (OFF) / 1 to 99	
		n + 3	Tracking zero width 0 (OFF) / 1 to 99	
Tracking zero time setting	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 42	
		n + 2	Tracking zero time 0 (OFF) / 1 to 99	
Tracking zero width setting	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 43	
		n + 2	Tracking zero width 0 (OFF) / 1 to 99	
Sensor power response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 44	
		n + 2	Sensor power 0: 5 V 1: 10 V	
Sensor power setting	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 45	
		n + 2	Sensor power 0: 5 V 1: 10 V	
Power-on delay time response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 46	
		n + 2	Power-on delay time 0 (OFF) / 1 to 30	
Power-on delay time setting	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 47	
		n + 2	Power-on delay time 0 (OFF) / 1 to 30	
Protection response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 48	
		n + 2	Protect 0: OFF 1: ON	
Protection setting	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 49	
		n + 2	Protect 0: OFF 1: ON	
Unit No. response	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 50	
		n + 2	Input unit number 1 to 18	
		n + 3	Output unit number 0 to 7	
Response to prohibition of key operations	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 51	
		n + 2	Prohibition of key operations 0: OFF 1: ON	
Prohibition of key operations setting	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 52	
		n + 2	Prohibition of key operations 0: OFF 1: ON	
Response to linearizing function status	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 53	
		n + 2	Linearizing function 0: OFF 1: ON 2: CLR	

Contents	F0	F1 (= \$u n)		F2
Linearizing function status setting	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 54	
		n + 2	Linearizing function 0: OFF 1: ON 2: CLR	
Response to the number of linearization correction data	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 55	
		n + 2	Linearization correction data 0 (clear) to 16	
The number of linearization correction data setting	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	Command: 56	
		n + 2	Linearization correction data 1 to 16	
Response to linearization data	1 - 2 (PLC1 - 2)	n	Station number	4
		n + 1	Command: 57	
		n + 2	Read start number 1 to 16	
		n + 3	The number of read data 1 to 16	
		n + 4	Linearization data input value (start number + 0)	
		n + 5	Linearization data output value (start number + 0)	
		n + 6	Linearization data input value (start number + 1)	
		n + 7	Linearization data output value (start number + 1)	
		n + 8	Linearization data input value (start number + 2)	
		n + 9	Linearization data output value (start number + 2)	
		n + 10	Linearization data input value (start number + 3)	
		n + 11	Linearization data output value (start number + 3)	
		n + 12	Linearization data input value (start number + 4)	
		n + 13	Linearization data output value (start number + 4)	
		n + 14	Linearization data input value (start number + 5)	
		n + 15	Linearization data output value (start number + 5)	
		n + 16	Linearization data input value (start number + 6)	
		n + 17	Linearization data output value (start number + 6)	
		n + 18	Linearization data input value (start number + 7)	
		n + 19	Linearization data output value (start number + 7)	
		n + 20	Linearization data input value (start number + 8)	
		n + 21	Linearization data output value (start number + 8)	
		n + 22	Linearization data input value (start number + 9)	
		n + 23	Linearization data output value (start number + 9)	
		n + 24	Linearization data input value (start number + 10)	
		n + 25	Linearization data output value (start number + 10)	
		n + 26	Linearization data input value (start number + 11)	
		n + 27	Linearization data output value (start number + 11)	
		n + 28	Linearization data input value (start number + 12)	
		n + 29	Linearization data output value (start number + 12)	
		n + 30	Linearization data input value (start number + 13)	
		n + 31	Linearization data output value (start number + 13)	
		n + 32	Linearization data input value (start number + 14)	
		n + 33	Linearization data output value (start number + 14)	
		n + 34	Linearization data input value (start number + 15)	
n + 35	Linearization data output value (start number + 15)			

Contents	F0	F1 (= \$u n)		F2
Linearization data setting	1 - 2 (PLC1 - 2)	n	Station number	6 , 36
		n + 1	Command: 58	
		n + 2	Read start number 1 to 16	
		n + 3	The number of read data 1 to 16	
		n + 4	Linearization data input value (start number + 0)	
		n + 5	Linearization data output value (start number + 0)	
		n + 6	Linearization data input value (start number + 1)	
		n + 7	Linearization data output value (start number + 1)	
		n + 8	Linearization data input value (start number + 2)	
		n + 9	Linearization data output value (start number + 2)	
		n + 10	Linearization data input value (start number + 3)	
		n + 11	Linearization data output value (start number + 3)	
		n + 12	Linearization data input value (start number + 4)	
		n + 13	Linearization data output value (start number + 4)	
		n + 14	Linearization data input value (start number + 5)	
		n + 15	Linearization data output value (start number + 5)	
		n + 16	Linearization data input value (start number + 6)	
		n + 17	Linearization data output value (start number + 6)	
		n + 18	Linearization data input value (start number + 7)	
		n + 19	Linearization data output value (start number + 7)	
		n + 20	Linearization data input value (start number + 8)	
		n + 21	Linearization data output value (start number + 8)	
		n + 22	Linearization data input value (start number + 9)	
		n + 23	Linearization data output value (start number + 9)	
		n + 24	Linearization data input value (start number + 10)	
		n + 25	Linearization data output value (start number + 10)	
		n + 26	Linearization data input value (start number + 11)	
		n + 27	Linearization data output value (start number + 11)	
		n + 28	Linearization data input value (start number + 12)	
		n + 29	Linearization data output value (start number + 12)	
		n + 30	Linearization data input value (start number + 13)	
		n + 31	Linearization data output value (start number + 13)	
		n + 32	Linearization data input value (start number + 14)	
		n + 33	Linearization data output value (start number + 14)	
		n + 34	Linearization data input value (start number + 15)	
n + 35	Linearization data output value (start number + 15)			

 Return data: Data stored from the panel meter to the S8

## 7.2.22 APR-N (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Even / <u>Odd</u>	
Target Port No.	<u>1</u> to 31	

#### AC Power Regulator

The communication parameter can be set using keys attached to the front of the AC power regulator.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Function Code	Item	Setting	Example
6.o02	Setting device selection*	<u>APd: Setting indicator</u> nEt: Network device APr: APR main unit	nEt
7.n01	Communication protocol selection*	<u>m-S: Master / slave parallel operation</u> nEt: MODBUS RTU	nEt
7.n02	Station address	A000: 0 , A031: 31 (default: A001: 1)	A001
7.n04	Baud rate selection	4800: 4800 bps <u>9600: 9600 bps</u> 1.920: 19200 bps 3.840: 38400 bps	9600
7.n05	Parity bit + Stop bit selection	P0: Without parity, Stop bit 2 bits P1: Even parity, Stop bit 1 bits <u>P2: Odd parity, Stop bit 1 bits</u> P3: Without parity, Stop bit 1 bits	P2

\* For communication with S8, select "Network device" for the setting device selection and "MODBUS RTU" for the communication protocol selection on this regulator.

#### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
---	02H	Byte address

#### Indirect Memory Designation

- For word designation, specify the memory No. (address) in even address.  
Example: To make the memory setting of "output setting" for the function code 1.b01;  
Specify "2" in the memory No. (address).
- For bit designation, it is possible to specify the memory No. (address) in both even and odd address.  
Specify "00H" for the extensional code because the setting range for the bit address is 0 to 7.  
Example: To make the memory setting of "gradient setting selection" for the function code 1.b09;  
Specify "1" in the memory No. (address), "00H" for the extensional code, and "00" or "01" in the bit No..

## 7.2.23 ALPHA5 (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-422/485</u>	
Baud Rate	9600 / 19200 / <u>38400</u> bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Even</u> / Odd	
Target Port No.	<u>1</u> to 31	

#### Servo Amplifier

Set communication parameters.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Parameter		Item	Setting	Example
PA2 Extensional Function Setting	PA2_72	(No. 72) Station number	<u>1</u> to 31	1
	PA2_73	(No. 73) Baud rate	<u>0: 38400 bps</u> 1: 19200 bps 2: 9600 bps	0
	PA2_93	(No. 93) Parity bit / Stop bit selection	<u>0: Even parity, Stop bit 1 bits</u> 1: Odd parity, Stop bit 1 bits 2: Without parity, Stop bit 1 bits 3: Even parity, Stop bit 2 bits 4: Odd parity, Stop bit 2 bits 5: Without parity, Stop bit 2 bits	0
	PA2_97	(No. 97) Communication protocol selection*	<u>0: PC Loader protocol</u> 1: MODBUS RTU	1

\* For communication with S8, select "MODBUS RTU" for the communication protocol selection on the servo amplifier.

### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
00 (communication CONT/OUT signals)	00H	Double-word*1
01 (monitor)	01H	Double-word, read only
02 (sequence monitor)	02H	Double-word, read only
03 (various commands)	03H	Double-word
04 (parameter)	04H	Double-word
05 (immediate value data)	05H	Double-word

\*1 Communication OUT signal is read only.

PLC\_CTL

Contents	F0	F1 (= \$u n)		F2	
Positioning data reading	1 - 2 (PLC1 - 2)	n	Station number	4	
		n+1	Command: 03 (HEX)		
		n+2	Reading memory address		
		n+3	Reading positioning data count: m (1 to 9)		
		n+4	Positioning data m = 1		Positioning status and M code Bit 15 to 8   7   6   5   4   3   2   1   0 M code output timing   Not used   M code valid/invalid   Step mode   Command mode
		n+5	Stop timer		
		n+6 to n+7	Stop position		
		n+8 to n+9	Rotation speed		
		n+10 to n+11	Acceleration time		
		n+12 to n+13	Deceleration time		
		n+14 to n+(3+10m)	Positioning data (m = 2)		
Positioning data writing	1 - 2 (PLC1 - 2)	n	Station number	4+10m	
		n+1	Command: 10 (HEX)		
		n+2	Writing memory address		
		n+3	Writing positioning data count: m (1 to 9)		
		n+4	Positioning data m = 1		Positioning status and M code Bit 15 to 8   7   6   5   4   3   2   1   0 M code output timing   Not used   M code valid/invalid   Step mode   Command mode
		n+5	Stop timer		
		n+6 to n+7	Stop position		
		n+8 to n+9	Rotation speed		
		n+10 to n+11	Acceleration time		
		n+12 to n+13	Deceleration time		
		n+14 to n+(3+10m)	Positioning data (m = 2)		

Return data: Data stored from the servo amplifier to the S8

## 7.2.24 WE1MA (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Even</u> / Odd	
Target Port No.	<u>1</u> to 31	

#### Electronic Multimeter

The communication parameter can be set using keys attached to the front of the electronic multimeter.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor. (Underlined setting: default)

Setting Component	Setting No.	Item	Setting	Example
Adr	231C	Station address	<u>1</u> to 31	1
bPS	232C	Baud rate	4800 / <u>9600</u> / 19200 / 38400 bps	9600
PAr	233C	Parity bit	<u>E</u> : Even o: Odd -: None	E
StoP	234C	Stop bit	<u>1</u> / 2 bits	1

#### Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

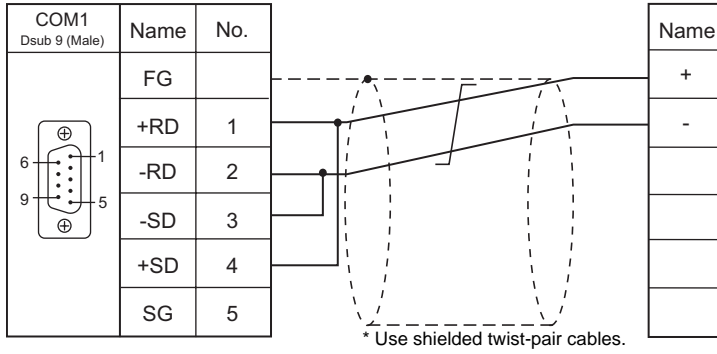
Memory	TYPE	Remarks
1 (input relay)	01H	Read only
4 (holding register)	02H	
3 (input register)	03H	Read only



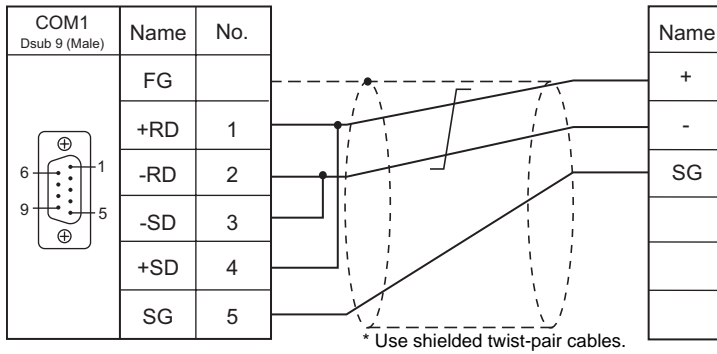
## 7.2.25 Wiring Diagrams

### When Connected at COM1 (RS-422 / RS-485):

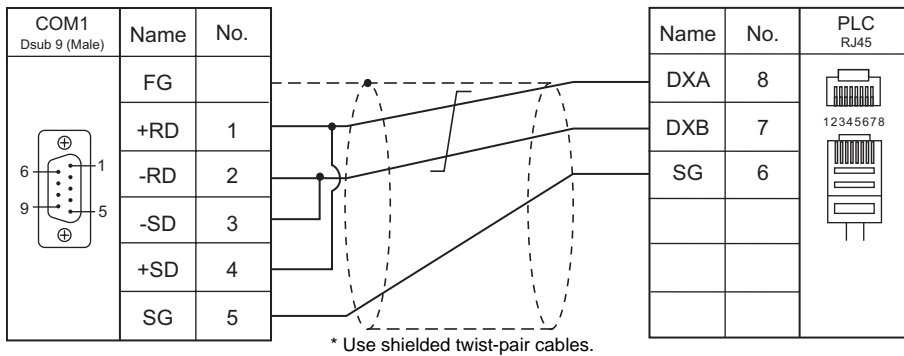
Wiring diagram 1 - COM1



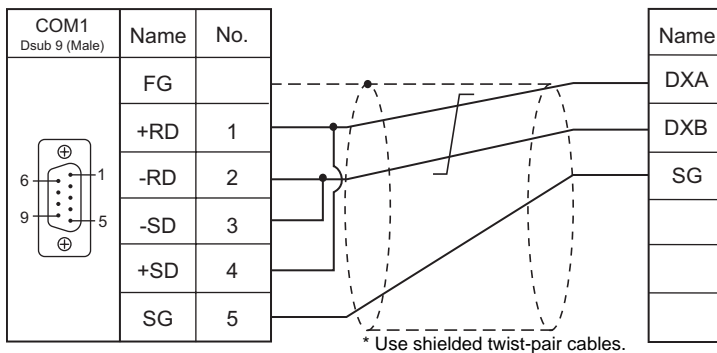
Wiring diagram 2 - COM1



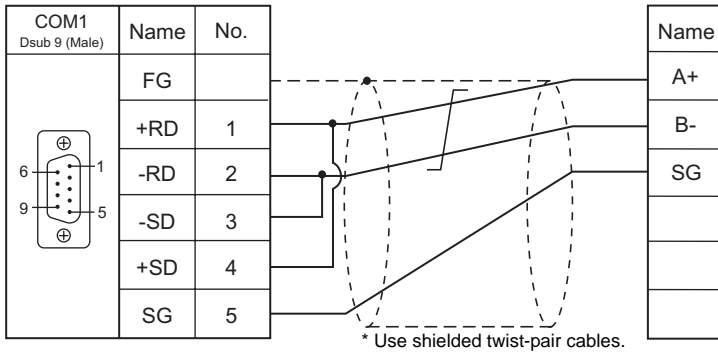
Wiring diagram 3 - COM1



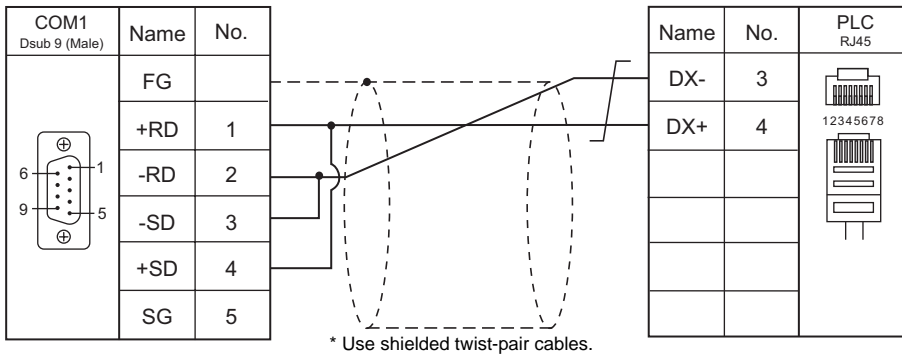
Wiring diagram 4 - COM1



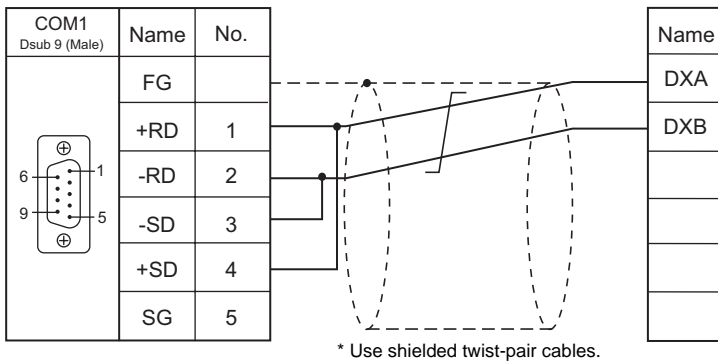
**Wiring diagram 5 - COM1**



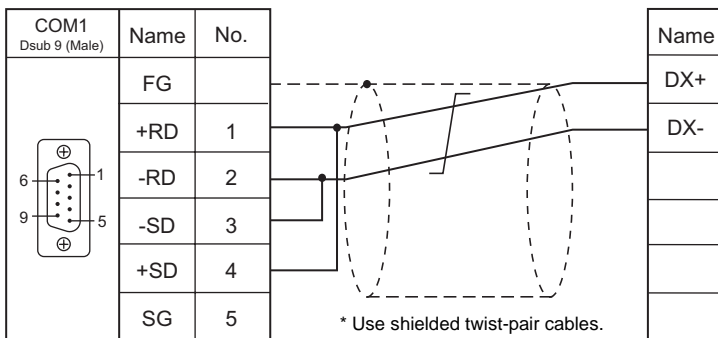
**Wiring diagram 6 - COM1**



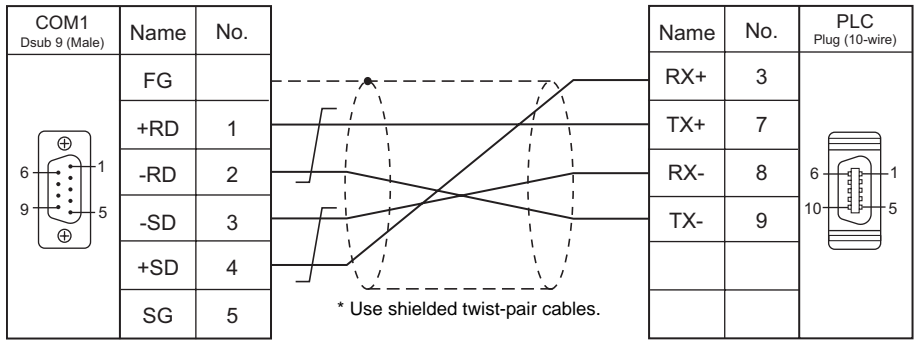
**Wiring diagram 7 - COM1**



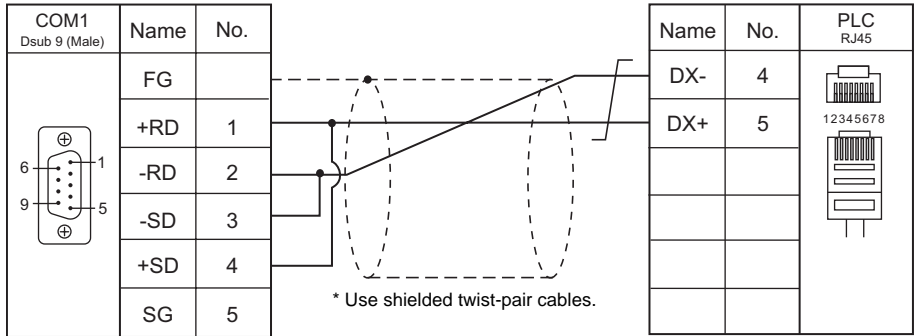
**Wiring diagram 8 - COM1**



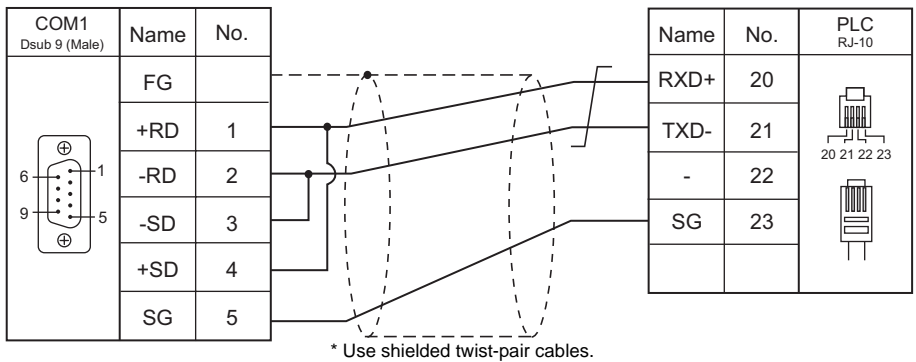
**Wiring diagram 9 - COM1**



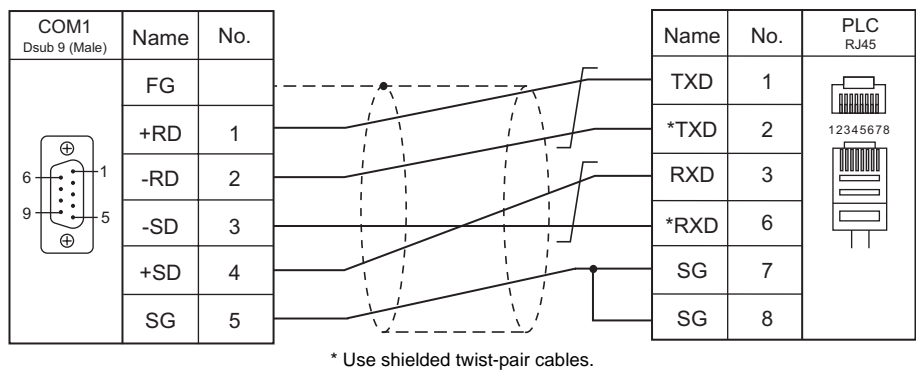
**Wiring diagram 10 - COM1**



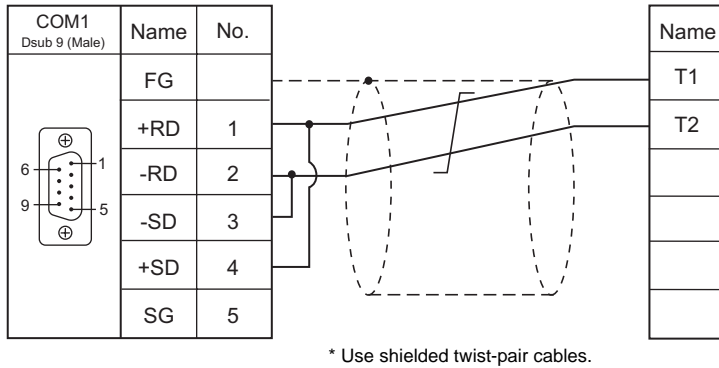
**Wiring diagram 11 - COM1**



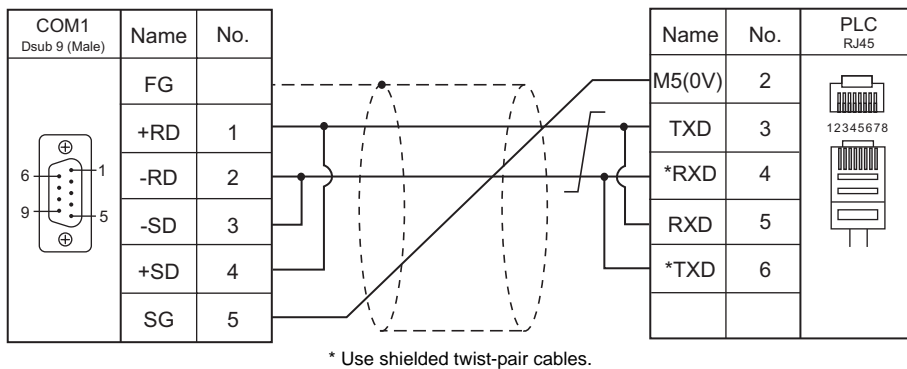
**Wiring diagram 12 - COM1**



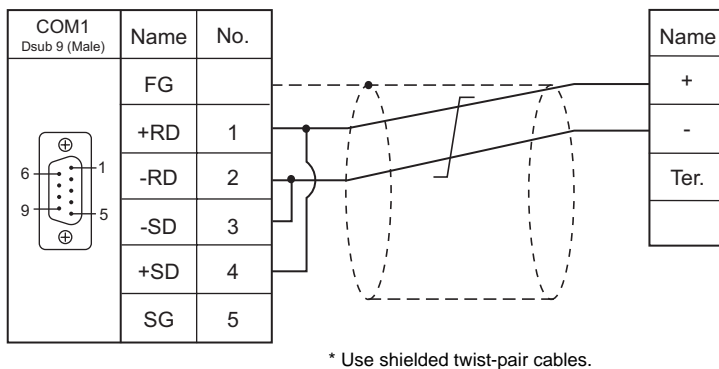
**Wiring diagram 13 - COM1**



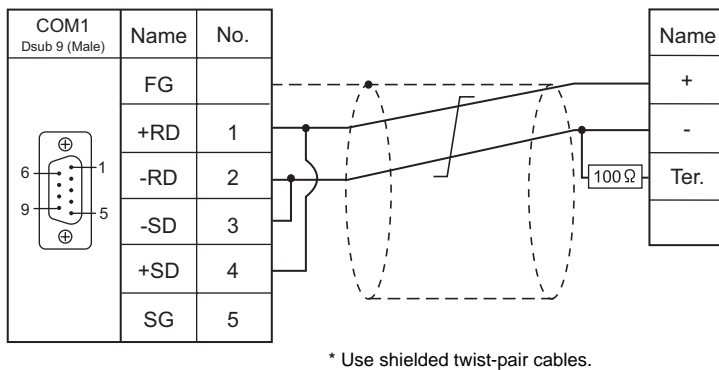
**Wiring diagram 14 - COM1**



**Wiring diagram 15 - COM1**

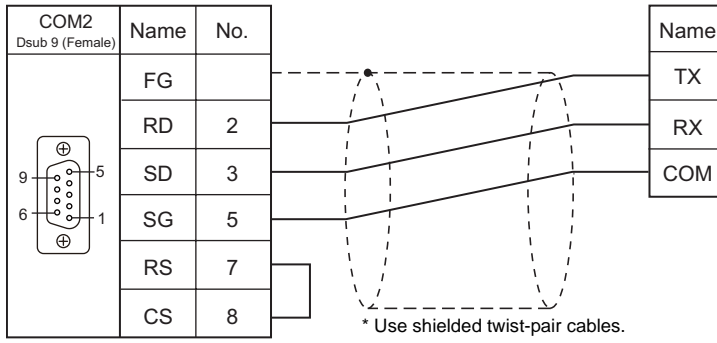


**Wiring diagram when connecting S8 to the electronic multimeter located at the terminal**

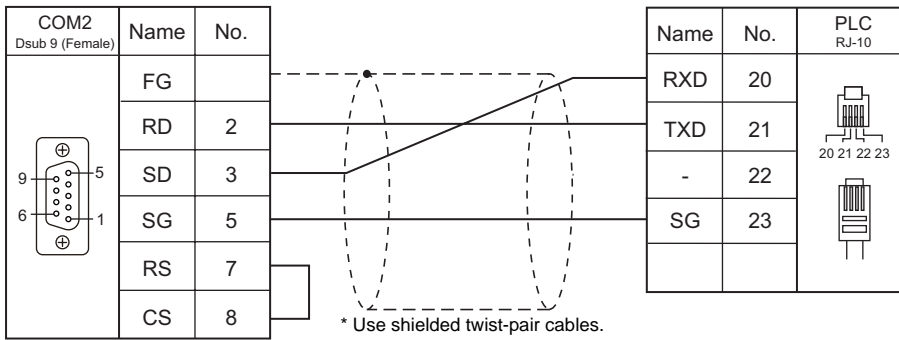


**When Connected at COM2 (RS-232C):**

**Wiring diagram 1 - COM2**



**Wiring diagram 2 - COM2**



# 8. IAI

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## 8.1 Temperature Controller/Servo/Inverter Connection



## 8.1 Temperature Controller/Servo/Inverter Connection

The controller models shown below can be connected.

### Serial Connection

#### X-SEL Controller

PLC Selection on the Editor	Model		Port	Signal Level	Connection		Lst File
					COM1	COM2	
X-SEL Controller	Orthogonal	XSEL-K XSEL-KE XSEL-KT/KET	HOST port	RS-232C	-	Wiring diagram 1 - COM2	IAI-XSEL.Lst
	Scalar	XSEL-KX					
	Orthogonal	XSEL-J XSEL-P XSEL-Q	TP port	RS-232C	-	Wiring diagram 2 - COM2	
	Scalar	XSEL-JX XSEL-PX XSEL-QX					

#### Robo Cylinder

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
PCON/ACON/SCON (MODBUS RTU)	PCON	SIO	RS-232C	-	Wiring diagram 3 - COM2	IAI-PCON.Lst
	ACON					
	SCON					



## 8.1.1 X-SEL Controller

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	9600 / 19200 / <u>38400</u> / 57600 / 115K bps	
Data Length	8 bits	
Stop Bit	1 bit	
Parity	None	
Target Port No.	0 to 31	

#### X-SEL Controller

##### Application software

Set parameters using the application software.

(Underlined setting: default)

Parameter	Parameter Name	Setting
I/O parameter 90	Channel 1 usage	2 (IAI protocol B)
I/O parameter 91	Channel 1 code	0 to 31
I/O parameter 92	Baud rate	<u>9600</u> / 19200 / 38400 bps
I/O parameter 93	Data length	8
I/O parameter 94	Stop bit	1
I/O parameter 95	Parity	None
Other parameter 46	Bit pattern	1

##### Mode switch

Select [AUTO].

## Available Memory

The available memory setting range varies depending on the models. Be sure to set within the range available for the device. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
20B (input port)	00H	Read only, virtual input port not available
20C (output port)	01H	Virtual output port not available
20D (flag)	02H	
20E (integer variable) *1	03H	Double-word
210 (string) *2	04H	
208 (effective point data count)	05H	Read only
212 (axis status)	06H	Double-word, read only
213 (program status)	07H	Read only
215 (system status)	08H	Read only
253 (program)	09H	Write only
2A1 (scalar axis status)	0AH	Double-word, read only

\*1 For 20E (integer variable) XXYYYY

Variable number 0000 to 4095  
Program number 00 to 99

\*2 For 210 (string) XXYYYY

Column number 0000 to 4095  
Program number 00 to 99

### Memory: 208 (Effective Point Data Count)

Address	Name
0	Effective point data count

### Memory: 212 (Axis Status)

Address	Name
0	Axis 1 axis status
1	Axis 1 axis sensor input status
2	Axis 1 axis-related error code
3	Axis 1 encoder status
4	Axis 1 current position
10	Axis 2 axis status
11	Axis 2 axis sensor input status
12	Axis 2 axis-related error code
13	Axis 2 encoder status
14	Axis 2 current position
20	Axis 3 axis status
21	Axis 3 axis sensor input status
22	Axis 3 axis-related error code
23	Axis 3 encoder status
24	Axis 3 current position
30	Axis 4 axis status
31	Axis 4 axis sensor input status
32	Axis 4 axis-related error code
33	Axis 4 encoder status
34	Axis 4 current position

### Memory: 213 (Program Status)

Address	Name
0	Status
1	Running program step number
2	Program-sensitive error code
3	Error occurrence step

**Memory: 215 (System Status)**

Address	Name
0	System mode
1	Most significant level system error number
2	Most recent system error number
3	System status byte 1
4	System status byte 2
5	System status byte 3
6	System status byte 4

**Memory: 253 (Program)**

Address	Name	Value
Program number	Program	0: Program end 1: Program execution 2: Program pause 3: Program one step execution 4: Program execution restart

**Memory: 2A1 (Scalar Axis Status)**

Address	Name
0	Workpiece coordinate system number
1	Tool coordinate system number
2	Axis common status
3	Axis 1 axis status
4	Axis 1 axis sensor input status
5	Axis 1 axis-related error code
6	Axis 1 encoder status
7	Axis 1 current position
10	Workpiece coordinate system number
11	Tool coordinate system number
12	Axis common status
13	Axis 2 axis status
14	Axis 2 axis sensor input status
15	Axis 2 axis-related error code
16	Axis 2 encoder status
17	Axis 2 current position
20	Workpiece coordinate system number
21	Tool coordinate system number
22	Axis common status
23	Axis 3 axis status
24	Axis 3 axis sensor input status
25	Axis 3 axis-related error code
26	Axis 3 encoder status
27	Axis 3 current position
30	Workpiece coordinate system number
31	Tool coordinate system number
32	Axis common status
33	Axis 4 axis status
34	Axis 4 axis sensor input status
35	Axis 4 axis-related error code
36	Axis 4 encoder status
37	Axis 4 current position

## PLC\_CTL

Real numbers used on the S8 series are IEEE 32-bit single precision ones.

Contents	F0	F1 (= \$u n)		F2									
Version inquiry	1 - 2 (PLC1 - 2)	n	Station number	4									
		n + 1	Command: 201 (HEX)										
		n + 2	Unit type 0: Main CPU application area 1: Main CPU core area 2: Driver CPU										
		n + 3	Device number										
		n + 4	Model code										
		n + 5	Unit code										
		n + 6	Version number										
		n + 7	Year (4-digit)										
		n + 8	Month										
		n + 9	Day										
		n + 10	Hour										
		n + 11	Minute										
		n + 12	Second										
Effective point data count inquiry	1 - 2 (PLC1 - 2)	n	Station number	2									
		n + 1	Command: 208 (HEX)										
		n + 2	Effective point data count										
Effective point data inquiry	1 - 2 (PLC1 - 2)	n	Station number	3									
		n + 1	Command: 209 (HEX)										
		n + 2	Inquiry point number										
		n + 3	Effective point data count										
		n + 4	Point number										
		n + 5	Axis pattern: m (number of ON bits)  Bit <table border="1" style="display: inline-table; vertical-align: middle;"><tr><td>-</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr></table> └─ Axis 1 : └─ Axis 6		-	7	6	5	4	3	2	1	0
		-	7		6	5	4	3	2	1	0		
		n + 6	Acceleration										
		n + 7	Deceleration										
		n + 8	Speed										
		n + 9 to n + 10	Axis pattern 1		Position data								
n + 11 -	:	:											
n + 11 -	Axis pattern m	Position data											
Real variable inquiry Disabled for X-SEL version 0.41 or earlier	1 - 2 (PLC1 - 2)	n	Station number	5									
		n + 1	Command: 20F (HEX)										
		n + 2	Program number										
		n + 3	Inquiry start variable number										
		n + 4	Inquiry data count: m (1 to 10)										
		n + 5	Response start variable number										
		n + 6	Response variable data count: m										
		n + 7 to n + 8	Data count 1		Data for variable								
		n + 9 -	:		:								
n + 9 -	Data count m	Data for variable											
Axis status inquiry For orthogonal	1 - 2 (PLC1 - 2)	n	Station number	3									
		n + 1	Command: 212 (HEX)										
		n + 2	Inquiry axis pattern: m (number of ON bits)  Bit <table border="1" style="display: inline-table; vertical-align: middle;"><tr><td>-</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr></table> └─ Axis 1 : └─ Axis 6		-	7	6	5	4	3	2	1	0
		-	7		6	5	4	3	2	1	0		
		n + 3	Status m = 1		Axis status								
		n + 4			Axis sensor input status								
		n + 5			Axis-related error code								
		n + 6			Encoder status								
		n + 7 to n + 8			Current position								
		n + 9 -	Status (m = 2)		:								
n + 9 -	:	:											

Contents	F0	F1 (= \$u n)		F2									
Program status inquiry	1 - 2 (PLC1 - 2)	n	Station number	3									
		n + 1	Command: 213 (HEX)										
		n + 2	Program number										
		n + 3	Status										
		n + 4	Running program step number										
		n + 5	Program-sensitive error code										
		n + 6	Error occurrence step number										
System status inquiry	1 - 2 (PLC1 - 2)	n	Station number	2									
		n + 1	Command: 215 (HEX)										
		n + 2	System mode										
		n + 3	Most significant level system error number										
		n + 4	Most recent system error number										
		n + 5	System status byte 1										
		n + 6	System status byte 2										
		n + 7	System status byte 3										
Error detailed information inquiry	1 - 2 (PLC1 - 2)	n	Station number	5									
		n + 1	Command: 216 (HEX)										
		n + 2	Type 1 0: System error 1: Axis error 2: Program error 3: Error in error list record										
		n + 3	Type 2 In the event of a system error: 0: Most significant level error 1: Most recent error In the event of an axis error: Axis number In the event of a program error: Program number In the event of an error in error list record: Record number										
		n + 4	Error number										
		n + 5 to n + 6	Detailed information 1										
		n + 7 to n + 8	Detailed information 2										
		n + 9 to n + 10	Detailed information 3										
		n + 11 to n + 12	Detailed information 4										
		n + 13 to n + 14	Detailed information 5										
		n + 15 to n + 16	Detailed information 6										
		n + 17 to n + 18	Detailed information 7										
		n + 19 to n + 20	Detailed information 8										
		n + 21 to n + 27	System reserved										
		n + 28	Number of message bytes										
		n + 29 -	Message character string (equivalent to message bytes)										
Servo ON/OFF	1 - 2 (PLC1 - 2)	n	Station number	4									
		n + 1	Command: 232 (HEX)										
		n + 2	Axis pattern Bit <table border="1" style="display: inline-table; vertical-align: middle;"><tr><td>-</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr></table> └─ Axis 1 ┆ ┆ ┆ └─ Axis 6		-	7	6	5	4	3	2	1	0
		-	7		6	5	4	3	2	1	0		
n + 3	Servo 0: OFF 1: ON												
Origin return For orthogonal	1 - 2 (PLC1 - 2)	n	Station number	5									
		n + 1	Command: 233 (HEX)										
		n + 2	Axis pattern Bit <table border="1" style="display: inline-table; vertical-align: middle;"><tr><td>-</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr></table> └─ Axis 1 ┆ ┆ ┆ └─ Axis 6		-	7	6	5	4	3	2	1	0
		-	7		6	5	4	3	2	1	0		
n + 3	End search speed for origin return (mm/sec)												
		n + 4	Creep speed for origin return (mm/sec)										

Contents	F0	F1 (= \$u n)	F2									
Traverse by absolute command For orthogonal	1 - 2 (PLC1 - 2)	n	Station number	6 + 2m								
		n + 1	Command: 234 (HEX)									
		n + 2	Axis pattern: m (number of ON bits)									
			Bit <table border="1" style="display: inline-table; vertical-align: middle;"> <tr><td>-</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr> </table> Axis 1 : Axis 6		-	7	6	5	4	3	2	1
		-	7		6	5	4	3	2	1	0	
		n + 3	Acceleration									
		n + 4	Deceleration									
		n + 5	Speed									
		n + 6 to n + 7	Axis pattern (m = 1)   Absolute coordinate data									
n + 8 -	Axis pattern (m = 2)   Absolute coordinate data											
	:											
Traverse by relative command For orthogonal	1 - 2 (PLC1 - 2)	n	Station number	6 + 2m								
		n + 1	Command: 235 (HEX)									
		n + 2	Axis pattern: m (number of ON bits)									
			Bit <table border="1" style="display: inline-table; vertical-align: middle;"> <tr><td>-</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr> </table> Axis 1 : Axis 6		-	7	6	5	4	3	2	1
		-	7		6	5	4	3	2	1	0	
		n + 3	Acceleration									
		n + 4	Deceleration									
		n + 5	Speed									
		n + 6 to n + 7	Axis pattern (m = 1)   Relative coordinate data									
n + 8 -	Axis pattern (m = 2)   Relative coordinate data											
	:											
Jog/inching traverse	1 - 2 (PLC1 - 2)	n	Station number	9								
		n + 1	Command: 236 (HEX)									
		n + 2	Axis pattern m									
			Bit <table border="1" style="display: inline-table; vertical-align: middle;"> <tr><td>-</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr> </table> Axis 1 : Axis 6		-	7	6	5	4	3	2	1
		-	7		6	5	4	3	2	1	0	
		n + 3	Acceleration									
		n + 4	Deceleration									
		n + 5	Speed									
n + 6 to n + 7	Inching distance (absolute command) 0: Distance not designated = jog											
n + 8	Direction 0: Negative direction 1: Positive direction											
Traverse by point number command For orthogonal	1 - 2 (PLC1 - 2)	n	Station number	7								
		n + 1	Command: 237 (HEX)									
		n + 2	Axis pattern									
			Bit <table border="1" style="display: inline-table; vertical-align: middle;"> <tr><td>-</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr> </table> Axis 1 : Axis 6		-	7	6	5	4	3	2	1
		-	7		6	5	4	3	2	1	0	
		n + 3	Acceleration									
		n + 4	Deceleration									
n + 5	Speed											
n + 6	Point number											
Operation stop and cancel	1 - 2 (PLC1 - 2)	n	Station number	4								
		n + 1	Command: 238 (HEX)									
		n + 2	Stop axis pattern									
			Bit <table border="1" style="display: inline-table; vertical-align: middle;"> <tr><td>-</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr> </table> Axis 1 : Axis 6		-	7	6	5	4	3	2	1
-	7	6	5	4	3	2	1	0				
n + 3	Additional command											

Contents	F0	F1 (= \$u n)		F2		
Successive writing within designated point data range	1 - 2 (PLC1 - 2)	n	Station number	$4 + (4 + 2m)t = \alpha$		
		n + 1	Command: 244 (HEX)			
		n + 2	Change start point data number			
		n + 3	Change point data count: t (1 to 2)			
		n + 4	Point data		Axis pattern: m (number of ON bits)	
					Bit	
		n + 5	t = 1		Acceleration	
		n + 6	Deceleration			
		n + 7	Speed			
		n + 8 to n + 9	Point data		Axis pattern (m = 1)	Position data
					Axis pattern (m = 2)	Position data
		n + 10 - α	Point data		:	:
					Point data (t = 2)	:
α + 1	Change start point data number					
α + 2	Change complete point data count					
Change point data successive writing	1 - 2 (PLC1 - 2)	n	Station number	$4 + (4 + 2m)t = \alpha$		
		n + 1	Command: 245 (HEX)			
		n + 2	Change point data count: t (1 to 2)			
		n + 3	Change point data number			
		n + 4	Point data		Axis pattern: m (number of ON bits)	
					Bit	
		n + 5	t = 1		Acceleration	
		n + 6	Deceleration			
		n + 7	Speed			
		n + 8 to n + 9	Point data		Axis pattern (m = 1)	Position data
					Axis pattern (m = 2)	Position data
		n + 10 to α	Point data		:	:
					Point data (t = 2)	:
α + 1	Change complete point data count					
Point data clear	1 - 2 (PLC1 - 2)	n	Station number	4		
		n + 1	Command: 246 (HEX)			
		n + 2	Clear start point data number			
		n + 3	Clear point data count			
Real variable change	1 - 2 (PLC1 - 2)	n	Station number	5 + 2m		
		n + 1	Command: 24D (HEX)			
		n + 2	Program number			
		n + 3	Change start variable number			
		n + 4	Change variable data count: m (1 to 10)			
		n + 5 to n + 6	Variable data (m = 1)		Real variable data	
					Real variable data	
		n + 7 -	Variable data (m = 2)		Real variable data	
:						
n + {5 + (2*m)}	Change complete data count					
Alarm reset	1 - 2 (PLC1 - 2)	n	Station number	2		
		n + 1	Command: 252 (HEX)			
Program execution	1 - 2 (PLC1 - 2)	n	Station number	3		
		n + 1	Command: 253 (HEX)			
		n + 2	Program number			
Program end	1 - 2 (PLC1 - 2)	n	Station number	3		
		n + 1	Command: 254 (HEX)			
		n + 2	Program number			

Contents	F0	F1 (= \$u n)		F2									
Program pause	1 - 2 (PLC1 - 2)	n	Station number	3									
		n + 1	Command: 255 (HEX)										
		n + 2	Program number										
Program one step execution	1 - 2 (PLC1 - 2)	n	Station number	3									
		n + 1	Command: 256 (HEX)										
		n + 2	Program number										
Program execution restart	1 - 2 (PLC1 - 2)	n	Station number	3									
		n + 1	Command: 257 (HEX)										
		n + 2	Program number										
Software reset	1 - 2 (PLC1 - 2)	n	Station number	2									
		n + 1	Command: 25B (HEX)										
Request for drive source recovery	1 - 2 (PLC1 - 2)	n	Station number	2									
		n + 1	Command: 25C (HEX)										
Request for operation pause cancel	1 - 2 (PLC1 - 2)	n	Station number	2									
		n + 1	Command: 25E (HEX)										
Speed change For orthogonal	1 - 2 (PLC1 - 2)	n	Station number	4									
		n + 1	Command: 262 (HEX)										
		n + 2	Axis pattern  Bit <table border="1" style="display: inline-table; vertical-align: middle;"><tr><td>-</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr></table> └─ Axis 1 └─ Axis 6		-	7	6	5	4	3	2	1	0
-	7	6	5	4	3	2	1	0					
n + 3	Speed												
Successive inquiry within designated range for coordinate system definition data For scalar	1 - 2 (PLC1 - 2)	n	Station number	5									
		n + 1	Command: 2A0 (HEX)										
		n + 2	Type 0: Workpiece coordinate system definition data 1: Tool coordinate system definition data										
		n + 3	Inquiry target top number for coordinate system definition data										
		n + 4	Inquiry record count t (1 to 32)										
		n + 5 to n + 6	Coordinate system definition data t = 1		Coordinate offset X axis								
		n + 7 to n + 8			Coordinate offset Y axis								
		n + 9 to n + 10			Coordinate offset Z axis								
		n + 11 to n + 12			Coordinate offset R axis								
		n + 13 -	Coordinate system definition data t = 2										
:	:												
Scalar axis status inquiry For scalar	1 - 2 (PLC1 - 2)	n	Station number	4									
		n + 1	Command: 2A1 (HEX)										
		n + 2	Inquiry axis pattern: m (number of ON bits)  Bit <table border="1" style="display: inline-table; vertical-align: middle;"><tr><td>-</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr></table> └─ Axis 1 └─ Axis 6		-	7	6	5	4	3	2	1	0
		-	7		6	5	4	3	2	1	0		
		n + 3	Type 0: Base coordinate system 1: Selected workpiece coordinate system 2: System reserved 3: Coordinate system for each axis										
		n + 4	Workpiece coordinate system number										
		n + 5	Tool coordinate system number										
		n + 6	Axis common status										
		n + 7	Axis pattern m = 1		Axis status								
		n + 8			Axis sensor input status								
		n + 9			Axis-related error code								
		n + 10			Encoder status								
		n + 11 to n + 12			Current position								
n + 13 -	Axis pattern (m = 2)												
:	:												



Contents	F0	F1 (= \$u n)		F2											
Successive inquiry within designated range for interference check zone definition data  For scalar	1 - 2 (PLC1 - 2)	n	Station number		4										
		n + 1	Command: 2A2 (HEX)												
		n + 2	Inquiry top number for interference check zone definition data												
		n + 3	Inquiry record count t (1 to 16)												
		n + 4	Interference check zone definition data  t = 1	Effective axis pattern: m (number of ON bits)  Bit <table border="1" style="display: inline-table; vertical-align: middle;"><tr><td>-</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr></table> └─ Axis 1 : : └─ Axis 6		-	7	6	5	4	3	2	1	0	
		-		7		6	5	4	3	2	1	0			
		n + 5 to n + 6		Axis pattern (m = 1)		Interference check zone definition coordinate 1									
		n + 7 -		Axis pattern (m = 2)		Interference check zone definition coordinate 1									
		:		:		:									
		n + (5 + 2m)		Axis pattern (m = 1)		Interference check zone definition coordinate 2									
		:		Axis pattern (m = 2)		Interference check zone definition coordinate 2									
		:		:		:									
		n + (5 + 4m)		Physical output port number at break-in or global flag number											
		n + (6 + 4m)		Error type definition at break-in											
		n + (7 + 4m)		System reserved											
:	Interference check data t = 2														
:	:														
Traverse by absolute command  For scalar	1 - 2 (PLC1 - 2)	n		Station number		7 + 2m									
		n + 1	Command: 2D4 (HEX)												
		n + 2	Axis pattern: m (number of ON bits)  Bit <table border="1" style="display: inline-table; vertical-align: middle;"><tr><td>-</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr></table> └─ Axis 1 : : └─ Axis 6		-		7	6	5	4	3	2	1	0	
		-	7	6	5		4	3	2	1	0				
		n + 3	Acceleration												
		n + 4	Deceleration												
		n + 5	Speed												
		n + 6	Positioning type												
		n + 7 to n + 8	Axis pattern (m = 1)	Absolute coordinate data											
		n + 9 to n + 10	Axis pattern (m = 2)	Absolute coordinate data											
:	:														
Traverse by relative command  For scalar	1 - 2 (PLC1 - 2)	n	Station number		7 + 2m										
		n + 1	Command: 2D5 (HEX)												
		n + 2	Inquiry axis pattern: m (number of ON bits)  Bit <table border="1" style="display: inline-table; vertical-align: middle;"><tr><td>-</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr></table> └─ Axis 1 : : └─ Axis 6			-	7	6	5	4	3	2	1	0	
		-	7	6		5	4	3	2	1	0				
		n + 3	Acceleration												
		n + 4	Deceleration												
		n + 5	Speed												
		n + 6	Positioning type												
		n + 7 to n + 8	Axis pattern (m = 1)	Relative coordinate data											
		n + 9 to n + 10	Axis pattern (m = 2)	Relative coordinate data											
:	:														

Contents	F0	F1 (= \$u n)	F2										
Traverse by point number command For scalar	1 - 2 (PLC1 - 2)	n	Station number	8									
		n + 1	Command: 2D6 (HEX)										
		n + 2	Inquiry axis pattern: m (number of ON bits) Bit <table border="1" style="display: inline-table; vertical-align: middle;"> <tr> <td>-</td> <td>7</td> <td>6</td> <td>5</td> <td>4</td> <td>3</td> <td>2</td> <td>1</td> <td>0</td> </tr> </table> Axis 1 : Axis 6		-	7	6	5	4	3	2	1	0
		-	7		6	5	4	3	2	1	0		
		n + 3	Acceleration										
		n + 4	Deceleration										
		n + 5	Speed										
		n + 6	Positioning type										
		n + 7 to n + 8	Point number										

Return data: Data stored from controller to S8 series

## 8.1.2 PCON / ACON / SCON (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	9600 / 19200 / <u>38400</u> / 57600 / 115K bps	
Data Length	8 bits	
Stop Bit	1 bit	
Parity	None	
Target Port No.	0 to 31	


#### PCON / ACON / SCON

#### Exclusive software

Set parameters using the exclusive software. (Underlined setting: default)

Parameter No.	Parameter Name	Setting
Parameter 16	SIO baud rate	9600 / 19200 / <u>38400</u> / 115200 bps

#### Axis number setting switch (ADRS)

ADRS	Setting	Remarks
	0 to F (0 to 15)	

#### Mode select switch

Select [MANU].

### Available Memory

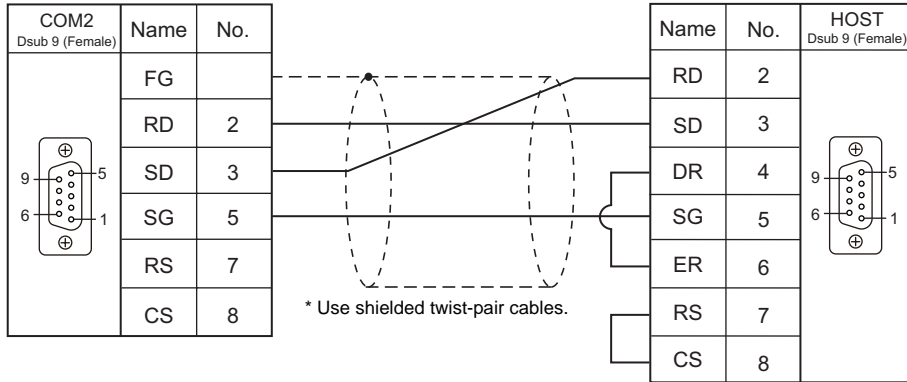
The available memory setting range varies depending on the models. Be sure to set within the range available for the device. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
Coil (coil)	00H	
Register (holding register)	02H	

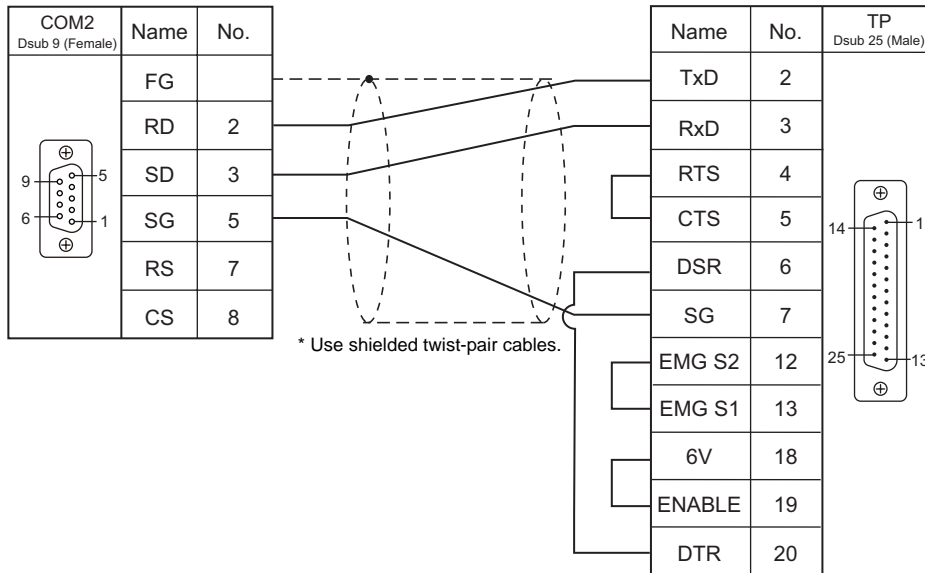
### 8.1.3 Wiring Diagrams

#### When Connected at COM2 (RS-232C):

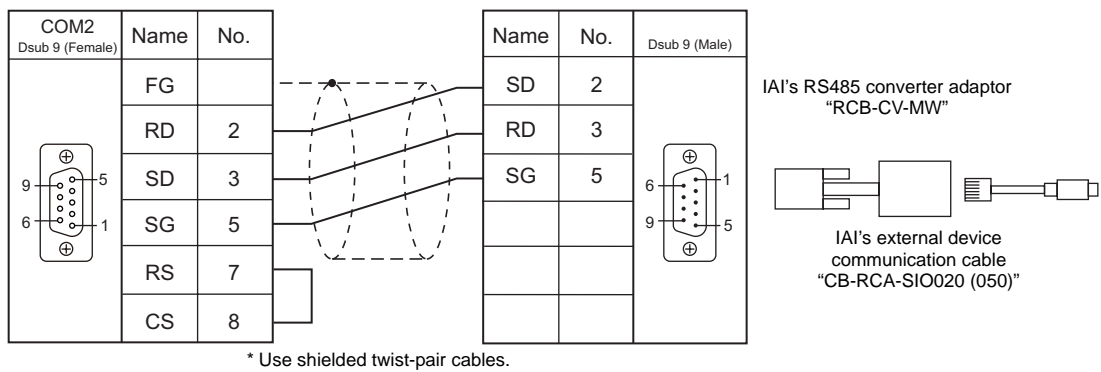
Wiring diagram 1 - COM2



Wiring diagram 2 - COM2



Wiring diagram 3 - COM2



# MEMO

Please use this page freely.

# 9. KEYENCE

---

## 9.1 PLC Connection



## 9.1 PLC Connection

The PLC models shown below can be connected.

### Serial Connection

#### KV Series

PLC Selection on the Editor	CPU	Unit/Port		Signal Level	Connection		Ladder Transfer <sup>*2</sup>
					COM1	COM2	
KV10/24CPU	KV-10 KV-24 KV-40	CPU modular port		RS-232C	-	Wiring diagram 1 - COM2 <sup>*1</sup>	×
		CPU modular port		RS-232C	-	Wiring diagram 2 - COM2	
KV-700	KV-700	KV-L20 KV-L20R	Port 1	RS-232C	-	Wiring diagram 3 - COM2	
			Port 2	RS-232C	-	Wiring diagram 1 - COM1	
			RS-422	Wiring diagram 1 - COM1	-		
KV-1000	KV-1000	CPU modular port		RS-232C	-	Wiring diagram 1 - COM2 <sup>*1</sup>	
		KV-L20R	Port 1	RS-232C	-	Wiring diagram 2 - COM2	
			Port 2	RS-232C	-	Wiring diagram 3 - COM2	
				RS-422	Wiring diagram 1 - COM1	-	
KV-3000/5000	KV-3000	CPU modular port		RS-232C	-	Wiring diagram 1 - COM2 <sup>*1</sup>	
		KV-L20V	Port 1	RS-232C	-	Wiring diagram 2 - COM2	
	Port 2		RS-232C	-	Wiring diagram 3 - COM2		
			RS-422	Wiring diagram 1 - COM1	-		

\*1 Can be connected using the Keyence's cable "OP-26487" + connector "OP-26486".

\*2 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".



## 9.1.1 KV10/24 CPU

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / Multi-link2	
Signal Level	RS-232C	
Baud Rate	9600 / 19200 / 38400 / <u>57600</u> bps	If a baud rate higher than 57600 bps is set, communication is performed at 9600 bps.
Data Length	8 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	0	

#### PLC

No particular setting is necessary on the PLC.

### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
DM (data memory)	00H	
CH (input/output/internal auxiliary relay)	01H	
TC (timer/current value)	02H	
CC (counter/current value)	03H	
TS (timer/set value)	04H	
CS (counter/set value)	05H	
T (timer/contact)	06H	
C (counter/contact)	07H	
TM (temporary data memory)	08H	

## 9.1.2 KV-700

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	<u>9600</u> / 19200 / 38400 / 57600 bps	
Data Length	8 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	<u>0</u> to 31	

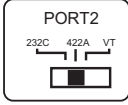
#### PLC

##### KV-700 (CPU Modular Port)

No particular setting is necessary on the PLC.

##### KV-L20

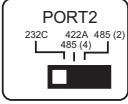
##### Unit editor setting

Port	Item	Setting	Remarks
Port 1	Operation Mode	KV BUILDER Mode	
	RS/CS Flow Control	No	
Port 2	Operation Mode	KV BUILDER Mode	
	Interface	RS-232C / RS-422A	Change the setting using the PORT 2 selector switch attached to the side. 
	Station No.	0 to 9	

\* These settings can be checked on the access window of the CPU. For more information, refer to the PLC manual issued by the manufacturer.

##### KV-L20R

##### Unit editor setting

Port	Item	Setting	Remarks
Basic Port	Station No.	0 to 9	Common to Port 1 and 2.
Port 1	Operation Mode	KV BUILDER/KV STUDIO Mode	
	RS/CS Flow Control	No	
Port 2	Operation Mode	KV BUILDER/KV STUDIO Mode	
	Interface	RS-232C/RS-422A/485 (4-wire system)	PORT 2 selector switch attached to the side 

\* These settings can be checked on the access window of the CPU. For more information, refer to the PLC manual issued by the manufacturer.

---

## Available Memory

---

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
DM (data memory)	00H	
R (input/output/internal auxiliary/special relay)	01H	
TC (timer/current value)	02H	
CC (counter/current value)	03H	
TS (timer/set value)	04H	
CS (counter/set value)	05H	
T (timer/contact)	06H	
C (counter/contact)	07H	
TM (temporary data memory)	08H	
CTH (high-speed counter/current value)	09H	
CTC (high-speed counter comparator/set value)	0AH	
CT (high-speed counter comparator/contact)	0BH	
CR (control relay)	0CH	
CM (control memory)	0DH	

## 9.1.3 KV-1000

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	<u>9600</u> / 19200 / 38400 / 57600/ 115k bps	
Data Length	8 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	<u>0</u> to 31	

#### PLC

#### KV-1000 (CPU Modular Port)

No particular setting is necessary on the PLC.

#### KV-L20R

#### Unit editor setting

Port	Item	Setting	Remarks
Basic Port	Station No.	0 to 9	Common to Port 1 and 2.
Port 1	Operation Mode	KV BUILDER/KV STUDIO Mode	
	RS/CS Flow Control	No	
Port 2	Operation Mode	KV BUILDER/KV STUDIO Mode	
	Interface	RS-232C/ RS-422A/485 (4-wire system)	PORT 2 selector switch attached to the side 

\* These settings can be checked on the access window of the CPU. For more information, refer to the PLC manual issued by the manufacturer.

## Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
DM (data memory)	00H	
R (input/output/internal auxiliary/special relay)	01H	
TC (timer/current value)	02H	
CC (counter/current value)	03H	
TS (timer/set value)	04H	
CS (counter/set value)	05H	
T (timer/contact)	06H	
C (counter/contact)	07H	
TM (temporary data memory)	08H	
CTH (high-speed counter/current value)	09H	
CTC (high-speed counter comparator/set value)	0AH	
CT (high-speed counter comparator/contact)	0BH	
CR (control relay)	0CH	
CM (control memory)	0DH	
MR (internal auxiliary relay)	0EH	
LR (latch relay)	0FH	
EM (extended data memory 1)	10H	
FM (extended data memory 2)	11H	
Z (index register)	12H	

## 9.1.4 KV-3000 / 5000

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	<u>9600</u> / 19200 / 38400 / 57600/ 115K bps	
Data Length	8 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	<u>Q</u> to 31	

#### PLC

##### KV-3000 (CPU Modular Port)

No particular setting is necessary on the PLC.

##### KV-L20V

##### Unit editor setting

Port	Item	Setting	Remarks
Basic Port	Station number	0 to 9	Common to Port 1 and 2.
Port 1	Operation mode	KV BUILDER/KV STUDIO mode	
	RS/CS flow control	No	
Port 2	Operation mode	KV BUILDER/KV STUDIO mode	
	Interface	RS-232C/ RS-422A/485 (4-wire system)	

\* These settings can be checked on the access window of the CPU. For more information, refer to the PLC manual issued by the manufacturer.

## Available Memory

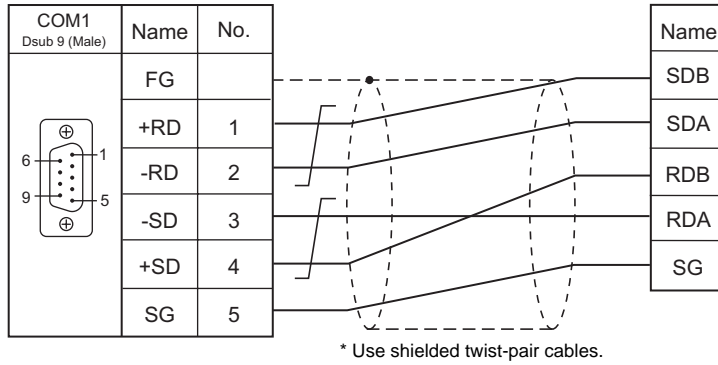
The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
DM (data memory)	00H	
R (input/output/internal auxiliary/special relay)	01H	
TC (timer/current value)	02H	Double-word
CC (counter/current value)	03H	Double-word
TS (timer/set value)	04H	Double-word
CS (counter/set value)	05H	Double-word
T (timer/contact)	06H	
C (counter/contact)	07H	
TM (temporary data memory)	08H	
CTH (high-speed counter/current value)	09H	Double-word
CTC (high-speed counter comparator/set value)	0AH	Double-word
CT (high-speed counter comparator/contact)	0BH	
CR (control relay)	0CH	
CM (control memory)	0DH	
MR (internal auxiliary relay)	0EH	
LR (latch relay)	0FH	
EM (extended data memory 1)	10H	
FM (extended data memory 2)	11H	
Z (index register)	12H	Double-word
B (link relay)	13H	
VB (work relay)	14H	
ZF (file register)	15H	
W (link register)	16H	
VM (work memory)	17H	

### 9.1.5 Wiring Diagrams

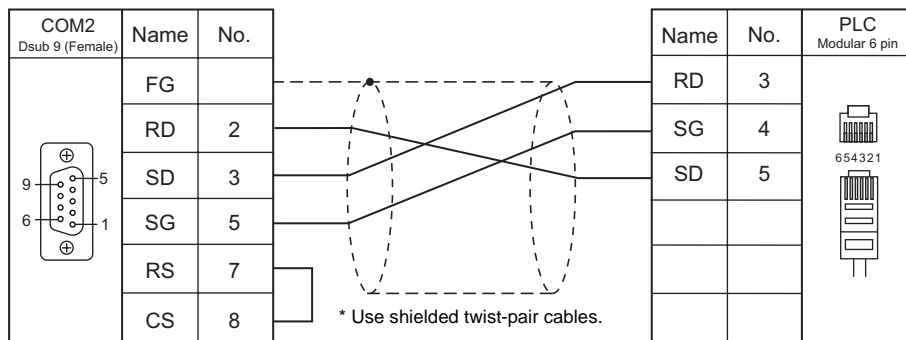
#### When Connected at COM1 (RS-422 / RS-485):

Wiring diagram 1 - COM1

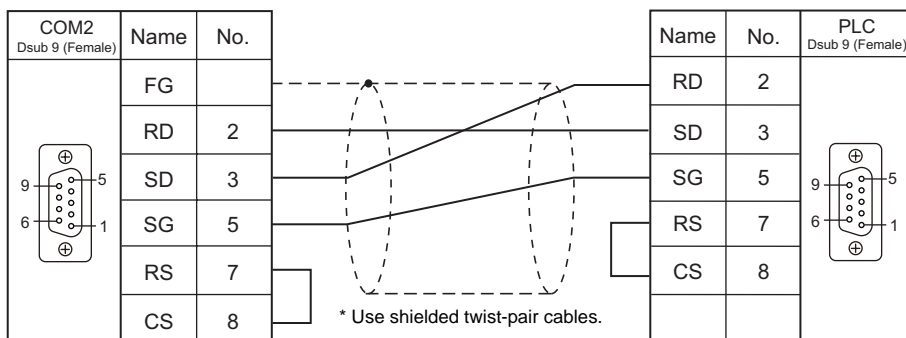


#### When Connected at COM2 (RS-232C):

Wiring diagram 1 - COM2

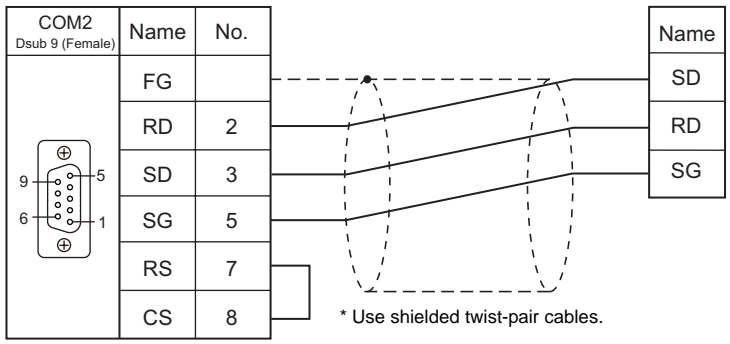


Wiring diagram 2 - COM2





**Wiring diagram 3 - COM2**



# 10. LS

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## 10.1 PLC Connection



## 10.1 PLC Connection

The PLC models shown below can be connected.

### Serial Connection

PLC Selection on the Editor	CPU		Unit/Port	Signal Level	Connection		Ladder Transfer *1
					COM1	COM2	
MASTER-KxxxS	K200S	K3P-07AS	RS-232C connector on the CPU unit	RS-232C	-	Wiring diagram 1 - COM2	×
		K3P-07CS					
	K300S	K4P-15AS					
	K1000S	K7P-30AS					
MASTER-KxxxS CNET	K200S	K3F-CU2A	RS-232C	-	Wiring diagram 2 - COM2		
		K3F-CU4A	RS-422	Wiring diagram 1 - COM1	-		
	K300S		K4F-CUEA	RS-485	Wiring diagram 2 - COM1	-	
		RS-232C		-	Wiring diagram 2 - COM2		
	K1000S	K7F-CUEA	RS-422	Wiring diagram 1 - COM1	-		
			RS-232C	-	Wiring diagram 2 - COM2		
XGT/XGK series	XGK-CPUH XGK-CPUA XGK-CPUS XGK-CPUE	XGL-C22A	RS-232C	-	Wiring diagram 3 - COM2		
			RS-232C	-	Wiring diagram 3 - COM2		
		XGL-CH2A	RS-422	Wiring diagram 3 - COM1	-		
			RS-485	Wiring diagram 4 - COM1	-		
		XGL-C42A	RS-422	Wiring diagram 3 - COM1	-		
			RS-485	Wiring diagram 4 - COM1	-		
XGT/XGK series CPU	XGK-CPUH XGK-CPUA XGK-CPUS XGK-CPUE	RS-232C connector on the CPU unit	RS-232C	-	Wiring diagram 3 - COM2		

\*1 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".

## 10.1.1 MASTER-KxxxS

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / Multi-link2	
Signal Level	RS-232C	
Baud Rate	9600 / 19200 / <u>38400</u> / 57600 / 76800 / 115200 bps	
Data Length	8 bits	
Stop Bit	1 bit	
Parity	None	

#### PLC

No particular setting is necessary on the PLC.

### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
P (input/output relay)	00H	*1
M (auxiliary relay)	01H	
L (link relay)	02H	
K (keep relay)	03H	
F (special relay)	04H	Read only
T (timer/current value)	05H	
C (counter/current value)	06H	
D (data register)	07H	
TC (timer/contact)	09H	
CC (counter/contact)	10H	

\*1 Input relay is read only.

## 10.1.2 MASTER-KxxxS CNET

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / 1 : n / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	9600 / 19200 / <u>38400</u> / 57600 / 76800 / 115200 bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bit	
Parity	<u>None</u> / Odd / Even	
Target Port No.	<u>0</u> to 31	

#### PLC

Make the setting of the signal level using the rotary switch on the communication unit. And make the PLC setting like the station number, the baud rate etc. using the configuration tool "KGL\_WE". For more information, refer to the PLC manual issued by the manufacturer.

### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
P (input/output relay)	00H	PW as word device *1
M (auxiliary relay)	01H	MW as word device
L (link relay)	02H	LW as word device
K (keep relay)	03H	KW as word device
F (special relay)	04H	FW as word device, read only
T (timer/current value)	05H	
C (counter/current value)	06H	
D (data register)	07H	
TC (timer/contact)	09H	
CC (counter/contact)	10H	

\*1 Input relay is read only.

## 10.1.3 XGT/XGK series

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / 1:n / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 / 115200 bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bit	
Parity	<u>None</u> / Odd / Even	
Target Port No.	<u>0</u> to 31	

#### PLC

Make the PLC setting using the configuration tool "XG-PD". For more information, refer to the PLC manual issued by the manufacturer.

### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
P (input/output relay)	00H	PW as word device *1
M (auxiliary relay)	01H	MW as word device
L (link relay)	02H	LW as word device
K (keep relay)	03H	KW as word device
F (special relay)	04H	FW as word device, read only
T (timer/current value)	05H	
C (counter/current value)	06H	
D (data register)	07H	
TC (timer/contact)	09H	
CC (counter/contact)	10H	
N (communication data register)	11H	
R (file register)	12H	RW as word device
ZR (file register)	13H	
U (analog data register)	14H	UW as word device

\*1 Input relay is read only.

## 10.1.4 XGT/XGK series CPU

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / Multi-link2	
Signal Level	RS-232C	
Baud Rate	115200 bps	
Data Length	8 bits	
Stop Bit	1 bit	
Parity	None	

#### PLC

All PLC parameters are fixed to the following settings: Baud rate: 115200 bps, data length: 8 bits, stop bit: 1 bit, parity: none.

### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
P (input/output relay)	00H	PW as word device *1
M (auxiliary relay)	01H	MW as word device
L (link relay)	02H	LW as word device
K (keep relay)	03H	KW as word device
F (special relay)	04H	FW as word device, read only
T (timer/current value)	05H	
C (counter/current value)	06H	
D (data register)	07H	
TC (timer/contact)	09H	
CC (counter/contact)	10H	
N (communication data register)	11H	
R (file register)	12H	RW as word device
ZR (file register)	13H	
U (analog data register)	14H	UW as word device

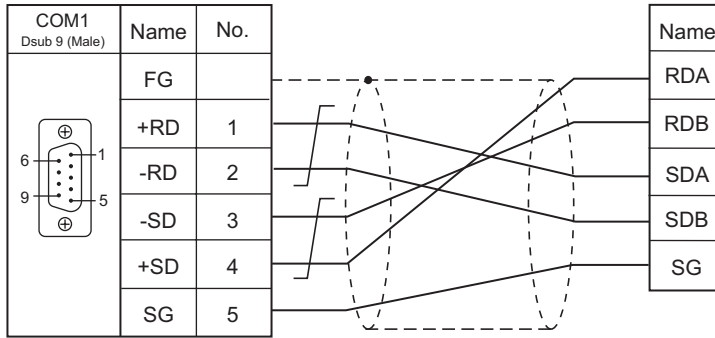
\*1 Input relay is read only.



## 10.1.5 Wiring Diagrams

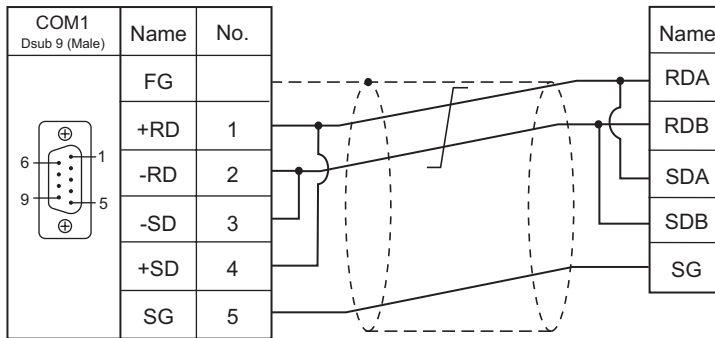
### When Connected at COM1 (RS-422 / RS-485):

**Wiring diagram 1 - COM1**



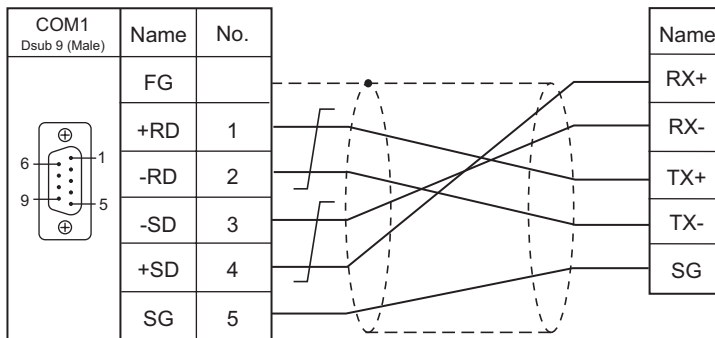
\* Use shielded twist-pair cables.

**Wiring diagram 2 - COM1**



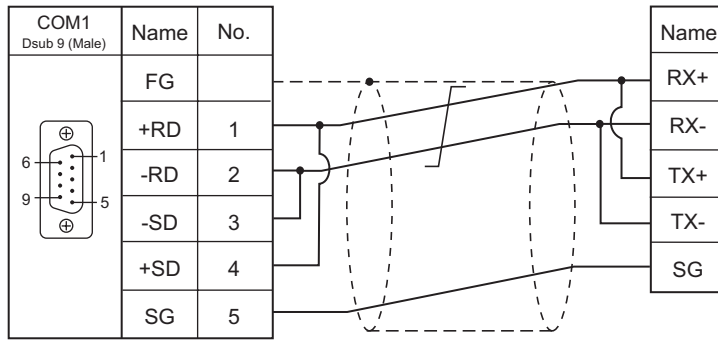
\* Use shielded twist-pair cables.

**Wiring diagram 3 - COM1**



\* Use shielded twist-pair cables.

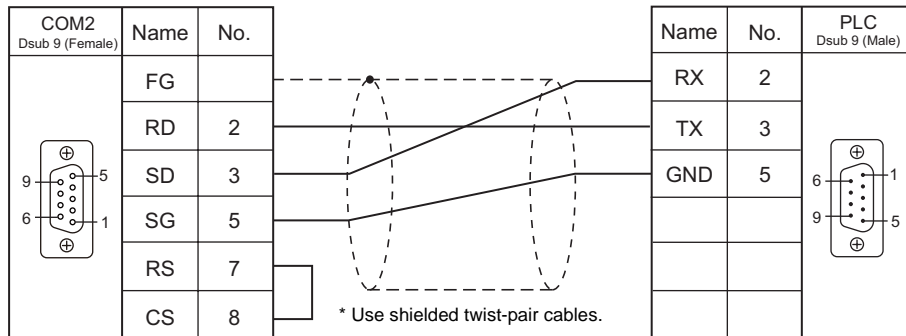
**Wiring diagram 4 - COM1**



\* Use shielded twist-pair cables.

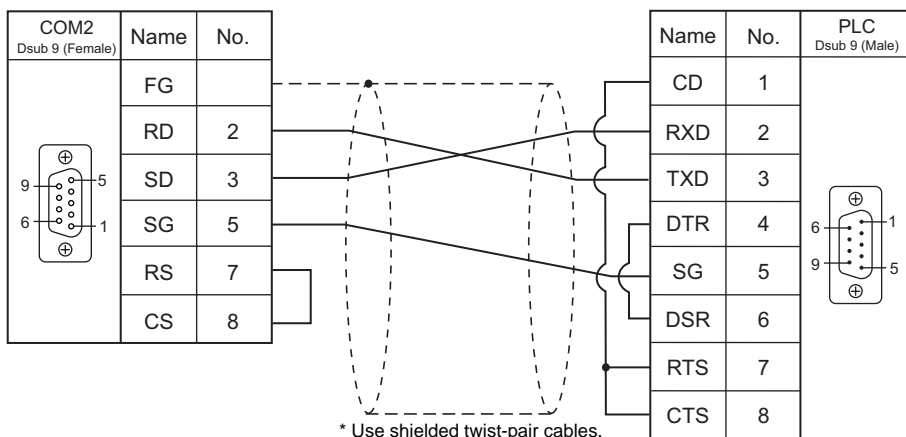
**When Connected at COM2 (RS-232C):**

**Wiring diagram 1 - COM2**



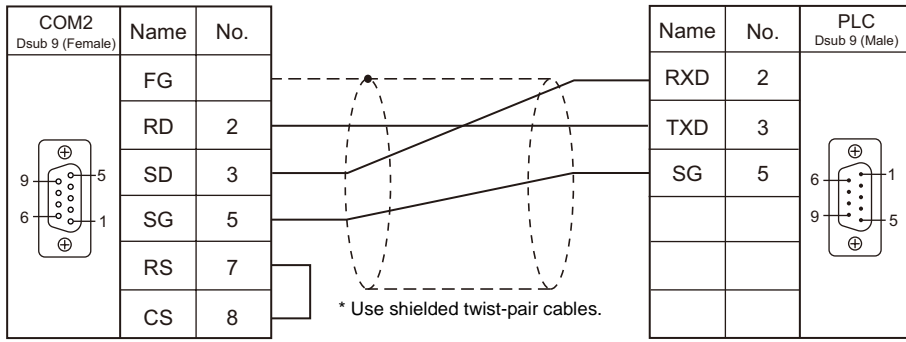
\* Use shielded twist-pair cables.

**Wiring diagram 2 - COM2**



\* Use shielded twist-pair cables.

**Wiring diagram 3 - COM2**



# 11. MITSUBISHI ELECTRIC

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11.1 PLC Connection

11.2 Temperature Controller/Servo/Inverter Connection



# 11.1 PLC Connection

The PLC models shown below can be connected.

## Serial Connection

### A/QnA/QnH Series Standard Type Link Unit

PLC Selection on the Editor	CPU	Unit/Port	Signal Level	Connection		Ladder Transfer <sup>*1</sup>	
				COM1	COM2		
A series link	A2A, A3A	AJ71C24-S6 AJ71C24-S8 AJ71UC24	RS-232C	-	Wiring diagram 2 - COM2	×	
	A2U, A3U, A4U	AJ71UC24					
	A1, A2, A3 A1N, A2N, A3N A3H, A3M, A73	AJ71C24 AJ71C24-S3 AJ71C24-S6 AJ71C24-S8 AJ71UC24	RS-422	Hakko Electronics' cable "D9-MI4-0T"	-		
	A0J2, A0J2H	A0J2C214-S1		Wiring diagram 1 - COM1			
	A2US	A1SJ71UC24-R2	RS-232C	-	Hakko Electronics' cable "D9-MI2-09" + Gender changer <sup>*2</sup> Wiring diagram 1 - COM2		
				RS-422	Hakko Electronics' cable "D9-MI4-0T" Wiring diagram 1 - COM1		-
		A1SJ71UC24-PRF	RS-232C	-	Hakko Electronics' cable "D9-MI2-09" + Gender changer <sup>*2</sup> Wiring diagram 1 - COM2		
	A1S, A1SJ, A2S	A1SJ71C24-R2		RS-422	Hakko Electronics' cable "D9-MI4-0T" Wiring diagram 1 - COM1		-
	A1S, A1SJ, A2S	A1SJ71C24-R4	RS-232C	-	Hakko Electronics' cable "D9-MI2-09" + Gender changer <sup>*2</sup> Wiring diagram 1 - COM2		
				RS-422	Hakko Electronics' cable "D9-MI4-0T" Wiring diagram 1 - COM1		-
		A1SJ71C24-PRF	RS-232C	-	Hakko Electronics' cable "D9-MI2-09" + Gender changer <sup>*2</sup> Wiring diagram 1 - COM2		
	A2CCPUC24	CPU with built-in link port		A1SJ71UC24-R2	RS-422		Hakko Electronics' cable "D9-MI4-0T" Wiring diagram 1 - COM1
	QnH (A mode)	A1SJ71UC24-R2	RS-232C	-	Hakko Electronics' cable "D9-MI2-09" + Gender changer <sup>*2</sup> Wiring diagram 1 - COM2		
				RS-422	Hakko Electronics' cable "D9-MI4-0T" Wiring diagram 1 - COM1		-
QnA series link	Q2A, Q3A, Q4A	AJ71QC24 AJ71QC24N	RS-232C	-	Wiring diagram 2 - COM2		
		AJ71QC24-R4 (CH1)	RS-422	Hakko Electronics' cable "D9-MI4-0T" Wiring diagram 1 - COM1	-		
				Wiring diagram 2 - COM1	-		
		AJ71QC24-R4 (CH2)	RS-422	Hakko Electronics' cable "D9-MI4-0T" Wiring diagram 1 - COM1	-		
	Q2ASx	A1SJ71QC24 A1SJ71QC24N A1SJ71QC24-R2	RS-232C	-	Hakko Electronics' cable "D9-MI2-09" + Gender changer <sup>*2</sup> Wiring diagram 1 - COM2		
				RS-422	Hakko Electronics' cable "D9-MI4-0T" Wiring diagram 1 - COM1	-	
		Q02, Q02H Q06H Q12H Q25H	QJ71C24 QJ71C24N QJ71C24-R2 QJ71C24N-R2 QJ71C24N-R4	RS-232C	-	Hakko Electronics' cable "D9-MI2-09" + Gender changer <sup>*2</sup> Wiring diagram 1 - COM2	
					RS-422	Hakko Electronics' cable "D9-MI4-0T" Wiring diagram 1 - COM1	-

PLC Selection on the Editor	CPU	Unit/Port	Signal Level	Connection		Ladder Transfer <sup>*1</sup>
				COM1	COM2	
QnH (Q) series link (multi CPU)	Q00U Q02U Q03UD(E) Q04UD(E)H Q06UD(E)H Q13UD(E)H Q26UD(E)H	QJ71C24N QJ71C24N-R2 QJ71C24N-R4	RS-232C	-	Hakko Electronics' cable "D9-MI2-09" + Gender changer <sup>*2</sup> Wiring diagram 1 - COM2	×
			RS-422	Hakko Electronics' cable "D9-MI4-0T" Wiring diagram 1 - COM1	-	
QnH (Q) series link	Q02, Q02H Q06H Q12H Q25H	QJ71C24 QJ71C24N QJ71C24-R2 QJ71C24N-R2 QJ71C24N-R4	RS-232C	-	Hakko Electronics' cable "D9-MI2-09" + Gender changer <sup>*2</sup> Wiring diagram 1 - COM2	
	RS-422		Hakko Electronics' cable "D9-MI4-0T" Wiring diagram 1 - COM1	-		
	Q00, Q01, Q00J	QJ71C24N QJ71C24N-R2 QJ71C24N-R4	RS-232C	-	Hakko Electronics' cable "D9-MI2-09" + Gender changer <sup>*2</sup> Wiring diagram 1 - COM2	
Q00U Q02U Q03UD(E) Q04UD(E)H Q06UD(E)H Q13UD(E)H Q26UD(E)H	RS-422		Hakko Electronics' cable "D9-MI4-0T" Wiring diagram 1 - COM1	-		

\*1 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".

\*2 Use a D-sub gender changer (9-pin, male-to-female) commercially available.

Manufacturer	Model
Black Box	FA445-R2
Misumi	DGC-9SS

### QnH/QnU Series CPU

PLC Selection on the Editor	CPU	Port	Signal Level	Connection		Ladder Transfer <sup>*1</sup>
				COM1	COM2	
QnH (Q) series CPU	Q02, Q02H Q06H Q12H Q25H	Tool port	RS-232C	-	Hakko Electronics' cable "D9-QCPU2" + Gender changer <sup>*3</sup>	○
QnH (Q) series CPU (multi CPU)		Tool port <sup>*2</sup>				
Q00J/00/01 CPU	Q00J, Q00, Q01	Tool port				
QnU series CPU	Q00U Q02U Q03UD Q04UDH Q06UDH	Tool port				

\*1 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".

\*2 Available for the CPU function version B or later.

\*3 Use a D-sub gender changer (9-pin, male-to-female) commercially available.

Manufacturer	Model
Black Box	FA445-R2
Misumi	DGC-9SS

## FX Series

PLC Selection on the Editor	CPU	Port	Signal Level	Connection		Ladder Transfer *1
				COM1	COM2	
FX2N/1N series CPU	FX2N FX1N FX2NC FX1NC	Tool port	RS-422	Hakko Electronics' cable "D9-MI4-FX"	-	
				Hakko Electronics' cable "D9-MB-CPUQ" + Mitsubishi's cable "FX-20P-CADP"		
FX series link (A protocol)	FX2N	FX2N-232-BD	RS-232C	-	Wiring diagram 3 - COM2	×
		FX2N-485-BD	RS-485	Hakko Electronics' cable "D9-MI4-0T"*2	-	
				Wiring diagram 1 - COM1		
	FX2N-422-BD	RS-422	Hakko Electronics' cable "D9-MI4-FX"	-		
	FX1N FX1S	FX1N-232-BD	RS-232C	-	Wiring diagram 3 - COM2	
		FX1N-485-BD	RS-485	Hakko Electronics' cable "D9-MI4-0T"*2	-	
				Wiring diagram 1 - COM1		
	FX1N-422-BD	RS-422	Hakko Electronics' cable "D9-MI4-FX"	-		
	FX0N FX1NC FX2NC	FX0N-232ADP	RS-232C	-	Wiring diagram 4 - COM2	
				Wiring diagram 3 - COM2		
		FX0N-485ADP	RS-485	Hakko Electronics' cable "D9-MI4-0T"*2	-	
				Wiring diagram 1 - COM1		
FX2NC-485ADP	RS-485	Hakko Electronics' cable "D9-MI4-FX"	-			
		Hakko Electronics' cable "D9-MB-CPUQ" + Mitsubishi's cable "FX-20P-CADP"				
FX-3UC series CPU	FX-3U FX-3UC	Tool port	RS-422	Hakko Electronics' cable "D9-MI4-FX"	-	
				Hakko Electronics' cable "D9-MB-CPUQ" + Mitsubishi's cable "FX-20P-CADP"		

\*1 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".

\*2 "D9-MI4-0T" is equipped with the Y-shaped terminal at the PLC side. Modification is necessary before use.



## 11.1.1 A Series Link

### Communication Setting

#### Editor

#### Communication setting


(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> : 1 / 1 : n / Multi-link / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Transmission Mode	<u>Transmission Mode 1</u> / Transmission Mode 4	Transmission Mode 1: Without CR/LF Transmission Mode 4: With CR/LF
Data Length	<u>Z</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>0</u> to 31	

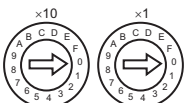
#### PLC

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor.

#### Mode setting

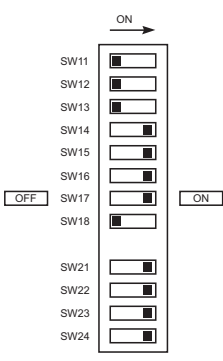
Mode	Setting	Contents	
	1	RS-232C	
	4		Dedicated protocol MODE 4
	5	RS-422	Dedicated protocol MODE 1
	8		Dedicated protocol MODE 4

#### Station number setting

Station No.	Setting	Contents
	0 to 31	Station number ×10: the tens place ×1: the ones place

#### Transmission setting

#### AJ71UC24

Switch	Contents	OFF	ON	Example: RS-232C, 19200 bps 
SW11	Main channel	RS-232C	RS-422	
SW12	Data bit	7	8	
SW13	Baud rate	9600	19200	
		ON	OFF	
		OFF	ON	
		ON	ON	
SW16	Parity bit	Not provided	Provided	
SW17	Parity	Odd	Even	
SW18	Stop bit	1	2	
SW21	Sum check	Not provided	<b>Provided</b>	
SW22	Write while running	Disabled	<b>Enabled</b>	
SW23	Standard type link unit / multi-drop link unit	Multi	<b>Standard</b>	
SW24	Master station / local station	-	-	

**A1SJ71C24-R2, A1SJ71UC24-R2**

Switch	Contents	ON	OFF	Example: RS-232C, 19200 bps
SW03	Not used	-	-	
SW04	Write while running	Enabled	Disabled	
		9600	19200	
SW05	Baud rate	ON	OFF	
SW06		OFF	ON	
SW07		ON	ON	
SW08	Data bit	8	7	
SW09	Parity bit	Provided	Not provided	
SW10	Parity	Even	Odd	
SW11	Stop bit	2	1	
SW12	Sum check	Provided	Not provided	

**A1SJ71UC24-R4, A1SJ71C24-R4**

Switch	Contents	ON	OFF	Example: RS-422, 19200 bps
SW01	Master station / local station	-	-	
SW02	Standard type link unit / multi-drop link unit	Standard	Multi	
SW03	Not used	-	-	
SW04	Write while running	Enabled	Disabled	
		9600	19200	
SW05	Baud rate	ON	OFF	
SW06		OFF	ON	
SW07		ON	ON	
SW08	Data bit	8	7	
SW09	Parity bit	Provided	Not provided	
SW10	Parity	Even	Odd	
SW11	Stop bit	2	1	
SW12	Sum check	Provided	Not provided	

**Available Memory**

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
D (data register)	00H	
W (link register)	01H	
R (file register)	02H	Cannot be set when the CPU is operated by ROM.
TN (timer/current value)	03H	
CN (counter/current value)	04H	
SPU (special unit buffer memory)	05H	*1
M (internal relay)	06H	
L (latch relay)	07H	
B (link relay)	08H	
X (input)	09H	
Y (output)	0AH	
TS (timer/contact)	0BH	
TC (timer/coil)	0CH	
CS (counter/contact)	0DH	
CC (counter/coil)	0EH	
H (link unit buffer memory)	0FH	

\*1 The unit number is required in addition to the memory type and address. Convert byte address into word address when entering the data on the editor if the memory device of the link unit is byte address.

## 11.1.2 QnA Series Link

### Communication Setting

#### Editor

#### Communication setting


(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> : 1 / 1 : n / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / 19200 / 38400 / 57600 / <u>115K</u> bps	
Data Length	8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>0</u> to 31	

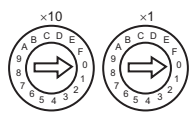
#### PLC

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor.

#### Mode setting

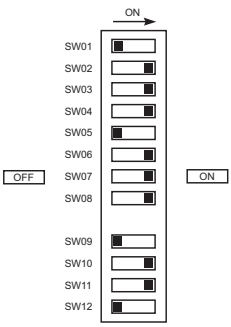
Mode	Setting	Contents
	5	Dedicated protocol binary mode Mode 5

#### Station number setting

Station No.	Setting	Contents
	0 to 31	Station number x10: the tens place x1: the ones place

#### Transmission setting

#### AJ71QC24, AJ71QC24N, A1SJ71QC24

Switch	Contents	OFF	ON	Example: 19200 bps			
SW01	Operation	<b>Independent</b>	Link				
SW02	Data bit	7	<b>8</b>				
SW03	Parity bit	Not provided	Provided				
SW04	Parity	Odd	Even				
SW05	Stop bit	1	2				
SW06	Sum check	Not provided	<b>Provided</b>				
SW07	Write while running	Disabled	<b>Enabled</b>				
SW08	Setting change	Disabled	Enabled				
SW09	Baud rate *1	9600	19200	38400		57600	115200
SW10		ON	OFF	ON		OFF	ON
SW11		OFF	ON	ON		ON	ON
SW12		ON	ON	ON		OFF	OFF
		OFF	OFF	OFF	ON	ON	

\*1 QJ71C24 (-R2/-R4): Max. 19200 bps

QJ71C24N (-R2/-R4): Max. 115200 bps (When CH1 and CH2 are used at the same time, a maximum of 115200 bps can be set in total.)

## Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
D (data register)	00H	
W (link register)	01H	
R (file register)	02H	
TN (timer/current value)	03H	
CN (counter/current value)	04H	
SPU (special unit buffer memory)	05H	*1
M (internal relay)	06H	
L (latch relay)	07H	
B (link relay)	08H	
X (input)	09H	
Y (output)	0AH	
TS (timer/contact)	0BH	
TC (timer/coil)	0CH	
CS (counter/contact)	0DH	
CC (counter/coil)	0EH	
H (link unit buffer memory)	0FH	
SD (special register)	10H	
SM (special relay)	11H	
SB (special link relay)	12H	
SW (special link register)	13H	
ZR (file register (for continuous access))	14H	

\*1 The unit number is required in addition to the memory type and address. Convert byte address into word address when entering the data on the editor if the memory device of the link unit is byte address.

### 11.1.3 QnH (Q) Series Link

#### Communication Setting

##### Editor

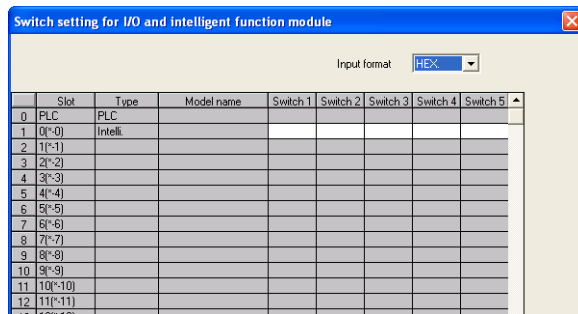
##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> : 1 / 1 : n / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / 19200 / 38400 / 57600 / <u>115K</u> bps	
Data Length	8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>0</u> to 31	

##### PLC (PC Parameter)

##### Switch setting for I/O and intelligent function module



Switch	Contents	Example																																																						
Switch 1	<p>CH1: baud rate, transmission setting</p> <p>Bit 15 - 8 7 - 0</p> <p>Baud rate      Transmission setting</p> <table border="1"> <thead> <tr> <th>bps</th> <th>Setting</th> <th>Bit</th> <th>Contents</th> <th>OFF</th> <th>ON</th> </tr> </thead> <tbody> <tr> <td>4800</td> <td>04H</td> <td>0</td> <td>Operation</td> <td><b>Independent</b></td> <td>Link</td> </tr> <tr> <td>9600</td> <td>05H</td> <td>1</td> <td>Data bit</td> <td>7</td> <td><b>8</b></td> </tr> <tr> <td>19200</td> <td>07H</td> <td>2</td> <td>Parity bit</td> <td>Not provided</td> <td>Provided</td> </tr> <tr> <td>38400</td> <td>09H</td> <td>3</td> <td>Parity</td> <td>Odd</td> <td>Even</td> </tr> <tr> <td>57600</td> <td>0AH</td> <td>4</td> <td>Stop bit</td> <td>1</td> <td>2</td> </tr> <tr> <td>115200</td> <td>0BH</td> <td>5</td> <td>Sum check</td> <td>Not provided</td> <td><b>Provided</b></td> </tr> <tr> <td></td> <td></td> <td>6</td> <td>Write while running</td> <td>Prohibited</td> <td><b>Allowed</b></td> </tr> <tr> <td></td> <td></td> <td>7</td> <td>Setting change</td> <td>Prohibited</td> <td>Allowed</td> </tr> </tbody> </table>	bps	Setting	Bit	Contents	OFF	ON	4800	04H	0	Operation	<b>Independent</b>	Link	9600	05H	1	Data bit	7	<b>8</b>	19200	07H	2	Parity bit	Not provided	Provided	38400	09H	3	Parity	Odd	Even	57600	0AH	4	Stop bit	1	2	115200	0BH	5	Sum check	Not provided	<b>Provided</b>			6	Write while running	Prohibited	<b>Allowed</b>			7	Setting change	Prohibited	Allowed	<p>0BEEH</p> <p>115 kbps 8 bits 1 bit Even</p>
bps	Setting	Bit	Contents	OFF	ON																																																			
4800	04H	0	Operation	<b>Independent</b>	Link																																																			
9600	05H	1	Data bit	7	<b>8</b>																																																			
19200	07H	2	Parity bit	Not provided	Provided																																																			
38400	09H	3	Parity	Odd	Even																																																			
57600	0AH	4	Stop bit	1	2																																																			
115200	0BH	5	Sum check	Not provided	<b>Provided</b>																																																			
		6	Write while running	Prohibited	<b>Allowed</b>																																																			
		7	Setting change	Prohibited	Allowed																																																			
Switch 2	CH1: communication protocol      MC protocol mode 5 binary code	0005H																																																						
Switch 3	CH2: baud rate, transmission setting (the same as those for switch 1)	0BEEH																																																						
Switch 4	CH2: communication protocol      MC protocol mode 5 binary code	0005H																																																						
Switch 5	Station number setting      0 to 31	0000H																																																						

## Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
D (data register)	00H	
W (link register)	01H	
R (file register)	02H	
TN (timer/current value)	03H	
CN (counter/current value)	04H	
SPU (special unit buffer memory)	05H	*1
M (internal relay)	06H	
L (latch relay)	07H	
B (link relay)	08H	
X (input)	09H	
Y (output)	0AH	
TS (timer/contact)	0BH	
TC (timer/coil)	0CH	
CS (counter/contact)	0DH	
CC (counter/coil)	0EH	
H (link unit buffer memory)	0FH	
SD (special register)	10H	
SM (special relay)	11H	
SB (special link relay)	12H	
SW (special link register)	13H	
ZR (file register (for continuous access))	14H	

\*1 The unit number is required in addition to the memory type and address. Convert byte address into word address when entering the data on the editor if the memory device of the link unit is byte address.

## 11.1.4 QnH (Q) Series CPU

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection mode	<u>1:1</u> / Multi-link2	
Signal level	RS-232C	
Baud rate	9600 / 19200 / 38400 / 57600 / <u>115K</u> bps	
Data length	8 bits	
Stop bit	1 bit	
Parity	Odd	

#### PLC

No particular setting is necessary on the PLC.

### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
D (data register)	00H	
W (link register)	01H	
R (file register)	02H	
TN (timer/current value)	03H	
CN (counter/current value)	04H	
SPU (special unit buffer memory)	05H	*1
M (internal relay)	06H	
L (latch relay)	07H	
B (link relay)	08H	
X (input)	09H	
Y (output)	0AH	
TS (timer/contact)	0BH	
TC (timer/coil)	0CH	
CS (counter/contact)	0DH	
CC (counter/coil)	0EH	
SD (special register)	10H	
SM (special relay)	11H	
SB (special link relay)	12H	
SW (special link register)	13H	
ZR (file register (for continuous access))	14H	

\*1 The unit number is required in addition to the memory type and address. Convert byte address into word address when entering the data on the editor if the memory device of the link unit is byte address.

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### 11.1.5 Q00J/00/01 CPU

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The communication setting and available memory are the same as those described in “11.1.4 QnH (Q) Series CPU”.

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### 11.1.6 QnH (Q) Series Link (Multi CPU)

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The communication setting and available memory are the same as those described in “11.1.3 QnH (Q) Series Link”.

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### 11.1.7 QnH (Q) Series CPU (Multi CPU)

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The communication setting and available memory are the same as those described in “11.1.4 QnH (Q) Series CPU”.

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### 11.1.8 QnU Series CPU

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The communication setting and available memory are the same as those described in “11.1.4 QnH (Q) Series CPU”.



## 11.1.9 FX2N/1N Series CPU

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / Multi-link2	
Signal Level	RS-422/485	
Baud Rate	9600 / 19200 / <u>38400</u> bps	
Data Length	7 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	<u>Q</u> to 31	

#### PLC

No particular setting is necessary on the PLC.

### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
D (data register)	00H	
TN (timer/current value)	01H	
CN (counter/current value)	02H	
32CN (32-bit counter/current value)	03H	*1
M (auxiliary relay)	04H	
S (state)	05H	
X (input relay)	06H	Read only
Y (output relay)	07H	
TS (timer/contact)	08H	
CS (counter/contact)	09H	

\*1 For items where double-words can be used (Num. Display, Graph, Sampling), data is processed as double-words.  
 For those where bits or words can be used, data is processed as words consisting of lower 16 bits.  
 For input: Upper 16 bits are ignored.  
 For output: "0" is written for upper 16 bits.

## 11.1.10 FX Series Link (A Protocol)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> :1 / 1:n / Multi-link / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Transmission Mode	<u>Transmission Mode 1</u> / Transmission Mode 4	
Data Length	<u>7</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Odd</u> / <u>Even</u>	
Target Port No.	<u>0</u> to 31	

#### PLC (PC Parameter)

#### PLC system (2)

Item	Setting	Remarks
<input type="checkbox"/> Operate communication setting	<b>Checked</b>	
Protocol	<b>Dedicated protocol</b>	
Data length	<u>7</u> bits / 8 bits	
Parity	None / <u>Odd</u> / Even	
Stop bit	<u>1</u> bit / 2 bits	
Transmission speed	4800 / <u>9600</u> / 19200 bps	
H/W type	<u>RS-232C</u> / RS-485	
<input type="checkbox"/> Sum check	<b>Checked</b>	
Transmission control protocol	<u>Form 1</u> / Form 4	
Station number setting	<u>00</u> to 0FH	

## Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
D (data register)	00H	
TN (timer/current value)	01H	
CN (counter/current value)	02H	*1
32CN (32-bit counter/current value)	03H	*2
M (auxiliary relay)	04H	
S (state)	05H	
X (input relay)	06H	Read only
Y (output relay)	07H	
TS (timer/contact)	08H	
CS (counter/contact)	09H	

\*1 CN200 to CN255 equals 32CN (32-bit counter).

\*2 For items where double-words can be used (Num. Display, Graph, Sampling), data is processed as double-words. For those where bits or words can be used, data is processed as words consisting of lower 16 bits.

For input: Upper 16 bits are ignored.

For output: "0" is written for upper 16 bits.

## 11.1.11 FX-3UC Series CPU

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / Multi-link2	
Signal Level	RS-422/485	
Baud Rate	9600 / 19200 / 38400 / 57600 / <u>115K</u> bps	
Data Length	7 bits	
Stop Bit	1 bit	
Parity	Even	

#### PLC

No particular setting is necessary on the PLC.

### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
D (data register)	00H	
TN (timer/current value)	01H	
CN (counter/current value)	02H	
32CN (32-bit counter/current value)	03H	*1
M (auxiliary relay)	04H	
S (state)	05H	
X (input relay)	06H	Read only
Y (output relay)	07H	
TS (timer/contact)	08H	
CS (counter/contact)	09H	
R (extension register)	0BH	

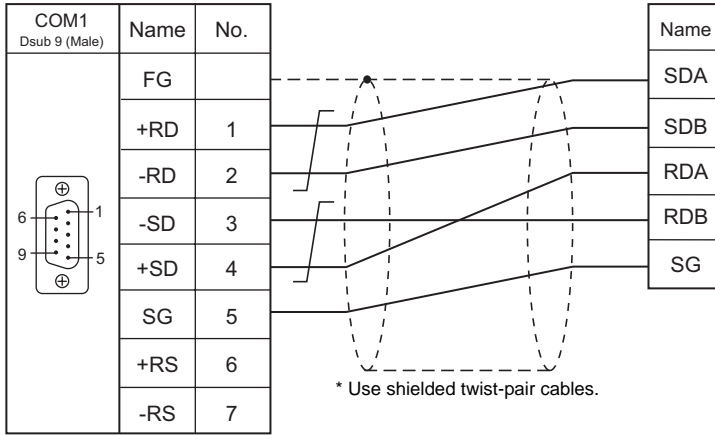
\*1 For items where double-words can be used (Num. Display, Graph, Sampling), data is processed as double-words.  
 For those where bits or words can be used, data is processed as words consisting of lower 16 bits.  
 For input Upper 16 bits are ignored.  
 For output "0" is written for upper 16 bits.

### 11.1.12 Wiring Diagrams

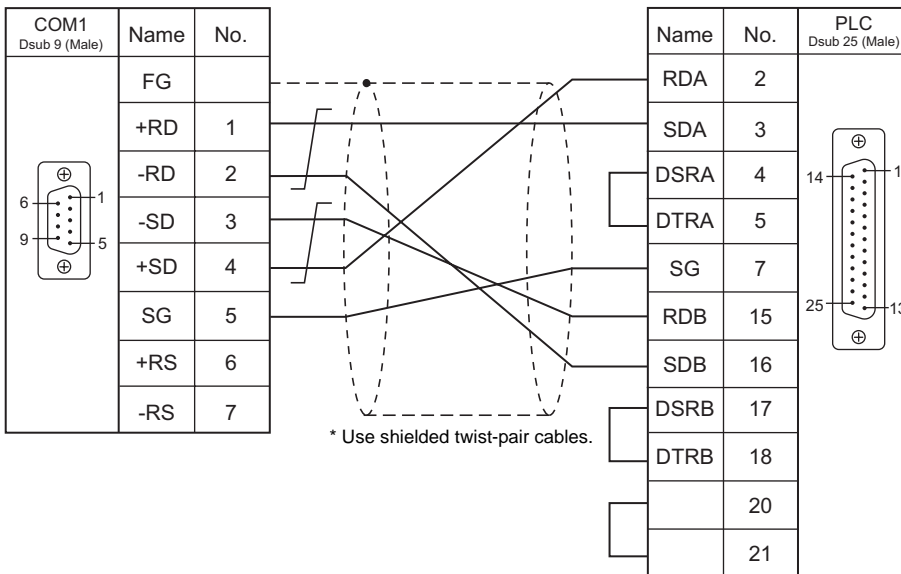
#### When Connected at COM1 (RS-422 / RS-485):

##### Wiring diagram 1 - COM1

Hakko Electronics' cable "D9-MI4-0T-□M" (□ = 2, 3, 5, 10, 15)

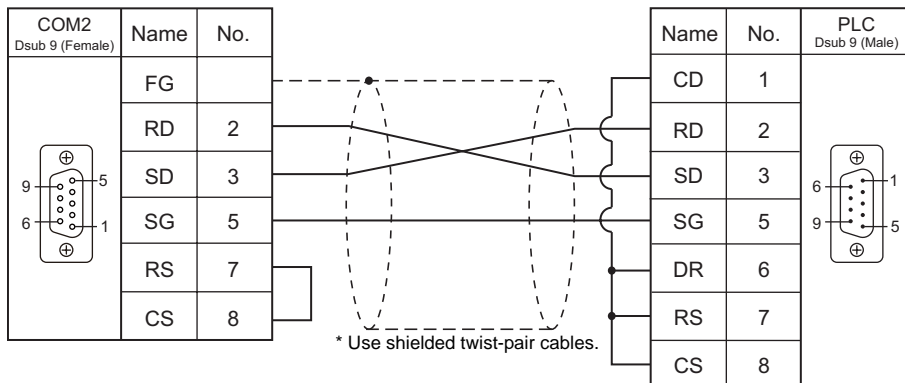


##### Wiring diagram 2 - COM1

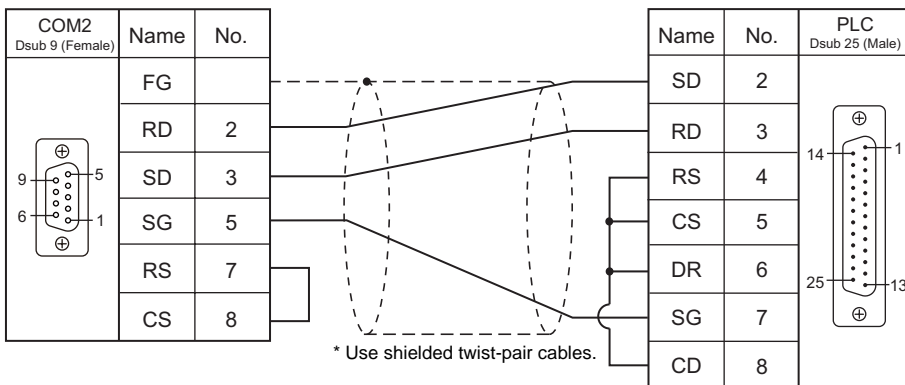


**When Connected at COM2 (RS-232C):**

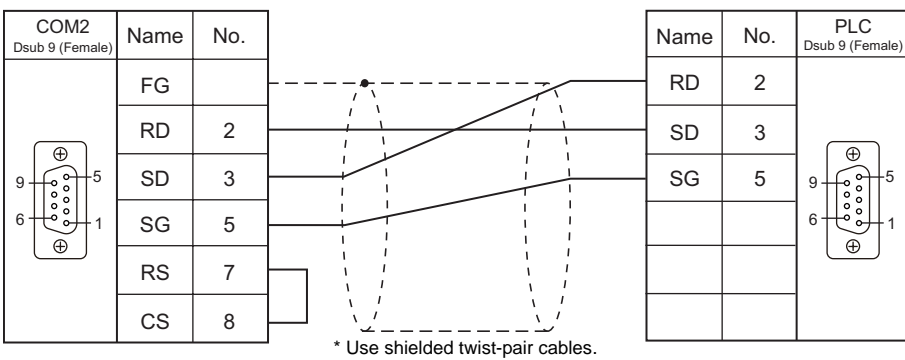
**Wiring diagram 1 - COM2**



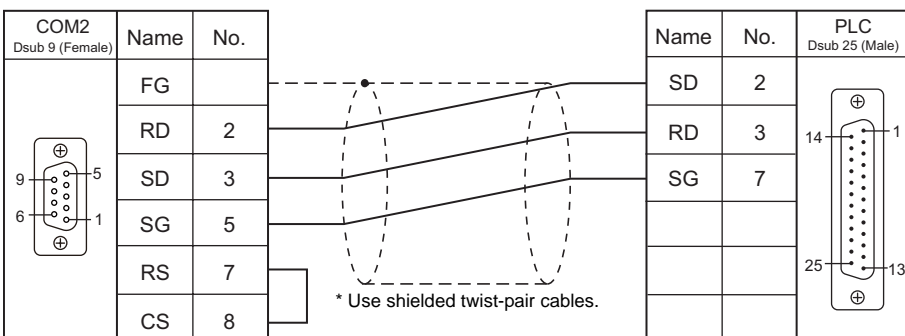
**Wiring diagram 2 - COM2**



**Wiring diagram 3 - COM2**



**Wiring diagram 4 - COM2**



## 11.2 Temperature Controller/Servo/Inverter Connection

The controller models shown below can be connected.

### Inverter

#### FR-\*500/FR-V500 Series

PLC Selection on the Editor	Model	Port	Signal level	Connection		Lst File
				COM1	COM2	
FR-*500	FR-A500 FR-E500 FR-F500	PU connector	RS-485	Wiring diagram 1 - COM1	-	FR-E500.Lst
	FR-S500	RS-485 connector				
FR-V500	FR-V500	PU connector				FR-V500.Lst

## 11.2.1 FR-\*500

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	1 / <u>2</u> bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>0</u> to 31	
CR/LF	None / <u>CR</u> / CRLF	

#### Inverter

Parameter No.	Item	Setting	Setting Example
77	Parameter writing permission	<u>0: Writing allowed when PU operation stops</u> 1: Writing prohibited 2: Writing allowed during operation	2: Writing allowed during operation
79	Operation mode selection *2	0 / <u>1</u> / 2 / 3 / 4 / 6 / 7 / 8	1: PU operation *3 2: External operation *3
117	Communicating station number	<u>0</u> to 31	0
118	Baud rate	4800 / 9600 / <u>19200</u> bps	19200 bps
119	Data length / stop bit length	0: 8 bits / 1 bit <u>1: 8 bits / 2 bits</u> 10: 7 bits / 1 bit 11: 7 bits / 2 bits	1: 8 bits / 2 bits
120	Parity check	0: None 1: Odd <u>2: Even</u>	2: Even
121	Communication retrial times	<u>0</u> to 10 / 9999	9999: The inverter does not stop even if a communication alarm occurs.
122	Communication check intervals *1	<u>0</u> / 0.1 to 999.8 / 9999	9999: Communication check stop
123	Wait time	0 to 150 / <u>9999</u>	9999: Can be set with the communication data
124	CR/LF selection	0: CR/LF not provided <u>1: CR provided, LF not provided</u> 2: CR/LF provided	1: CR provided, LF not provided
146	Frequency setting *2	<u>0</u> / 1 / 9999	9999

\*1 When the value in the range from 0.1 to 999.8 is set:

If the S8 series does not start communication within the preset time, the inverter stops due to an alarm. This can be avoided by the periodical reading setting.

\*2 When the inverter, FR-A500 or FR-E500, is turned on with the settings of Pr.79=0 and Pr.146=9999, the inverter enters in the PU operation mode.  
When the inverter, FR-F500 or FR-S500, is turned on with the settings of Pr.79=2 and n10=1, the inverter enters in the computer link operation mode.

\*3 When "1" is specified for 79 (operation mode selection), the running frequency and operation command for the FR-A500 or FR-E500 can be set on the S8.

When "2" is specified for 79 (operation mode selection), the running frequency and operation command for the FR-F500 or FR-S500 can be set on the S8.

Set the sensible operation mode when you do not need to set the running frequency and operation command from the S8.



## Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
P (parameter)	00H	Refer to the list file or the parameter list for the inverter.
D (parameter)	01H	Refer to the table below.

### Memory D (Parameter)

Address	Name																																																																																																																								
D0	Operation mode When issuing a command, such as a run command, from the S8 series, select "Communication and Run". FR-E500 : 0002 H FR-A500 : 0002 H FR-F500 : 0002 H FR-S500 : 0000 H																																																																																																																								
D1	Output frequency (Rotation)																																																																																																																								
D2	Output current																																																																																																																								
D3	Output voltage																																																																																																																								
D4	Alarm contents (last / most recent) <table border="1"> <thead> <tr> <th>Data</th> <th>Contents</th> <th>Data</th> <th>Contents</th> <th>Data</th> <th>Contents</th> <th>Data</th> <th>Contents</th> </tr> </thead> <tbody> <tr> <td>H00</td> <td>none</td> <td>H22</td> <td>OV3</td> <td>H80</td> <td>GF</td> <td>HB2</td> <td>RET</td> </tr> <tr> <td>H10</td> <td>OC1</td> <td>H30</td> <td>THT</td> <td>H81</td> <td>LF</td> <td>HC2</td> <td>P24</td> </tr> <tr> <td>H11</td> <td>OC2</td> <td>H31</td> <td>THM</td> <td>H90</td> <td>OHT</td> <td>HF3</td> <td>E.3</td> </tr> <tr> <td>H12</td> <td>OC3</td> <td>H40</td> <td>FIN</td> <td>HA0</td> <td>OPT</td> <td>HF6</td> <td>E.6</td> </tr> <tr> <td>H20</td> <td>OV1</td> <td>H60</td> <td>OLT</td> <td>HB0</td> <td>PE</td> <td>HF7</td> <td>E.7</td> </tr> <tr> <td>H21</td> <td>OV2</td> <td>H70</td> <td>BE</td> <td>HB1</td> <td>PUE</td> <td></td> <td></td> </tr> </tbody> </table>	Data	Contents	Data	Contents	Data	Contents	Data	Contents	H00	none	H22	OV3	H80	GF	HB2	RET	H10	OC1	H30	THT	H81	LF	HC2	P24	H11	OC2	H31	THM	H90	OHT	HF3	E.3	H12	OC3	H40	FIN	HA0	OPT	HF6	E.6	H20	OV1	H60	OLT	HB0	PE	HF7	E.7	H21	OV2	H70	BE	HB1	PUE																																																																		
Data	Contents	Data	Contents	Data	Contents	Data	Contents																																																																																																																		
H00	none	H22	OV3	H80	GF	HB2	RET																																																																																																																		
H10	OC1	H30	THT	H81	LF	HC2	P24																																																																																																																		
H11	OC2	H31	THM	H90	OHT	HF3	E.3																																																																																																																		
H12	OC3	H40	FIN	HA0	OPT	HF6	E.6																																																																																																																		
H20	OV1	H60	OLT	HB0	PE	HF7	E.7																																																																																																																		
H21	OV2	H70	BE	HB1	PUE																																																																																																																				
D5	Alarm contents (three times before / two times before)																																																																																																																								
D6	Alarm contents (five times before / four times before) *1																																																																																																																								
D7	Alarm contents (seven times before / six times before) *1																																																																																																																								
D8	Inverter status monitor <table border="1"> <thead> <tr> <th>Bit</th> <th>15</th> <th>-</th> <th>8</th> <th>7</th> <th>6</th> <th>5</th> <th>4</th> <th>3</th> <th>2</th> <th>1</th> <th>0</th> </tr> </thead> <tbody> <tr> <td>Not used</td> <td colspan="3"></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Error occurrence</td> <td colspan="3"></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Frequency detection (FU)</td> <td colspan="3"></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Not used</td> <td colspan="3"></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Overload (OL)</td> <td colspan="3"></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Frequency accession (SU)</td> <td colspan="3"></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Reverse rotation (STR)</td> <td colspan="3"></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Normal rotation (STF)</td> <td colspan="3"></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Inverter running (RUN)</td> <td colspan="3"></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> </tbody> </table>	Bit	15	-	8	7	6	5	4	3	2	1	0	Not used												Error occurrence												Frequency detection (FU)												Not used												Overload (OL)												Frequency accession (SU)												Reverse rotation (STR)												Normal rotation (STF)												Inverter running (RUN)											
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D9	Changeover to second parameter																																																																																																																								

\*1 These memory addresses are not available for FR-S500

#### Note on Setting the Memory

Only the "List" file of "FR-E500" can be browsed by pressing the [Refer] button by default.

If the inverter such as "A500", "F500", or "S500" is used, refer to the parameter list described in each inverter's manual and set the memory.

## PLC\_CTL

Macro command "PLC\_CTL F0 F1 F2"

Contents	F0	F1 (= \$u n)					F2	
		n	Station number					
Writing running frequency (EEPROM)	1 - 2 (PLC1 - 2)	n + 1	Command: 00EEH				3	
		n + 2	Running frequency					
		n	Station number					
Writing running frequency (RAM)	1 - 2 (PLC1 - 2)	n + 1	Command: 00EDH				3	
		n + 2	Running frequency					
		n	Station number					
All alarms clear	1 - 2 (PLC1 - 2)	n + 1	Command: 00F4H				2	
		n	Station number					
Operation command	1 - 2 (PLC1 - 2)	n + 1	Command: 00FAH				3	
		n + 2	0000H: Stop 0002H: Normal rotation (STF) 0004H: Reverse rotation (STR)					
		n	Station number					
All parameter clear	1 - 2 (PLC1 - 2)	n + 1	Command: 00FCH				3	
		n + 2	Pr.	Communic ation Pr.	Calibration	Other Pr.		00ECH 00F3H 00FFH
			Data					
			9696H	○	×	○		○
			9966H	○	○	○		○
		5A5AH	×	×	○	○		
55AAH	×	○	○	○				
Inverter reset	1 - 2 (PLC1 - 2)	n	Station number				2	
		n+1	Command: 00FDH					

## 11.2.2 FR-V500

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	1 / <u>2</u> bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>0</u> to 31	
CR/LF	None / <u>CR</u> / CRLF	

#### Inverter

Parameter No.	Item	Setting	Setting Example
77	Parameter writing permission	<u>0: Writing allowed when PU operation stops</u> 1: Writing prohibited 2: Writing allowed during operation	2: Writing allowed during operation
79	Operation mode selection *2	<u>0</u> / 1 / 2 / 3 / 4 / 6 / 7 / 8	1: PU operation
117	Communicating station number	<u>0</u> to 31	0
118	Baud rate	4800 / 9600 / <u>19200</u> bps	19200 bps
119	Data length / stop bit length	0: 8 bits / 1 bit <u>1: 8 bits / 2 bits</u> 10: 7 bits / 1 bit 11: 7 bits / 2 bits	1: 8 bits / 2 bits
120	Parity check	0: None 1: Odd 2: Even	2: Even
121	Communication retrial times	0 to 10 / 9999	9999: The inverter does not stop even if a communication alarm occurs.
122	Communication check intervals *1	<u>0</u> / 0.1 to 999.8 / 9999	9999: Communication check stop
123	Wait time	0 to 150 / <u>9999</u>	9999: Can be set with the communication data
124	CR/LF selection	0: CR/LF not provided <u>1: CR provided, LF not provided</u> 2: CR/LF provided	1: CR provided, LF not provided
146	Frequency setting *2	<u>0</u> / 1 / 9999	9999

\*1 When the value in the range from 0.1 to 999.8 is set:

If the S8 series does not start communication within the preset time, the inverter stops due to an alarm. This can be avoided by the periodical reading setting.

\*2 When the inverter is turned on with the settings of Pr.79=0 and Pr.146=9999, the inverter enters in the PU operation mode.

## Available Memory

The available memory setting range varies depending on the device. Be sure to set within the range available with the device to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
P (parameter)	00H	Refer to the list file or the parameter list for the inverter.
D (parameter)	01H	Refer to the table below.

### Memory D (Parameter)

Address	Name																																																																																																		
D0	Operation mode When issuing a command, such as a run command, from the S8 series, select "Communication and Run". 0002 H																																																																																																		
D1	Rotation speed																																																																																																		
D2	Output current																																																																																																		
D3	Output voltage																																																																																																		
D4	Alarm contents (last / most recent)																																																																																																		
D5	Alarm contents (three times before / two times before)																																																																																																		
D6	Alarm contents (five times before / four times before)																																																																																																		
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D9	Changeover to second parameter																																																																																																		
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D11	<p>Special monitor selection No.</p> <table border="1"> <thead> <tr> <th>Data</th> <th>Contents</th> <th>Unit</th> <th>Data</th> <th>Contents</th> <th>Unit</th> </tr> </thead> <tbody> <tr> <td>H01</td> <td>Output frequency</td> <td>0.01 Hz</td> <td>H10</td> <td>Output terminal status</td> <td>-</td> </tr> <tr> <td>H02</td> <td>Output current</td> <td>0.01 A</td> <td>H11</td> <td>Load meter</td> <td>0.1%</td> </tr> <tr> <td>H03</td> <td>Output voltage</td> <td>0.1V</td> <td>H12</td> <td>Motor exciting current</td> <td>0.01A</td> </tr> <tr> <td>H05</td> <td>Speed setting</td> <td>1 r/min</td> <td>H13</td> <td>Position pulse</td> <td>-</td> </tr> <tr> <td>H06</td> <td>Operation speed</td> <td>1 r/min</td> <td>H14</td> <td>Total power-on time</td> <td>1h</td> </tr> <tr> <td>H07</td> <td>Motor torque</td> <td>0.1%</td> <td>H17</td> <td>Operating time</td> <td>1h</td> </tr> <tr> <td>H08</td> <td>Converter output</td> <td>0.1 V</td> <td>H18</td> <td>Motor load ratio</td> <td>0.1%</td> </tr> <tr> <td>H09</td> <td>Regenerative brake</td> <td>0.1%</td> <td>H20</td> <td>Torque command</td> <td>0.1%</td> </tr> <tr> <td>H0A</td> <td>Electric thermal load ratio</td> <td>0.1%</td> <td>H21</td> <td>Torque current command</td> <td>0.1%</td> </tr> <tr> <td>H0B</td> <td>Output current peak value</td> <td>0.01 A</td> <td>H22</td> <td>Motor output</td> <td>0.01 kW</td> </tr> <tr> <td>H0C</td> <td>Output voltage peak value of converter</td> <td>0.1 V</td> <td>H23</td> <td>Feed back pulse</td> <td>-</td> </tr> <tr> <td>H0F</td> <td>Input terminal status</td> <td>-</td> <td></td> <td></td> <td></td> </tr> </tbody> </table> <p>Input terminal status</p> <table border="1"> <tr> <td>Bit</td> <td>15</td> <td>-</td> <td>8</td> <td>RES</td> <td>CH</td> <td>DI4</td> <td>DI3</td> <td>DI2</td> <td>DI1</td> <td>STR</td> <td>STF</td> </tr> </table> <p>Output terminal status</p> <table border="1"> <tr> <td>Bit</td> <td>15</td> <td>-</td> <td>4</td> <td>ABC</td> <td>D03</td> <td>D02</td> <td>D01</td> </tr> </table>	Data	Contents	Unit	Data	Contents	Unit	H01	Output frequency	0.01 Hz	H10	Output terminal status	-	H02	Output current	0.01 A	H11	Load meter	0.1%	H03	Output voltage	0.1V	H12	Motor exciting current	0.01A	H05	Speed setting	1 r/min	H13	Position pulse	-	H06	Operation speed	1 r/min	H14	Total power-on time	1h	H07	Motor torque	0.1%	H17	Operating time	1h	H08	Converter output	0.1 V	H18	Motor load ratio	0.1%	H09	Regenerative brake	0.1%	H20	Torque command	0.1%	H0A	Electric thermal load ratio	0.1%	H21	Torque current command	0.1%	H0B	Output current peak value	0.01 A	H22	Motor output	0.01 kW	H0C	Output voltage peak value of converter	0.1 V	H23	Feed back pulse	-	H0F	Input terminal status	-				Bit	15	-	8	RES	CH	DI4	DI3	DI2	DI1	STR	STF	Bit	15	-	4	ABC	D03	D02	D01
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## PLC\_CTL

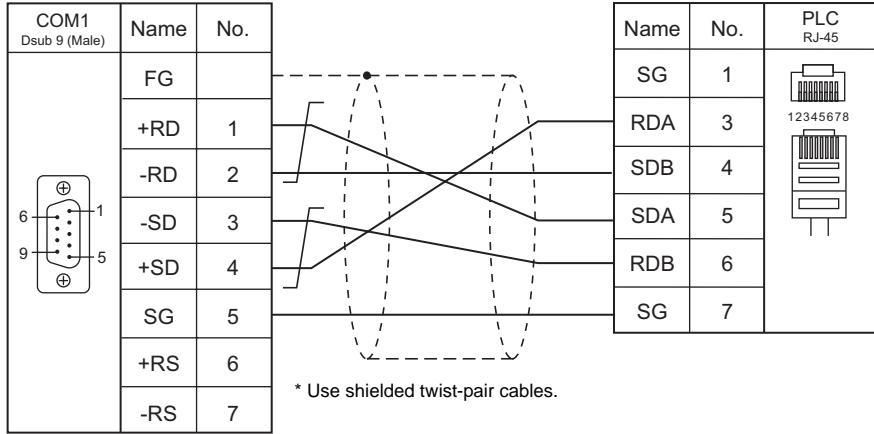
Macro command "PLC\_CTL F0 F1 F2"

Contents	F0	F1 (= \$u n)					F2	
		n	Station number					
Writing setting speed (EEPROM)	1 - 2 (PLC1 - 2)	n + 1	Command: 00EEH					3
		n + 2	Running frequency					
		n	Station number					
Writing setting speed (RAM)	1 - 2 (PLC1 - 2)	n + 1	Command: 00EDH					3
		n + 2	Running frequency					
		n	Station number					
All alarms clear	1 - 2 (PLC1 - 2)	n + 1	Command: 00F4H					2
		n	Station number					
Operation command	1 - 2 (PLC1 - 2)	n + 1	Command: 00FAH					3
		n + 2	0000H: Stop 0002H: Normal rotation (STF) 0004H: Reverse rotation (STR)					
		n	Station number					
All parameter clear	1 - 2 (PLC1 - 2)	n + 1	Command: 00FCH					3
		n + 2	Pr.	Communic ation Pr.	Calibration	Other Pr.	00ECH 00F3H 00FFH	
			Data					
			9696H	○	×	○	○	
			9966H	○	○	○	○	
		5A5AH	×	×	○	○		
55AAH	×	○	○	○				
Inverter reset	1 - 2 (PLC1 - 2)	n + 1	Command: 00FDH					2
		n	Station number					

### 11.2.3 Wiring Diagrams

#### When Connected at COM1 (RS-422 / RS-485):

Wiring diagram 1 - COM1



MEMO

Please use this page freely.

# 12. OMRON

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12.1 PLC Connection

12.2 Temperature Controller/Servo/Inverter Connection





## 12.1 PLC Connection

The PLC models shown below can be connected.

### Serial Connection

#### SYSMAC C

PLC Selection on the Editor	CPU	Unit/Port	Signal Level	Connection		Ladder Transfer *1
				COM1	COM2	
SYSMAC C	C20H, C28H, C40H	RS-232C port	RS-232C	-	Wiring diagram 1 - COM2	×
	C120, C120F C200H C500, C500F C1000H C2000, C2000H	C120-LK201-V1	RS-232C	-	Wiring diagram 3 - COM2	
		C120-LK202-V1	RS-422	Wiring diagram 1 - COM1	-	
	C200H C200HS-CPU01, 03 C200HS-CPU21, 23 C200HS-CPU31, 33	C200H-LK201 C200H-LK201-V1	RS-232C	-	Wiring diagram 3 - COM2	
		C200H-LK202 C200H-LK202-V1	RS-422	Wiring diagram 1 - COM1	-	
	C200HS-CPU21, 23 C200HS-CPU31, 33 CQM1-CPU21 CQM1-CPU41, 42, 43, 44	RS-232C port	RS-232C	-	Hakko Electronics' cable "D9-OM2-09" + Gender changer *2	
					Wiring diagram 2 - COM2	
	C500, C500F C1000H C2000, C2000H	C500-LK203	RS-232C	-	Wiring diagram 3 - COM2	
			RS-422	Wiring diagram 1 - COM1	-	
	C200HX C200HG C200HE	RS-232C port	RS-232C	-	Hakko Electronics' cable "D9-OM2-09" + Gender changer *2	
		C200HW-COM02 C200HW-COM03 C200HW-COM04 C200HW-COM05 C200HW-COM06			RS-422	
	SRM1-C02	RS-232C port	RS-232C	-	Hakko Electronics' cable "D9-OM2-09" + Gender changer *2	
	CPM1A	Peripheral port	RS-232C	-	Wiring diagram 2 - COM2	
					Omron's "CQM1-CIF02"	
	CPM2A	RS-232C port	RS-232C	-	Hakko Electronics' cable "D9-OM2-09" + Gender changer *2	
		Peripheral port	RS-232C	-	Wiring diagram 2 - COM2	
CPM2C	CS1W-CN118	RS-232C	-	Hakko Electronics' cable "D9-OM2-09" + Gender changer *2		
	CPM2C-CIF01			Wiring diagram 2 - COM2		
	CPM2C-CIF11	RS-422	Wiring diagram 4 - COM1	-		

\*1 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".

\*2 Use a D-sub gender changer (9-pin, male-to-female) commercially available.

Manufacturer	Model
Black Box	FA445-R2
Misumi	DGC-9SS

## SYSMAC CS1/CJ1

PLC Selection on the Editor	CPU	Unit/Port		Signal Level	Connection		Ladder Transfer *1
					COM1	COM2	
SYSMAC CS1/CJ1	CS1	RS-232C port		RS-232C	-	Hakko Electronics' cable "D9-OM2-09" + Gender changer *2	×
		CS1W-SCU21					
		CS1W-SCB21					
		CS1W-SCB41	Port 1	RS-422	Wiring diagram 3 - COM1	-	
	Port 2						
	CJ1H CJ1M	RS-232C port		RS-232C	-	Hakko Electronics' cable "D9-OM2-09" + Gender changer *2	
		CJ1W-SCU21					
		CJ1W-SCU41	Port 2				
Port 1							

\*1 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".

\*2 Use a D-sub gender changer (9-pin, male-to-female) commercially available.

Manufacturer	Model
Black Box	FA445-R2
Misumi	DGC-9SS

## 12.1.1 SYSMAC C

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> :1 / 1:n / Multi-link / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	1 / <u>2</u> bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>0</u> to 31	
Transmission Mode	<u>Transmission Mode 1</u> / Transmission Mode 2	Transmission Mode 1: BCD without signs Transmission Mode 2: BCD with signs

#### Transmission mode 2

When the transmission mode 2 (BCD with signs) is selected, data in the PLC memory can be displayed on MONITOUCH as data with signs.

When higher 4 bits in the memory indicates [F] or [A], it is treated as negative.

[F]: Regards higher 4 bits as [-0].

[A]: Regards higher 4 bits as [-1].

- Displayable range 1 word: -1999 to +9999  
2 words: -19999999 to +99999999

Example:

PLC Memory	Indication on the S8 Series
0000 to 9999	0 to 9999
F001 to F999	-1 to -999
A000 to A999	-1000 to -1999
0000000 to 9999999	0 to 9999999
F0000001 to F9999999	-1 to -9999999
A0000000 to A9999999	-10000000 to -19999999

- Setting procedure: Num. Display [Input Type: BCD]  
[Display Type: DEC] (w/ sign -, w/ sign +-)

## PLC

**C20H / C28H / C40H****Standard setting**

Item	Setting	Remarks
Start Bit	1 bit	Communication parameter format can be specified in the DM920 to DM923 memory. For more information, refer to the PLC manual issued by the manufacturer.
Data Length	7 bits	
Parity	Even	
Stop Bit	2 bits	
Baud Rate	9600 bps	

**C120-LK201-V1 / C120-LK202-V1****Switch setting**

Switch	No.	Setting	Contents
SW1	1 to 5	OFF	Unit No. 0
	6 to 7	OFF	Not used
	8	ON	Starts operation at power-up
SW2	1	OFF	19200 bps
	2	OFF	
	3	ON	
	4	OFF	
	5	OFF	Not used
	6	OFF	1 : n protocol
	7	ON	Enables command levels 1, 2, and 3
	8	ON	
SW3	1	ON	CTS switch: always ON
	2	OFF	
	3	ON	LK201-V1: internal synchronization LK202-V1: terminating resistance provided
	4	OFF	
	5	ON	
	6	OFF	
	7 to 8	OFF	Not used

The communication parameter setting is fixed to 7 bits for data length, 2 bits for stop bit, and even for parity.

**C200H-LK201-V1 / C200H-LK202-V1****Front switch setting**

Switch	Setting	Contents
SW1	0	Higher-order digit of the unit No. ( $\times 10$ )
SW2	0	Lower-order digit of the unit No. ( $\times 1$ )
SW3	6	19200 bps
SW4	2	Enables command levels 1, 2 and 3 / 7 / 2 / even

**Back switch setting**

Unit	Switch	Setting	Contents
LK201	SW1	OFF	Not used
	SW2	OFF	
	SW3	ON	1 : n protocol
	SW4	OFF	5-V power not supplied
	CTS switch	0	0 V (always ON)
LK202	Terminating resistance	ON	Provided
	Protocol	OFF	1 : n protocol

## C500H-LK203

### Back switch setting

Switch	Setting	Contents
5-V power supply	OFF	
I/O port	-	RS-232C/RS422
Synchronization	Internal	
Terminating resistance	Provided	Applicable for RS-422
CTS	0V	0 V
SW1	1 to 5	OFF
	6	OFF
	7	OFF
	8	ON
SW2	1	OFF
	2	OFF
	3	ON
	4	OFF
	5	ON
	6	OFF
	7	ON
	8	ON

## C200HW-COM02 - 06

### DIP switch

For the port A of C200HW-CCM03/06 (RS-422), the DIP switch setting is available.


DIP Switch	Contents	Setting
SW1	Change-over of 2-wire or 4-wire system	4 (4-wire system)
SW2	Terminator	ON

### PLC system setting

Item	Setting	Remarks
User Setting	Checked	The system setting can be made by specifying a value for the address using a programming console. For more information, refer to the PLC manual issued by the manufacturer.
Baud Rate	4800 / 9600 / 19200	
Parameter	1, 7, 2, E	
Mode	Host link	
Unit No.	00	

## CPM2A

### Communication condition setting switch


Communication Condition Setting Switch	Setting	Contents
	OFF	The peripheral port and RS-232C port are operated according to the communication protocol and communication format set on the PLC system setting.

### PLC system setting

Item	Setting	Remarks
User Setting	Checked	The system setting can be made by specifying a value for the address using a programming console. For more information, refer to the PLC manual issued by the manufacturer.
Baud Rate	4800 / 9600 / 19200	
Parameter	1, 7, 2, E	
Mode	Host link	
Unit No.	00	

## CPM1A/CPM2C

### Communication port function setting switch (only for CPM2C)

Communication Port Function Setting Switch	Setting	Contents
	OFF	The RS-232C port is operated according to the communication protocol and communication format set on the PLC system setting.

### PLC system setting (peripheral port)

Item	Setting	Remarks
User Setting	Checked	The system setting can be made by specifying a value for the address using a programming console. For more information, refer to the PLC manual issued by the manufacturer.
Baud Rate	4800 / 9600 / 19200	
Parameter	1, 7, 2, E	
Mode	Host link	
Unit No.	00	

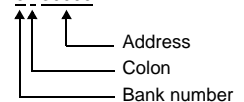
## Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
DM (data memory)	00H	
CH (input/output/internal auxiliary relay)	01H	
HR (holding relay)	02H	
LR (link relay)	03H	
AR (auxiliary memory relay)	04H	
T (timer/current value)	05H	
C (counter/current value)	06H	
EMn (extended data memory)	07H	*1
TU (timer/contact)	09H	Read only
CU (counter/contact)	0AH	Read only

\*1 When using EMn (extended data memory), specify the bank number 0 to 7.  
The assigned memory is indicated when editing the screen as shown on the right.

example: EM0 : 30000



## 12.1.2 SYSMAC CS1/CJ1

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> :1 / 1 : n / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115k bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	1 / <u>2</u> bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>0</u> to 31	
Transmission Mode	<u>Transmission Mode 1</u> / Transmission Mode 2	Transmission Mode 1: BCD without signs Transmission Mode 2: BCD with signs

#### Transmission mode 2

When the transmission mode 2 (BCD with signs) is selected, data in the PLC memory can be displayed on MONITOUCH as data with signs.

When higher 4 bits in the memory indicates [F] or [A], it is treated as negative.

[F]: Regards higher 4 bits as [-0].

[A]: Regards higher 4 bits as [-1].

- Displayable range 1 word: -1999 to +9999  
2 words: -19999999 to +99999999

Example:

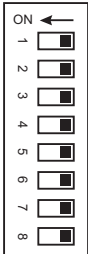
PLC Memory	Indication on the V Series
0000 to 9999	0 to 9999
F001 to F999	-1 to -999
A000 to A999	-1000 to -1999
00000000 to 99999999	0 to 99999999
F0000001 to F9999999	-1 to -9999999
A0000000 to A9999999	-10000000 to -19999999

- Setting procedure: Num. Display [Input Type: BCD]  
[Display Type: DEC] (w/ sign -, w/ sign +-)

#### PLC

#### CJ1/CS1 (CPU RS-232C Port)

#### DIP switch

Switch	Contents	Setting	
	SW1	User memory writing	OFF: enabled
	SW2	Automatic user program transfer at power-up	OFF: not executed
	SW3	CJ1: blank CS1: message of the programming console (Japanese/English)	OFF
	SW4	Communication settings for the peripheral port	OFF: CX-Programmer connection
	SW5	RS-232C communication setting	OFF: According to the setting made on the PLC system setting
	SW6	User-specified switch	OFF
	SW7	Simple-backup type specification	OFF
	SW8	Fixed to OFF	OFF



### PLC system setting (host link port)

Item	Setting	Remarks
User Setting	Checked	The system setting can be made by specifying a value for the address using a programming console. For more information, refer to the PLC manual issued by the manufacturer.
Baud Rate	4800 / 9600 / 19200 / 38400 / 57600 / 115200	
Parameter	7, 2, E	
Mode	Host link	
Unit No.	00	

### CJ1/CS1 (Serial Communication Board/Unit)

#### Advanced unit setting

Item	Setting	Remarks
Random Setting	Provided	
Serial Communication Mode	Default (host link) / Host link	When "Default (host link)" is selected, the unit operates as the unit No. 0.
Data Length	7 bits / 8 bits	
Stop Bit	2 bits / 1 bit	
Parity	Even, odd, none	
Baud Rate	4800 / 9600 / 19200 / 38400 / 57600 / 115200	
Send Delay Time	Default: 0 ms	
Send Delay Time Random Setting	0	
CTS control	None	
Host link unit No.	00	

#### DM area setting

m = D30000 + 100 x unit No. (CH)

DM Area				Bit	Contents	Setting
Board		Unit				
Port 1	Port 2	Port 1	Port 2			
D32000	D32010	m	m + 10	15	Port setting	1: Random setting
				14 to 12	Reserved	-
				11 to 08	Host link	0 or 5
				07 to 05	Reserved	-
				04	Start bit	0: 1 bit
				03	Data length	0: 7 bits 1: 8 bits
				02	Stop bit	0: 2 bits 1: 1 bit
				01	Parity	0: Provided 1: None
D32001	D32011	m + 1	m + 11	15 to 04	Reserved	-
				03 to 00	Baud rate	0: 9600 5: 4800 6: 9600 7: 19200 8: 38400 9: 57600 A: 115200
D32002	D32012	m + 2	m + 12	15	Send delay time	0: 0 ms 1: Random setting
				14 to 00	Send delay time random setting	0 to 7530H Unit: 10 ms
D32003	D32013	m + 3	m + 13	15	CTS control	0: None 1: Provided
				14	1 : n/1 : 1 protocol setting	1 : 1 : 1 protocol 0 : 1 : n protocol
				13 to 11	Reserved	-
				10 to 08	Host link-compatible model mode	
				07 to 00	Unit No.	00 to 1FH

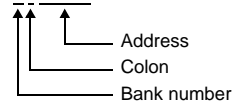
## Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
DM (data memory)	00H	
CH (input/output/internal auxiliary relay)	01H	
H (holding relay)	02H	
A (auxiliary memory relay)	04H	
T (timer/current value)	05H	
C (counter/current value)	06H	
EMn (extended data memory)	07H	*1
W (internal relay)	08H	
TU (timer/contact)	09H	Read only
CU (counter/contact)	0AH	Read only

\*1 When using EMn (extended data memory), specify the bank number 0 to C.  
The assigned memory is indicated when editing the screen as shown on the right.

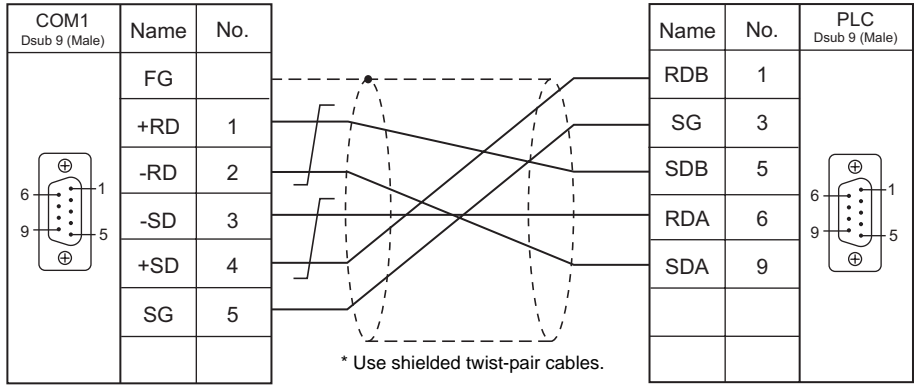
example: EM0 : 30000



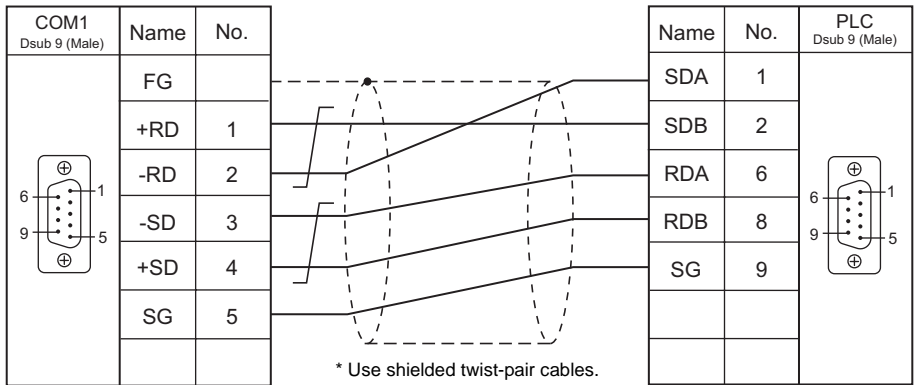
### 12.1.3 Wiring Diagrams

#### When Connected at COM1 (RS-422 / RS-485):

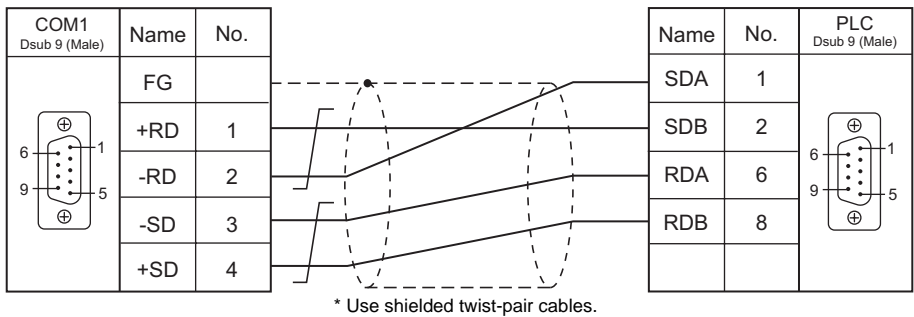
**Wiring diagram 1 - COM1**



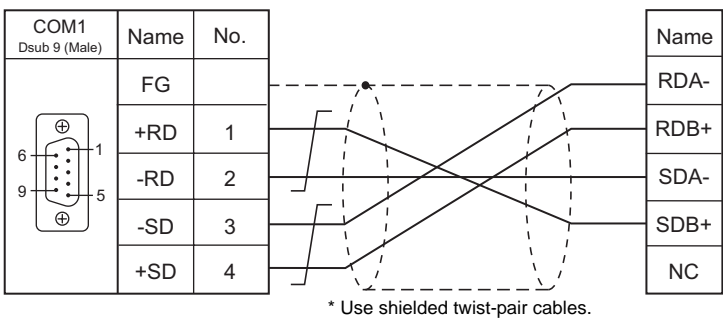
**Wiring diagram 2 - COM1**



**Wiring diagram 3 - COM1**

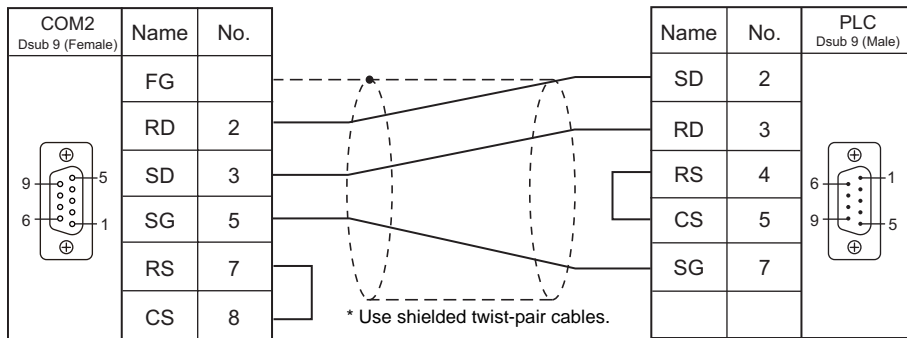


**Wiring diagram 4 - COM1**

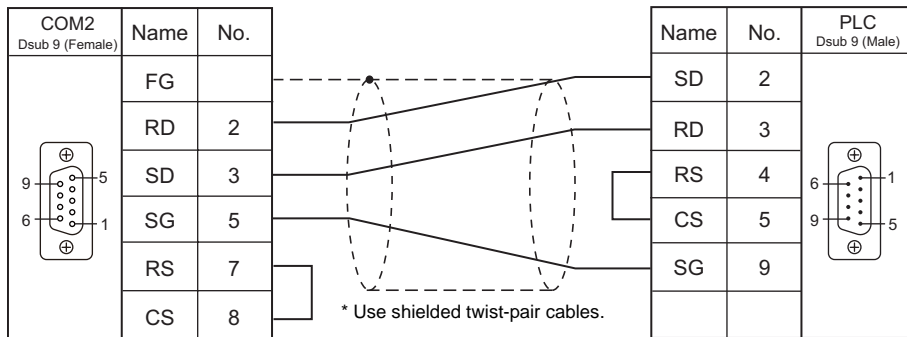


**When Connected at COM2 (RS-232C):**

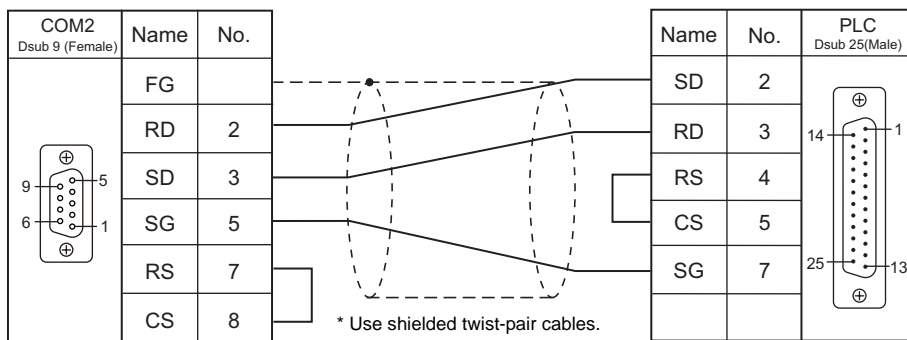
**Wiring diagram 1 - COM2**



**Wiring diagram 2 - COM2**



**Wiring diagram 3 - COM2**



## 12.2 Temperature Controller/Servo/Inverter Connection

The controller models shown below can be connected.

### Digital Temperature Controller

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
E5AR/E5ER	E5AR-xxxxxxx-FLK E5ER-xxxxxxx-FLK	Terminal	RS-485	Wiring diagram 1 - COM1	-	E5AR.Lst
E5AN/E5EN/E5CN /E5GN	E5AN-xxx01xxxFLK E5EN-xxx01xxxFLK	Terminal	RS-232C	-	Wiring diagram 1 - COM2	E5AN.Lst
	E5CN-xxx03xxxFLK E5AN-xxx03xxxFLK E5EN-xxx03xxxFLK E5GN-xx03x-FLK	Terminal	RS-485	Wiring diagram 1 - COM1	-	

## 12.2.1 E5AR

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-422/485	
Baud Rate	<u>9600</u> / 19200 / 38400 bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	1 / <u>2</u> bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>0</u> to 31	

#### Temperature Controller

#### Communication level setting (LS)

Level	Displayed Character	Setting Data	Setting
Communication level (L.S)	PSEL	Protocol selection	CompoWay/F
	U-no	Communication unit No.	0 to 31
	bps	Baud rate	<u>9600</u> / 19200 / 38400 bps
	LEn	Communication data length	<u>7</u> / 8 bits
	Sbit	Communication stop bit	1 / <u>2</u> bits
	PrtY	Communication parity	None / Odd / <u>Even</u>
Adjustment level (L.Adj)	CMWT	Communication writing*1	OFF / <b>ON</b>

\*1 When writing setting data from the S8, set "ON" for the "communication writing" setting.

#### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
C0 (communication monitor)	00H	Double-word
C1 (communication monitor)	01H	Double-word
C4 (communication monitor)	03H	Double-word
C5 (protection level)	04H	Double-word
C6 (run level)	05H	Double-word
C7 (adjustment level)	06H	Double-word
C8 (adjustment 2 level)	07H	Double-word
C9 (bank setting level)	08H	Double-word
CA (PID setting level)	09H	Double-word
CB (approximation setting level)	0AH	Double-word
CC (default setting level for input)	0BH	Double-word
CD (default setting level for control)	0CH	Double-word
CE (default setting level 2 for control)	0DH	Double-word
CF (warning setting level)	0EH	Double-word
D0 (display adjustment level)	0FH	Double-word
D1 (communication level)	10H	Double-word
D2 (high-performance setting level)	11H	Double-word
D3 (extended control setting level)	12H	Double-word

## Indirect Memory Designation

For bit designation, an expansion code setting is required.

00H: when designating bit 0 to 15

01H: when designating bit 16 to 31


## PLC\_CTL

Macro command "PLC\_CTL F0 F1 F2"

Contents	F0	F1 (= \$u n)		F2
Read controller status	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 0006H	
		n + 2	Status	
		n + 3	Relevant information	
Operation instructions	1 - 2 (PLC1 - 2)	n	Station number *1	3
		n + 1	Command: 0030H	
		n + 2	Communication writing 0000H: Communication writing OFF (disabled) 0001H: Communication writing ON (enabled)	
			Control start/stop 0100H: Channel 1 RUN 0101H: Channel 1 STOP 0110H: Channel 2 RUN 0111H: Channel 2 STOP 0120H: Channel 3 RUN 0121H: Channel 3 STOP 0130H: Channel 4 RUN 0131H: Channel 4 STOP 01F0H: All channels RUN 01F1H: All channels STOP	
			Bank selection 0200 to 0207H: Channel 1 Bank Nos. 0 to 7 0210 to 0217H: Channel 2 Bank Nos. 0 to 7 0220 to 0227H: Channel 3 Bank Nos. 0 to 7 0230 to 0237H: Channel 4 Bank Nos. 0 to 7 02F0 to 02F7H: All channels Bank Nos. 0 to 7	
			AT execution 0300H: Channel 1 PID group number currently selected 0301 to 0308H: Channel 1 PID group Nos. 1 to 8 designation 0310H: Channel 2 PID group number currently selected 0311 to 0318H: Channel 2 PID group Nos. 1 to 8 designation 0320H: Channel 3 PID group number currently selected 0321 to 0328H: Channel 3 PID group Nos. 1 to 8 designation 0330H: Channel 4 PID group number currently selected 0331 to 0338H: Channel 4 PID group Nos. 1 to 8 designation 03F0H: All channels PID group number currently selected 03F1 to 03F8H: All channels PID group Nos. 1 to 8 designation	
			AT cancellation 0A00H: Channel 1 0A10H: Channel 2 0A20H: Channel 3 0A30H: Channel 4 09F0H: All channels	
			Write mode 0400H: Backup mode 0401H: RAM write mode	
			0500H: Save RAM data	
			0600H: Software reset	
			0700H: Move to set area 1	
			0800H: Move to protect level	
			Auto/manual 0900H: Channel 1 Auto mode 0901H: Channel 1 Manual mode 0910H: Channel 2 Auto mode 0911H: Channel 2 Manual mode 0920H: Channel 3 Auto mode 0921H: Channel 3 Manual mode 0930H: Channel 4 Auto mode 0931H: Channel 4 Manual mode 09F0H: All channels Auto mode 09F1H: All channels Manual mode	
			0B00H: Initialize	

Contents	F0	F1 (= \$u n)		F2
Operation instructions	1 - 2 (PLC1 - 2)	n + 2	Unlatch 0C00H: Channel 1 Warning unlatch 0C10H: Channel 2 Warning unlatch 0C20H: Channel 3 Warning unlatch 0C30H: Channel 4 Warning unlatch 0CF0H: All channels Warning unlatch SP mode 0D00H: Channel 1 Local SP 0D01H: Channel 1 Remote SP 0D10H: Channel 2 Local SP (Cascade open) 0D11H: Channel 2 Remote SP (Cascade close)	3

\*1 8000 (HEX): broadcasting

 Return data: Data stored from temperature controller to S8 series



## 12.2.2 E5AN/E5EN/E5CN/E5GN

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	1 / <u>2</u> bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	0 to 31	

#### Temperature Controller

##### E5CN/E5SAN/E5EN

##### Communication level setting

Level	Displayed Character	Setting Data	Setting
Communication level	PSEL	Protocol selection	CompoWay/F
	U-no	Communication unit No.	0 to 31
	bps	Baud rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 bps
	LEn	Data length	<u>7</u> / 8 bits
	Sbit	Communication stop bit	1 / <u>2</u> bits
	Prty	Parity	None / Odd / <u>Even</u>
Adjustment level	CMWT	Communication writing <sup>*1</sup>	OFF / <b>ON</b>

\*1 When writing setting data from the S8, set "ON" for the "communication writing" setting.

##### E5GN

##### Communication level setting

Level	Displayed Character	Setting Data	Setting
Communication level	U-no	Communication unit No.	0 to 31
	bps	Baud rate	4800 / 9600 / 19200 bps
	LEn	Data length	<u>7</u> / 8 bits
	Sbit	Communication stop bit	1 / <u>2</u> bits
	Prty	Parity	None / Odd / <u>Even</u>
Adjustment level	CMWT	Communication writing <sup>*1</sup>	OFF / <b>ON</b>

\*1 When writing setting data from the S8, set "ON" for the "communication writing" setting.

## Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
C0 (setting area 0)	00H	Double-word, read only
C1 (setting area 0)	01H	Double-word
C3 (setting area 1)	03H	Double-word

## Indirect Memory Designation

For bit designation, an expansion code setting is required.

00H: when designating bit 0 to 15

01H: when designating bit 16 to 31

## PLC\_CTL

Macro command "PLC\_CTL F0 F1 F2"

Contents	F0	F1 (= \$u n)		F2
Read controller status	1 - 2 (PLC1 - 2)	n	Station number	2
		n + 1	Command: 0006H	
		n + 2	Operation status	
Operation instructions	1 - 2 (PLC1 - 2)	n n + 1 n + 2	Station number *1	3
			Command: 0030H	
			Communication writing 0000H: Communication writing OFF (disabled) 0001H: Communication writing ON (enabled)	
			Control start/stop 0100H: Channel 1 Run 0101H: Channel 1 Stop	
			Multi-SP 0200H: Target value 1 0201H: Target value 2 0202H: Target value 3 0203H: Target value 4	
			AT execution/cancel 0300H: Cancel 0301H: Execute	
			Write mode 0400H: Backup mode 0401H: RAM write mode	
			0500H: Save RAM data	
			0600H: Software reset	
			0700H: Move to set area 1	
0800H: Move to protect level				

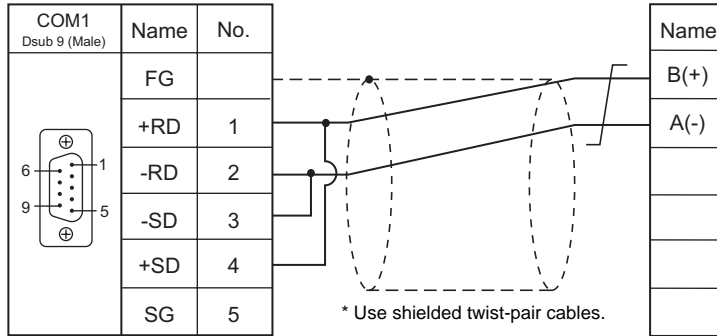
\*1 8000 (HEX): broadcasting

Return data: Data stored from temperature controller to S8 series

### 12.2.3 Wiring Diagrams

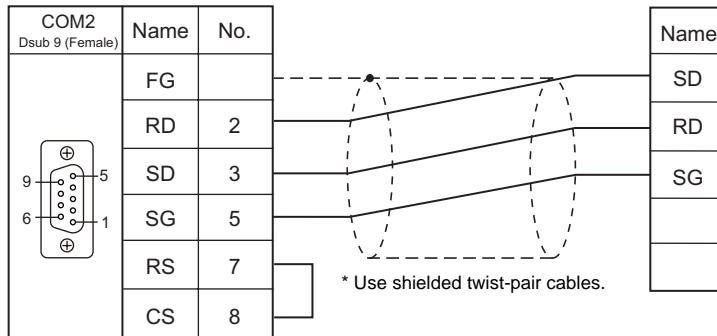
#### When Connected at COM1 (RS-422 / RS-485):

Wiring diagram 1 - COM1



#### When Connected at COM2 (RS-232C):

Wiring diagram 1 - COM2



# 13. Panasonic Electric Works

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## 13.1 PLC Connection



## 13.1 PLC Connection

The PLC models shown below can be connected.

### Serial Connection

PLC Selection on the Editor	CPU	Unit/Port	Signal Level	Connection		Ladder Transfer *1	
				COM1	COM2		
FP Series	FP1	COM port of the CPU	RS-232C	-	Wiring diagram 1 - COM2	X	
	FP3	AFP3462 (CCU)	RS-232C				
		AFP3463 (C-NET)	RS-422	Wiring diagram 1 - COM1	-		
	FP5	AFP5462 (CCU)	RS-232C	-	Wiring diagram 1 - COM2		
	FP10	COM port of the CPU	RS-232C				
		AFP5462 (CCU)	RS-232C				
	FP10S FP10SH	COM port of the CPU	RS-232C	-	Wiring diagram 1 - COM2		
		AFP3462 (CCU)	RS-232C				
		AFP3463 (C-NET)	RS-422	Wiring diagram 1 - COM1	-		
	FP0	Tool port of the CPU	RS-232C	-	Panasonic's "AFC8503"		
		COM port of the CPU	RS-232C	-	Wiring diagram 3 - COM2		
	FP2 FP2SH	Tool port of the CPU	RS-232C	-	Panasonic's "AFC8503"		
		COM port of the CPU	RS-232C	-	Wiring diagram 2 - COM2		
	FPΣ	Tool port of the CPU		RS-232C	-		Panasonic's "AFC8503"
		AFPG801	COM1	RS-232C	-		Wiring diagram 4 - COM2
		AFPG802	COM1, C2	RS-232C	-		Wiring diagram 5 - COM2
		AFPG803	COM1	RS-485	Wiring diagram 2 - COM1		-
		AFPG806	COM1	RS-485	Wiring diagram 1 - COM1		-
	COM2		RS-232C	-	Wiring diagram 3 - COM2		
	FP-e	Tool port of the CPU		RS-232C	-		Panasonic's "AFC8503"
		COM port of the CPU		RS-232C	-		Wiring diagram 3 - COM2
	FP-X	Tool port of the CPU		RS-232C	-		Panasonic's "AFC8503"
		AFPX-COM1	COM1	RS-232C	-		Wiring diagram 4 - COM2
		AFPX-COM2	COM1, C2	RS-232C	-		Wiring diagram 5 - COM2
		AFPX-COM3	COM1	RS-485	Wiring diagram 1 - COM1		-
		AFPX-COM4	COM1	RS-485			
			COM2	RS-232C	-		Wiring diagram 3 - COM2

\*1 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".

## 13.1.1 MEWNET

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> : 1 / 1 : n / Multi-link / Multi-link2	
Signal Level	RS-232C / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115k bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Odd</u> / Even	
Target Port No.	0 to 31	

#### PLC

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor.

#### FP-X

##### Tool port setting

System Register *1	Contents	
410	Unit No.	<u>1</u> to 99
412	Communication Mode	<b>Computer link</b>
413	Data Length	7 / <u>8</u> bits
	Parity	None / <u>Odd</u> / Even
	Stop Bit	<u>1</u> / 2 bits
415	Baud Rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 / 115k bps

\*1 System register setting is enabled in the RUN mode.

##### COM port setting

System Register *1		Contents	
COM1	COM2		
410	411	Unit No.	<u>1</u> to 99
412		Communication Mode	<b>Computer link</b>
413	414	Data Length	7 / <u>8</u> bits
		Parity	None / <u>Odd</u> / Even
		Stop Bit	<u>1</u> / 2 bits
415		Baud Rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 / 115k bps *2

\*1 System register setting is enabled in the RUN mode.

\*2 For AFPX COM3, set the switch attached to the back of the cassette as well.  
SW1 to 3: ON (RS-485), SW4: ON (terminator ON)

\*3 Some restrictions may apply to the communication cassette when the USB port is used on the CPU. For more information, refer to the PLC manual issued by the manufacturer.

#### P-Σ

##### Tool port setting

System Register *1	Contents	
410	Unit No.	<u>1</u> to 99
413	Data Length	7 / <u>8</u> bits
	Parity	None / <u>Odd</u> / Even
	Stop Bit	<u>1</u> / 2 bits
415	Baud Rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 / 115k bps

\*1 System register setting is enabled in the RUN mode.

## COM port setting

System Register *1		Contents	
COM1	COM2		
410	411	Unit No.	1 to 99*3
412		Communication Mode	<b>Computer link</b>
413		Data Length	7 / <u>8</u> bits
		Parity	None / <u>Odd</u> / Even
		Stop Bit	<u>1</u> / 2 bits
415		Baud Rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 / 115k bps *2

\*1 System register setting is enabled in the RUN mode.

\*2 For AFPG806COM1, set the switch attached to the back of the cassette as well.  
SW1 to 2: OFF 19200 bps, ON 115 kbps

\*3 In addition to system register setting, the station number setting is also possible with the station number setting switch. For more information, refer to the PLC manual issued by the manufacturer.

## FP1 / FP0 / FP-e

### Tool port setting

System Register *1		Contents	
411		Data Length	7 / <u>8</u> bits
414		Baud Rate	<u>9600</u> / 19200 bps
-		Parity	Odd (fixed)
-		Stop Bit	1 (fixed)

\*1 System register setting is enabled in the RUN mode.

## COM port setting

System Register *1		Contents	
412		Communication Mode	<b>Computer link</b>
413		Data Length	7 / <u>8</u> bits
		Parity	None / <u>Odd</u> / Even
		Stop Bit	<u>1</u> / 2 bits
414		Baud Rate	4800 / <u>9600</u> / 19200 bps
415		Unit No.	<u>1</u> to 99

\*1 System register setting is enabled in the RUN mode.

## FP2

### Tool port setting

System Register *1		Contents	
411		Data Length	7 / <u>8</u> bits
414		Baud Rate *2	4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115200 bps
-		Parity	Odd (fixed)
-		Stop Bit	1 (fixed)

\*1 System register setting is enabled in the RUN mode.

\*2 Enabled when the DIP switch 1 on the back of the CPU unit is set to the OFF position.

## COM port setting

System Register *1		Contents	
412		Communication Mode	<b>Computer link</b>
413		Data Length	7 / <u>8</u> bits
		Parity	None / <u>Odd</u> / Even
		Stop Bit	<u>1</u> / 2 bits
414		Baud Rate	4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115200 bps
415		Unit No.	<u>1</u> to 99

\*1 System register setting is enabled in the RUN mode.



**FP10/FP10s (COM Port)****Operation mode setting switch**

Switch	Setting	Contents
4	OFF	Baud rate: 19200 bps
5	ON	Data length: 8 bits
6	ON	With parity
7	OFF	Odd
8	OFF	Stop bit 1

**Station number setting switch**

Switch		Setting
The tens place	The ones place	<u>0</u> 1 to 32

**FP10SH (COM Port)****Operation mode setting switch (upper)**

Switch	Setting	Contents
1	OFF	Not control with a modem
2	OFF	Beginning code STX invalid
3	OFF	Terminating code CR
4	ON	
5	ON	Stop bit 1
6	ON	Odd parity
7	ON	
8	ON	Data length: 8 bits

**Operation mode setting switch (lower)**

Switch	Setting	Contents
6	ON	Baud rate: 19200 bps
7	ON	
8	OFF	

**Station number setting switch (lower)**

Switch		Setting
The tens place	The ones place	<u>0</u> 1 to 32

**AFP3462 / AFP5462 (CCU)****DIP switch setting**

Switch	Setting	Contents
1	ON	Baud rate: 19200 bps
2	OFF	
3	OFF	
4	ON	Data length: 8 bits
5	ON	With parity
6	OFF	Odd
7	OFF	Stop bit 1
8	OFF	CS, CD invalid

## AFP3463 (C-NET Link Unit)

### DIP switch setting

Switch	Setting	Contents
1	OFF	Baud rate: 19200 bps
2	ON	Data length: 8 bits
3	ON	With parity
4	OFF	Odd
5	OFF	Stop bit 1
6	OFF	-
7	OFF	-
8	OFF	-

## Available Memory

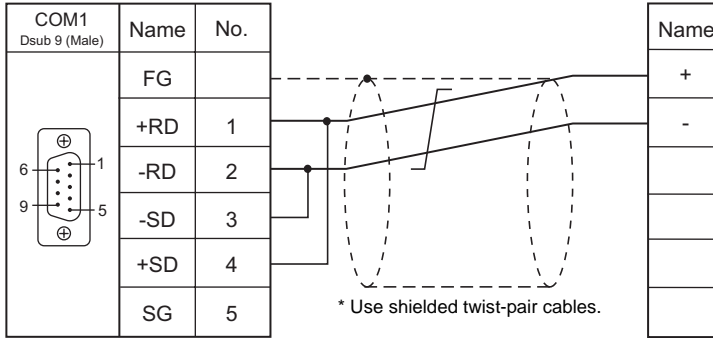
The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
DT (data register)	00H	
X (external input)	01H	WX as word device, read only
Y (external output)	02H	WY as word device
R (internal relay)	03H	WR as word device, including special relays
L (link relay)	04H	WL as word device
LD (link register)	05H	
FL (file register)	06H	FP2, 3, 5, 10 only
SV (timer, counter/set value)	07H	
EV (timer, counter/elapsed time)	08H	
T (timer/contact)	09H	Read only
C (counter/contact)	0AH	Read only

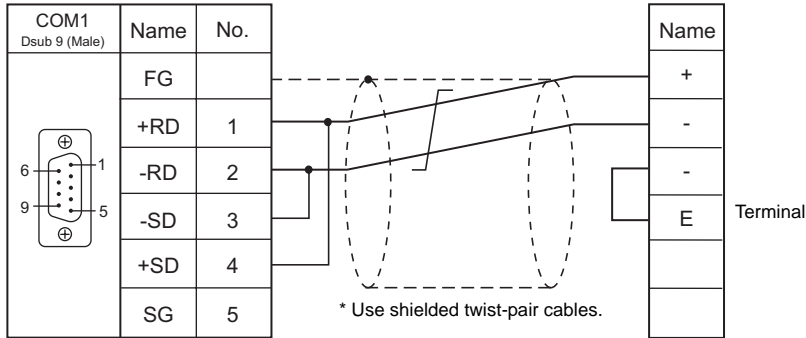
### 13.1.2 Wiring Diagrams

#### When Connected at COM1 (RS-422 / RS-485):

Wiring diagram 1 - COM1

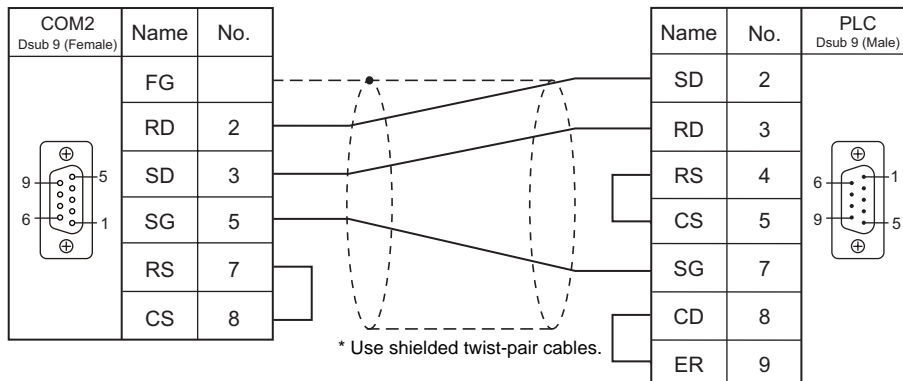


Wiring diagram 2 - COM1

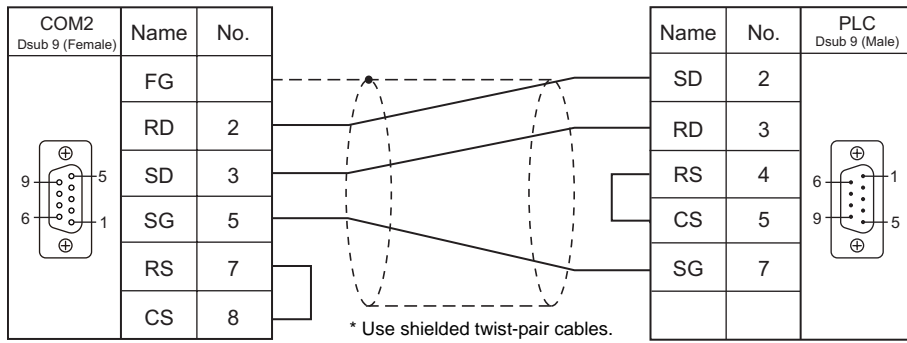


#### When Connected at COM2 (RS-232C):

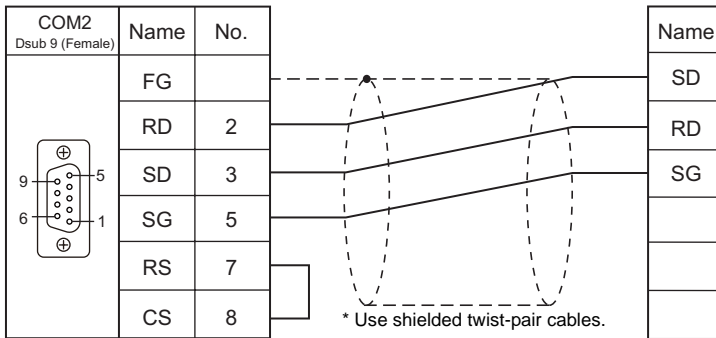
Wiring diagram 1 - COM2



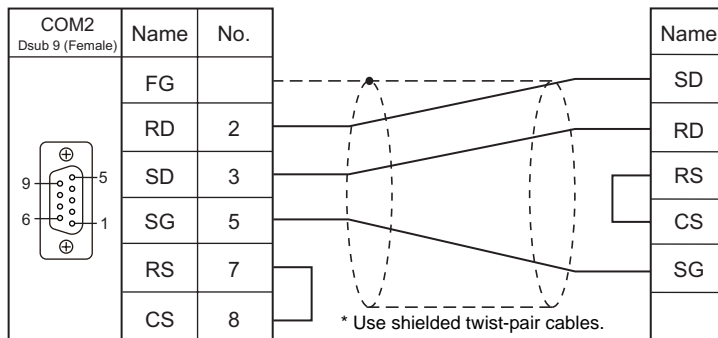
**Wiring diagram 2 - COM2**



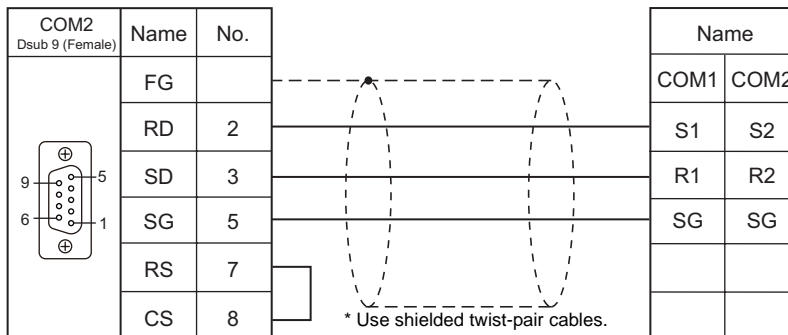
**Wiring diagram 3 - COM2**



**Wiring diagram 4 - COM2**



**Wiring diagram 5 - COM2**



MEMO

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# 14. RKC

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## 14.1 Temperature Controller/Servo/Inverter Connection



# 14.1 Temperature Controller/Servo/Inverter Connection

## Serial Connection

### Module-type Temperature Controller

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
SR-Mini (MODBUS RTU)	H-PCP-A-x4N-4 * xx Z-1021	Modular connector 1/2	RS-422A	Wiring diagram 2 - COM1	-	SR-Mini.Lst
	H-PCP-B-x4N-4 * xx Z-1021					
SR-Mini (Standard Protocol)	H-PCP-A-x4N-4 * xx	Modular connector 1/2	RS-422A	Wiring diagram 2 - COM1	-	RKC_Std.Lst
	H-PCP-B-x4N-4 * xx					
SRV (MODBUS RTU)	V-TIO-A-xxxx-xx*xxx-xx -x-6	Communication terminal	RS-485 (2-wire system)	Wiring diagram 1 - COM1	-	RKC_SRV.Lst
	V-TIO-C-xxxx-xx*xxx-x x-x-6					
SRZ (MODBUS RTU)	Z-TIO-A-x-xxxx/x2-x xxx/Y <sup>*1</sup>	Communication terminal	RS-485 (2-wire system)	Wiring diagram 1 - COM1	-	RKC_SRZ_TI O.Lst
	Z-TIO-B-x-xx/xN2-xxxx/ Y <sup>*1</sup>					RKC_SRZ_DI O.Lst
	Z-DIO-A-x-xx/x-xxx2					

\*1 Select a model on which Modbus communication is available.  
 \*2: Modbus\* for the communication protocol is selectable in the initial setting code when "specify quick start code 1 and 2" is selected as the quick start code.

### Single Loop Temperature Controller

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
CB100/CB400/ CB500/CB700/ CB900 (MODBUS RTU)	CB100xxxx-xx*xx-5x/x Z-1021	Communication terminal	RS-485	Wiring diagram 1 - COM1	-	CB100.Lst
	CB400xxxx-xx*xx-5x/x Z-1021					
	CB500xxxx-xx*xx-5x/x Z-1021					
	CB700xxxx-xx*xx-5x/x Z-1021					
	CB900xxxx-xx*xx-5x/x Z-1021					

### Multi-loop Temperature Controller

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
MA900/MA901 (MODBUS RTU)	MA900-4xxxx-xx-x*xxx- x6/x	Communication terminal	RS-485	Wiring diagram 1 - COM1	-	RKC_MA900.Lst
	MA901-8xxxx-xx-x*xxx- x6/x					RKC_MA901.Lst



## 14.1.1 CB100/CB400/CB500/CB700/CB900 (MODBUS RTU)

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Parity	<u>None</u> / Odd / Even	
Data Length	8 bits	
Stop Bit	1 bit	
Target Port No.	1 to 31	

#### CB100

##### Communication setting mode

When the [R/S] key is pressed while the [SET] key is held down in the PV/SV display mode, the controller enters in the "communication setting" mode.

(Underlined setting: default)

Indication	Item	Setting	Remarks
Add	Slave address	1 to 31	Communication is not performed when "0" is set.
bPS	Baud rate	1: 4800 bps <u>2: 9600 bps</u> 3: 19200 bps	
blT	Data configuration	<u>0: 8 bits / 1 bit / none</u> 6: 8 bits / 1 bit / even 7: 8 bits / 1 bit / odd	
InT	Interval time setting	0 to 150	Interval time = set value × 1.666 ms

### Available Memory

The available memory setting range varies depending on the controller model. Be sure to set within the range available for the controller. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
---	00H	

## 14.1.2 SRV (MODBUS RTU)

### Communication Setting

#### Editor

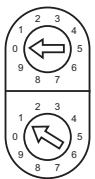
#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	9600 / 19200 / <u>38400</u> bps	
Data Length	8 bits	
Stop Bit	1 bit	
Parity	<u>None</u> / Odd / Even	
Target Port No.	1 to 31	

#### SRV

#### Address setting switch

Switch	Setting	Remarks
	<u>00</u> to 30	<p>Higher-order digit setting (× 10) Lower-order digit setting (× 1)</p> <p>The number that is one greater than the set value is the address.</p>

#### DIP switch setting

Switch	Setting	Contents	Remarks
1	ON	Baud rate: 38400 bps	ON, OFF: 9600 bps OFF, ON: 19200 bps
2	ON		
3	ON	Data bit configuration 8 bits / 1 bit / without parity	ON, OFF, ON: 8 bits / 1 bit / even ON, ON, ON: 8 bits / 1 bit / odd
4	OFF		
5	OFF		
6	ON	Protocol: Modbus	
7	OFF	-	
8	OFF	-	

\* Communication time settings (send changeover time/data interval delay time) can be made using the switches 4, 5, and 6. For more information, refer to the communication instruction manual for SRV.

### Available Memory

The available memory setting range varies depending on the controller model. Be sure to set within the range available for the controller. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
---	00H	

## 14.1.3 SR-Mini (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)


Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	<u>9600</u> / 19200 bps	
Data Length	8 bits	
Stop Bit	1 bit	
Parity	<u>None</u> / Odd / Even	
Target Port No.	1 to 16	

#### SR-Mini

#### DIP switch

Switch	Setting	Contents	Remarks
1	ON	Modbus communication 8 bits / 1 bit / without parity	OFF, ON: 4800 bps ON, ON: 19200 bps
2	ON		
3	ON	Baud rate: 9600 bps	
4	OFF		

#### Slave address setting switch

Switch	Setting	Remarks
	<u>8</u> to F (= 1 to 16)	The number that is one greater than the set value is the address.

### Available Memory

The available memory setting range varies depending on the controller model. Be sure to set within the range available for the controller. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
---	00H	

## 14.1.4 SR-Mini (Standard Protocol)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)


Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	<u>9600</u> / 19200 bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	<u>None</u> / Odd / Even	
Target Port No.	0 to 15	

#### SR-Mini

#### DIP switch

Switch	Setting	Contents	Remarks
1	ON	8 bits / 1 bit / without parity	OFF, ON: 7 bits, even parity ON, OFF: 7 bits, odd parity
2	ON		
3	ON	Baud rate: 9600 bps	OFF, ON: 4800 bps ON, ON: 19200 bps
4	OFF		

#### Unit address setting switch

Switch	Setting	Remarks
	<u>Q</u> to F (= 0 to 15)	

### Available Memory

The available memory setting range varies depending on the controller model. Be sure to set within the range available for the controller. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
---	00H	

## 14.1.5 MA900 / MA901 (MODBUS RTU)

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> bit	
Parity	<u>None</u> / Odd / Even	
Target Port No.	1 to 31	

#### MA900/MA901

##### Setup setting mode

When the [R/S] key is pressed while the [SET] key is held down in the PV/SV monitor mode, the controller enters in the "setup setting" mode.

(Underlined setting: default)

Indication	Item	Setting	Remarks
Add	Slave address	1 to 31	Communication is not performed when "0" is set.
bPS	Baud rate	1: 4800 bps <u>2: 9600 bps</u> 3: 19200 bps	
bIT	Data configuration	<u>0: 8 bits / 1 bit / none</u> 2: 8 bits / 1 bit / even 4: 8 bits / 1 bit / odd	
InT	Interval time setting	0 to 250	Interval time = set value × 1.666 ms

### Available Memory

The available memory setting range varies depending on the controller model. Be sure to set within the range available for the controller. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
---	00H	

## 14.1.6 SRZ (MODBUS RTU)

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)


Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 bps	
Data Length	8 bits	
Stop Bit	1 bit	
Parity	<u>None</u> / Odd / Even	
Target Port No.	Z-TIO: 1 to 16 Z-DIO: 17 to 31	Default: 1

#### SRZ

#### DIP switch

Switch	Setting	Contents	Remarks
1	OFF	Baud rate: 19200 bps	OFF, OFF: 4800 bps ON, OFF: 9600 bps OFF, ON: 19200 bps ON, ON: 38400 bps
2	ON		
3	OFF	Data bit configuration 8 bits / without parity / 1 bit	OFF, ON, ON: 8 bits / even / 1 bit ON, ON, ON: 8 bits / odd / 1 bit
4	OFF		
5	ON		
6	ON	Protocol: Modbus	
7	OFF	-	
8	OFF	-	

#### Slave address setting switch

Switch	Setting	Remarks
	Q to F	For Z-TIO, the number that is one greater than the set value is the address. (Range: 1 to 16)  For Z-DIO, the number that is seventeen greater than the set value is the address. (Range: 17 to 32)

\* For connection to S8, the available address setting range is 0 to E (17 to 31).

### Available Memory

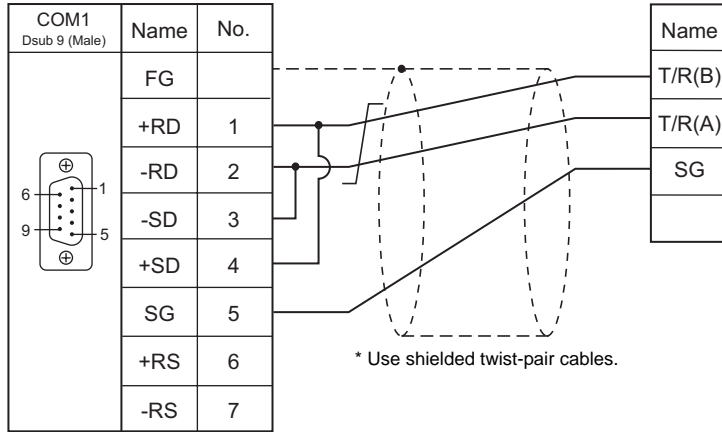
The available memory setting range varies depending on the controller model. Be sure to set within the range available for the controller. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
---	00H	

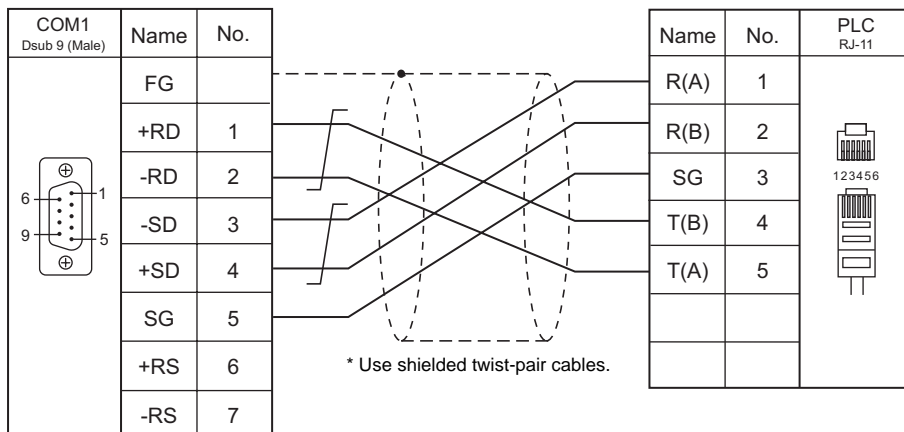
### 14.1.7 Wiring Diagrams

#### When Connected at COM1 (RS-422 / RS-485):

**Wiring diagram 1 - COM1**



**Wiring diagram 2 - COM1**



# 15. SAIA

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## 15.1 PLC Connection





# 15.1 PLC Connection

## Serial Connection

PLC Selection on the Editor	CPU	Unit/Port	Signal Level	Connection		Ladder Transfer *1
				COM1	COM2	
PCD	PCD1.M120	PGU port	RS-232C	-	Wiring diagram 1 - COM2	×
	PCD1.M130	PCD7.F120	RS-232C	-	Wiring diagram 2 - COM2	
	PCD2.M120					
	PCD2.M130	PCD7.F110	RS-422	Wiring diagram 1 - COM1	-	
	PCD2.M170					
	PCD2.M480					

\*1 For the ladder transfer function, see "Appendix 5 Ladder Transfer Function".

## 15.1.1 PCD

### Communication Setting

#### Editor

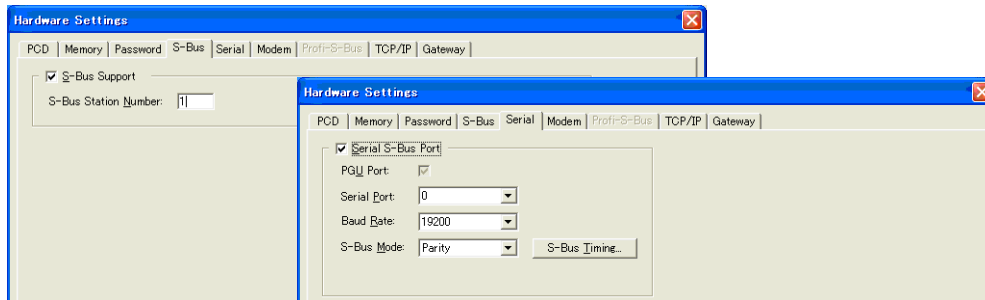
#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / 1 : n / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	9600 / <u>19200</u> / 38400 / 57600 / 115K bps	
Data Length	8 bits	
Stop Bit	1 bits	
Target Port No.	1	

#### PLC

#### PCD



Item	Setting	Remarks
S-Bus Station Number	1	
Serial Port	0: PGU Port 1: PCD7.F120 / F110	
Baud Rate	19200 bps	
S-Bus Mode	Parity	

### Available Memory

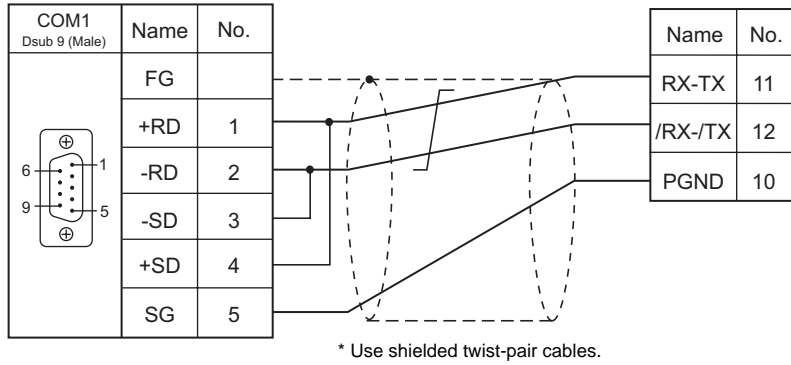
The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
R (register)	00H	Double-word
Rfp (register/floating point)	01H	Double-word
T (timer)	02H	Double-word
C (counter)	03H	Double-word
I (input)	04H	Read only
O (output)	05H	
F (flag)	06H	

## 15.1.2 Wiring Diagrams

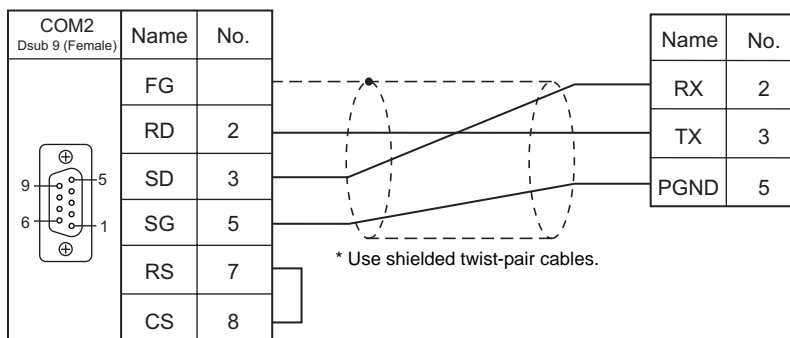
### When Connected at COM1 (RS-422 / RS-485):

Wiring diagram 1 - COM1

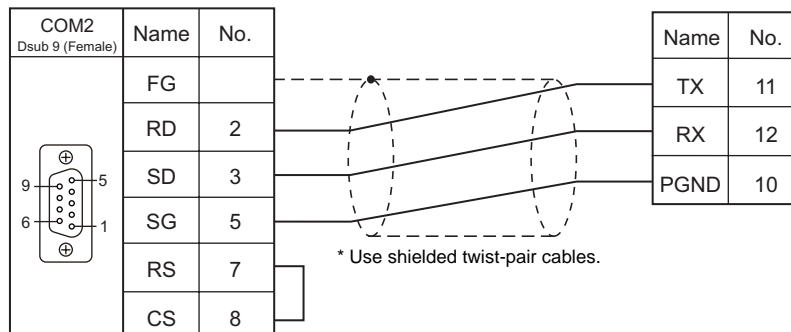


### When Connected at COM2 (RS-232C):

Wiring diagram 1 - COM2



Wiring diagram 2 - COM2



# MEMO

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# 16. Siemens

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## 16.1 PLC Connection



# 16.1 PLC Connection

## Serial Connection

PLC Selection on the Editor	CPU	Unit/Port	Signal Level	Connection		Ladder Transfer <sup>*1</sup>
				COM1	COM2	
S7-200PPI	CPU 226 CPU 224 CPU 222 CPU 221 CPU 216 CPU 215 CPU 214 CPU 212	PPI	RS-422			
S7-300/400MPI	CPU 312 CPU 312C CPU 313C CPU 313C-2 DP CPU 314 CPU 314C-2 DP CPU 315-2 DP CPU 315-2 PN/DP CPU 315F-2 DP CPU 317-2 DP CPU 317-2 PN/DP CPU 317F-2 DP CPU 319-3 PN/DP CPU 412-1 CPU 412-2 CPU 414-2 CPU 414-3 CPU 416-2 CPU 416-3 CPU 417-4	MPI (MPI/DP)	RS-422	Wiring diagram 1 - COM1	-	×

\*1 For the ladder transfer function, see Appendix 4 Ladder Transfer Function.



## 16.1.1 S7-200PPI

### Communication Setting

#### Editor

#### Communication setting (PLC1)

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / 1 : n / Multi-link2	
Signal Level	RS-422/485	
Baud Rate	<u>9600</u> / 19200 / 187.5k bps	For S806M10D, 187.5k bps communication is not available.
Data Length	<b>8 bits</b>	
Stop Bit	<b>1 bit</b>	
Parity	<b>Even</b>	
Target Port No.	1 to 31 ( <u>2</u> )	

#### S7-200

Make the setting for communication using the ladder tool "STEP 7 MicroWIN".

#### System block

(Underlined setting: default)

Item	Setting	Remarks
PLC Address	1 to 31 ( <u>2</u> )	Numbers from 1 to 126 can be specified, however, communication with S8 cannot be established when a number from 32 to 126 is specified.
Highest Address	1 to <u>31</u>	
Baud Rate	<u>9.6k</u> / 19.2k / 187.5k bps	

The following settings are fixed; data length: 8 bits, stop bit: 1 bit and parity: even.

### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
V (data memory)	00H	VW as word device
I (input)	01H	IW as word device, possible to write to the unused area
Q (output)	02H	QW as word device
M (bit memory/internal relay)	03H	MW as word device
T (timer/current value)	04H	
C (counter/current value)	05H	
HC (high-speed counter/current value)	08H	Double-word usable
AIW (analog input)	09H	
AQW (analog output)	0AH	
SM (special memory/special relay)	0BH	SMW as word device
S (stage)	0CH	SW as word device

## 16.1.2 S7-300/400MPI

### Communication Setting

#### Editor

#### Communication setting (PLC1)

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> :1 / 1 : n	A maximum of four MPI-capable units can be connected.
Signal Level	<b>RS-422/485</b>	
Baud Rate	<u>19200</u> / 187.5k bps	For S806M10D, 187.5k bps communication is not available.
Data Length	<b>8 bits</b>	
Stop Bit	<b>1 bit</b>	
Parity	<b>Even</b>	
Target Port No.	0 to 31 ( <u>2</u> )	Specify the MPI station number of S7-300/400.

#### MPI setting

(Underlined setting: default)

Item	Setting	Remarks
Highest MPI Address	<u>15</u> / 31 / 63 / 126	Specify the highest address in the MPI network.
Local Port No.	0 to 126 ( <u>3</u> )	Specify the port number of S8. It must be a unique number.

#### S7-300/400MPI

Specify the MPI address and the baud rate using "SIMATIC Manager". For more information, refer to the PLC manual issued by the manufacturer.

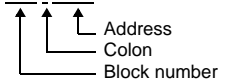
### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
DB (data word)	00H	Use memory address DB1 and later.
I (input)	01H	IW as word device
Q (output)	02H	QW as word device
M (marker word)	03H	MW as word device
T (timer/current value)	04H	
C (counter/current value)	05H	

The assigned memory is indicated when editing the screen as shown on the right.

Example: DB001 : 0000



#### Indirect Memory Designation

- DB device

	15	8 7	0
n + 0	9x (x = 1 to 2)		00
n + 1	Block number	Address number (word designation)	
n + 2	00		Block number
n + 3	Expansion code		Bit designation
n + 4	00		Station number

### 16.1.3 Wiring Diagrams

We recommend the following cable and the connectors for cable configuration. For more information, refer to related documents issued by Siemens.

- Recommended cable

Manufacturer	Model
Siemens	6XV1 830-0EH10

- Recommended connector

Manufacturer	Model	Remarks			
Siemens	6ES7 972-0BA50-0XA0	Fast Connect	For vertical wiring 90-degree angle of outgoing cable		
	6ES7 972-0BB50-0XA0		Without PG I/F		
	6ES7 972-0BA60-0XA0		With PG I/F		
	6ES7 972-0BB60-0XA0		For vertical wiring 35-degree angle of outgoing cable		
	6GK1 500-0FC00		Without PG I/F		
			For horizontal wiring	With PG I/F	-

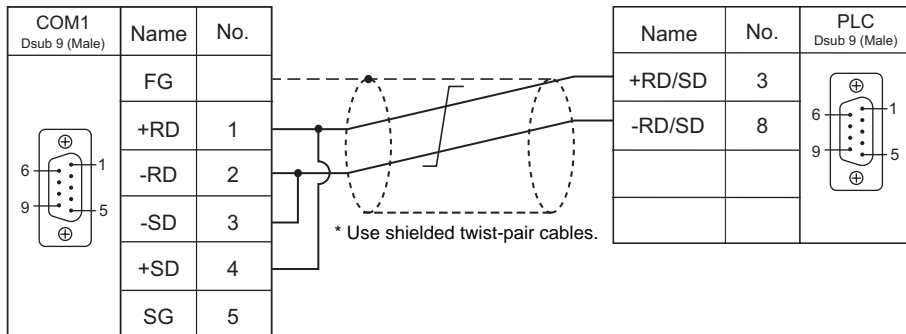
### When Connected at COM1 (RS-422 / RS-485):

#### Terminating resistance

Set the DIP switches 3 and 4 of the S8 unit to the ON position\*1, and set the terminating resistance by referring to "Terminating resistance setting" described below.

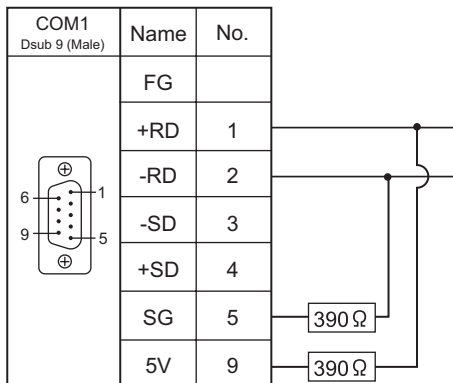
\*1 S806M10D is not equipped with DIP switches. Therefore, the terminating resistance of COM1 is always set to ON.

#### Wiring diagram 1 - COM1



#### Terminating resistance setting

Set the DIP switch of the S8 unit to the ON position and connect the terminating resistance to COM1 as shown below. If the terminating resistance is not connected, a communication error may occur.



# 17. Yamatake

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## 17.1 Temperature Controller/Servo/Inverter Connection



# 17.1 Temperature Controller/Servo/Inverter Connection

## Serial Connection

### Digital Indicating Controller

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
SDC35/36	SDC35xxxxx2xx SDC35xxxxx4xx SDC36xxxxx2xx SDC36xxxxx4xx	Terminal on the back	RS-485	Wiring diagram 1 - COM1	-	SDC36.Lst
	SDC15Txxxx03xx SDC15Txxxx06xx SDC25Txxxx2xx SDC26Txxxx2xx					None*1

\*1 Enter addresses manually by referring to the instruction manual for the controller.

### Module-type Controller

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
DMC10	DMC10S DMC10D	CPL communication terminal	RS-485	Wiring diagram 1 - COM1	-	DMC10.Lst
DMC50 (COM)	DMC50ME20X DMC50MR20X	RS-485 port 1	RS-485	Wiring diagram 2 - COM1	-	DMC50.Lst
		Display communication port	RS-485	Wiring diagram 3 - COM1	-	
	DMC50CH40X DMC50CH20X DMC50CS40X DMC50CS20X	Display communication port	RS-485			

## 17.1.1 SDC35/36

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>1</u> to 31	

#### Controller

##### CPL communication setting

(Underlined setting: default)

Item (Bank)	Indication	Setting	Remarks
Communication type (Setup bank)	C64	<u>0: CPL</u>	See "20. MODBUS".
Device address (Setup bank)	C65	1 to 127	Communication is disabled when "0" is set.
Baud rate (Setup bank)	C66	0: 4800 bps 1: 9600 bps <u>2: 19200 bps</u> 3: 38400 bps	
Data type: data length (Setup bank)	C67	0: 7 bits <u>1: 8 bits</u>	
Data type: parity (Setup bank)	C68	<u>0: Even</u> 1: Odd 2: None	
Data type: stop bit (Setup bank)	C69	<u>0: 1 bit</u> 1: 2 bits	

### Available Memory

The available memory setting range varies depending on the models. Be sure to set within the range available for the device. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
---	00H	

\* Addresses 16657 to 31243 are allocated for EEPROM data addresses.

The number of times EEPROM can be reprogrammed is limited (approx. 100000 times). As such, we recommend that you write such a parameter as to be reprogrammed frequently into RAM, where the number of reprogramming times is not limited. However, when the parameter has been written into RAM, and the power is turned off and back on, data in EEPROM is transferred.

For more information, refer to the instruction manual for the controller issued by the manufacturer.

## 17.1.2 DMC10

### Communication Setting

#### Editor


#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>1</u> to 31	

#### Controller

#### Rotary switch for device address

MODULE ADDRESS	Setting	Remarks
	1 to F	Communication is disabled when "0" is set.

#### CPL communication setting

Make the following settings on the PC loader. (Underlined setting: default)

Setting Items	Setting	Remarks
CPL/MODBUS	<u>0</u> : CPL	See "20. MODBUS".
Baud rate	1: 4800 bps 2: 9600 bps 3: <u>19200</u> bps	
Data type	<u>0</u> : 8 bits / 1 bit / even 1: 8 bits / 2 bits / none	

### Available Memory

The available memory setting range varies depending on the controller model. Be sure to set within the range available for the controller. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
---	00H	

\* Addresses 5000 to 8999 are allocated for EEPROM data addresses.

The number of times EEPROM can be reprogrammed is limited (approx. 100000 times). As such, we recommend that you write such a parameter as to be reprogrammed frequently into RAM, where the number of reprogramming times is not limited. However, when the parameter has been written into RAM, and the power is turned off and back on, data in EEPROM is transferred.

For more information, refer to the instruction manual for the controller issued by the manufacturer.



## 17.1.3 DMC50 (COM)

### Communication Setting

#### Editor


#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	<u>9600</u> / 19200 / 38400 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> bit	
Parity	<u>Even</u>	
Target Port No.	<u>1</u> to 16	When connecting to the COM module: Station number: COM module Sub-station number: CTRL module
Sub-station No.	<u>0</u> to 16	

#### Controller

#### Rotary address for module address

MODULE ADDRESS	Setting	Remarks
	1 to F	Communication is disabled when "0" is set.

#### COM module: RS-485 port 1

Make the following settings on the PC loader.

(Underlined setting: default)

Setting Items	Contents	Remarks
Baud rate (port 1)	<u>9600 bps</u> 19200 bps 38400 bps	
Protocol (port 1)	<u>1: CPL communication</u>	

#### CTRL module: Display communication port

Make the following settings on the PC loader.

(Underlined setting: default)

Setting Items	Contents	Remarks
Baud rate for display communication port	<u>9600 bps</u> 19200 bps 38400 bps	

\* The display communication port is a dedicated port for 1 : 1 communication.

## Available Memory

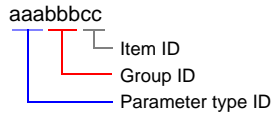
The available memory setting range varies depending on the controller model. Be sure to set within the range available for the controller. Use [TYPE] when assigning the indirect memory for macro programs.

Memory (Parameter Type ID)	TYPE	Remarks
000 (NA area)	00H	Double-word
001 (H/W information)	01H	Double-word, read only
002 (calendar time setting)	02H	Double-word
021 (AI setting) high-resolution monitor: for standard input	03H	Double-word
022 (AI setting) special monitor	04H	Double-word
023 (AI setting) high-resolution monitor: for option input	05H	Double-word
041 (AUX-IN setting)	06H	Double-word
045 (AO setting)	07H	Double-word
061 (DO setting)	08H	Double-word
071 (TP setting)	09H	Double-word
074 (zener barrier adjustment value)	0AH	Double-word
0A1 (communication setting: for ME200)	0BH	Double-word, read only
0A2 (communication setting: for MR200)	0CH	Double-word, read only
0A3 (communication setting: front port)	0DH	Double-word, read only
0C1 (system status)	0EH	Double-word, read only
0C3 (calendar time display)	0FH	Double-word, read only
0C4 (log: system alarm)	10H	Double-word
0C5 (log: AI alarm)	11H	Double-word
0C6 (log: AUX-IN alarm)	12H	Double-word
0E1 (AI status)	13H	Double-word, read only
0E2 (AUX-IN setting)	14H	Double-word, read only
0E3 (AO status)	15H	Double-word
0E5 (DI status)	16H	Double-word, read only
0E6 (AO status)	17H	Double-word
0E7 (TP status)	18H	Double-word
0E8 (zener barrier adjustment count)	19H	Double-word, read only
0F1 (communication setting in use: for ME200)	1AH	Double-word, read only
0F2 (communication setting in use: for MR200)	1BH	Double-word, read only
0F3 (communication setting in use: front port)	1CH	Double-word, read only
201 (PID_A setting)	1DH	Double-word
202 (PID_A constant)	1EH	Double-word
203 (PID_A monitor)	1FH	Double-word, read only
211 (PID_CAS setting)	20H	Double-word
212 (PID_CAS constant: master side)	21H	Double-word
213 (PID_CAS constant: slave side)	22H	Double-word
214 (PID_CAS monitor)	23H	Double-word, read only
234 (Ra_PID setting)	24H	Double-word
235 (Ra_PID constant)	25H	Double-word
236 (Ra_PID monitor)	26H	Double-word, read only
241 (UP_PID setting)	27H	Double-word
242 (UP_PID constant)	28H	Double-word
243 (UP_PID monitor)	29H	Double-word, read only
301 (TBL/TBR setting)	2AH	Double-word
801 (user-defined parameter)	2BH	Double-word
802 (user-defined parameter)	2CH	Double-word
803 (user-defined parameter)	2DH	Double-word
804 (user-defined parameter)	2EH	Double-word
805 (user-defined parameter)	2FH	Double-word
806 (user-defined parameter)	30H	Double-word
80D (user-defined parameter)	31H	Double-word
80E (user-defined parameter)	32H	Double-word
E01 (user-defined parameter)	33H	Double-word
E02 (user-defined parameter)	34H	Double-word
E04 (user-defined parameter)	35H	Double-word
E05 (user-defined parameter)	36H	Double-word
E06 (user-defined parameter)	37H	Double-word
E07 (user-defined parameter)	38H	Double-word
E08 (user-defined parameter)	39H	Double-word

Memory (Parameter Type ID)	TYPE	Remarks
E0A (user-defined parameter)	3AH	Double-word
E12 (user-defined parameter)	3BH	Double-word
E13 (user-defined parameter)	3CH	Double-word
E14 (user-defined parameter)	3DH	Double-word
E15 (user-defined parameter)	3EH	Double-word
610 (user-defined parameter)	3FH	Double-word

### Address denotations

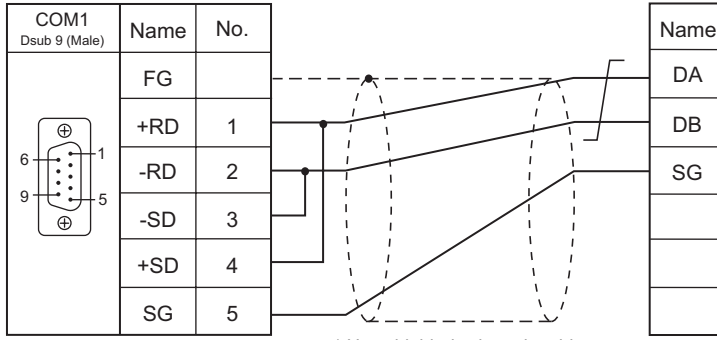
On the signal name reference list, every group ID is designated as "001". To access any group ID other than "001", input the desired ID via manual operation.



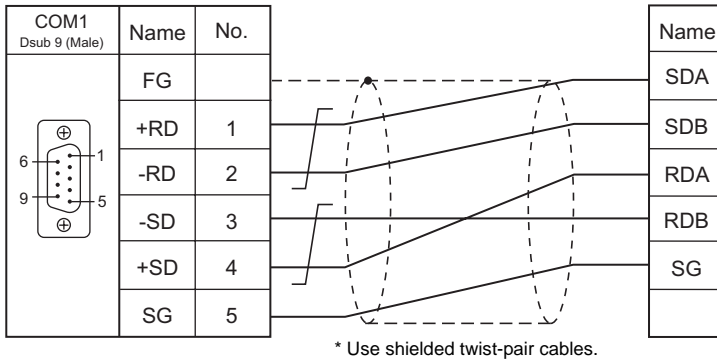
### 17.1.4 Wiring Diagrams

#### When Connected at COM1 (RS-422 / RS-485):

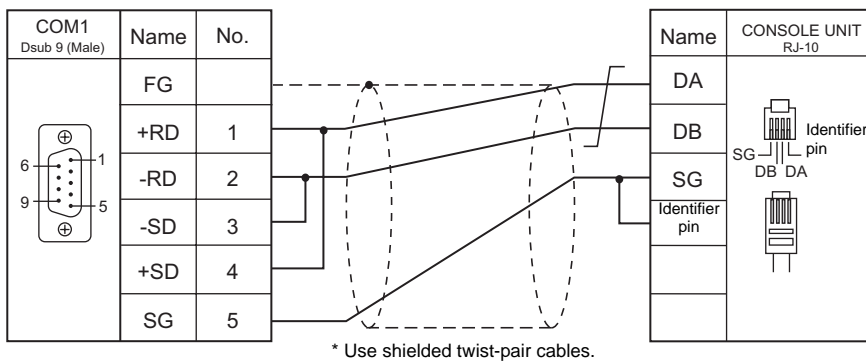
Wiring diagram 1 - COM1



Wiring diagram 2 - COM1



Wiring diagram 3 - COM1



# MEMO

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# 18. Yaskawa Electric

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## 18.1 PLC Connection



## 18.1 PLC Connection

The PLC models shown below can be connected.

### Serial Connection

PLC Selection on the Editor	CPU	Unit/Port		Signal Level	Connection		Ladder Transfer *1
					COM1	COM2	
Memobus	GL60 series	JAMSC-IF60 JAMSC-IF61 JAMSC-IF611		RS-232C	-	Wiring diagram 1 - COM2	
		JAMSC-IF612 JAMSC-IF613		RS-422	Wiring diagram 1 - COM1	-	
	GL120 GL130 series	Memobus port on the CPU module		RS-232C	-	Wiring diagram 1 - COM2	
		JAMSC-120NOM 27100		RS-422	Wiring diagram 2 - COM1	-	
	PROGIC-8	PORT2 on the CPU unit		RS-232C	-	Wiring diagram 2 - COM2	
CP9200SH/ MP900	CP9200SH	CP-217IF	CN1	RS-232C	-	Wiring diagram 1 - COM2	×
			CN2		-	Wiring diagram 3 - COM2	
			CN3	RS-422	Wiring diagram 3 - COM1	-	
	MP920 MP930	Memobus port on the CPU module		RS-232C	-	Wiring diagram 1 - COM2	
		217IF	CN1 CN2	RS-232C	-	Wiring diagram 1 - COM2	
			CN3	RS-422	Wiring diagram 4 - COM1	-	
	MP2200 MP2300 MP2300S	217IF-01 218IF-01	PORT	RS-232C	-	Wiring diagram 4 - COM2	
		217IF-01	RS422/485	RS-422	Wiring diagram 5 - COM1	-	

\*1 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".



## 18.1.1 Memobus

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> / 1 : n / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Data Length	8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>1</u> to 31	
Transmission Mode	<u>Type 1</u> / Type 2	For GL60 series or PROGIC-8: Type 1: special binary code For GL120/130 series: Type 2: standard binary code

#### PLC

Be sure to match the settings to those made on the [Communication Settings] tab window of the editor. For more information, refer to the PLC manual issued by the manufacturer.

Item	Setting	Remarks
Signal Level	RS-232C / RS-422	
Baud Rate	4800 / 9600 / 19200 bps	
Data Length	<b>8 bits</b>	RTU mode
Stop Bit	1 bit	
Parity	Even	
Station No.	1 to 31	
Error Check	<b>CRC</b>	
Port Delay Timer	<b>0</b>	

### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
4 (holding register)	00H	
3 (input register)	01H	Including constant register, read only
R (link register)	02H	
A (extension register)	03H	
0 (coil)	04H	
D (link coil)	05H	
1 (input relay)	06H	Read only
7 (constant register)	07H	

## 18.1.2 CP9200SH/MP900

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> : 1 / 1 : n / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 / 57600 / 76800 bps	
Data Length	8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>1</u> to 31	

#### PLC

#### CP-217IF

Be sure to match the settings to those made on the [Communication Settings] tab window of the editor.  
For more information on communication settings, refer to the PLC manual issued by the manufacturer.

#### Memobus Port on the CPU Module (MP920, MP930) / 217IF

#### Module configuration

Item	Setting	Remarks
Transmission Protocol	<b>Memobus</b>	
Master/Slave	<b>Slave</b>	
Device Address	1 to 31	
Serial I/F	RS-232	
Transmission Mode	<b>RTU</b>	
Data Length	<b>8 bits</b>	
Parity Bit	Even	
Stop Bit	1 stop	
Baud Rate	19.2K	For connection via RS-422 on "217IF", 76800 bps can also be selected. For more information, refer to the PLC manual issued by the manufacturer.

## 217IF-01, 218IF-01

### Module configuration

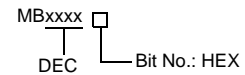
Item	Setting	Remarks
Transmission Protocol	<b>Memobus</b>	
Master/Slave	<b>Slave</b>	
Device Address	1	
Serial I/F	RS-232 / RS-485	
Transmission Mode	<b>RTU</b>	
Data Length	<b>8 bits</b>	
Parity Bit	Even	
Stop Bit	1 stop	
Baud Rate	19.2K	The maximum baud rate available is 76.8 kbps.
Automatic Reception	Specified / Not Specified	To speed up communications, select [Not Specified]. When [Not Specified] is selected, the MSG-RCV function is required. For more information, refer to the PLC manual issued by the manufacturer.
Automatic Reception Setting	As desired	Make the setting when [Specified] is selected for [Automatic Reception].

### Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
MW (holding register)	00H	MB as bit device
IW (input register)	01H	IB as bit device, read only
MB (coil)	04H	MW as word device
IB (input relay)	06H	IW as word device, read only

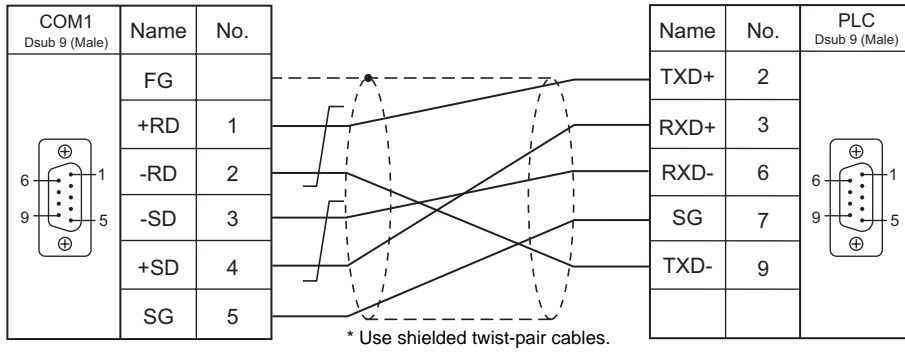
When setting the MB/IB memory, set the bit numbers in the hexadecimal notation.



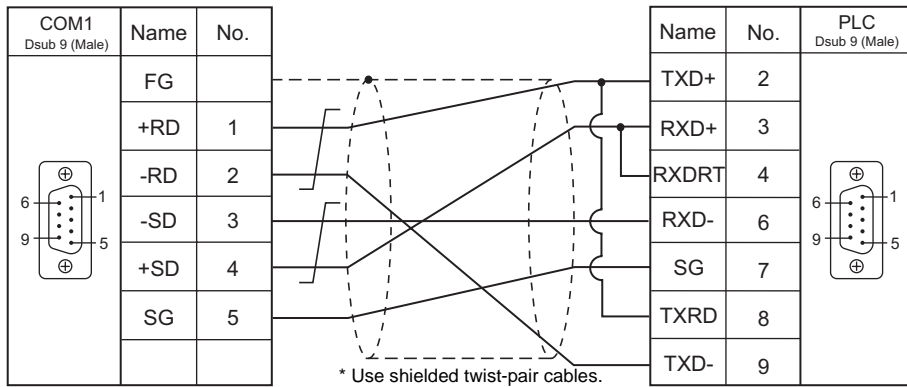
### 18.1.3 Wiring Diagrams

#### When Connected at COM1 (RS-422 / RS-485):

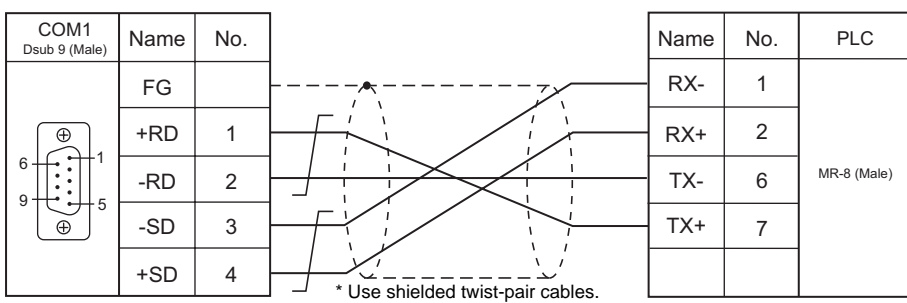
**Wiring diagram 1 - COM1**



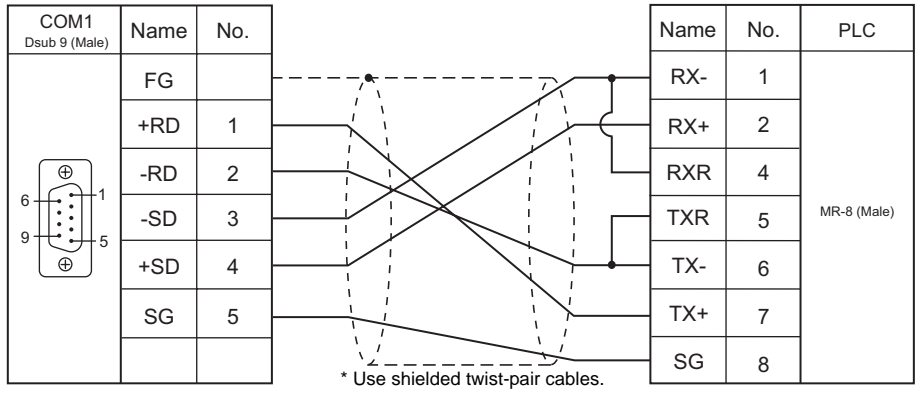
**Wiring diagram 2 - COM1**



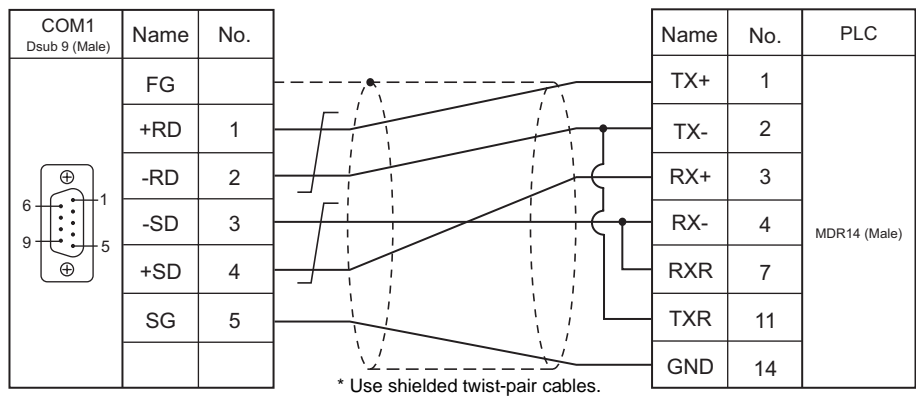
**Wiring diagram 3 - COM1**



**Wiring diagram 4 - COM1**

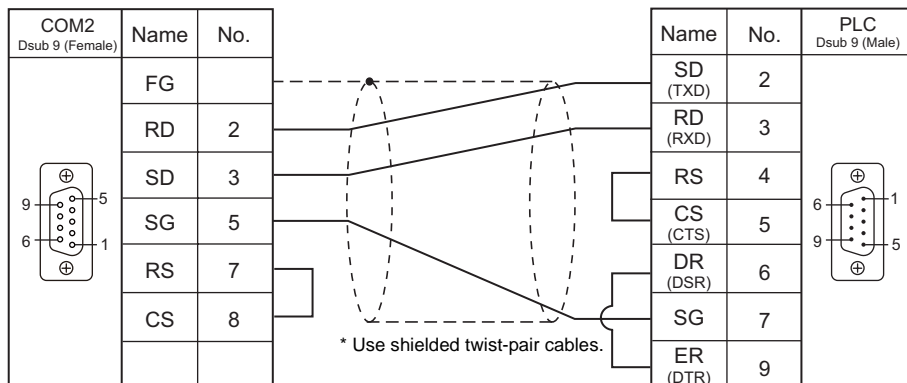


**Wiring diagram 5 - COM1**

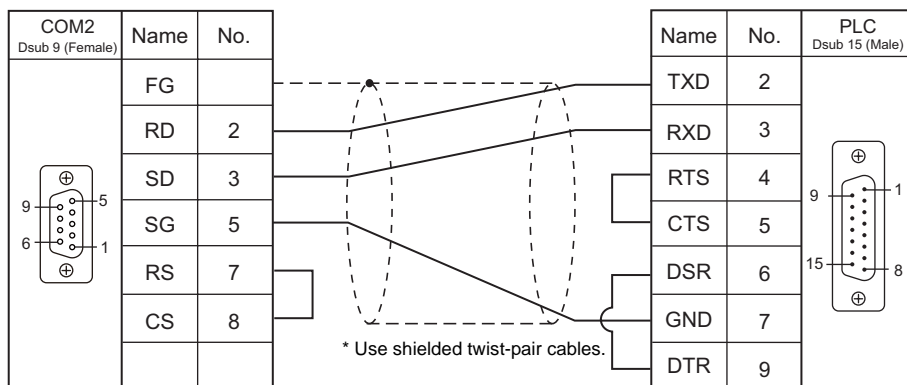


**When Connected at COM2 (RS-232C):**

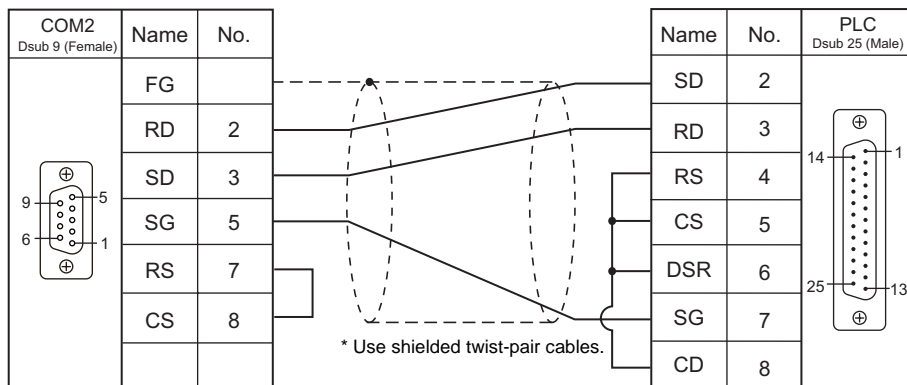
**Wiring diagram 1 - COM2**



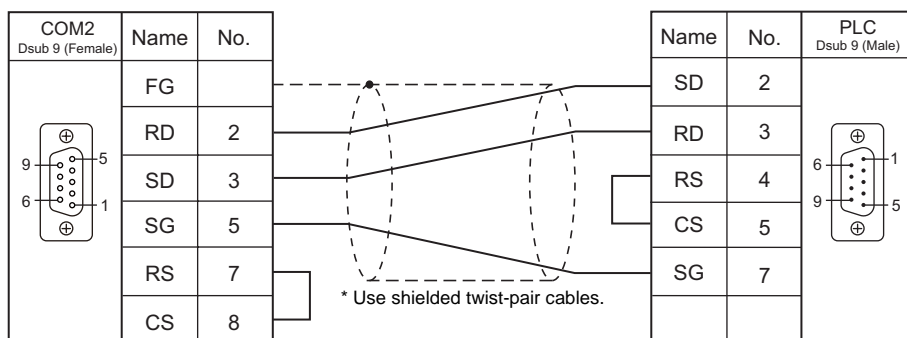
**Wiring diagram 2 - COM2**



**Wiring diagram 3 - COM2**



**Wiring diagram 4 - COM2**



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# 19. Yokogawa Electric

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19.1 PLC Connection

19.2 Temperature Controller/Servo/Inverter Connection





## 19.1 PLC Connection

The PLC models shown below can be connected.

### Serial Connection

PLC Selection on the Editor	CPU	Unit/Port	Signal Level	Connection		Ladder Transfer <sup>*2</sup>
				COM1	COM2	
FA-M3	F3SP21-0N F3SP25-2N F3SP35-5N	PROGRAMMER port	RS-232C	-	Yokogawa's "KM11-xT"	×
	F3SP20-0N F3SP21-0N F3SP25-2N F3SP35-5N	F3LC01-1N <sup>*1</sup>	RS-232C	-	Wiring diagram 1 - COM2	
		F3LC11-1N				
F3LC11-2N		RS-422	Wiring diagram 1 - COM1	-		
FA-M3R	F3SP28-3N/3S F3SP38-6N/6S F3SP53-4H/4S F3SP58-6H/6S F3SP59-7S	PROGRAMMER port	RS-232C	-	Yokogawa's "KM11-xT"	
	F3SP28-3N/3S F3SP38-6N/6S F3SP53-4H/4S F3SP58-6H/6S F3SP59-7S	F3LC11-1N F3LC11-1F F3LC12-1F	RS-232C	-	Wiring diagram 1 - COM2	
		F3LC11-2N F3LC11-2F	RS-422	Wiring diagram 1 - COM1	-	
	F3SP66-4S F3SP67-4S	SIO port	RS-232C	-	Yokogawa's "KM21-2T"	

\*1 When the link unit "F3LC01-1N" is used, the communication setting and available memory are the same as those for "FA-500". However, "B" (common register) cannot be used.

\*2 For the ladder transfer function, see "Appendix 4 Ladder Transfer Function".

## 19.1.1 FA-M3/FA-M3R

### Communication Setting

#### Editor

#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> : 1 / 1 : n / Multi-link / Multi-link2	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / 19200 / 38400 / 57600 / 76800 / <u>115K</u> bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Odd</u> / Even	
Target Port No.	<u>0</u> to 31	
Transmission Mode	With Sum Check / <u>Without Sum Check</u>	

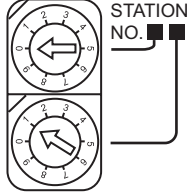
#### PLC

#### CPU Programmer Port / SIO Port

Item	Programmer port	SIO Port
Communication Mode	<u>9600 bps, even parity</u> 9600 bps, no parity 19200 bps, even parity 19200 bps, no parity 38400 bps, even parity 38400 bps, no parity 57600 bps, even parity 57600 bps, no parity 115200 bps, even parity 115200 bps, no parity	9600 bps, even parity 9600 bps, no parity 19200 bps, even parity 19200 bps, no parity 38400 bps, even parity 38400 bps, no parity 57600 bps, even parity 57600 bps, no parity <u>115200 bps, even parity</u> 115200 bps, no parity
PC Link Function	<b>Use</b>	
Sum check	Provided / <u>Not provided</u>	
Terminal Character	<b>None</b>	
Protection Function	<b>None</b>	
Data Length	<b>8</b>	


**PC Link Module**

**Station number setting**

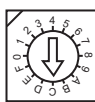
Station Number Setting	Setting	Setting Example
	01 to 32	01

**Baud rate setting switch**

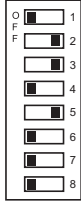
**F3LC01-1N / F3LC11-1N / F3LC11-2N**

Baud Rate Setting Switch	Setting	Baud Rate	Remarks
	4	4800 bps	
	5	9600 bps	
	6	19200 bps	

**F3LC11-1F / F3LC12-1F / F3LC11-2F**

Baud Rate Setting Switch	Setting	Baud Rate	Remarks
	4	4800 bps	
	5	9600 bps	
	6	14400 bps	
	7	19200 bps	
	8	28800 bps	
	9	38400 bps	
	A	5736 kbps	
	C	115.2 kbps	

**Data format setting switch**

Switch	Functions	OFF	ON	Setting Example
1	Data length	7	8	
2	Parity	Not provided	Provided	
3		Odd	Even	
4	Stop bit	1	2	
5	Sum check	Not provided	Provided	
6	Terminal character	Not provided	Provided	
7	Protection function	Not provided	Provided	
8	-	-	-	

**Function setting switch**

All OFF

## Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available with the PLC to be used. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
D (data register)	00H	
R (common register)	01H	
V (index register)	02H	
W (link register)	03H	
Z (special register)	04H	
TP (count-down timer/current value)	05H	
TS (timer/set value)	06H	Read only
CP (count-down counter/current value)	07H	
CS (counter/set value)	08H	
X (input relay)	09H	
Y (output relay)	0AH	
I (internal relay)	0BH	
E (common relay)	0CH	
L (link relay)	0DH	
M (special relay)	0EH	
B (file register)	0FH	

\* The CPU number is required in addition to the memory type and address. The assigned memory is indicated when editing the screen as shown on the right.

Example: 1 : D00001

Address  
Memory type  
CPU number

## PLC\_CTL

The user log can be read using the macro command "PLC\_CTL".

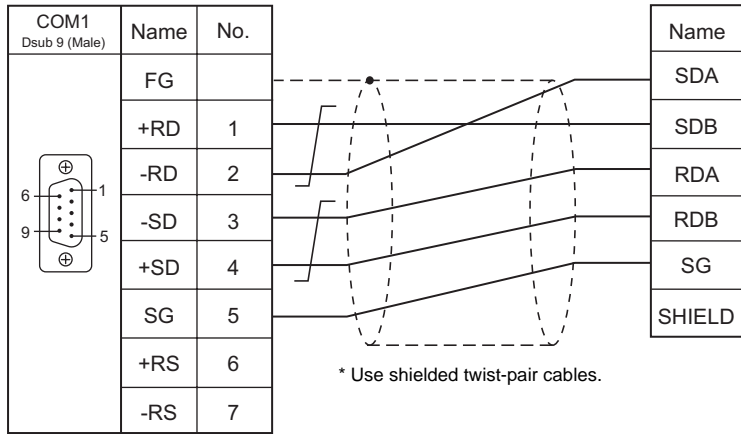
Contents	F0	F1 (= \$u n)		F2
User log registration number read	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	CPU No. CPU No. 1: 0 CPU No. 2: 1 CPU No. 3: 2 CPU No. 4: 3	
		n + 2	Command: -1	
		n + 3	Registration number (Stores the same number as the one stored in special register Z105.)	
Latest user log read	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	CPU No. CPU No. 1: 0 CPU No. 2: 1 CPU No. 3: 2 CPU No. 4: 3	
		n + 2	Command: 0	
		n + 3	Header 0: Normal -1: Error (data not exist/communication error)	
		n + 4	Year (ASCII)	
		n + 5	Month (ASCII)	
		n + 6	Day (ASCII)	
		n + 7	Hour (ASCII)	
		n + 8	Minute (ASCII)	
		n + 9	Second (ASCII)	
		n + 10	Main code (DEC)	
		n + 11	Sub code (DEC)	
"n"th user log read	1 - 2 (PLC1 - 2)	n	Station number	3
		n + 1	CPU No. CPU No. 1: 0 CPU No. 2: 1 CPU No. 3: 2 CPU No. 4: 3	
		n + 2	Command: 1 to 63	
		n + 3	Header 0: Normal -1: Error (data not exist/communication error)	
		n + 4	Year (ASCII)	
		n + 5	Month (ASCII)	
		n + 6	Day (ASCII)	
		n + 7	Hour (ASCII)	
		n + 8	Minute (ASCII)	
		n + 9	Second (ASCII)	
		n + 10	Main code (DEC)	
		n + 11	Sub code (DEC)	

Return data: Data stored from temperature controller to S8 series

## 19.1.2 Wiring Diagrams

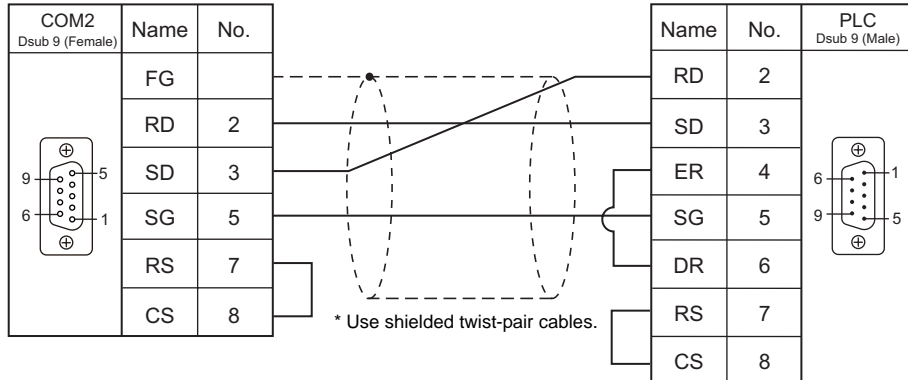
### When Connected at COM1 (RS-422 / RS-485):

Wiring diagram 1 - COM1



### When Connected at COM2 (RS-232C):

Wiring diagram 1 - COM2



## 19.2 Temperature Controller/Servo/Inverter Connection

The controllers shown below can be connected.

### Digital Indicating Controller

#### UT350/UT450 Series

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				COM1	COM2	
UT350	UT350-01 UT350-21 UT350-31	Communication terminal	RS-485	Wiring diagram 1 - COM1	-	UT350.Lst
UT450	UT450-01 UT450-02 UT450-11 UT450-12 UT450-21 UT450-22 UT450-31 UT450-32 UT450-41 UT450-42					UT450.Lst



## 19.2.1 UT350

### Communication Setting

#### Editor

##### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1:n</u> / Multi-link2	
Signal Level	<u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>1</u> to 31	
Transmission Mode *	With Sum Check / <u>Without Sum Check</u>	

\* Select "Without Sum Check" for the transmission mode on the editor when "1: PC link communication (with checksum)" is specified for P.SL (Protocol selection) on the controller.

#### Digital Indicating Controller

The communication parameter can be set using keys attached to the front of the controller.

Be sure to match the settings to those made on the [Communication Setting] tab window of the editor.

(Underlined setting: default)

Parameter	Display	Item	Setting	Example
Communication	P.SL	Protocol selection	<u>0: PC link communication</u> 1: PC link communication (with checksum) 2: Ladder communication 3: Coordinated master station 4: Coordinated slave station 7: MODBUS (ASCII) 8: MODBUS (RTU) 10: Coordinated slave station (loop-1 mode) 11: Coordinated slave station (loop-2 mode)	0
	bPS	Baud rate	3: 4800 bps <u>4: 9600 bps</u>	4
	PrI	Parity	0: None <u>1: Even</u> 2: Odd	1
	StP	Stop bit	<u>1</u> / 2 bits	1
	dLn	Data length	7 / <u>8</u> bits	8
	Adr	Address	<u>1</u> to 31	1

#### Available Memory

The available memory setting range varies depending on the models. Be sure to set within the range available for the device. Use [TYPE] when assigning the indirect memory for macro programs.

Memory	TYPE	Remarks
D (data register)	00H	
I (input relay)	01H	

#### Indirect Memory Designation

Specify the value subtracted "1" from the real memory address for the memory address No..

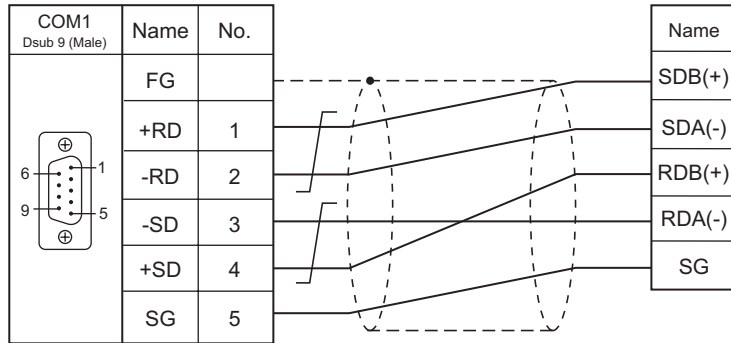
## 19.2.2 UT450

The communication setting and available memory are the same as those described in "19.2.1 UT350".

## 19.2.3 Wiring Diagrams

### When Connected at COM1 (RS-422 / RS-485):

Wiring diagram 1 - COM1



\* Use shielded twist-pair cables.

# MEMO

Please use this page freely.

# 20. MODBUS

---

## 20.1 PLC Connection



---

## 20.1 PLC Connection

---

### Serial Connection

---

The S8 series works as the Modbus RTU master station. It can be connected with devices that support Modbus RTU communication.

PLC Selection on the Editor	Applicable Device	Signal Level	Connection	
			COM1	COM2
MODBUS RTU	Modbus RTU slave device	RS-232C	-	Wiring diagram 1 - COM2
		RS-422	Wiring diagram 1 - COM1	-
		RS-485	Wiring diagram 2 - COM1	-

## 20.1.1 MODBUS RTU

### Communication Setting

#### Editor

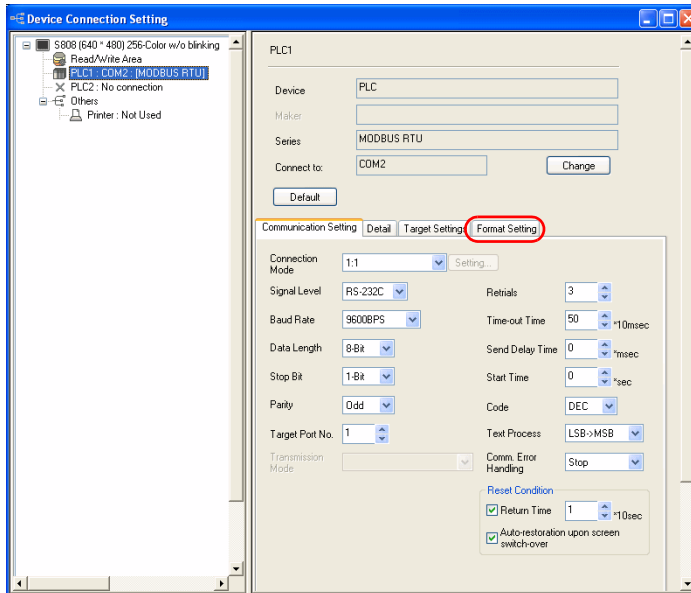
#### Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1</u> :1 / 1 : n / Multi-link2	
Signal Level	RS-232C / RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 / 115K bps	
Data Length	8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Odd</u> / Even	
Target Port No.	<u>1</u> to 255	

#### Format setting

Make communication format settings for each connected device.



No. 1 to 255	Port number of the connected device
Device connected	Select a connected device for each number. When creating screen data, you can set memory by referring to the list file of the device selected here.
Read Coil	Format setting Set the number of words to be read or written at one communication for each memory. The format setting also serves as the function code <sup>*1</sup> setting used for Modbus communication. The available function codes vary depending on the device used. Refer to the instruction manual of the connected device as well as the table shown below, and set the options on the dialog correctly.
Write to Coil	
Read Input Relay	
Read Holding Register	
Write Holding Register	
Read Input Register	

\*1 Format setting on V-SFT and function code for the Modbus communication

Format Setting		Modbus Communication Function Code
Reading coil		01H
Writing coil	1 bit	05H
	16 bits or more	0FH
Reading input relay		02H
Reading holding register		03H
Writing holding register	1 word	06H
	2 words or more	10H
Reading input register		04H

## PLC

Make communication settings of the connected device according to the settings made for the S8 series. For more information on settings, refer to the instruction manual issued by the manufacturer.

## Available Memory

The available memory setting range varies depending on the PLC model. Be sure to set within the range available for the PLC. Use [TYPE] when assigning the indirect memory for macro programs.

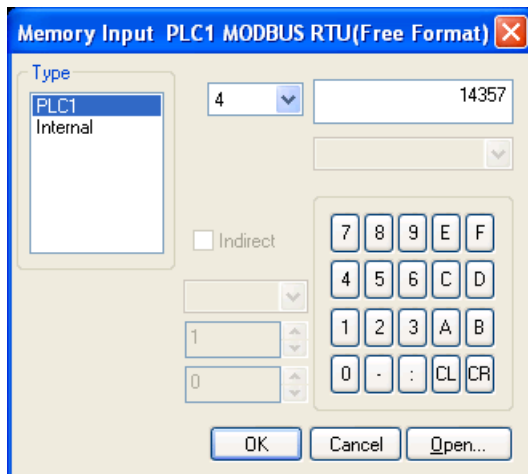
Memory	TYPE	Remarks
0 (output coil)	00H	
1 (input relay)	01H	
4 (holding register)	02H	
3 (input register)	03H	

## Notes on Creating Screen Data

On the editor, the memory address is specified in decimal notation. Thus, when setting the address of the connected device that recognizes the memory address in hexadecimal notation, specify the value by converting the address into decimal one and add "1".

### Setting example

- When specifying the PV (current value) RAM address "3814H" for Modbus RTU connection with Yamatake's "SDC35":
  - Convert the hexadecimal address into the decimal one.  
3814HEX → 14356DEC
  - Add "1" to the decimal address.  
14356 + 1 = 14357DEC
  - On the editor, specify "14357" for the holding register (4).

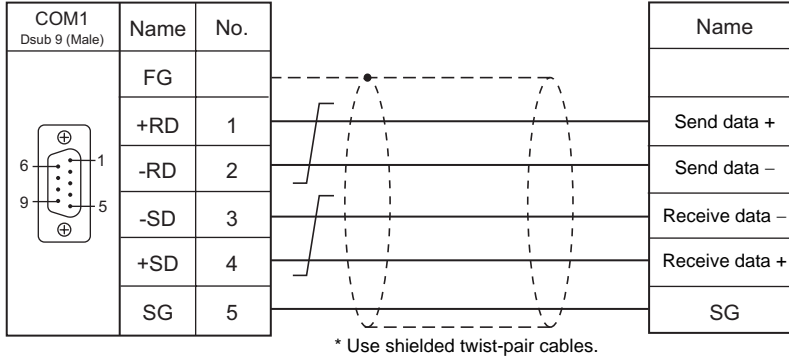




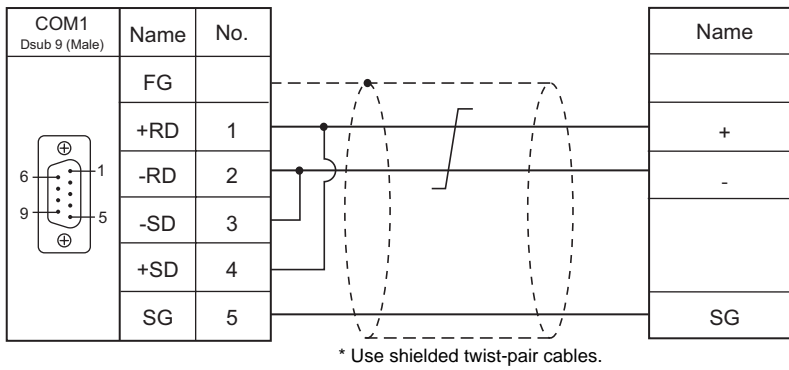
## 20.1.2 Wiring Diagrams

### When Connected at COM1 (RS-422 / RS-485):

Wiring diagram 1 - COM1

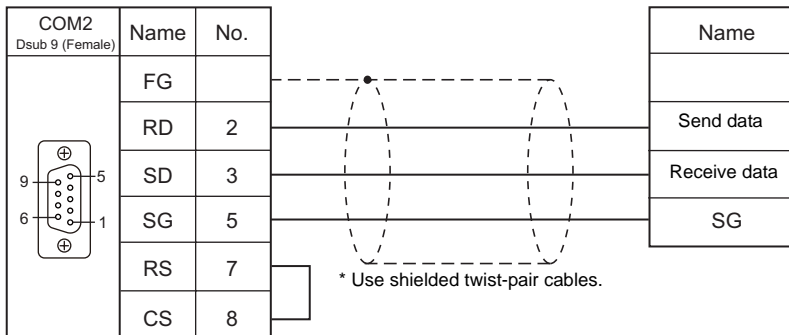


Wiring diagram 2 - COM1



### When Connected at COM2 (RS-232C):

Wiring diagram 1 - COM2



# 21. Barcode Reader

---

## 21.1 Barcode Reader Connection



# 21.1 Barcode Reader Connection

Barcode readers can be connected to the serial port COM2 at the S8 series.

## 21.1.1 Recommended Models (Operations Verified)

Operations of the following models have been verified by Hako Electronics.

Manufacturer	Model	Signal Level	Connection	
			COM1	COM2
Tohken	THIR-6000 THIR-3000N-RF TFIR3102 THLS-6800 TLMS-3500RV THLS6912	RS-232C	-	Wiring diagram 1 - COM2
Omron	V500-R521b V520-RH series			
Keyence	BL-210 series BL-600 series BL-N60 series BL-80 series			
Cognex	In-Sight 5100 In-Sight 5400			
Nichiei Intec	FFTA10ARS			
Unitech	MS210-1			
SICK	LD9000E			
OLYMPUS-symbol	LSH3502			
symbol	LS2104			
WelchAllyn	IT3800			

## 21.1.2 Communication Setting

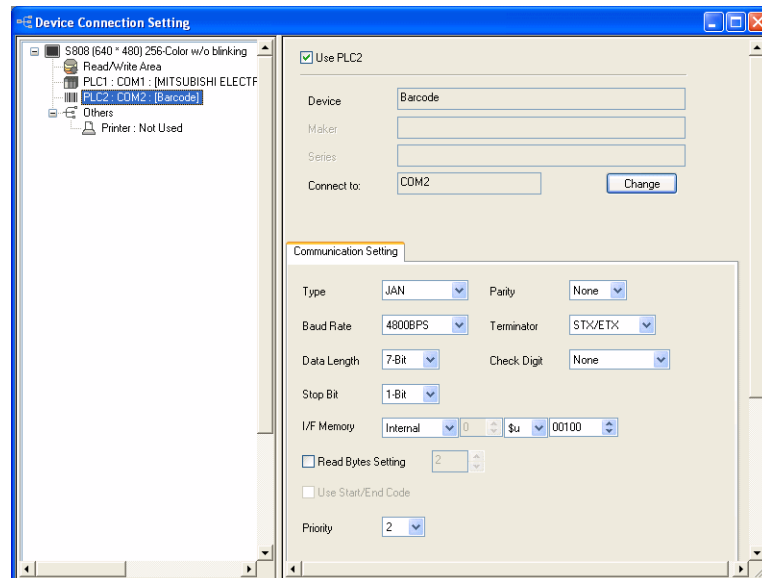
### Editor

#### Device selection

Select [Barcode] at [Device] for the logical ports PLC2. [Barcode] cannot be selected for PLC1.



#### Communication setting



(Underlined setting: default)

Item	Setting	Remarks
Type	<u>JAN</u> / ITF / CODABAR / CODE39 / ANY	
Baud Rate	<u>4800</u> / 9600 / 19200 bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	<u>None</u> / Odd / Even	
Terminator	<u>STX/ETX</u> CR/LF CR	
Check Digit	<u>None</u> / Do Not Delete / Delete	
I/F Memory	See "I/F Memory" (page 21-3).	
Read Bytes Setting		
Use Start/End Code	<ul style="list-style-type: none"> <li>When checked: Data is saved with "*" attached.</li> <li>When unchecked: Data is saved without "*".</li> </ul>	Enabled when [CODE39] is selected for [Type].

### Barcode Reader

Match communication settings of the barcode reader to those made on the S8 series. For more information on settings, refer to the specifications issued by the manufacturer.

## 21.1.3 I/F Memory

I/F memory stores barcode information. The number of words used varies depending on the setting.

### I/F Memory

Type: JAN / ITF / CORDABAR / CODE39

Memory	Contents																		
n	Flag / the number of bytes read <table border="1" style="margin-left: 20px;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>-</td><td>0</td> </tr> <tr> <td>0</td><td></td><td>0</td><td></td><td>0</td><td>0</td><td></td><td></td><td></td> </tr> </table> <p style="margin-left: 20px;">             Communication error      Reading complete      The number of bytes read (0 to 256 bytes)           </p> <p>* Be sure to reset the bits not in use to "0".</p>	15	14	13	12	11	10	9	-	0	0		0		0	0			
15	14	13	12	11	10	9	-	0											
0		0		0	0														
n + 1	Data read (ASCII) * "0" (null code) is attached to the last.																		
:																			
n + m																			

Type : ANY

Memory	Contents																		
n	Flag <table border="1" style="margin-left: 20px;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>-</td><td>0</td> </tr> <tr> <td>0</td><td></td><td>0</td><td></td><td>0</td><td>0</td><td>0</td><td>-</td><td>0</td> </tr> </table> <p style="margin-left: 20px;">             Communication error      Reading complete           </p> <p>* Be sure to reset the bits not in use to "0".</p>	15	14	13	12	11	10	9	-	0	0		0		0	0	0	-	0
15	14	13	12	11	10	9	-	0											
0		0		0	0	0	-	0											
n + 1	The number of bytes read (0 to 2048 bytes)																		
n + 2	Data read (ASCII) * "0" (null code) is attached to the last.																		
:																			
n + m																			

### Details of flag

Communication error	When an error occurs in communication between the barcode reader and the S8 series, "1" is set. Check the communication settings and wiring.
Reading complete	When data received from the barcode reader has been written into the I/F memory, "1" is set. When this bit is set, reset it to "0" before reading the next data.
The number of bytes read	Stores the number of bytes read from the barcode reader.

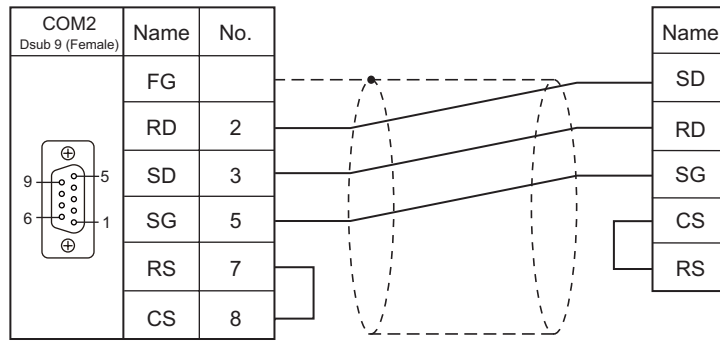
### Read Bytes Setting

Data of the specified number of bytes is stored into the I/F memory. When this option is unchecked, the number of bytes read varies depending on the codes read.

## 21.1.4 Wiring Diagrams

### When Connected at COM2 (RS-232C):

Wiring diagram 1 - COM2



# 22. Slave Communication Function

---

22.1 V-Link

22.2 Modbus RTU Slave Communication

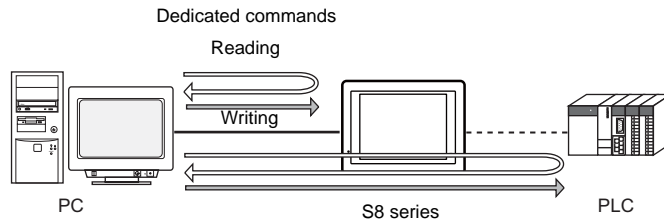




## 22.1 V-Link

### 22.1.1 Overview

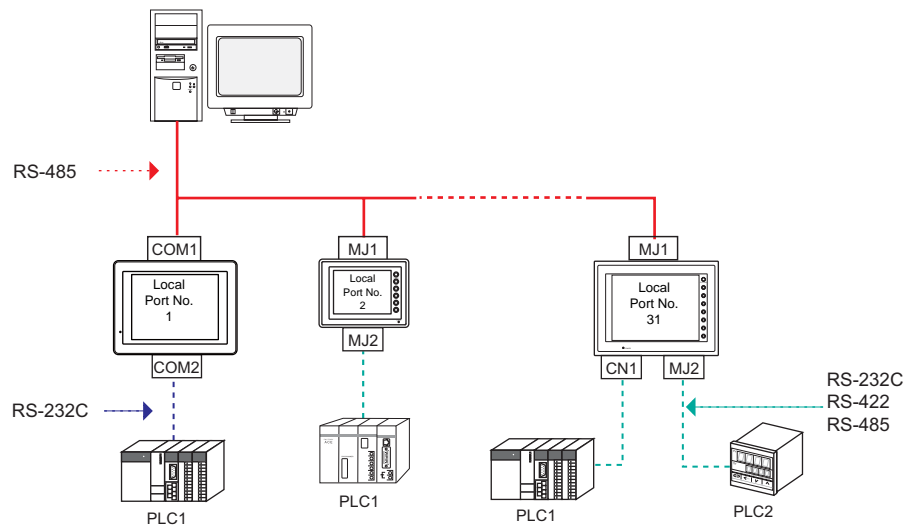
- "V-Link" is the network where the computer reads from and writes to the internal memory of the S8 series, or PLC1 memory using a dedicated protocol.



- Data of the connected devices can be collected through communications with the S8 series. Data collection is available even between devices of different manufacturers.
- Either signal level RS-232C or RS-485 can be selected. With RS-232C, one S8 series unit can be connected; with RS-485, a maximum of 31 S8 series units\* can be connected. The S8, V8, V7, and V6 series can be used together.

\* The terminating resistance of COM1 on S806M10D is always set to ON. So, S806M10D is available only in the termination of V-Link.

- RS-485 connection

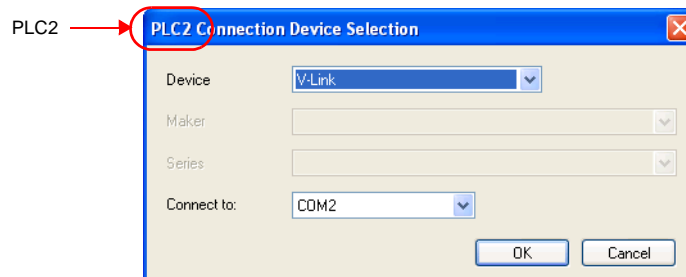


## 22.1.2 Communication Setting

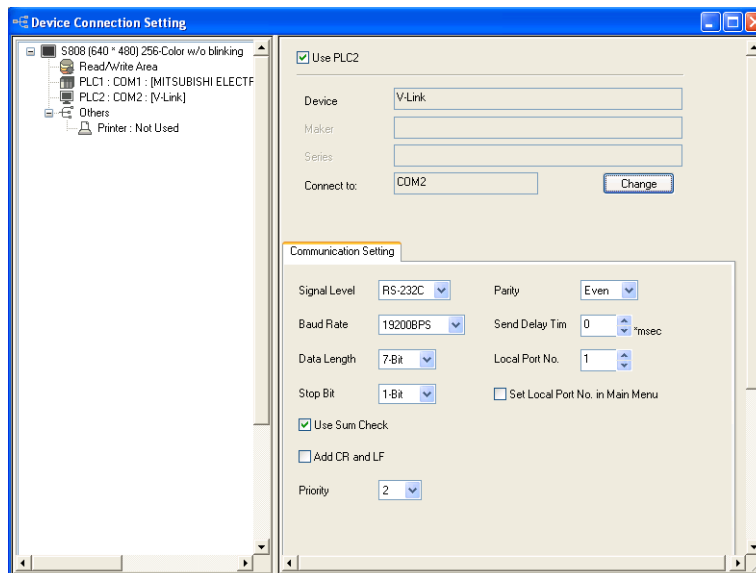
### Editor

#### Device selection

Select [V-Link] at [Device] for the logical ports PLC2. [V-Link] cannot be selected for PLC1.



#### Communication setting



(Underlined setting: default)

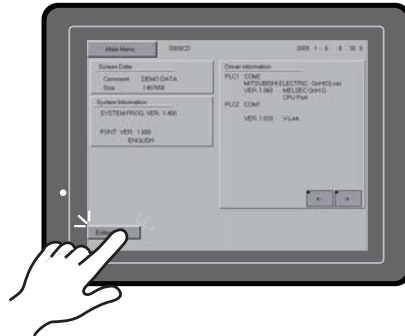
Item	Setting
Signal Level	<u>RS-232C</u> / RS-485
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115 Kbps
Data Length	<u>7</u> / 8 bits
Stop Bit	<u>1</u> / 2 bits
Parity	None / Odd / <u>Even</u>
Send Delay Time	<u>0</u> to 255 msec
Local Port No.	<u>1</u> to 31
<input type="checkbox"/> Set Local Port No. in Main Menu	<ul style="list-style-type: none"> <li><u>Unchecked</u>: Set the local port number for screen data.</li> <li><b>Checked</b>: Set the local port number on MONITOUCH (see page 22-3).</li> </ul>
<input type="checkbox"/> Use Sum Check	<u>Checked</u> / unchecked
<input type="checkbox"/> Add CR and LF	Checked / <u>unchecked</u>

## MONITOUCH

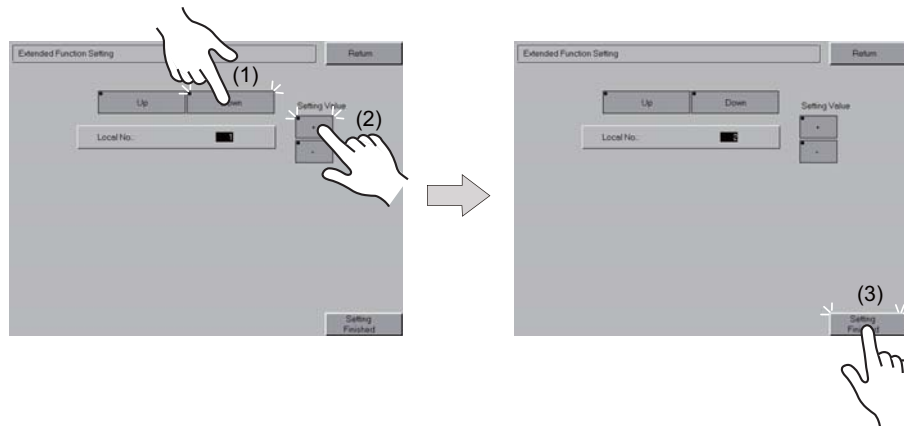
### Local port number setting (Main Menu)

When [ Set Local Port No. in Main Menu] is checked in the [Communication Setting] tab window for V-Link, the local port number must be set on the Main Menu screen of the S8 series.

1. Transfer screen data.
2. Bring up the Main Menu screen on MONITOUCH.
3. Press the [Editor: USB] for three seconds. The Extended Function Setting screen is displayed.



4. Display the [Local No.] field using the [Up] and [Down] switches. (See (1) in the figure below.)

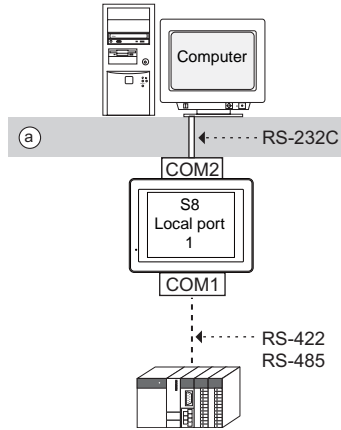


5. Set the local port number using the [+] and [-] switches. (See (2) in the figure above.)
6. Press the [Setting Finished] switch. The Main Menu screen is displayed again. (See (3) in the figure above.)

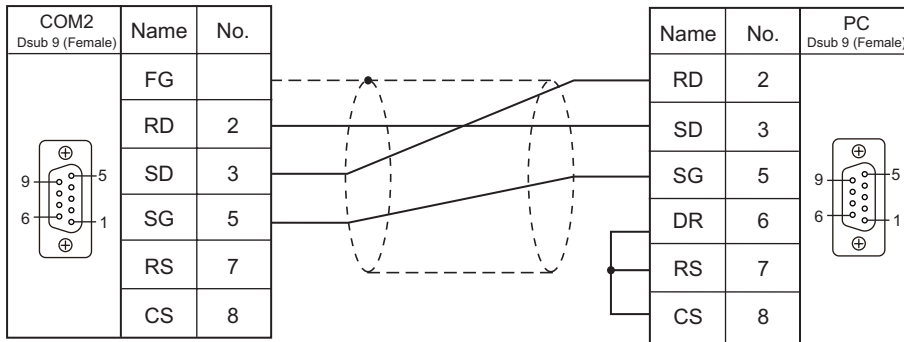
### 22.1.3 Connection

#### RS-232C

The S8 unit is connected to a personal computer with the COM2 port via RS-232C. The COM1 port is used to connect to a PLC (RS-422).



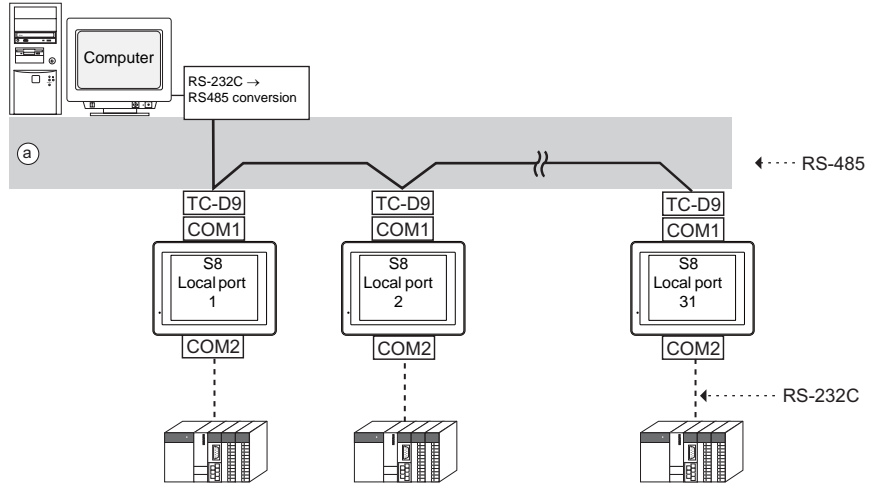
- Wiring example of above (a)



**RS-485**

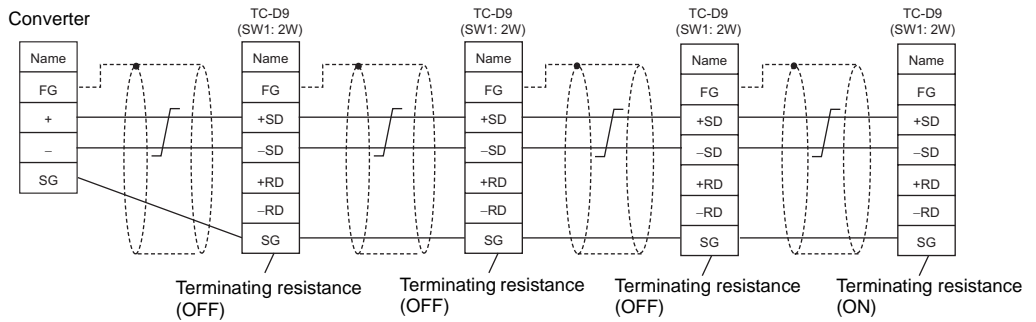
The S8 unit is connected to a personal computer with the COM1 port via RS-485. With RS-485, a maximum of 31 S8 series units\* can be connected. The COM2 port is used to connect to a PLC (RS-232C).

\* The terminating resistance of COM1 on S806M10D is always set to ON. So, S806M10D is available only in the termination of V-Link.

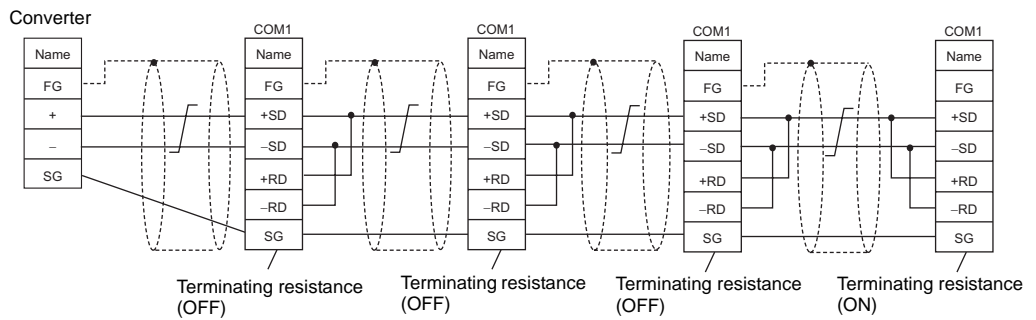


**Wiring example of above (a)**

- S8 series with TC-D9

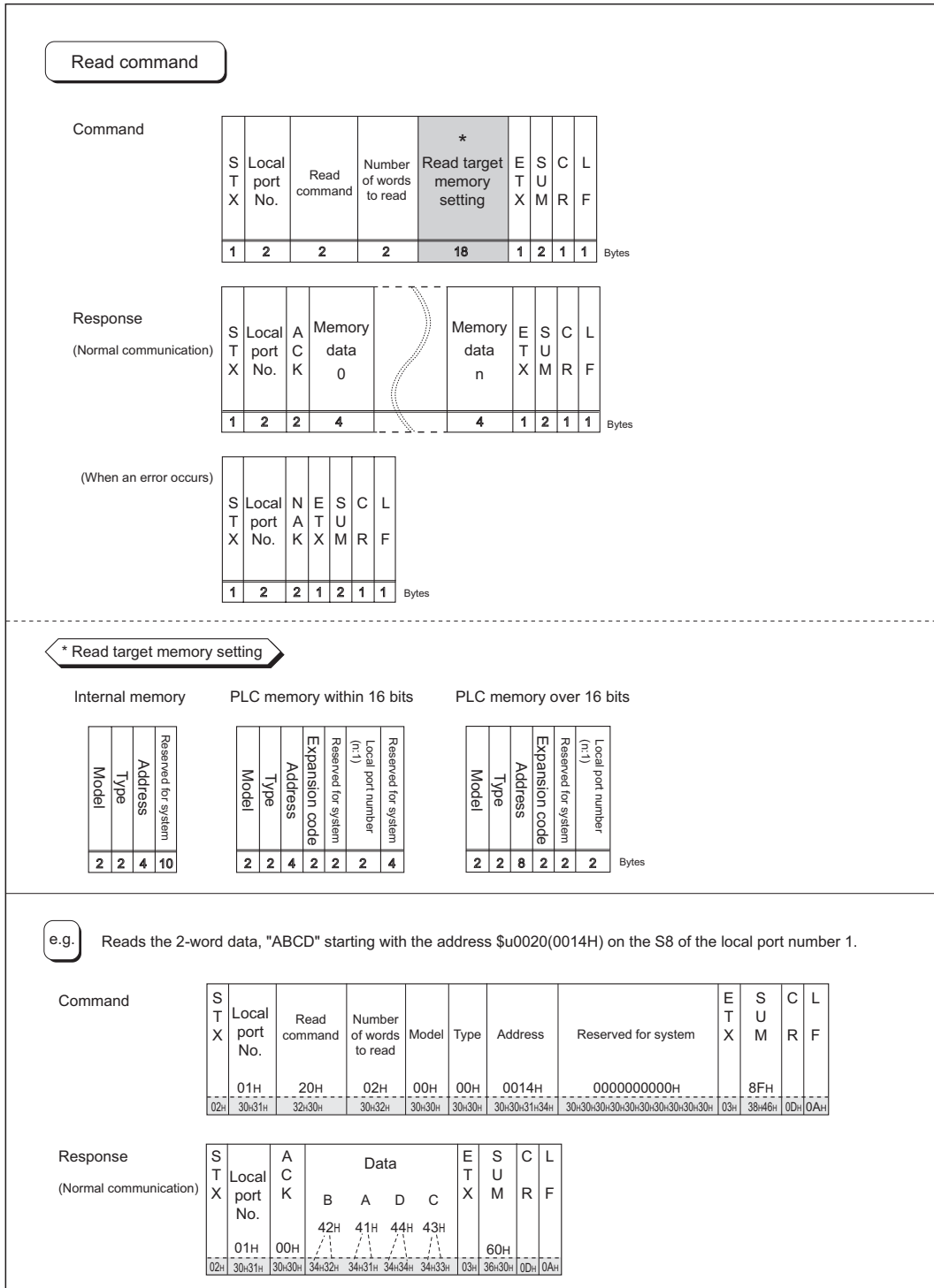


- S8 series without TC-D9



## 22.1.4 Protocol

### Read (with Sum Check and CR/LF)



Write (with Sum Check and CR/LF)

Write command

Command

S T X	Local port No.	Write command	Number of words to write	* Write target memory setting	Memory data 0		Memory data n	E T X	S U M	C R	L F
1	2	2	2	18	4		4	1	2	1	1

Bytes

Response

(Normal communication)

S T X	Local port No.	A C K	E T X	S U M	C R	L F
1	2	2	1	2	1	1

Bytes

(When an error occurs)

S T X	Local port No.	N A K	E T X	S U M	C R	L F
1	2	2	1	2	1	1

Bytes

---

\* Write target memory setting

Internal memory

Reserved for system	Address	Type	Model
2	2	4	10

PLC memory within 16 bits

Reserved for system	Local port number (n-1)	Expansion code	Address	Type	Model
2	2	4	2	2	2

PLC memory over 16 bits

Reserved for system	Local port number (n+1)	Expansion code	Address	Type	Model
2	2	8	2	2	2

Bytes

e.g. Writes "AB12" to the addresses D0100 to 101(0064 to 0065H) on the PLC connected to the S8 of the local port number 1.

Command

S T X	Local port No.	Write command	Number of words to write	Model	Type	Address	Reserved for system	Data				E T X	S U M	C R	L F	
01H	21H	02H	01H	00H	0064H	0000000000H		B	A	2	1					
02H	30H-31H	32H-31H	30H-32H	30H-31H	30H-30H	30H-30H-36H-34H	30H-30H-30H-30H-30H-30H-30H-30H-30H-30H	34H-32H	34H-31H	33H-32H	33H-31H	03H	32H-41H	00H	0AH	

Response

(Normal communication)

S T X	Local port No.	A C K	E T X	S U M	C R	L F
01H	00H	C6H				
02H	30H-31H	30H-30H	03H	43H-36H	00H	0AH



## Items for Protocols

### Transmission control code: 1 byte

Signal Name	Code (Hexadecimal)	Content
STX	02H	Start of transmission block
ETX	03H	End of transmission block
CR	0DH	Carriage return
LF	0AH	Line feed

### Local port number: 2 bytes

Local port numbers are used so that the host computer can identify each S8 series for access. The data range is from 01H to 1FH (1 to 31) and is converted into the ASCII code before use. Set the S8 series' local port number for [Local Port No.] on the editor. See page 22-2.

### Command: 2 bytes

Available commands are shown below.

Name	Code (Hexadecimal)	ASCII	Content
Read	20H	32 30	Read from memory
Write	21H	32 31	Write to memory

### The number of words to be read or written: 2 bytes

Set the number of words to be read or written by one command. The data range is from 01H to FFH (1 to 255) and is converted into the ASCII code before use.

### Memory address to be read or written: 18 bytes

Specify the memory address to be accessed.

Set the following code in the format as shown for "Read target memory setting" on page 22-6 and "Write target memory setting" on page 22-7.

- Model

Memory	Word Address		Double-word Address	
	Code (Hexadecimal)	ASCII	Code (Hexadecimal)	ASCII
Internal memory	00H	3030	80H	3830
PLC1 memory	01/11H	3031/3131	81/91H	3831/3931
PLC2 memory	03/12H	3033/3132	83/92H	3833/3932

- Type

	Type	Code (Hexadecimal)	ASCII
Internal memory	\$u (user memory)	00H	3030
	\$s (system memory)	01H	3031
	\$L (non-volatile word memory)	02H	3032
	\$LD (non-volatile double-word memory)	03H	3033
	\$T (temporary user memory)	04H	3034
	\$P (memory for 2-way communication)	05H	3035
PLC1-to-2 memory	Depends on the PLC to be used. Set [TYPE No.] of the memory used for each device.		

- Address

Specify the memory address to be accessed.

- Expansion code

When accessing to the memory shown below, set the expansion code in addition to the type and address.

\$P	PLC number 1 to 2
Mitsubishi Electric PLC	Slot No. of SPU memory
Yokogawa Electric PLC	CPU No.
Omron PLC	Bank number

\* If there is no need to set the expansion code, set "00" (= 3030 in the ASCII code).

- Port number

Set the port number used for 1 : n connection (multi-drop)

For 1 : 1 connection or n:1 connection (multi-link), the port number setting is not used. Alternatively, set "00" (= 3030 in the ASCII code).

- System reserved

Enter "0" (= 30 in the ASCII code) for the number of bytes.

The number of bytes for "system reserved" varies depending on the model.

Example:

Model	Bytes	Code (Hexadecimal)	ASCII
S8 internal memory	10	0000000000H	30303030303030303030

## Sum Check Code (SUM): 2 Bytes

Data is added up (SUM), and the lower one byte (8 bits) of the sum is converted into a two-digit ASCII code (hexadecimal). A sum check code is shown below.

Example: Transmission mode: without CR/LF, with sum check

Command: 20 (data read)

Address: 10 words from \$u1000 (03E8H)

When reading, a sum check will be performed as shown below.

STX	Port No.	Command	Read words	Memory model	Memory type	Address	System reserved	ETX	SUM
	01H	20H	0AH	00H	00H	03E8H	0 0 0 0 0 0 0 0 0H		B9H
02H	30H31H	32H30H	30H41H	30H30H	30H30H	30H 33H 45H 38H	30H 30H 30H 30H 30H 30H 30H 30H 30H 30H	03H	42H39H

$02H + 30H + 31H + 32H + 30H + 30H + 41H + 30H + 30H + 30H + 30H + 30H + 33H + 45H + 38H$   
 $+ 30H + 30H + 30H + 30H + 30H + 30H + 30H + 30H + 30H + 30H + 03H = 4B9H$

## Response Code: 2 Bytes

"ACK" code is received at normal termination, and "NAK" code at abnormal termination. The following table shows the details of each code.

Code		Contents
ACK	00H	Normal termination
NAK	02H	Overrun/Framing error An overrun or framing error is detected in the received data. Send the command again.
	03H	Parity error A parity error is detected in the received data. Send the command again.
	04H	Sum check error A sum error occurs with the received data.
	06H	Count error The memory read/write count is "0".
	0FH	ETX error No ETX code is found.
	11H	Character error A character not used in the received data is found (other than 0 to F). Check the character and send the command again.
	12H	Command error An invalid command is given.
	13H	Memory setting error The address or device number is invalid.



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## 22.2 Modbus RTU Slave Communication

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For details on Modbus RTU slave communication, refer to the Modbus Slave Communication Specifications manual provided separately.

MEMO

Please use this page freely.

# 23. Universal Serial Communication

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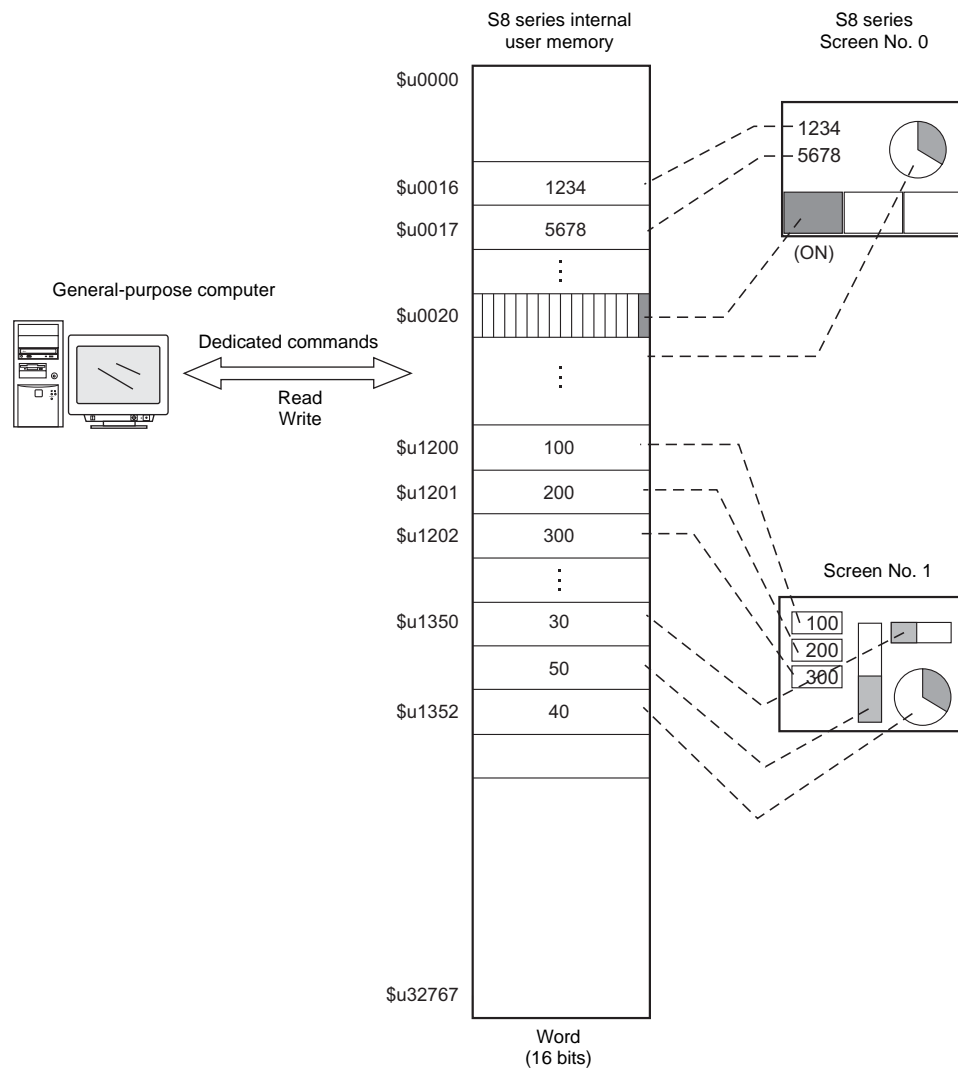
- 23.1 Overview
- 23.2 Wiring Diagrams
- 23.3 Device Connection Setting
- 23.4 Standard Type Protocol
- 23.5 Memory Map



## 23.1 Overview

### Overview of Communication

- As shown in the diagram below, when a general-purpose computer communicates with the S8 series, the general-purpose computer acts as the host and the S8 series acts as the slave.
- Switch, lamp, data display, etc., are allocated within the internal user memory (\$u0 to 32767). Assign memory addresses for system, lamp, data display, and mode within this range.
- When a screen number is specified from the host, a write action takes place to the internal memory address specified for the screen. When a screen is changed internally by a switch, etc., the changed screen number is read, and written in the internal memory address specified for the screen.





## Differences between Connecting to General-purpose Computer and Connecting to PLC

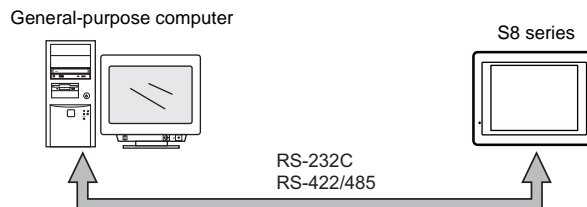
- Input format (code)  
The input format used for screen number, block number, message number, etc., is fixed in [DEC].
- Write area  
When connecting to the PLC, only the three words shaded in the diagram below are used, but when connecting to a general-purpose computer, all 16 words shown below are used.

Address	Name	Contents
n + 0	CFMDAT	Sub command/data
n + 1	SCRN_COM	Screen status
n + 2	SCRN_No	Displayed screen
n + 3	SW0	No. 0 switch data
n + 4		Reserved
n + 5	ENT0	Entry information 0
n + 6	ENT1	Entry information 1
n + 7	ENT2	Entry information 2
n + 8	GREPNS	Global response
n + 9 • • n + 15		Reserved (7 words)

## System Configuration

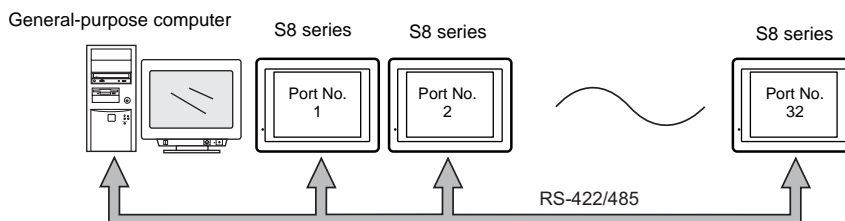
### 1 : 1 connection

- The transmission distance available via RS-232C is 15 m and RS-422/485 is 500 m at the maximum.
  - It is possible to use an interrupt\* when connecting a computer to a S8 series in a 1 : 1 connection.
- \* For RS-485 (2-wire connection), interrupts cannot be used. For details on interrupts, see page 23-25.



### 1 : n connection

- 1 : n connection is available via RS-422/485. A maximum of 32 S8 series units\* can be connected with the serial port, COM1.
- \* The terminating resistance of COM1 on S806M10D is always set to ON. So, S806M10D is available only in the termination.
- The transmission distance available is 500 m at the maximum.
  - For 1 : n connection, interrupts cannot be used.

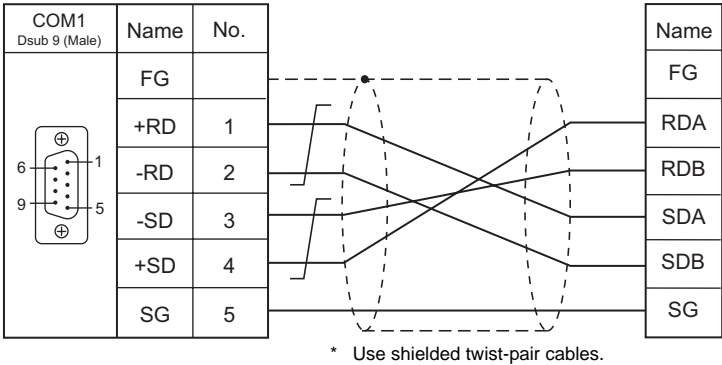


# 23.2 Wiring Diagrams

## When Connected at COM1 (RS-422 / RS-485):

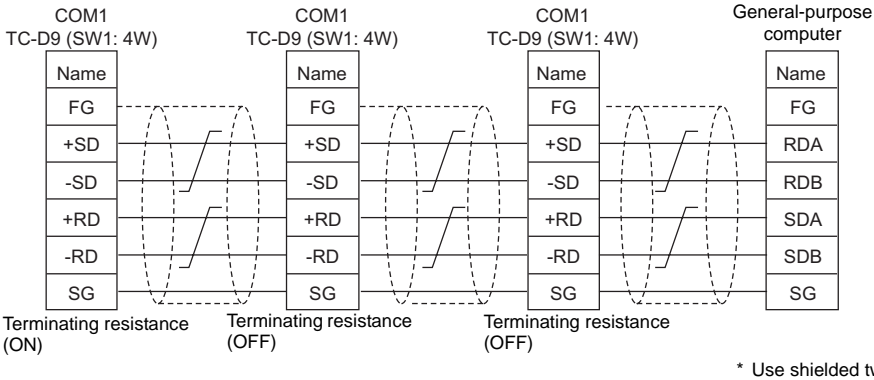
### RS-422

#### 1 : 1 connection



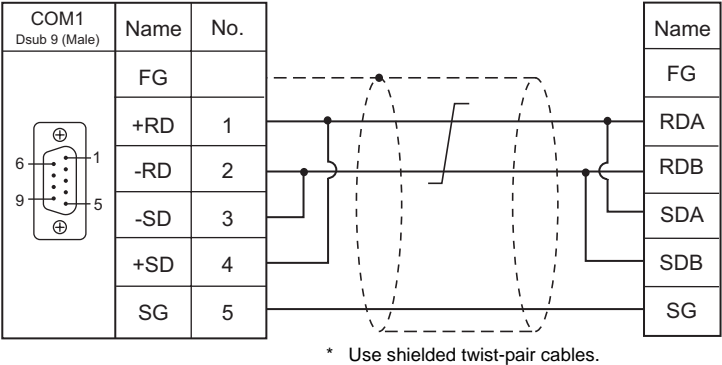
#### 1 : n connection

It is convenient to use the optional terminal converter "TC-D9".  
 The terminating resistance of COM1 on S806M10D is always set to ON. So, S806M10D is available only in the termination.



### RS-485

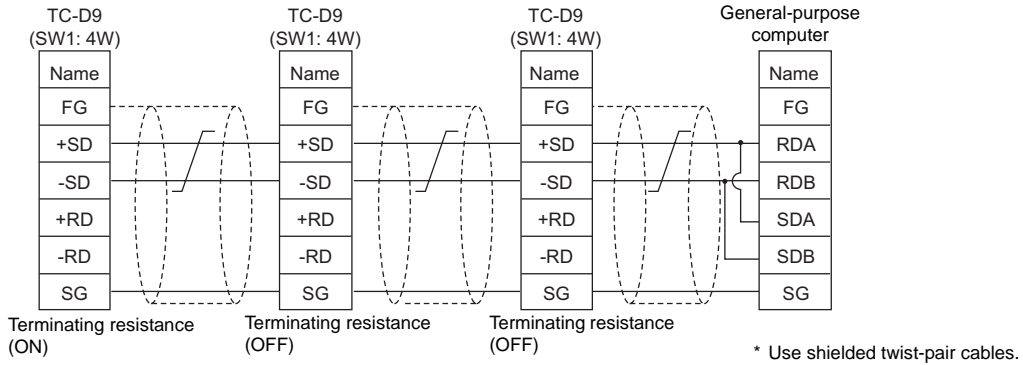
#### 1 : 1 connection



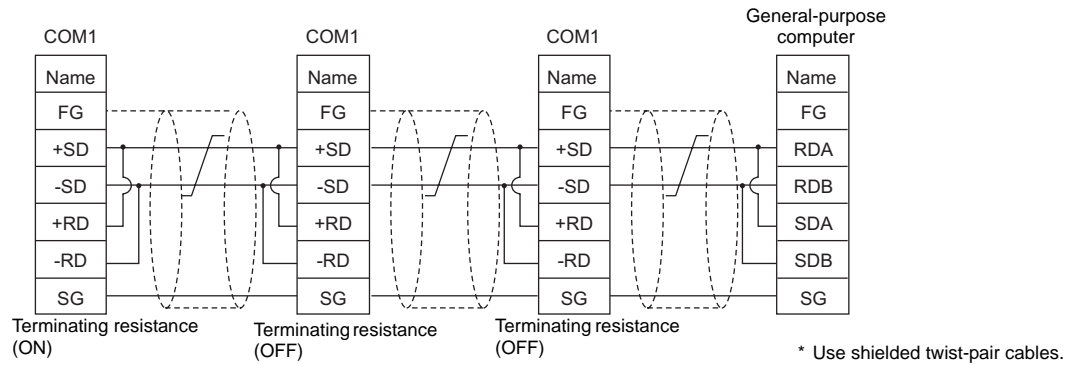
**1 : n connection**

The terminating resistance of COM1 on S806M10D is always set to ON. So, S806M10D is available only in the termination.

- S8 series with TC-D9

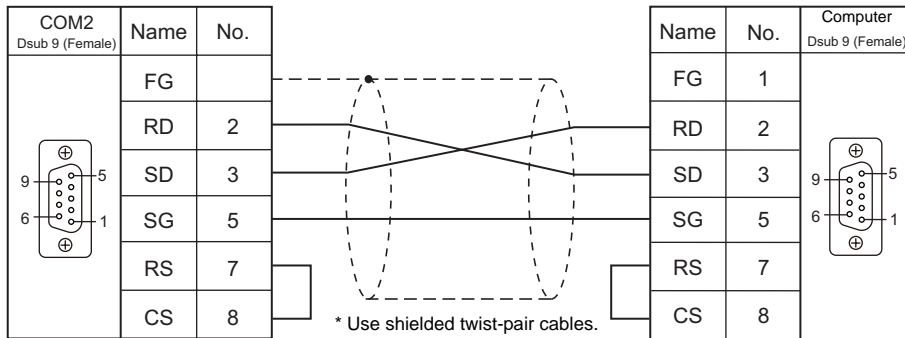


- S8 series without TC-D9  
Install jumpers between +RD/+SD and -RD/-SD.

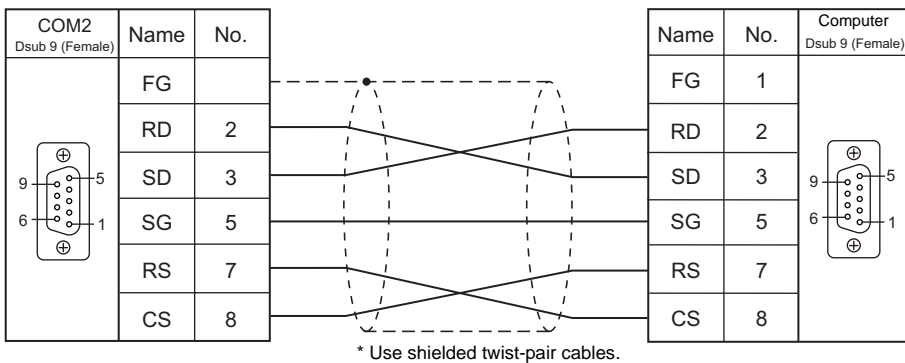


**When Connected at COM2 (RS-232C):**

**Without flow control**



**With flow control**

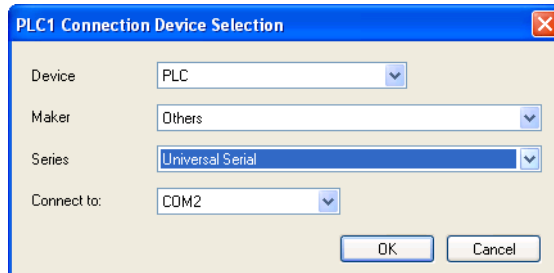


## 23.3 Device Connection Setting

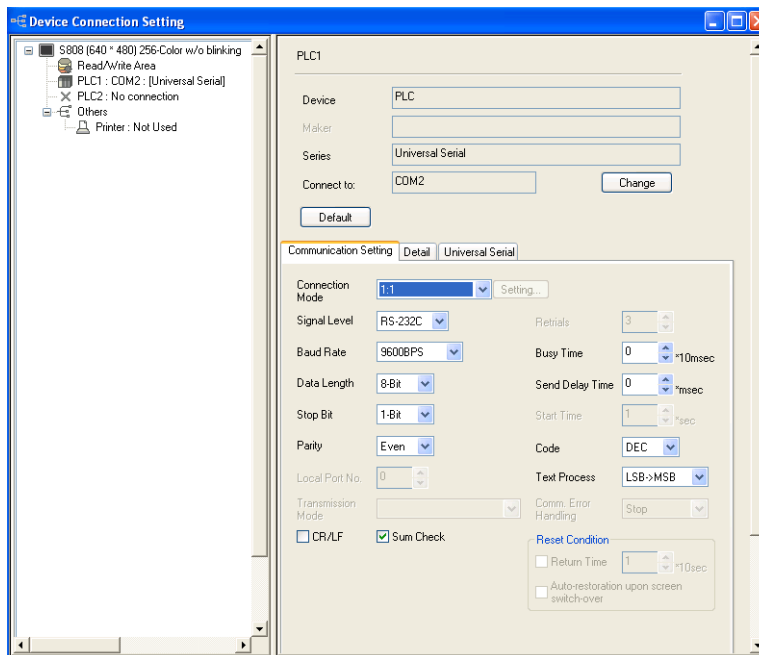
### PLC1

Make settings of universal serial communication for the logical port PLC1. You cannot select this type as PLC2.

#### Device Selection (PLC1)



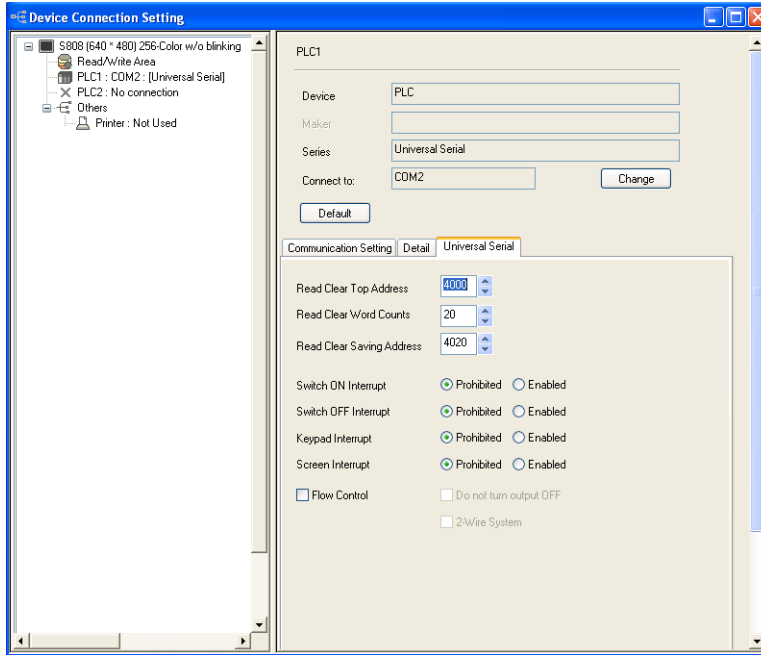
#### Communication Setting



Connection Mode	Set the connection method for the S8 series and host. 1 : 1 : Select it when connecting one S8 series unit to one host. 1 : n : Select it when connecting multiple S8 series units to one host.
Signal Level	Set the signal level used for communication between the host and the S8 series. RS-232C / RS-422/485
Baud Rate	Set the communication speed between the host and the S8 series. 4800 / 9600 / 19200 / 38400 / 57600 / 76800 / 115K bps
Data Length	8 bits (fixed)
Stop Bit	Select a stop bit. 1 bit / 2 bits
Parity	Select an option for parity bit. None / Odd / Even
Local Port No.	This option is valid when 1 : n connection is used. Set the port number of the S8 series.
CR/LF	Set whether or not to add a CR/LF code at the end of transmission data.
Sum Check	Set whether or not to add a sum check code at the end of transmission data.
Busy Time	For details, see page 23-17.
Send Delay Time	Set the time for S8 series to send a response to a host after receiving a command from a host.
Code	DEC (fixed)

Text Process	When using text process, choose either [LSB → MSB] or [MSB → LSB] in order to make arrangements for the order of the first and the second bytes in one word.
	<div style="display: flex; justify-content: space-around; align-items: center;"> <div style="text-align: center;"> <p>[LSB → MSB]</p> </div> <div style="text-align: center;"> <p>[MSB → LSB]</p> </div> </div>

Universal Serial

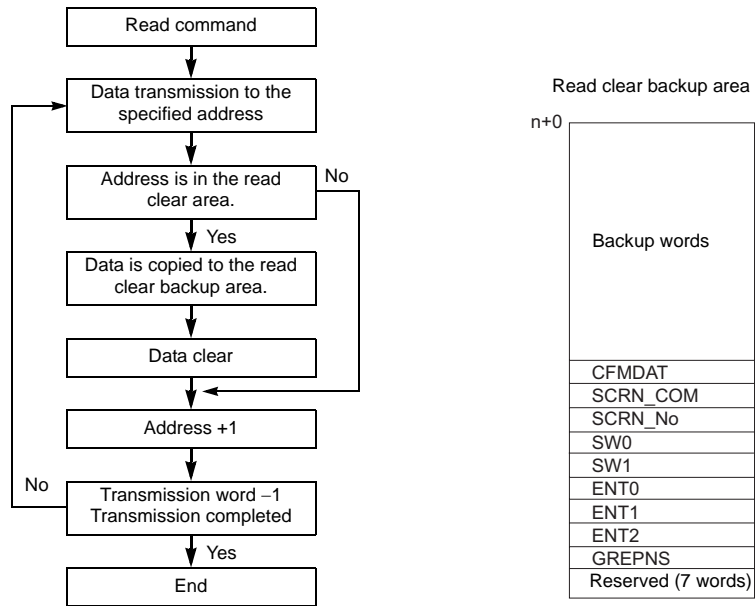


Read Clear Top Address <sup>*2</sup>	Set the top address number of the read clear area. The read clear area is the starting area from which the S8 series clears data that was previously read. Due to the fact that it is cleared to "0", once this area is read, the data remains at "0" even if you attempt to read again when a read response error occurs.
Read Clear Word Counts <sup>*2</sup>	Set the number of words that will be used for clearing the read area.
Read Clear Saving <sup>*2</sup>	Set the top address for the read clear backup area. The area size will be the same as the previously described read clear area. The number of words written in the read clear backup area are the same as the number specified for the read clear area.
Switch ON Interrupt <sup>*1</sup>	Select whether or not to enable or disable an interrupt when the switch changes from OFF to ON.
Switch OFF Interrupt <sup>*1</sup>	Select whether or not to enable or disable an interrupt when the switch changes from ON to OFF.
Keypad Interrupt <sup>*1</sup>	Select whether or not to enable or disable an interrupt when the switch on the keypad or the ENT switch on the keyboard is pressed and it changes from OFF to ON.
Screen Interrupt <sup>*1</sup>	Select whether or not to enable or disable an interrupt when the screen change switch is pressed.
<input type="checkbox"/> Flow Control	This option is valid only for 1 : 1 communication via RS-232C using COM2. Check this box when disabling an interrupt from the S8 series (e.g. when the host cannot receive interrupt data). When this box is checked, the action shown below takes place. <ul style="list-style-type: none"> <li>Interrupt enabled when CS (pin 8) on the S8 series side is ON</li> <li>Interrupt disabled when CS (pin 8) on the S8 series side is OFF</li> </ul> When CS is ON, interruption information stored by then is output in succession. (Interruption information for 3 times can be stored at the most.)
<input type="checkbox"/> Do not turn output OFF	This option is valid only for 1 : 1 communication via RS-422 using four-wire. Normally, S8 series uses the same cables to send or receive data. For this reason, send output remains OFF (High impedance) except for sending signals from S8 series. However, depending on the host specifications, send output OFF operation from the S8 series is not required. In this case, check <input type="checkbox"/> Do not turn output OFF].
<input type="checkbox"/> 2-Wire System	This option is valid only for 1 : 1 communication with RS-422 using two-wire. When this box is checked, interrupt is disabled.

\*1 Interrupt settings can be changed from the host using the [W] command during communication. For details on interruption, see "23.4.4 Interrupt (ENQ)".

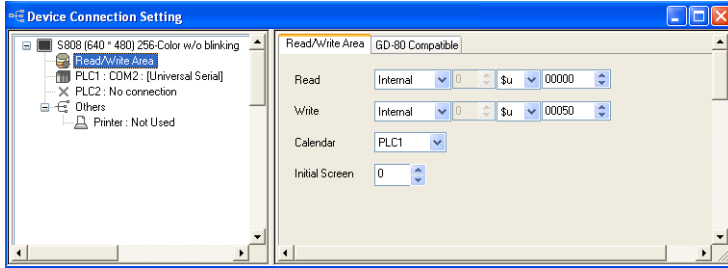
## \*2 Read clear and read clear backup action

The action that occurs when a read command from the host tries to access to the read clear area is shown in the following diagram. Backup data of the system memory write area is allocated following the read clear backup area.



## Read/Write Area

### Read/Write Area



#### Read area

This memory area is necessary to change the screen display status by giving a command from the host. Be sure to set the \$u memory. Address allocation is shown in the table below. For more information, see “Read/Write Area” (page 1-16).

Address	Name	Contents
n + 0	RCVDAT	Sub command/data
n + 1	SCRN_COM	Screen status command
n + 2	SCRN_No	External screen command

#### Write area

This memory area is used to store information regarding screen number, overlap display, and entry mode when the screen display status is changed by a command received from the host. Be sure to set the \$u memory. Address allocation is shown in the table below.

Address	Name	Contents
n + 0	CFMDAT	Sub command/data
n + 1	SCRN_COM	Screen status
n + 2	SCRN_No	Displayed screen
n + 3	SW0	No. 0 switch data
n + 4		Reserved
n + 5	ENT0	Entry information 0
n + 6	ENT1	Entry information 1
n + 7	ENT2	Entry information 2
n + 8	GREPNS	Global response
n + 9 : n + 15		Reserved (7 words)

- n + 0 to n + 2  
For details, see “Read/Write Area” (page 1-16).
- n + 3 (SW0) switch data No. 0  
When the switch, for which [Output Action] is set to [Momentary/Momentary W] and [Output Memory] is set in location from \$s0080 to 0095, is pressed, the status and the number of the switch is stored.

n + 3 (SW0)

15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
	0	0	0	0	0	0	0								

Switch status  
0: OFF  
1: ON

Switch number

For the relationship between the switch output memory and the switch number, see page 23-29.

- n + 4  
System reserved
- n + 5 (ENT0) entry information 0, n + 6 (ENT1) entry information 1  
The same contents as n + 0 and n + 1 of the [Info. Output Memory] that is set in the entry mode are written. Write operation occurs when the key whose function is set to “Write” is pressed in the entry mode. When the entry selection has changed, write operation will not occur. When (n + 5) entry information 0 is read by the host, writing completed bit (bit 15) is reset. Data is written in the backup (escape) area before it is read. (See page 23-7.)

- n + 7 (ENT2) entry information 2

The entry mode window number where a write operation was executed is written.

The relationship between the window number and base and the window number and overlap is shown in the following table.

Window No.	Contents
0	Base entry mode
1	Overlap 0 entry mode
2	Overlap 1 entry mode
3	Overlap 2 entry mode

- In case of using the entry mode for the table data display

The line number and the column number will be output to the address n + 1 and the block number to the address n + 2 of the "Info. Output Memory," when the bit No. 12 of "Command Memory" in the [Entry] dialog is ON [1]. In only this case, therefore, the window number cannot be referred because the block number is output to the address n + 7 (ENT2) of the write area.

- n + 8 (GREPNS) global response

A response is written when a global port number is used in 1 : n communication. The contents of a response are shown in the following table. For details on the global port number, see page 23-15.

Memory Contents	Contents
0000	Global command not received
0100	ACK
Others	Identical to NAK code (see page 23-16).

- n + 9 to n + 15  
System reserved

## Calendar

Select a device from which the calendar data is read without using the S8 series' built-in clock. For more information on the built-in clock, refer to the S8 Series Reference Manual.

- PLC1 to 2

Calendar data is read from the selected device.

The calendar data will be updated when:

- The power is turned on.
- STOP → RUN
- The date changes.
- At the leading edge of a bit (0 → 1) in the calendar memory in the reading area

## Initial screen

Set the number of the screen to be displayed when power to the S8 series is turned on.

## GD-80 Compatible

This setting is not valid because the GD-80 series cannot be used for universal serial communication.



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## 23.4 Standard Type Protocol

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### 23.4.1 Standard Type Protocol

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The connection mode and transmission mode are set in the [Communication Setting] tab window under [System Setting]. The mode contents are as follows.

- Connection mode

1 : 1: Select it when connecting one S8 series unit to one host.

1 : n: Select it when connecting multiple S8 series units to one host. A maximum of 32 units\* can be connected. (Multi-drop specifications)

\* The terminating resistance of COM1 on S806M10D is always set to ON. So, S806M10D is available only in the termination.

- Transmission mode

There are four transmission modes, depending on whether or not a sum check or CR/LF code is attached to the end of transmission and received data, as shown below.

Transmission Mode	Sum Check	CR/LF
1	Not provided	Not provided
2	Provided	Not provided
3	Not provided	Provided
4	Provided	Provided

**Connection (1 : 1), Transmission Mode (with Sum Check)**

This protocol is used when one host communicates with one S8 series unit (1 : 1).

Contents	Protocol
<p>Reading the S8 series data at the host side</p>	<p>Host side</p> <p>S8 series side</p> <p>Transmission sequence</p> <p>or</p> <p>Error code</p>
<p>Writing data from the host to the S8 series</p>	<p>Host side</p> <p>S8 series side</p> <p>Transmission sequence</p> <p>or</p> <p>Error code</p>

- When 1 : 1 connection is used, an interrupt can be used. For more information, see page 23-25.

### Connection (1 : 1), Transmission Mode (with Sum Check and CR/LF)

This protocol is used when one host communicates with one S8 series unit (1 : 1).

Contents	Protocol
<p>Reading the S8 series data at the host side</p>	<p>Host side</p> <p>S8 series side</p> <p>Transmission sequence</p> <p>or</p>
<p>Writing data from the host to the S8 series</p>	<p>Host side</p> <p>S8 series side</p> <p>Transmission sequence</p> <p>or</p>

- When 1 : 1 connection is used, an interrupt can be used. For more information, see page 23-25.

**Connection (1 : n), Transmission Mode (with Sum Check)**

It is possible to connect as many as 32 S8 series units\* to one host.

\* The terminating resistance of COM1 on S806M10D is always set to ON. So, S806M10D is available only in the termination.

(For information on the global command, see page 23-18.)

Contents	Protocol
<p>Reading the S8 series data at the host side</p>	<p>Host side</p> <p>S8 series side</p> <p>Transmission sequence</p> <p>or</p> <p>Error code</p> <p>Port No.</p> <p>N A K</p>
<p>Writing data from the host to the S8 series</p>	<p>Host side</p> <p>S8 series side</p> <p>Transmission sequence</p> <p>or</p> <p>Error code</p> <p>Port No.</p> <p>N A K</p>

### Connection (1 : n), Transmission Mode (with Sum Check and CR/LF)

It is possible to connect as many as 32 S8 series units\* to one host.

\* The terminating resistance of COM1 on S806M10D is always set to ON. So, S806M10D is available only in the termination.

(For information on the global command, see page 23-18.)

Contents	Protocol
<p>Reading the S8 series data at the host side</p>	
<p>Writing data from the host to the S8 series</p>	

## 23.4.2 Protocol Contents

### Transmission Control Code

The transmission control codes are shown in the table below.

Signal Name	Code (Hexadecimal)	Contents
STX	02H	Start of transmission block
ETX	03H	End of transmission block
ENQ	05H	Interrupt
ACK	06H	Positive acknowledge
CR	0DH	Carriage return
DLE	10H	Change contents within a block
NAK	15H	Negative acknowledge
LF	0AH	Line feed

### Port Number

Port numbers can be set for connection mode "1 : n".

They are used so that the host computer can identify each S8 series for access.

The data range is from 00H to 1FH (0 to 31) and is converted into a two-digit ASCII code (HEX) before use. Set port numbers of the S8 series at [Local Port No.] in the [Communication Setting] tab window.

#### Global port number (FFH)

When the global port number [FFH] is set, commands are sent to all S8 series units at one time.

Commands for which global port numbers are active are shown below. If commands other than these are used, a command error will occur.

Signal Name	Name	Contents
WM	Write	Write data memory
WC	Write CHR	Write data memory as characters

Responses to global port numbers are not transmitted to the host. However, responses are written in write area n + 8.

Memory Contents	Contents
0000H	Global command not received
0100H	ACK
Others	Identical to NAK code (see page 23-16.)

### Command

Available commands are shown below. The details on commands are described on pages shown at "Refer to:".

Signal Name	Name	Contents	Refer to:
RM	Read	Read data memory	page 23-19
WM	Write	Write data memory (512 words maximum)	page 23-21
TR	Retry	Retry when NAK [01] is BUSY	page 23-22
WI	Interrupt Setting	Allow interrupt (Connection mode 1 : 1)	page 23-23
RI	Read interrupt status	Read interrupt setting status (Connection mode 1 : 1)	page 23-24
RC	Read CHR	Read data memory as characters	page 23-18
WC	Write CHR	Write data memory as characters (1024 bytes maximum)	page 23-20

## Sum Check Code (SUM)

Data is added up (SUM), and the lower one byte (8 bits) of the sum is converted into a two-digit ASCII code (HEX).

### Example:

Transmission mode: without CR/LF, with sum check

The sum check code is added as shown below when data "3882" (OF2AH) is transmitted to the address "\$u1453" (05ADH) using the command [WM] (data writing).

STX	Command	DLE	Address	Count	Memory data	ETX	SUM
	"W" "M"		"0" "5" "A" "D"	"0" "0" "0" "1"	"0" "F" "2" "A"		"4" "D"
02H	57H 4DH	10H	30H 35H 41H 44H	30H 30H 30H 31H	30H 46H 32H 41H	03H	34H 44H

$$02H + 57H + 4DH + 10H + 30H + 35H + 41H + 44H + 30H + 30H + 30H + 31H + 30H + 46H + 32H + 41H + 03H = 34DH$$

\* In the case of an interrupt, data from ENQ to ETX is subject to a sum check.

## Error Codes

An error code is sent along with an NAK response as a two-digit ASCII code (HEX).

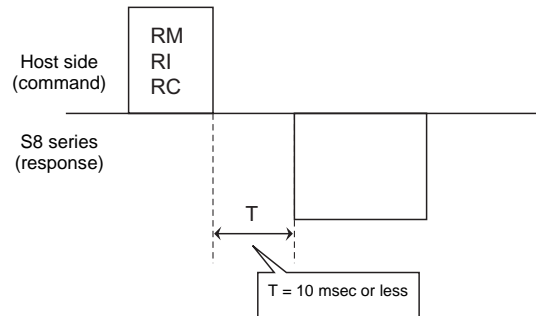
Error Codes	Contents
01H	The S8 series is currently engaged in display processing. The received command is on standby due to display processing. Wait a few moments and re-transmit the command.
02H	Overrun/Framing error An overrun or framing error is detected in the received data. Send the command again.
03H	Parity error A parity error is detected in the received data. Send the command again.
04H	Sum check error A sum error occurs with the received data.
05H	Address error The address specified by the memory read/write command is incorrect. Check the address or counter and re-transmit the command.
06H	Count error The memory read/write count is "0".
07H	Screen error The data to be written in read area n + 2 (screen status command), as specified by a write command, is not registered on the screen. Check the screen number and re-transmit the data.
08H	Format error The number of DLEs is 0 or greater than 6.
09H	Received data over The number of write command data received from the host exceeded that of data shown below. <ul style="list-style-type: none"> <li>Write memory command = 512 words</li> <li>Write CHR command = 1024 bytes</li> </ul>
0BH	Retry command error When a retry command is received, there is no BUSY status (NAK [01]) command.
0FH	ETX error No ETX code is found.
10H	DLE error No DLE code is found.
11H	Character error A character not used in the received data is found (other than 0 to F). Check the character and send the command again.
12H	Command error An invalid command is given.

## Response Time and BUSY

Response time varies depending on the type of command.

### RM / RI / RC

These commands immediately send a response once receipt of data is complete. No NAK [01] (BUSY) signal is given.



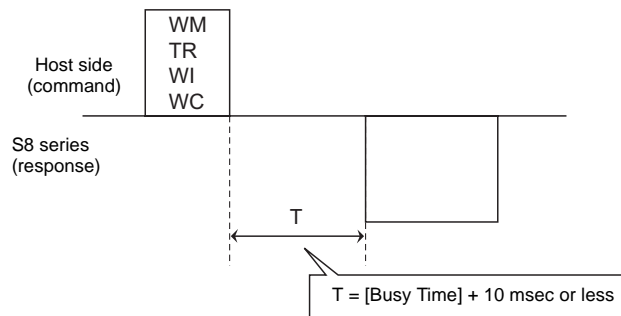
### WM / TR / WI / WC

Once receipt of data is complete, these commands first check the display status. If the display status is found to be complete, a response is sent and a command is executed.

If the status is BUSY and the display is completed within the time set in [Busy Time], a response is sent.

If the display is not completed within the specified time, an NAK [01] (BUSY) signal is sent. In this case, it is necessary to retransmit the command.

When [Busy Time] is set as [0], the machine waits until the display is complete, and then a response is transmitted after a command is executed.





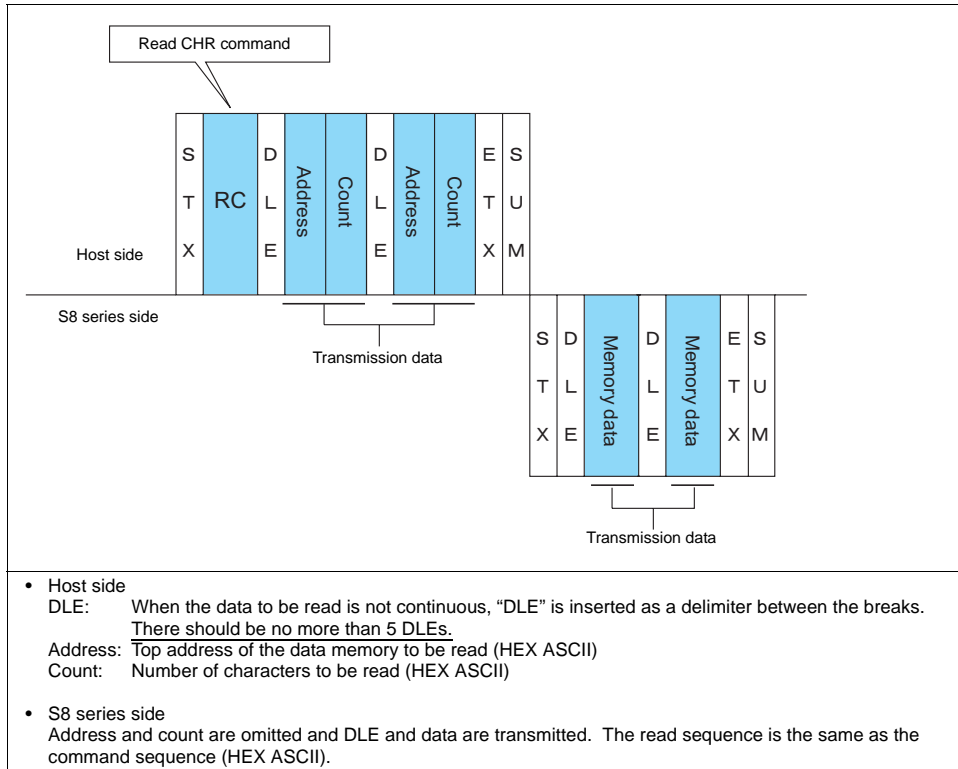
### 23.4.3 Command

#### RC: Read CHR

This command is used to read data memory as characters.

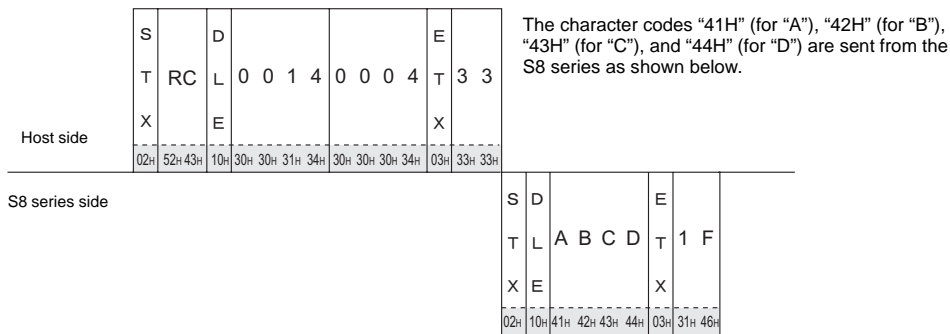
- \* When character data is sent, 1 character (1 byte) is converted into a two-byte ASCII code and transmitted by the read memory command. When the read CHR command is given, character data is not converted into the ASCII code before transmission, and thus, the transmission time is decreased by approximately 1/2.

#### Details of read CHR



#### Example:

Call up 4 characters that are written at the top of the address \$u0020 (0014H).

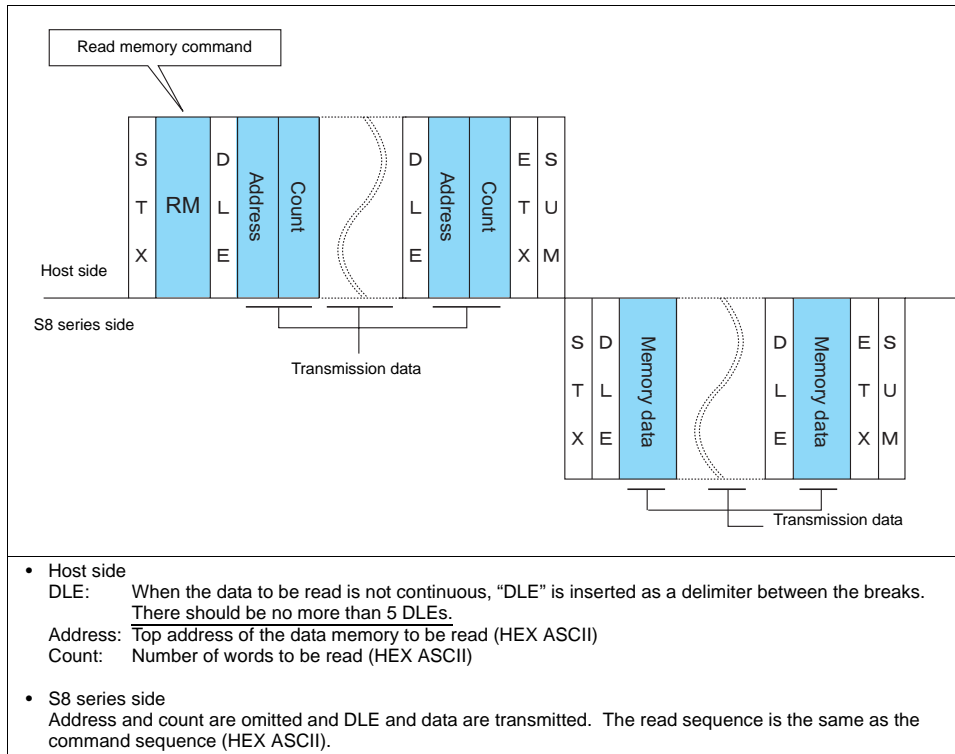


## RM: Read Memory

This command is used to read data memory.

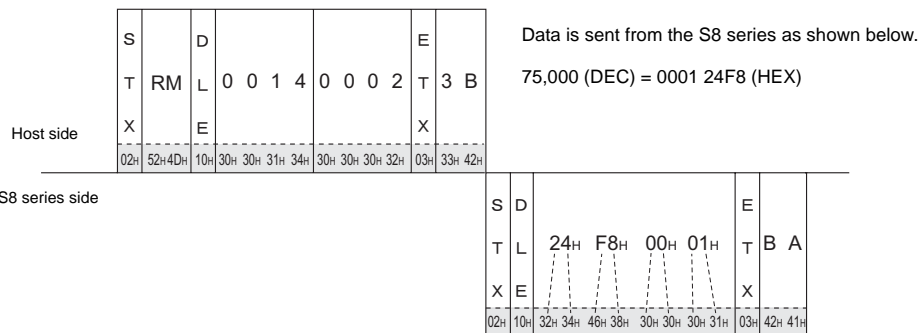
- \* Communication speed is increased when you use the read CHR command to read characters.

### Details of read memory



### Example:

Read the double-word data "75,000" (DEC) contained in the address \$u0020 (0014H).



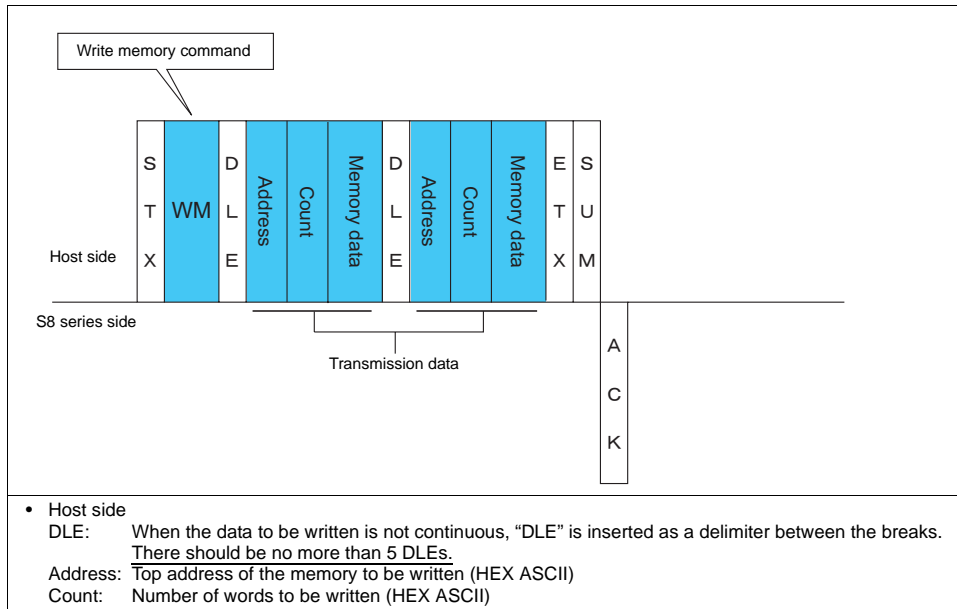


## WM: Write Memory

This command is used to write data memory.

- \* Communication speed is increased when you use the write CHR command to write characters.

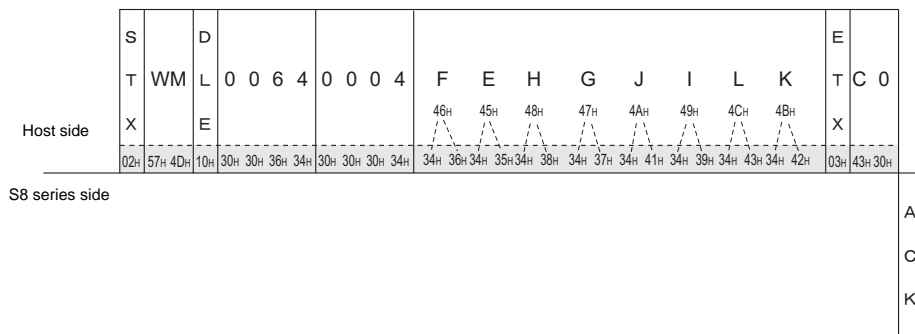
### Details of write memory



### Example:

Send data to display the following characters on the S8 series.

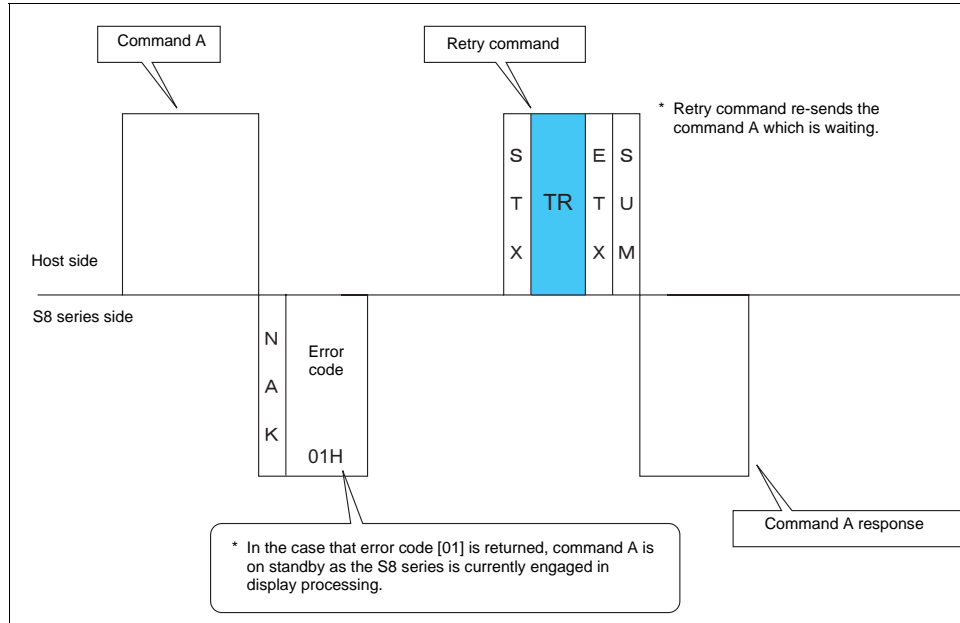
- \$u0100 (0064H), EF (= 4645 H)
- \$u0101 (0065H), GH (= 4847 H)
- \$u0102 (0066H), IJ (= 4A49 H)
- \$u0103 (0067H), KL (= 4C4B H)



## TR: Retry Command

This command is used to re-send a write command/write CHR command when an NAK error code [01] is returned.

### Details of retry



## WI: Interrupt Setting Command

This command is used to send interrupt conditions. It can be used for 1 : 1 connection.

### Details of interrupt setting command

Interrupt setting command

	S	WI	Data	E	S	
Host side	T			T	U	
	X			X	M	

---

S8 series side

A  
C  
K

- Host side
  - Data: Interrupt conditions is specified when the interrupt data bit is set. (HEX ASCII)

Interrupt conditions

07	06	05	04	03	02	01	00

0: Interrupt prohibited  
1: Interrupt allowed

- Switch ON
- Switch OFF
- Keypad write & character entry
- Screen internal switching

Switch ON	Interrupt when the switch changes from OFF to ON Valid only when [Action] of the switch is [Normal], [Block], [+Block], [-Block] or [Mode]
Switch OFF	Interrupt when the switch changes from ON to OFF Valid only when [Action] of the switch is [Normal], [Block], [+Block], [-Block] or [Mode]
Keypad write	Interrupt when the [ENTER] switch on the keypad is pressed
Screen internal switching	Interrupt when the screen changes based on an internal switch

\* Macro (OUT\_ENQ): Interrupt enabled all the time

### Example:

Interrupt settings are as shown below.

07	06	05	04	03	02	01	00
0	0	0	0	1	1	0	0

- Switch ON: disabled
- Switch OFF: disabled
- Keypad write & character entry: enabled
- Screen internal switching: enabled

	S			E		
	T	WI	0C	T	18	
Host side	X			X		
	02H	57H 49H	30H 43H	03H	31H 38H	

---

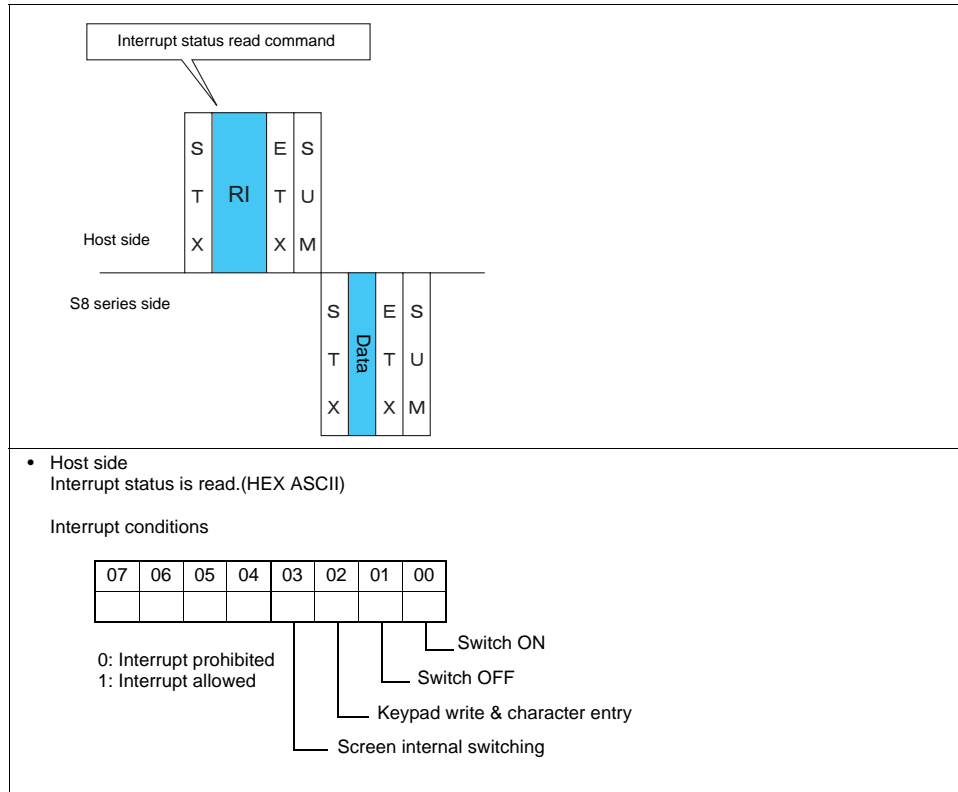
S8 series side

A  
C  
K

## RI: Interrupt Status Read Command

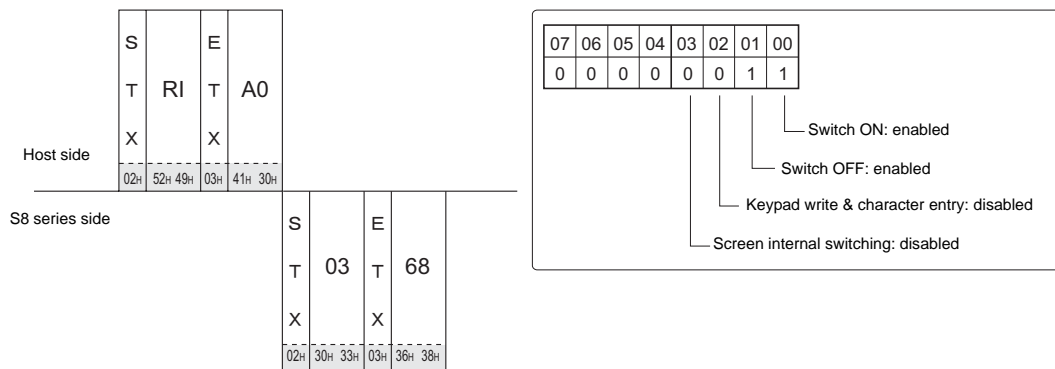
This command is used to read interrupt setting status. It can be used for 1 : 1 connection.

### Details of interrupt status read command



### Example:

Interrupt status is read.



## 23.4.4 Interrupt (ENQ)

The interrupt command can be used for 1 : 1 connection.\* Interrupt data becomes the contents of write areas n + 2 to n + 7. (See page 23-8.)

\* For RS-485 (2-wire connection), interrupts cannot be used.

### Interrupt codes and conditions

An interrupt code is sent to the host for the following actions.

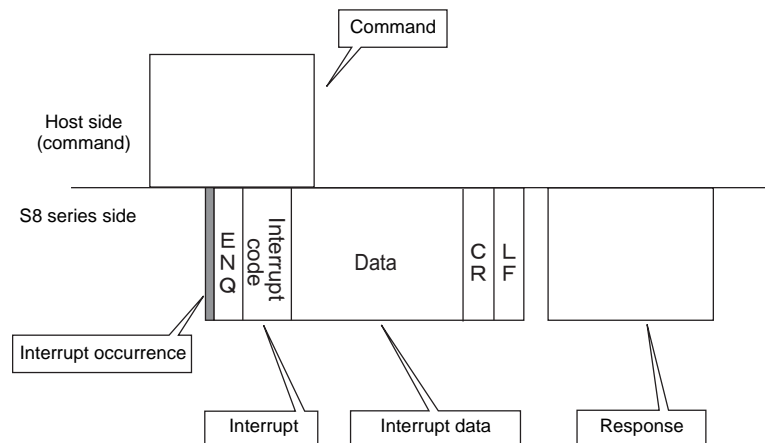
Interrupt Codes	Interrupt Conditions
00H	The regular switch is changed from ON to OFF or OFF to ON when it is pressed.
01H	The "Write" switch on the keypad or on the keyboard is changed from OFF to ON when it is pressed.*
02H	The screen is switched by an internal switch.
10H ⋮ 2FH	The macro command [OUT_ENQ] is executed (user setting).

\* (If [Use the Write Flag] is checked, write enable bit must be set in order to send an interrupt code.

### Interrupt timing

When an interrupt condition occurs while the host is transmitting a command or before the S8 series transmits a response, the interrupt code will be transmitted before the response is transmitted.

To use an interrupt, it is necessary to enable interrupt code detection when a response is received on the host program.



### Interrupt data

- When a regular switch is pressed:

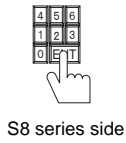
 S8 series side	E	00	Screen No.	SW0	SW1	ENT0	ENT1	ENT2	E	S
	N								T	U
	Q		WORD	WORD	WORD	WORD	WORD	WORD	X	M

A "regular switch" means a switch for which [Momentary] is selected for [Output Action] and \$s0080 to 0095 is set for [Output Memory]. When this switch is pressed, the following actions take place. Output memory is set (0 → 1) while the switch is held down, and is reset (1 → 0) when the switch is released. At the same time, the switch number that corresponds to the output memory is written in write areas n + 3. For details on the output memory and the switch number, see page 23-31.



- When the "Write" switch on the keypad is pressed:

When the [ENT] switch on the keypad is pressed

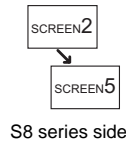


S8 series side

E N Q	01	Screen No.	SW0	SW1	ENT0	ENT1	ENT2	E	S
								T	U
		WORD	WORD	WORD	WORD	WORD	WORD	X	M

ENT0/1/2 is the same as system memory area (n + 5, n + 6, n + 7).

- When the screen is internally changed:

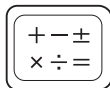


S8 series side

E N Q	02	Screen No.	SW0	SW1	ENT0	ENT1	ENT2	E	S
								T	U
		WORD	WORD	WORD	WORD	WORD	WORD	X	M

- When a macro command (OUT\_ENQ) is executed:

With an OUT\_ENQ command, you can either convert the data into HEX code and transmit it (word transmission), or you can transmit the data just as it is without converting it (character transmission).  
For more information on "OUT\_ENQ", refer to the Macro Reference manual.



Word transmission

S8 series side

E N Q	XX	00	Transmission memory address	Number of transmission words	Word data	E	S
						T	U
			WORD	WORD		X	M

Transmission format: word transmission  
Interrupt code (10H to 2FH)

Character transmission

S8 series side

E N Q	XX	01	Transmission memory address	Number of transmission characters	Word data	E	S
						T	U
			WORD	WORD		X	M

Transmission format: character transmission  
Interrupt code (10H to 2FH)



## 23.5 Memory Map

### Memory

Inside the S8 series, there is internal memory necessary for screen display called “user memory (\$u)”, as well as memory that the S8 series uses for the system called “system memory (\$s)”.

### User Memory (\$u)

32768 words are available for user memory. This area is usable as desired for screen data. Also the host computer can write to and read from the area.

The memory map is as shown below.

\$u0000	
\$u0001	
\$u0002	
\$u0003	
\$u0004	
\$u0005	
\$u0006	
User memory (32768 words)	
\$u32761	
\$u32762	
\$u32763	
\$u32764	
\$u32765	
\$u32766	
\$u32767	

## System Memory (\$s)

2048 words are available for system memory. System memory is memory that writes S8 series action status when the S8 series is currently displaying something. With this written information, it is possible to check overlap status, buffer area, printer, backlight, and slave station status in multi-drop connection mode. In the table below, a small part (\$s80 to 95) of system memory is extracted. For other memory addresses, refer to the Reference Manual.

\* System memory cannot be read or written from the host computer.

### Address \$s0080 to 95

Set [Output Memory] in location (\$s0080 to 95) of system memory, and select [Momentary] for [Output Action] of a switch. When the switch is pressed, output memory is set (0 → 1) and the corresponding switch number is written in system setting areas n + 3. (See page 23-8.)

The relationship between the output memory and the switch number is shown in the following diagram. For details about the output of a switch, see page 23-26.

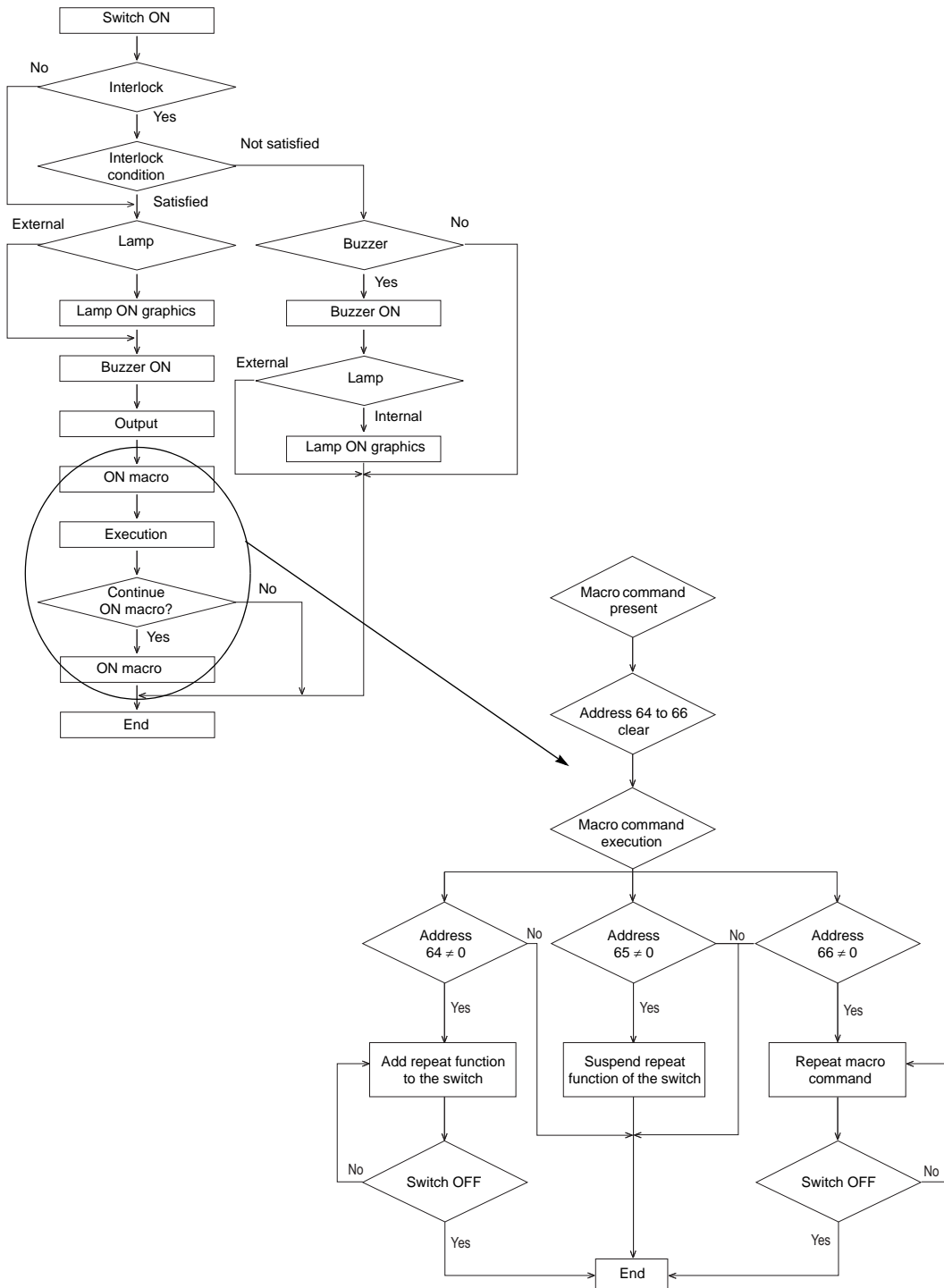
Address	Contents																																
.																																	
\$s80	Universal serial switch output 0 Switch No. 0 to 15																																
	MSB																																
	<table border="1" style="width: 100%; text-align: center;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>No.</td><td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> </table>	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	No.	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																		
No.	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																	
LSB																																	
\$s81	Universal serial switch output 1 Switch No. 16 to 31																																
	MSB																																
	<table border="1" style="width: 100%; text-align: center;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>No.</td><td>31</td><td>30</td><td>29</td><td>28</td><td>27</td><td>26</td><td>25</td><td>24</td><td>23</td><td>22</td><td>21</td><td>20</td><td>19</td><td>18</td><td>17</td><td>16</td> </tr> </table>	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	No.	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																		
No.	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16																	
LSB																																	
\$s82	Universal serial switch output 2 Switch No. 32 to 47																																
	MSB																																
	<table border="1" style="width: 100%; text-align: center;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>No.</td><td>47</td><td>46</td><td>45</td><td>44</td><td>43</td><td>42</td><td>41</td><td>40</td><td>39</td><td>38</td><td>37</td><td>36</td><td>35</td><td>34</td><td>33</td><td>32</td> </tr> </table>	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	No.	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																		
No.	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33	32																	
LSB																																	
\$s83	Universal serial switch output 3 Switch No. 48 to 63																																
	MSB																																
	<table border="1" style="width: 100%; text-align: center;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>No.</td><td>63</td><td>62</td><td>61</td><td>60</td><td>59</td><td>58</td><td>57</td><td>56</td><td>55</td><td>54</td><td>53</td><td>52</td><td>51</td><td>50</td><td>49</td><td>48</td> </tr> </table>	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	No.	63	62	61	60	59	58	57	56	55	54	53	52	51	50	49
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																		
No.	63	62	61	60	59	58	57	56	55	54	53	52	51	50	49	48																	
LSB																																	
\$s84	Universal serial switch output 4 Switch No. 64 to 79																																
	MSB																																
	<table border="1" style="width: 100%; text-align: center;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>No.</td><td>79</td><td>78</td><td>77</td><td>76</td><td>75</td><td>74</td><td>73</td><td>72</td><td>71</td><td>70</td><td>69</td><td>68</td><td>67</td><td>66</td><td>65</td><td>64</td> </tr> </table>	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	No.	79	78	77	76	75	74	73	72	71	70	69	68	67	66	65
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																		
No.	79	78	77	76	75	74	73	72	71	70	69	68	67	66	65	64																	
LSB																																	
\$s85	Universal serial switch output 5 Switch No. 80 to 95																																
	MSB																																
	<table border="1" style="width: 100%; text-align: center;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>No.</td><td>95</td><td>94</td><td>93</td><td>92</td><td>91</td><td>90</td><td>89</td><td>88</td><td>87</td><td>86</td><td>85</td><td>84</td><td>83</td><td>82</td><td>81</td><td>80</td> </tr> </table>	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	No.	95	94	93	92	91	90	89	88	87	86	85	84	83	82	81
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																		
No.	95	94	93	92	91	90	89	88	87	86	85	84	83	82	81	80																	
LSB																																	
\$s86	Universal serial switch output 6 Switch No. 96 to 111																																
	MSB																																
	<table border="1" style="width: 100%; text-align: center;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>No.</td><td>111</td><td>110</td><td>109</td><td>108</td><td>107</td><td>106</td><td>105</td><td>104</td><td>103</td><td>102</td><td>101</td><td>100</td><td>99</td><td>98</td><td>97</td><td>96</td> </tr> </table>	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	No.	111	110	109	108	107	106	105	104	103	102	101	100	99	98	97
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																		
No.	111	110	109	108	107	106	105	104	103	102	101	100	99	98	97	96																	
LSB																																	
\$s87	Universal serial switch output 7 Switch No. 112 to 127																																
	MSB																																
	<table border="1" style="width: 100%; text-align: center;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>No.</td><td>127</td><td>126</td><td>125</td><td>124</td><td>123</td><td>122</td><td>121</td><td>120</td><td>119</td><td>118</td><td>117</td><td>116</td><td>115</td><td>114</td><td>113</td><td>112</td> </tr> </table>	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	No.	127	126	125	124	123	122	121	120	119	118	117	116	115	114	113
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																		
No.	127	126	125	124	123	122	121	120	119	118	117	116	115	114	113	112																	
LSB																																	
\$s88	Universal serial switch output 8 Switch No. 128 to 143																																
	MSB																																
	<table border="1" style="width: 100%; text-align: center;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>No.</td><td>143</td><td>142</td><td>141</td><td>140</td><td>139</td><td>138</td><td>137</td><td>136</td><td>135</td><td>134</td><td>133</td><td>132</td><td>131</td><td>130</td><td>129</td><td>128</td> </tr> </table>	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	No.	143	142	141	140	139	138	137	136	135	134	133	132	131	130	129
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																		
No.	143	142	141	140	139	138	137	136	135	134	133	132	131	130	129	128																	
LSB																																	

Address	Contents																
\$s89	Universal serial switch output 9 Switch No. 144 to 159																
	MSB															LSB	
	No.	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	159	158	157	156	155	154	153	152	151	150	149	148	147	146	145	144	
\$s90	Universal serial switch output 10 Switch No. 160 to 175																
	MSB															LSB	
	No.	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	175	174	173	172	171	170	169	168	167	166	165	164	163	162	161	160	
\$s91	Universal serial switch output 11 Switch No. 176 to 191																
	MSB															LSB	
	No.	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	191	190	189	188	187	186	185	184	183	182	181	180	179	178	177	176	
\$s92	Universal serial switch output 12 Switch No. 192 to 207																
	MSB															LSB	
	No.	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	207	206	205	204	203	202	201	200	199	198	197	196	195	194	193	192	
\$s93	Universal serial switch output 13 Switch No. 208 to 223																
	MSB															LSB	
	No.	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	223	222	221	220	219	217	218	216	215	214	213	212	211	210	209	208	
\$s94	Universal serial switch output 14 Switch No. 224 to 239																
	MSB															LSB	
	No.	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	239	238	237	236	235	234	233	232	231	230	229	228	227	226	225	224	
\$s95	Universal serial switch output 15 Switch No. 240 to 255																
	MSB															LSB	
	No.	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	255	254	253	252	251	250	249	248	247	246	245	244	243	242	241	240	
:																	

### Switch ON Macro Action

The macro command that controls a repeat function in the switch ON macro, as well as the processing sequence, is shown in the following diagram.

Switch action flowchart



MEMO

Please use this page freely.

# Appendix

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Appendix 1 Device Memory Map

Appendix 2 System Memory

Appendix 3 n : 1 Connection

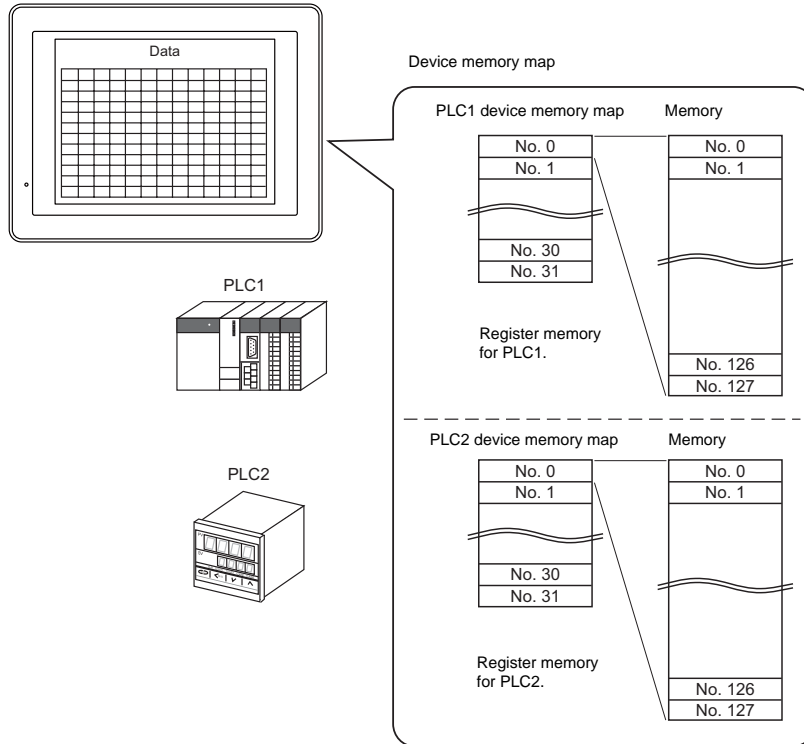
Appendix 4 Ladder Transfer Function



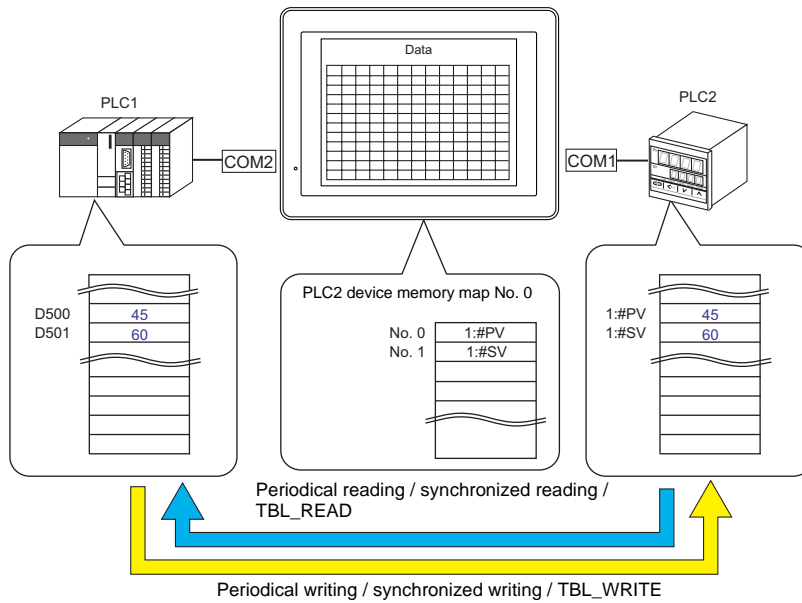


## Appendix 1 Device Memory Map

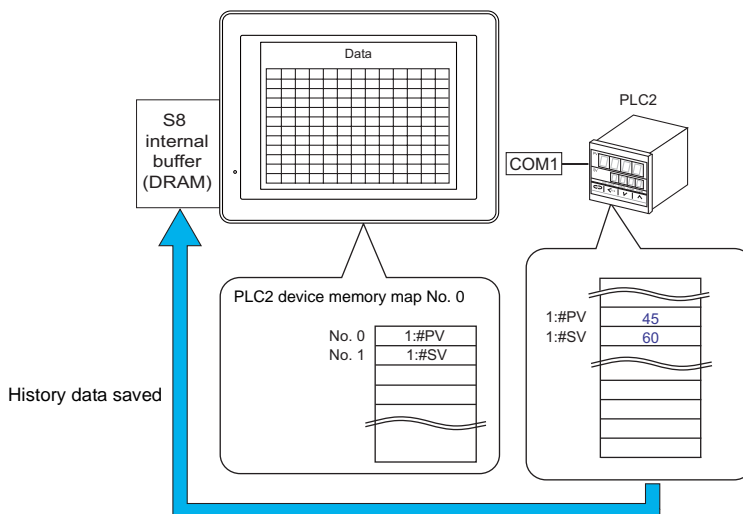
- Within the S8 series, for each logical port there are a total of 32 device memory maps from No. 0 to No. 31. 128 memory addresses can be registered in each memory map, and batch transfer of data among devices, and sampling, are possible.



- Functions that use device memory maps
  - Periodical reading  
The memory data registered in a device memory map is periodically transferred to other devices. (page App1-7)
  - Periodical writing  
The data of other devices is periodically transferred to the memories registered in a device memory map. (page App1-9)
  - Synchronized reading  
The data of each memory registered in a device memory map is transferred to another device when its bit is set (ON). (page App1-8)
  - Synchronized writing  
The data of other devices is transferred to memory addresses that are registered in the memory map and whose bits are set (ON). (page App1-10)
  - Macro (TBL\_READ, TBL\_WRITE)  
The data of memory addresses registered in a device memory map is transferred by using a macro command. (page App1-14)



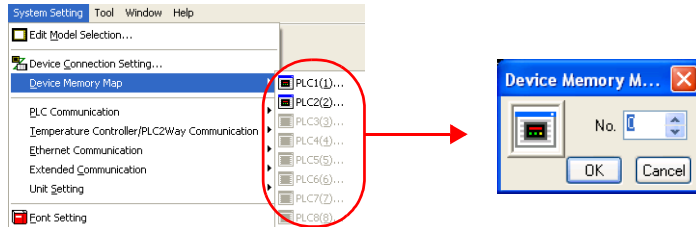
- Sampling  
The history data of the memory addresses registered in a device memory map is saved in the S8 series internal buffer. (page App1-12)



## Device Memory Map Editing

### Starting

- Click [System Setting] → [Device Memory Map] → [PLCn].  
The [Device Memory Map: PLCn] dialog is displayed.



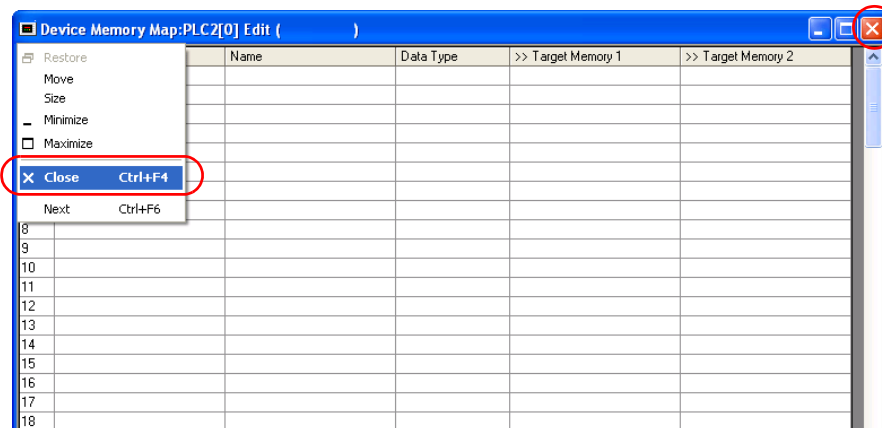
- Select the device memory map number from 0 to 31 and click [OK].  
The [Device Memory Map Edit] window is opened.

No.	PLC2 Memory	Name	Data Type	>> Target Memory 1	>> Target Memory 2
0					
1					
2					
3					
4					
5					
6					
7					
8					
9					
10					
11					
12					
13					

There are a total of 32 device memory maps numbered from 0 to 31 for each logical port, and 128 memory points can be registered for each memory map.

### Ending

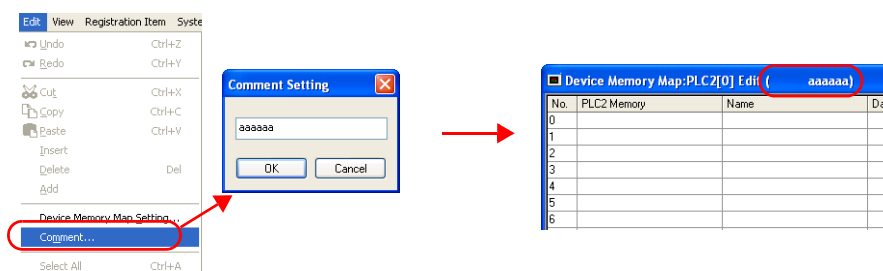
Click [Close] in the drop-down menu, or click the [Close] button at the top right corner.



### Comment Setting

A comment can be set for each device memory map.

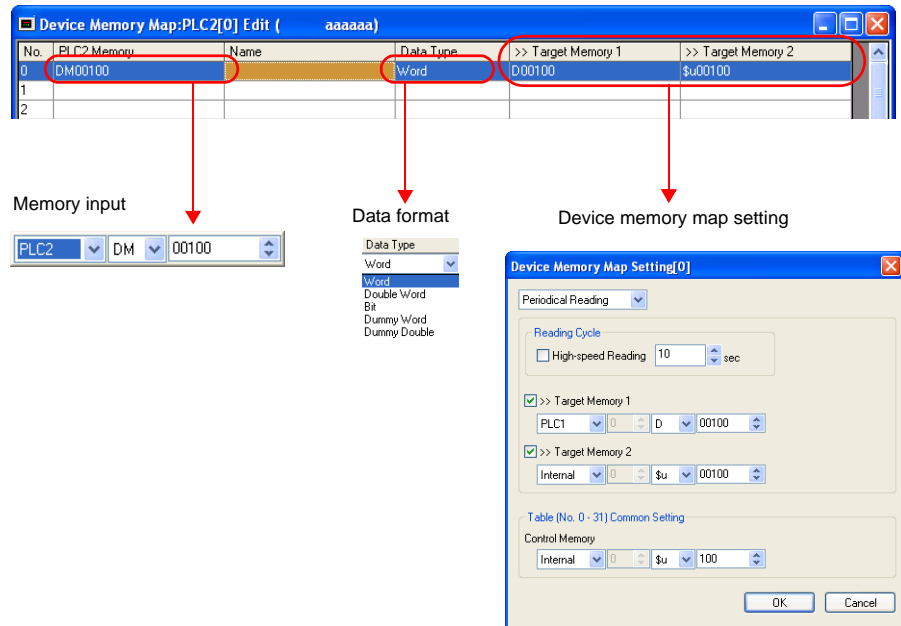
- Click [Edit] → [Comment]. The [Comment Setting] dialog is displayed.



- Enter the desired comment and click [OK]. The entered comment is displayed.

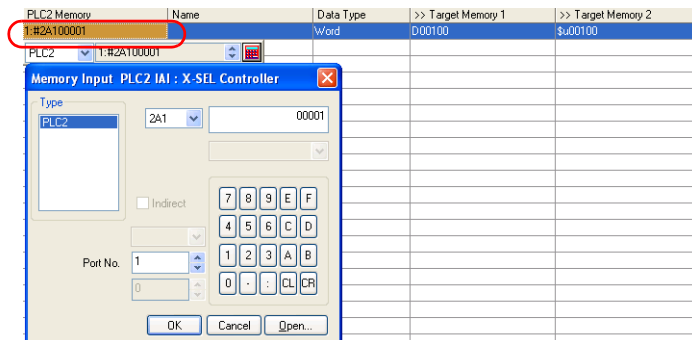
## Device Memory Map Editing

Clicking any cell displays the relevant setting menu.

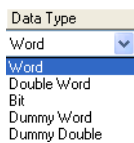


### 1. Memory Input

Specify the memory address whose data is to be transferred. If you have opened the PLC2 device memory map editing dialog, register the PLC2 memory.



### 2. Data Type



Word	Data is handled as numerical data of one word. Data is transferred based on the setting at [Code] in the [Communication Setting] tab window for each logical port. <sup>*1</sup>
Double Word	Data is handled as numerical data of two words. Data is transferred based on the setting at [Code] in the [Communication Setting] tab window for each logical port. <sup>*1</sup>
Bit	Data is handled as bit information of one word. Data is transferred <u>without conversion</u> . <sup>*2</sup>
Dummy Word Dummy Double	The source and target memory addresses are automatically registered with serial numbers assigned. If you would like to skip any memory address, keep the cell blank (no setting). It is regarded as a dummy word or double-word. For reading: "0" is always stored in the target memory address. The memory is not usable for any other purposes. For writing: The source memory address can be used for other purposes.

\*1 When [Word] or [Double Word] is selected:  
In the internal memory of the S8 series, data is normally handled as DEC with signs.

		Code	Bit																																																															
Read ↓	Transfer source PLCn	Communication setting BCD	<table border="1" style="width: 100%; text-align: center;"> <tr> <td colspan="15">MSB</td> <td>LSB</td> </tr> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>0</td><td>0</td><td>0</td><td>0</td> </tr> </table>																MSB															LSB	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0
	MSB															LSB																																																		
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																																																		
	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0																																																		
S8 internal memory	DEC	<table border="1" style="width: 100%; text-align: center;"> <tr> <td colspan="15">MSB</td> <td>LSB</td> </tr> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>0</td><td>1</td><td>0</td> </tr> </table>																MSB															LSB	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	
MSB															LSB																																																			
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																																																			
0	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0																																																			
Transfer target PLCm	Communication setting DEC	<table border="1" style="width: 100%; text-align: center;"> <tr> <td colspan="15">MSB</td> <td>LSB</td> </tr> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>0</td><td>1</td><td>0</td> </tr> </table>																MSB															LSB	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	
	MSB															LSB																																																		
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																																																			
0	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0																																																			
	Communication setting BCD	<table border="1" style="width: 100%; text-align: center;"> <tr> <td colspan="15">MSB</td> <td>LSB</td> </tr> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>0</td><td>0</td><td>0</td><td>0</td> </tr> </table>																MSB															LSB	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	
MSB															LSB																																																			
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																																																			
0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0																																																			

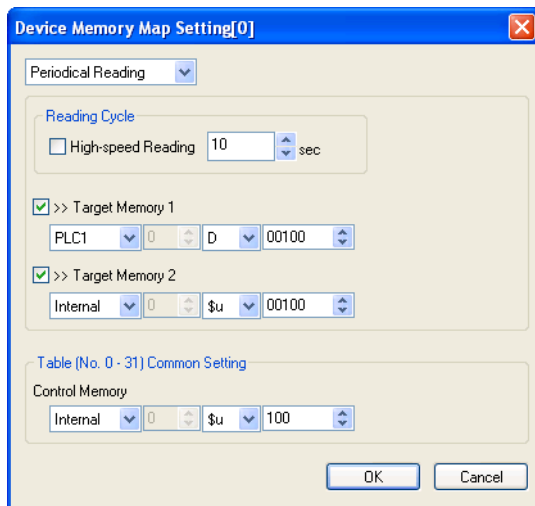
\*2 When [Bit] is selected:

		Code	Bit																																																															
Read ↓	Transfer source PLCn	Communication setting BCD																																																																
	S8 internal memory	DEC	<table border="1" style="width: 100%; text-align: center;"> <tr> <td colspan="15">MSB</td> <td>LSB</td> </tr> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>0</td><td>0</td><td>0</td><td>0</td> </tr> </table>																MSB															LSB	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0
	MSB															LSB																																																		
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																																																			
0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0																																																			
Transfer target PLCm	Communication setting DEC BCD																																																																	

3. Device memory map setting

In this dialog, set the use of each memory map.

- TBL\_READ, TBL\_WRITE
- Periodical Reading → page App1-7
- Synchronized Reading → page App1-8
- Periodical Writing → page App1-9
- Synchronized Writing → page App1-10



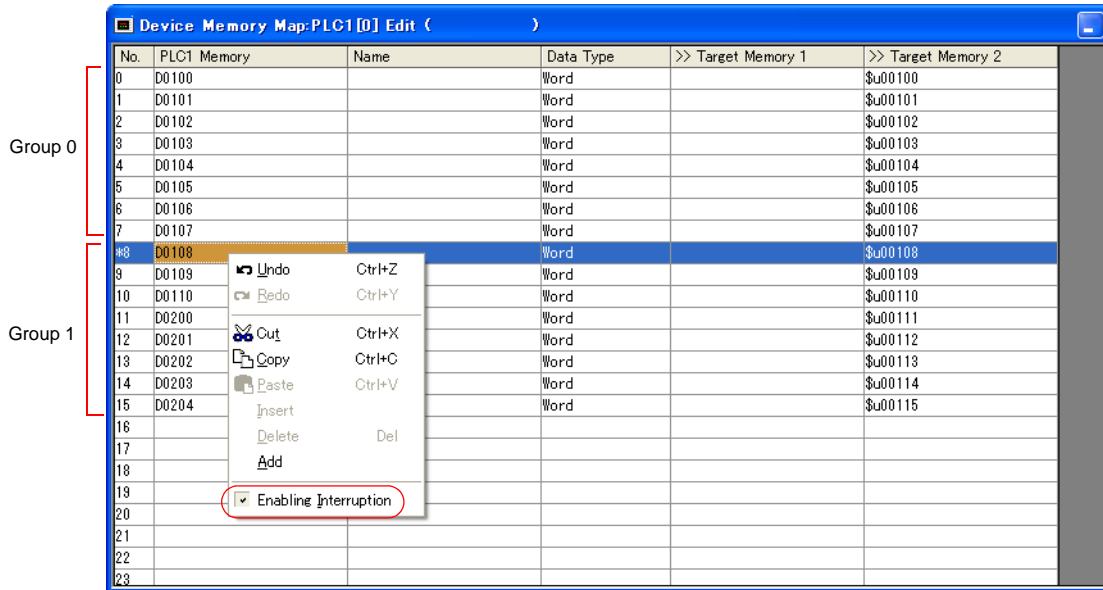
### Enabling interruption

Interrupt is enabled by selecting [Enabling Interruption] in the right-click menu displayed by right-clicking on the device memory map number. The “\*” mark is displayed at the selected memory.

When interruption is enabled, switch data output, cycle reading or sampling can be executed during the device memory map process.

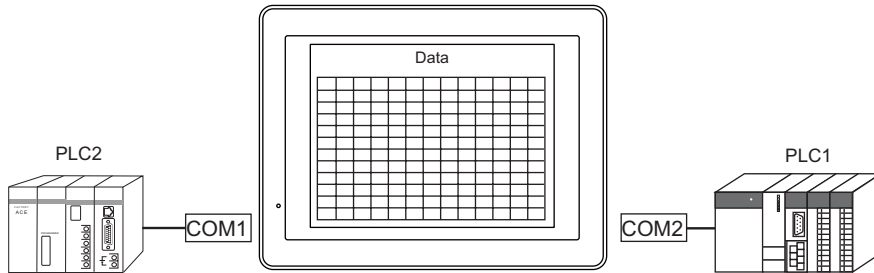
Operation in the setting shown below:

- Reading group 0 (No. 0 to No. 7)
- ↓
- Switch data output, cycle reading or sampling
- ↓
- Reading group 1 (No. 8 to No. 15)



## Periodical Reading

The memory data registered in a device memory map is transferred to the target memory address every cycle set at [Reading Cycle].



PLC2 device memory map No. 0

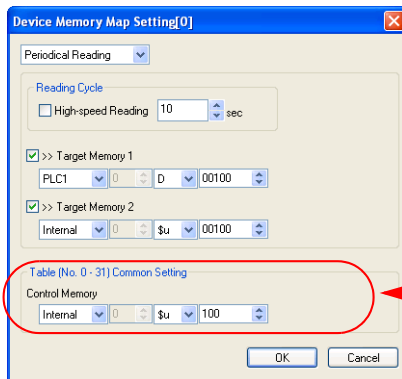
No.	PLC2 Memory	Name	Data Type	>> Target Memory 1	>> Target Memory 2
0	1:#2A100001		Word	D00100	\$u00100
1	0:#20B01600		Word	D00101	\$u00101
2					
3					
4					
5					
6					
7					

Transferred at intervals of 5 sec.

### Setting items

Items that must be set to perform periodical reading

- "Device Memory Map Editing" (page App1-3)
- Device memory map setting



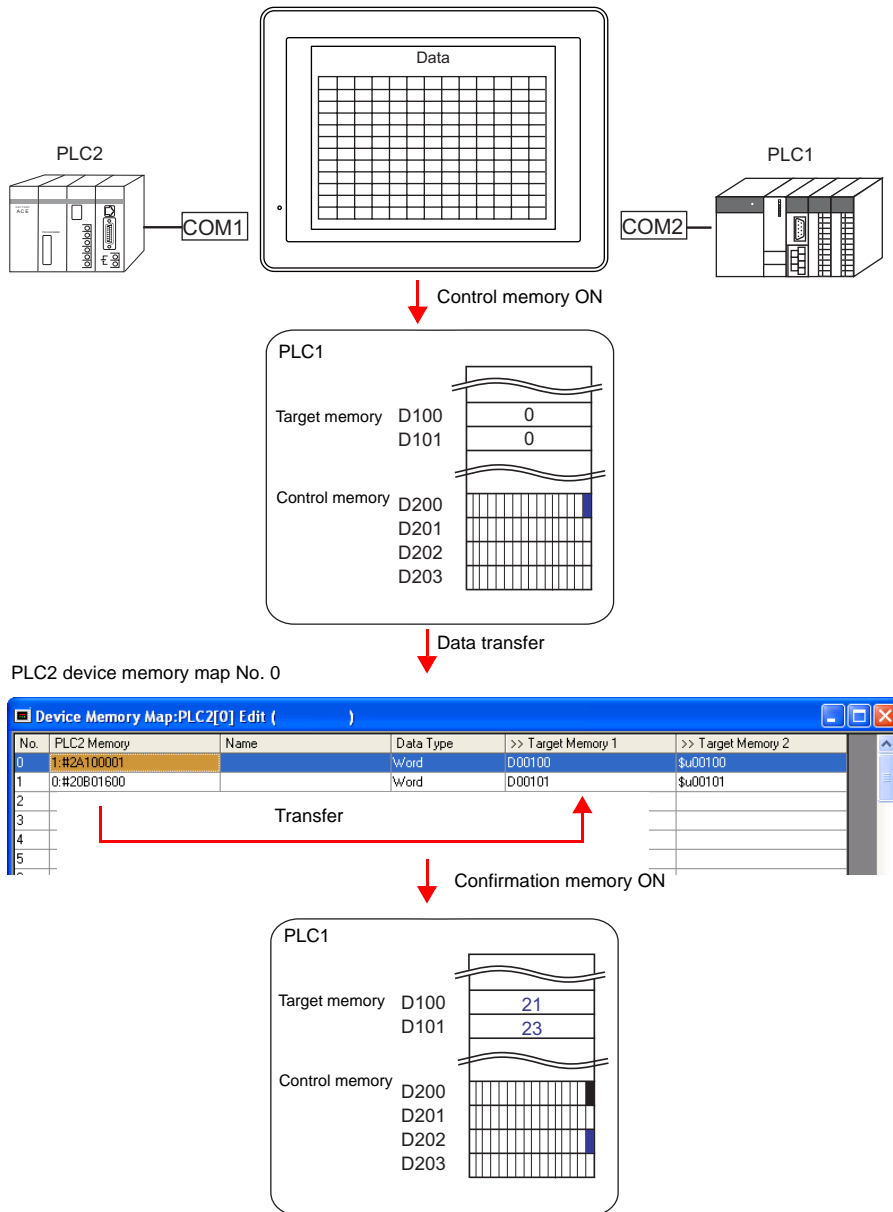
Disabled when [Periodical Reading] is selected.

Function	Periodical Reading											
Reading Cycle	Specify the data read cycle. <table border="1" style="margin-left: 20px;"> <thead> <tr> <th rowspan="2">[High-speed Reading] check box*</th> <th colspan="2">Reading Cycle</th> </tr> <tr> <th>Setting Range</th> <th>Unit</th> </tr> </thead> <tbody> <tr> <td>Unchecked</td> <td>1 to 3600</td> <td>1s</td> </tr> <tr> <td>Checked</td> <td>1 to 3600</td> <td>100 ms</td> </tr> </tbody> </table>	[High-speed Reading] check box*	Reading Cycle		Setting Range	Unit	Unchecked	1 to 3600	1s	Checked	1 to 3600	100 ms
[High-speed Reading] check box*	Reading Cycle											
	Setting Range	Unit										
Unchecked	1 to 3600	1s										
Checked	1 to 3600	100 ms										
>> Target Memory 1 >> Target Memory 2	Set the memory address at which the read data is to be stored.											
Control Memory	This option is disabled when [Periodical Reading] is selected.											



## Synchronized Reading

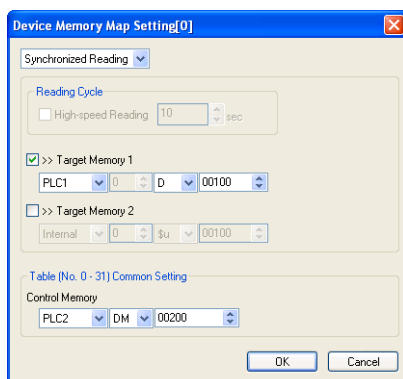
The memory data registered in a device memory map is transferred to the target memory address at the leading edge of each bit (0 → 1).



### Setting items

Items that must be set to perform synchronized reading

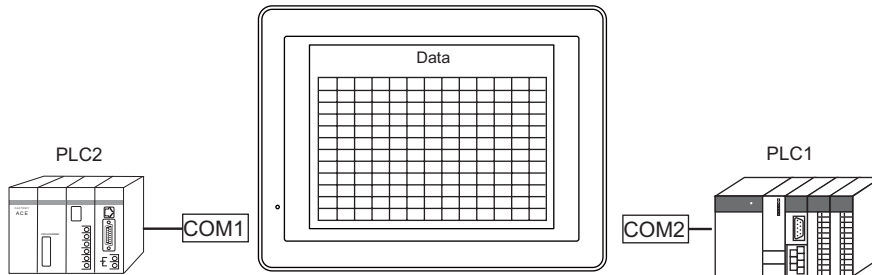
- “Device Memory Map Editing” (page App1-3)
- Device memory map setting



Function	Synchronized Reading
>> Target Memory 1 >> Target Memory 2	Set the memory address at which the read data is to be stored.
Control Memory	Enter a memory address as the trigger for synchronized reading. The specified memory address is used for the device memory map Nos. 0 to 31. Four words are occupied. For more information, see "Control Memory" (page App1-11).

## Periodical Writing

The data at the source memory address is transferred to a memory registered in a device memory map in each cycle set at [Writing Cycle].



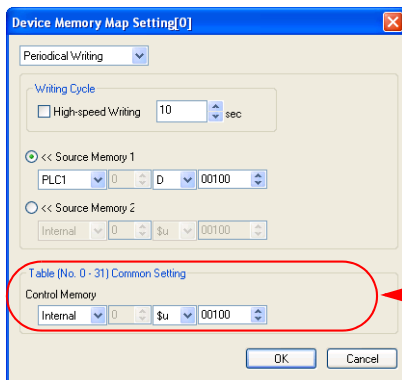
PLC2 device memory map No. 0

No.	PLC2 Memory	Name	Data Type	<< Source Memory 1	<< Source Memory 2
0	1.#2A100001		Word	D00100	
1	0.#20B01600		Word	D00101	
2					
3					
4					
5					
6					

### Setting items

Items that must be set to perform periodical writing

- "Device Memory Map Editing" (page App1-3)
- Device memory map setting

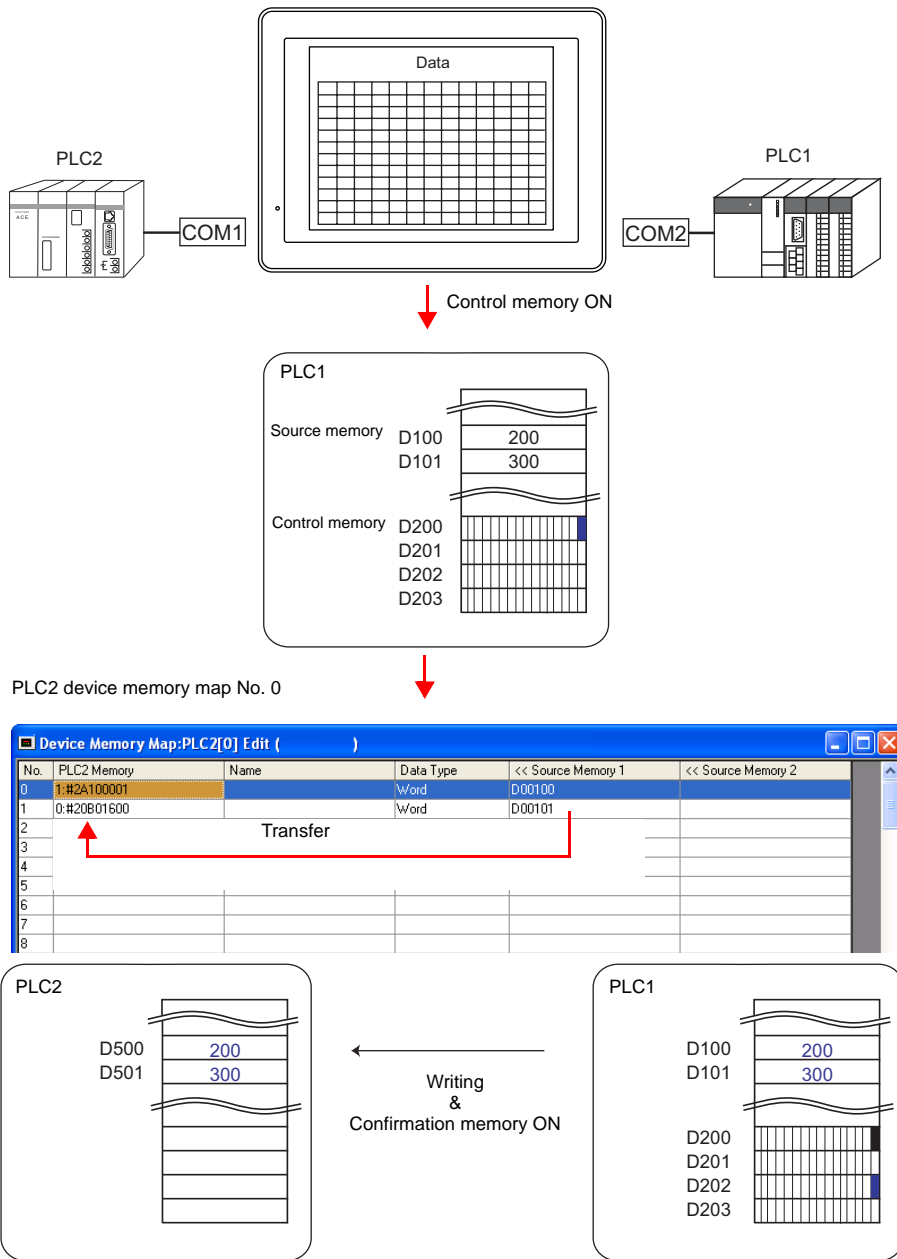


Disabled when [Periodical Writing] is selected.

Function	Periodical Writing									
Writing Cycle	Specify the data writing cycle. <table border="1" style="margin-left: 20px;"> <tr> <td rowspan="3" style="text-align: center;"><input type="checkbox"/> [High-speed Writing] check box*</td> <td colspan="2" style="text-align: center;">Writing Cycle</td> </tr> <tr> <td style="text-align: center;">Setting Range</td> <td style="text-align: center;">Unit</td> </tr> <tr> <td style="text-align: center;">Unchecked</td> <td style="text-align: center;">1 to 3600 1 s</td> </tr> <tr> <td style="text-align: center;">Checked</td> <td style="text-align: center;">1 to 3600 100 ms</td> </tr> </table>	<input type="checkbox"/> [High-speed Writing] check box*	Writing Cycle		Setting Range	Unit	Unchecked	1 to 3600 1 s	Checked	1 to 3600 100 ms
<input type="checkbox"/> [High-speed Writing] check box*	Writing Cycle									
	Setting Range		Unit							
	Unchecked	1 to 3600 1 s								
Checked	1 to 3600 100 ms									
<< Source Memory 1 << Source Memory 2	Specify the memory address of the source data.									
Control Memory	This option is disabled when [Periodical Writing] is selected.									

## Synchronized Writing

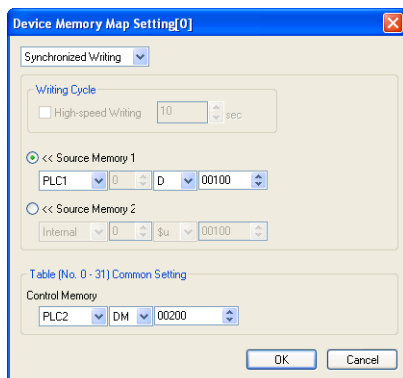
The data at the source memory address is transferred to a memory address registered in a device memory map at the leading edge of the control memory bit (0 → 1).



### Setting items

Items that must be set to perform synchronized writing

- "Device Memory Map Editing" (page App1-3)
- Device memory map setting



Function	Synchronized Writing
<< Source Memory 1 << Source Memory 2	Specify the storage target memory address for the source data.
Control Memory	Enter a memory address as the trigger for synchronized reading. The specified memory address is used for the device memory map Nos. 0 to 31. Four words are occupied. For more information, see "Control Memory" (page App1-11).

## Control Memory

Control memory is used for executing synchronized reading/synchronized writing.  
Consecutive four words starting from control memory "n" are allocated.

Control Memory n	Contents	Memory Type
n	Read/Write command memory	→ S8
n + 1		
n + 2	Read/Write confirmation memory	← S8
n + 3		

### Read/Write command memory (control memory "n" and "n + 1")

One bit is allocated to each table.

At the leading edge of a bit (0 → 1), reading from or writing to memory set in the corresponding device memory map occurs.

n

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	← Bit number
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	←

Device memory map Nos. 0 to 15

n + 1

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	← Bit number
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	←

Device memory map Nos. 16 to 31

### Read/Write confirmation memory (control memory "n + 2" and "n + 3")

One bit is allocated to each table.

When the bit of the command memory is set (0 → 1) and the resulting reading or writing is completed, the bit of the corresponding confirmation memory is set (0 → 1).

When a bit of the command memory is reset (1 → 0), the confirmation memory bit of the corresponding memory map number is reset (1 → 0).

n + 2

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	← Bit number
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	←

Device memory map Nos. 0 to 15

n + 3

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	← Bit number
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	←

Device memory map Nos. 16 to 31

## Sampling

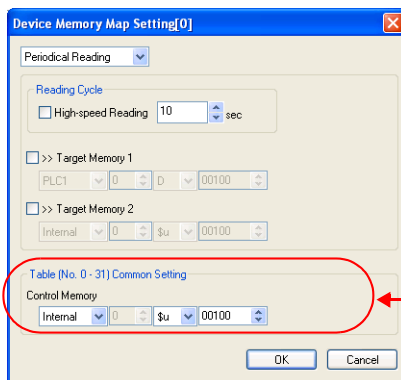
The history data of the memory addresses registered in a device memory map is saved in the S8 series internal buffer.

### Setting items

Items that must be set to perform sampling

- “Device Memory Map Editing” (page App1-3)
- Device memory map setting
- Buffering area setting
- Trend sampling or data sampling

### Device memory map setting

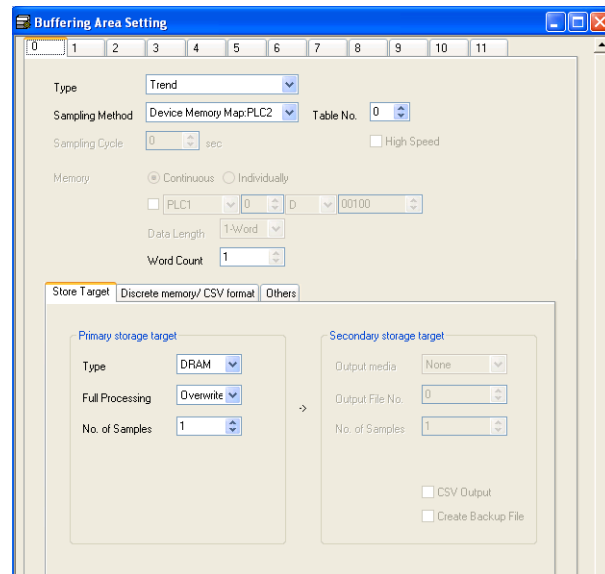


Disabled when [Periodical Reading] is selected.

Function	Periodical Reading										
Reading Cycle	Specify the data read cycle.										
	<table border="1"> <thead> <tr> <th rowspan="2">[High-speed Reading] check box*</th> <th colspan="2">Reading Cycle</th> </tr> <tr> <th>Setting Range</th> <th>Unit</th> </tr> </thead> <tbody> <tr> <td>Unchecked</td> <td>1 to 3600</td> <td>1 s</td> </tr> <tr> <td>Checked</td> <td>1 to 3600</td> <td>100 ms</td> </tr> </tbody> </table>	[High-speed Reading] check box*	Reading Cycle		Setting Range	Unit	Unchecked	1 to 3600	1 s	Checked	1 to 3600
[High-speed Reading] check box*	Reading Cycle										
	Setting Range	Unit									
Unchecked	1 to 3600	1 s									
Checked	1 to 3600	100 ms									
>> Target Memory 1 >> Target Memory 2	When unchecked: Since sampling data is stored in the S8 internal buffer, it is not necessary to set these items.										
Control Memory	This option is disabled when [Periodical Reading] is selected.										

## Buffering area setting

Click [System Setting] → [Buffering Area Setting]. The [Buffering Area Setting] dialog is opened.

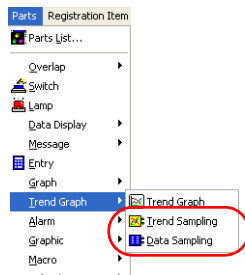


Type	Trend
Sampling Method	Device Memory Map: PLCn
Table No.	Select the device memory map number for sampling.
Word Count	The number of words is automatically set in this area based on the data in the device memory map.
Store Target	Set the desired storage target for storing sampling data.
Discrete memory / CSV format	The memory addresses of the device memory map set at [Table No.] are displayed here.

\* For more information on the buffering area setting, refer to the S8 Series Reference Manual.

## Trend sampling/data sampling part

To display the sampling data on the screen, place a trend sampling part or a data sampling part. Click the [Trend Sampling] or [Data Sampling] icon and make the setting.



\* The numbers in the [Discrete memory/ CSV format] menu of the [Buffering Area Setting] dialog are automatically set according to the data in the [Device Memory Map]. Therefore, specify the same number as that in the [Discrete memory/ CSV format] menu for the [Sampling Buffer Word No.].

For more information, refer to the S8 Series Reference Manual provided separately.

## TBL\_READ / TBL\_WRITE

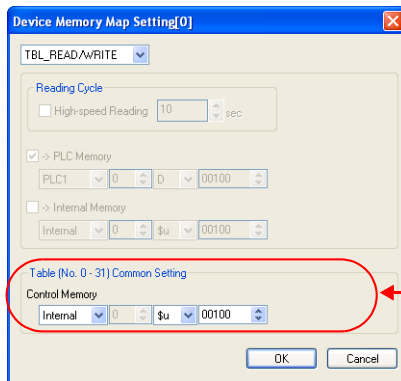
The data at the memory addresses registered in a device memory map is batch transferred using the [TBL\_READ] and [TBL\_WRITE] macro commands.

### Setting items

Items that must be set to perform memory data transfer set in the device memory map

- “Device Memory Map Editing” (page App1-3)
- Device memory map setting
- Macro (TBL\_READ / TBL\_WRITE)

### Device memory map setting



Disabled when [TBL\_READ/TBL\_WRITE] is selected.

Function	TBL_READ/TBL_WRITE * Even device memory maps for which other functions have been selected can be transferred using these macros.
Control Memory	This option is disabled when [TBL_READ/TBL_WRITE] is selected.

### Macro

Register the following macros for switch ON macro or interval timer. For more information on macros, refer to the Macro Reference manual.

- TBL\_READ  
Data at a memory address registered in a device memory map is transferred to a memory address in another device.
- TBL\_WRITE  
Data at another device is transferred to a memory address registered in a device memory map.

---

## Appendix 2 System Memory

---

The S8 series has system memories \$s and \$Pn.

### \$s

The memory addresses \$s0 to 2047 (2 k words) are for system use. Data can be read from and write to these areas. For more information, refer to the S8 Series Reference Manual.

\$s0000 : \$s1023	1 k words (compatible with V7)
\$s1024 : \$s2047	1 k words (dedicated to S8)

### \$Pn

This is the system memory for 2-way communications, and there are 512 words for each logical port. Refer to the next section for more information.

\$P1: 0000 : \$P1: 0511	PLC1 area
\$P2: 0000 : \$P2: 0511	PLC2 area



## \$Pn List

The \$Pn list is presented below. Part of the information of logical ports PLC1/PLC2 can also be stored in \$\$.\*<sup>1</sup>

\$Pn (n = 1 to 2)	\$\$.* <sup>1</sup>	Contents	Memory Type
000	111 (PLC1)	S8 local port number Stores the local port number of the S8 series. (Universal serial communication, slave communication, etc.)	← S8
:	-	:	
010	128 (PLC1)	With 1 : n connection Link down information (station No. 0 - 15) 0 : Normal 1 : Down	← S8
011	129 (PLC1)	With 1 : n connection Link down information (station No. 16 - 31) 0 : Normal 1 : Down	
012	114 (PLC1)	With 1 : n connection Link down information (station No. 32 - 47) 0 : Normal 1 : Down	
013	115 (PLC1)	With 1 : n connection Link down information (station No. 48 - 63) 0 : Normal 1 : Down	
014	116 (PLC1)	With 1 : n connection Link down information (station No. 64 - 79) 0 : Normal 1 : Down	
015	117 (PLC1)	With 1 : n connection Link down information (station No. 80 - 95) 0 : Normal 1 : Down	
016	118 (PLC1)	With 1 : n connection Link down information (station No. 96 - 111) 0 : Normal 1 : Down	
017	119 (PLC1)	With 1 : n connection Link down information (station No. 112 - 127) 0 : Normal 1 : Down	
018	120 (PLC1)	With 1 : n connection Link down information (station No. 128 - 143) 0 : Normal 1 : Down	
019	121 (PLC1)	With 1 : n connection Link down information (station No. 144 - 159) 0 : Normal 1 : Down	
020	122 (PLC1)	With 1 : n connection Link down information (station No. 160 - 175) 0 : Normal 1 : Down	
021	123 (PLC1)	With 1 : n connection Link down information (station No. 176 - 191) 0 : Normal 1 : Down	
022	124 (PLC1)	With 1 : n connection Link down information (station No. 192 - 207) 0 : Normal 1 : Down	
023	125 (PLC1)	With 1 : n connection Link down information (station No. 208 - 223) 0 : Normal 1 : Down	
024	126 (PLC1)	With 1 : n connection Link down information (station No. 224 - 239) 0 : Normal 1 : Down	
025	127 (PLC1)	With 1 : n connection Link down information (station No. 240 - 255) 0 : Normal 1 : Down	
:	-	:	
099	-	Error information hold (page App2-4) \$Pn: Setting for the update timing of the 010 to 025 link down information 0: Always updated with the latest information Other than 0: Only updated when a communication error occurs	→ S8
100	730 (PLC2)	Error status Station No. 00 status (page App2-4)	← S8
101	731 (PLC2)	Error status Station No. 01 status (page App2-4)	
102	732 (PLC2)	Error status Station No. 02 status (page App2-4)	
103	733 (PLC2)	Error status Station No. 03 status (page App2-4)	
104	734 (PLC2)	Error status Station No. 04 status (page App2-4)	
105	735 (PLC2)	Error status Station No. 05 status (page App2-4)	
106	736 (PLC2)	Error status Station No. 06 status (page App2-4)	
107	737 (PLC2)	Error status Station No. 07 status (page App2-4)	
108	738 (PLC2)	Error status Station No. 08 status (page App2-4)	
109	739 (PLC2)	Error status Station No. 09 status (page App2-4)	
110	740 (PLC2)	Error status Station No. 10 status (page App2-4)	
:	:	:	
120	750 (PLC2)	Error status Station No. 20 status (page App2-4)	
:	:	:	
130	760 (PLC2)	Error status Station No. 30 status (page App2-4)	
131	761 (PLC2)	Error status Station No. 31 status (page App2-4)	
132	820 (PLC2)	Error status Station No. 32 status (page App2-4)	
133	821 (PLC2)	Error status Station No. 33 status (page App2-4)	
:	:	:	
140	828 (PLC2)	Error status Station No. 40 status (page App2-4)	

\$Pn (n = 1 to 2)	\$s*1	Contents	Memory Type
:	:	:	
150	838 (PLC2)	Error status Station No. 50 status (page App2-4)	
:	:	:	
160	848 (PLC2)	Error status Station No. 60 status (page App2-4)	
:	:	:	
170	858 (PLC2)	Error status Station No. 70 status (page App2-4)	
:	:	:	
180	868 (PLC2)	Error status Station No. 80 status (page App2-4)	
:	:	:	
190	878 (PLC2)	Error status Station No. 90 status (page App2-4)	← S8
:	:	:	
199	887 (PLC2)	Error status Station No. 99 status (page App2-4)	
200	-	Error status Station No. 100 status (page App2-4)	
:	:	:	
350	-	Error status Station No. 250 status (page App2-4)	
:	:	:	
355	-	Error status Station No. 255 status (page App2-4)	
:	:	:	
493	762 (PLC2)*2	Device memory map reading prohibited flag (page App2-5) 0: Periodical reading/synchronized reading executed Other than 0: Periodical reading/synchronized reading stopped	
494	763 (PLC2)*2	Forced execution of the device memory map TRL_READ/TBL_WRITE macro Setting for macro operation when there is a station with communication down 0: The macro is not executed in relation to any of the stations. Other than 0: The macro is executed in relation to connected stations.	→ S8
495	764 (PLC2)*2	Device memory map writing prohibited flag (page App2-5) 0: Periodical writing/synchronized writing executed Other than 0: Periodical writing/synchronized writing stopped	
:	-	:	
500	800 (PLC2)	Memory for Modbus slave communications Used for reference table No. and free area 31 reference memory setting \$Pn500 to 505 are exclusively for monitoring: \$s800 to 805 are used for writing from the Modbus master. Refer to the Modbus Slave Communication manual.	→ S8
501	801 (PLC2)		
502	802 (PLC2)		
503	803 (PLC2)		
504	804 (PLC2)		
505	805 (PLC2)		
:	:	:	
508	765 (PLC2)	Error response code (page App2-6) If "800BH" (error code received) is stored for the error status (\$Pn100 to 355), it is possible to check the error code.	← S8
509	766 (PLC2)		
510	767 (PLC2)		
511	768 (PLC2)		

\*1 For PLC1, check the [System memory (\$s) V7 Compatible] check box in the [Detail] tab window of the [Device Connection Setting] dialog. The same information is stored in the \$P1 memory and \$s.

\*2 If executing device memory map control using \$s762, \$s763 and \$s764, check the [System memory (\$s) V7 Compatible] check box in the [Detail] tab window of the [Device Connection Setting] dialog for PLC2. Note that \$P2: 493/494/495 cannot be used in this case.

Detail

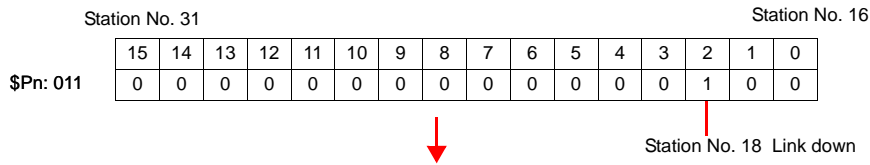
**\$Pn: 99**

The update timing for the link down information stored in \$Pn: 010 to 025 is set here.

- 0: Always updated with the latest information
- Other than 0: Only updated when a communication error occurs

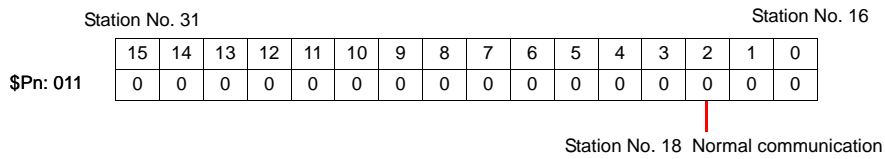
• Example:

An error has occurred at station No. 18. 2nd bit of \$Pn: 11 is set (ON).

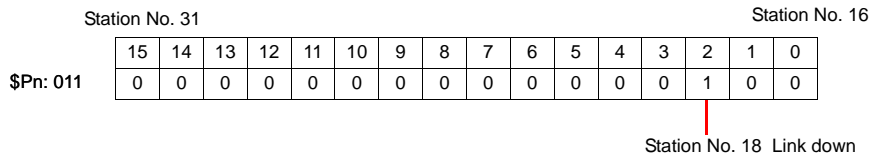


After resetting communications

- If \$Pn: 99 = 0, the link down information is updated.



- If \$Pn: 99 = other than 0, the link down information is not updated.

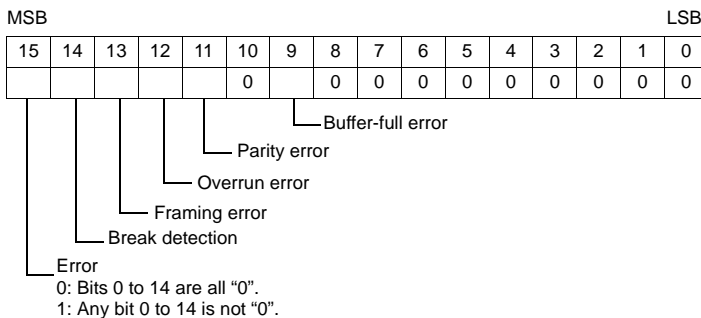


**\$Pn: 100 to 355**

The results of communication with each station are stored here. The status codes are shown below.

Code (HEX)	Contents
0000H	Normal
FFFFH	Time-out
8001H	Check code error
8002H	Data error
800BH	Receives the error code from the connected device

Errors other than the above are stored as shown below.



Error	Detail	Solution
Time-out	Although a request to send is given, no answer is returned within the specified time.	Implement solutions 1, 2, and 3.
Check code	The check code of the response is incorrect.	Implement solutions 1 and 3.
Data error	The code of the received data is invalid.	Implement solutions 1, 2, and 3.
Error code received	An error occurs on the connected device.	Refer to the instruction manual for the PLC.
Buffer full	The S8 buffer is full.	Contact your local distributor.
Parity	An error occurred in parity check.	Implement solutions 2 and 3.
Overrun	After one character is received, the next character is received before internal processing is completed.	Implement solutions 1 and 3.
Framing	Although the stop bit must be "1", it is detected as "0".	Implement solutions 1, 2, and 3.
Break detection	The connected device's SD remains at the low level.	Examine the connection with the connected device's SD/RD.

• Solution

- 1) Check if the communication settings of the S8 series and the connected device are matched.
- 2) Check the cable connection.
- 3) Data may be disrupted because of noise. Fix noise.

If you still cannot solve the error even after following the suggestions above, contact your local distributor.

**\$Pn: 493, 495**

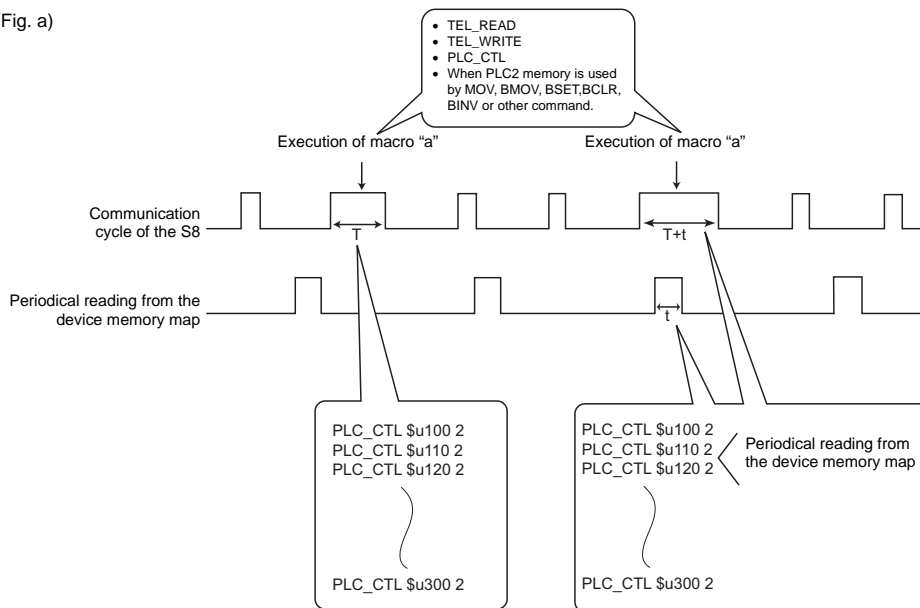
Periodical or synchronized reading set in the [Device Memory Map Setting] dialog is suspended.

- 0: Periodical/synchronized reading is performed.
- Other than 0: Periodical/synchronized reading is suspended.

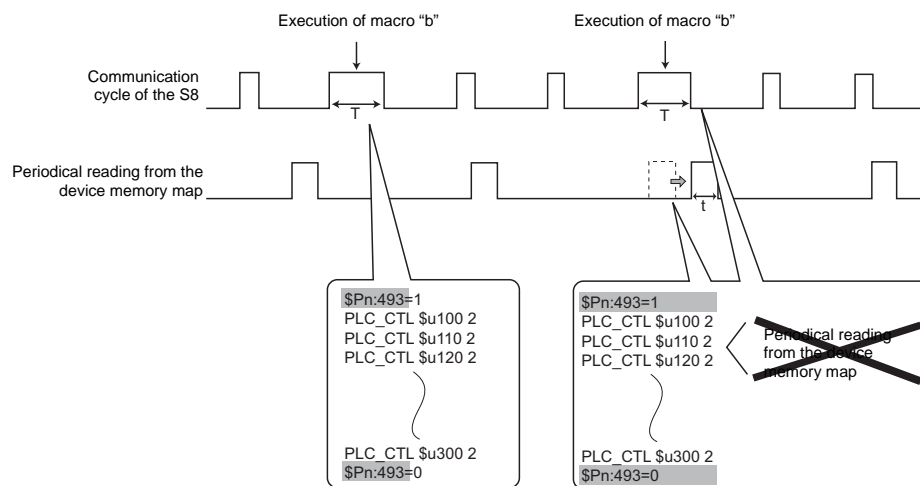
• Example: Periodical reading

If periodical reading of the device memory map is performed while the PLC2 memory is being accessed using a macro command, the macro execution will be delayed (Fig. a). To avoid this, periodical reading can be suspended using memory address \$s762 (Fig. b).

(Fig. a)



(Fig. b)



**\$Pn: 508 to 511**

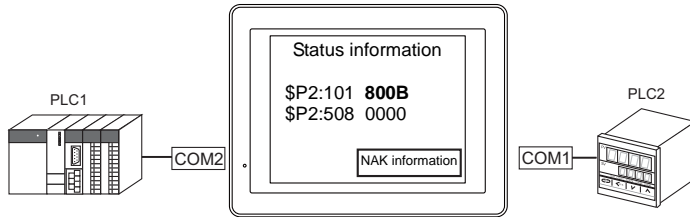
If "800BH" is stored for the error status information (\$Pn: 100 to 355), on transferring the data of that station number to any internal memory address, the reception code will be obtained at \$Pn: 508 to 511.

Notes on Use

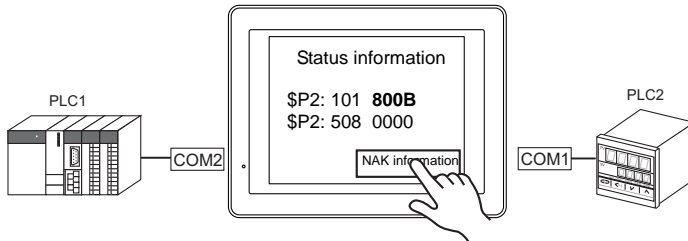
- Use \$u/\$T as the target internal memory.
- Use the macro command MOV (W). MOV (D) cannot be used.
- "0" is stored for devices that have no expansion error code.

- Example PLC2: Fuji Electric PXR station No. 1

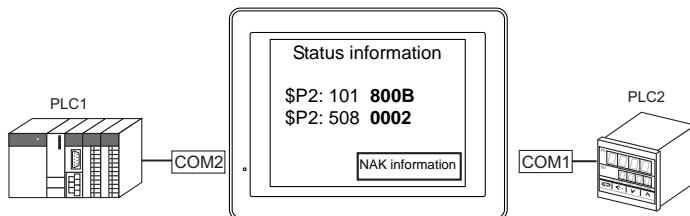
- 1) On receipt of an error code at station No. 1 of PLC2, "800BH" is stored in \$P2: 101.



- 2) The data of \$P2: 101 is transferred to \$u1000 by a MOV command.  
 $\$u1000 = \$P2: 101 (W)$



- 3) The reception code is stored in \$P2: 508.  
 $\$P2:508 = 0002H$

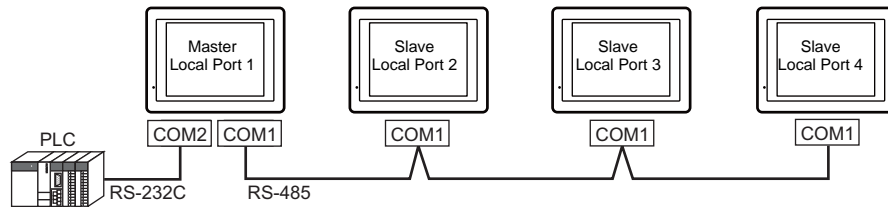


- 4) The PXR manual shows that code 002H means "memory address range exceeded".  
 Amend the screen data address designation.

## Appendix 3 n : 1 Connection

### Appendix 3.1 Multi-link2

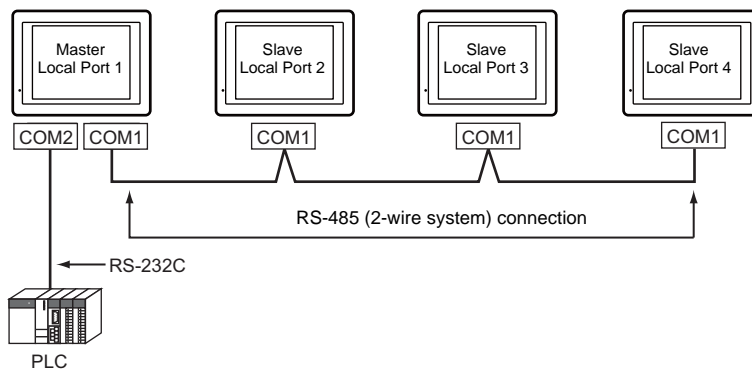
- One PLC is connected to a maximum of four\* S8/V8 units. The S8 series cannot be connected with the V7 and V6 series as multi-link2.



Type	Local Port 1 (Terminating resistance:ON)	Local Port 2 (Terminating resistance:OFF)	Local Port 3 (Terminating resistance:OFF)	Local Port 4 (Terminating resistance:ON)
S808	○	○	○	○
S806CD S806M20D	○	○	○	○
S806M10D	○	X	X	○
V8	○	○	○	○
V7 / V6	X	X	X	X

\* The terminating resistance of COM1 on S806M10D is always set to ON. If you use S806M10D in multi-link2 connection, S806M10D is available only in the termination of multi-link2 (master and slave). So, a maximum of two units is available.

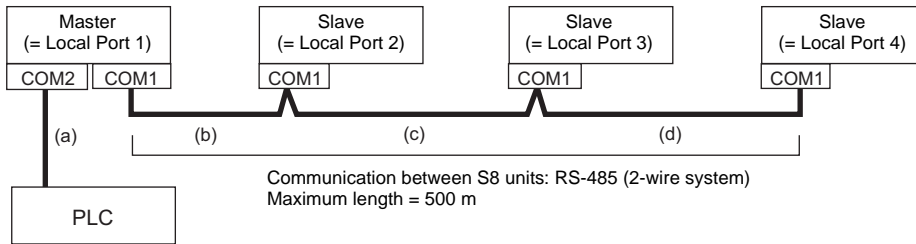
- Multi-link2 enables you to establish an original network consisting of a master S8 of local port No. 1 and slave S8 units of local port Nos. 2, 3, and 4. The master S8 communicates with the PLC directly, and the slave S8 units communicate with the PLC through the master.



- You can make settings for multi-link2 in the [Communication Setting] tab window for PLC1.
- Multi-link2 enables PLC1 memory data to be shared among the S8 units.
- The S8 series can be used together with the V8 series.
- Communication speed between the master station and the PLC depend on the setting made on the PLC. The maximum communication speed between S8 units is 115 kbps, which is higher than the one available with multi-link connection described in "Appendix 3.2 Multi-link".
- For PLCs that support multi-link2 connection, see the list provided at the end of this manual. The COM2 port (RS-232C) must be used for PLC connection (1:1 connection). The COM1 port (RS-485, 2-wire system) must be used for connection between S8 units.

## System Configuration and Wiring Diagram

The COM1 of the master S8 unit is connected to the COM1 of the slave S8 units.



(a) Connection from master to PLC

Use the COM2 port.

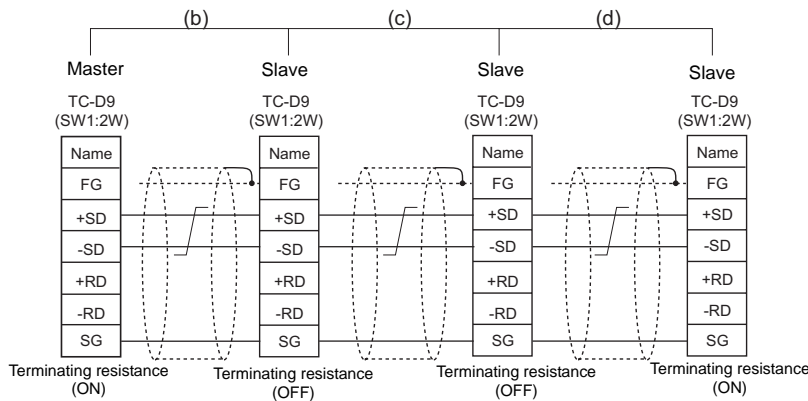
The communication settings and connection method are the same as those for 1 : 1 connection.

(b), (c), (d) Connection from master to slave

Use the RS-485 (2-wire) connection at the COM1 port. It is convenient to install the optional terminal converter "TC-D9" when S8 unit is connected. Use twisted-pair cables of 0.3 mm sq or greater. The maximum length of the wiring is 500 m.

### Wiring diagram

- S8 series with TC-D9



\* As a measure against noise, connect the frame ground terminal of each S8 series at one side only.

- S8 series without TC-D9

Install jumpers between +RD/+SD and -RD/-SD.

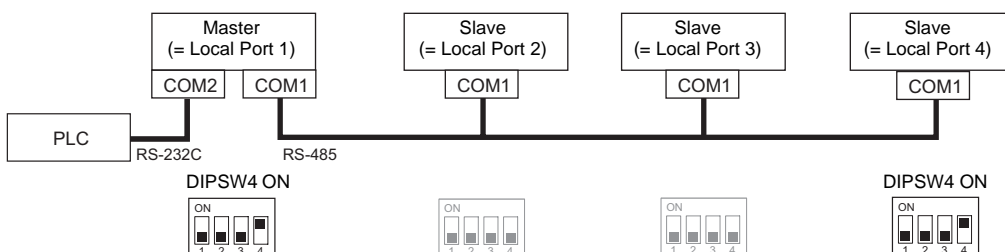
## Terminating Resistance Setting

The terminating resistance should be set on the DIP switch.

\* The terminating resistance of COM1 on S806M10D is always set to ON.



There is no terminating resistance setting for communications between the master and the PLC. Set terminating resistances as shown below for connections between S8 units.

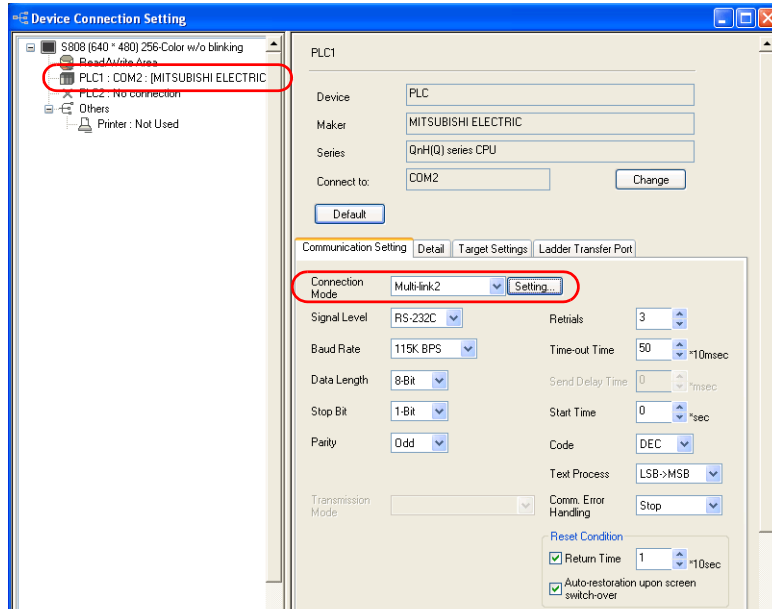


## Setting on the Editor

The settings for Multi-link2 are covered below. The differences with respect to a 1 : 1 connection and the points where care is required are explained here.

### Communication Setting

[System Setting] → [Device Connection Setting] → [PLC1] → [Communication Setting]



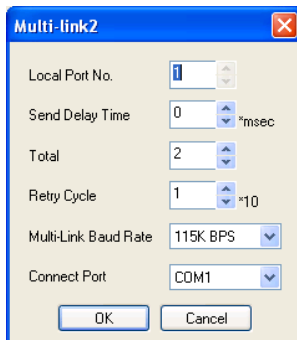
Connection Mode	Multi-link2
-----------------	-------------

### Multi-link2

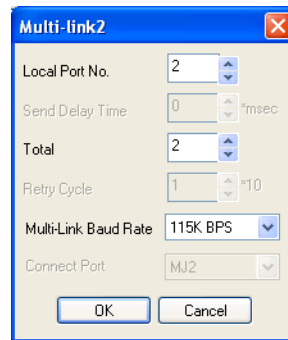
Click the [Setting] button next to [Connection Mode: Multi-link2] to display the [Multi-link2] dialog, then make the necessary settings in this dialog.

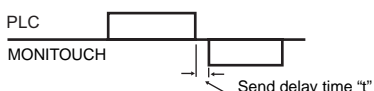
For a master, set all of the items. For a slave, set only those items marked “◆”.

- Master



- Slave



Local Port No. ◆	1 to 4 Specify a port number of the S8 series. For the master set “1”, and for the slaves set “2” to “4”. Note that if the port number specified is the same as that already set for another S8 unit, the system will not operate correctly.
Send Delay Time	Specify a delay time that elapses before S8 sends the next command after receiving data from the PLC. Normally use the default setting (0).  
Total ◆	2 to 4 Set the total number of S8 units connected in the “Multi-link2” connection. The setting must be the same as other S8 series on the same communication line.



---

Retry Cycle	Set the number of cycles before the master sends an inquiry for restoration to the slave that has a communication problem (= system down). When a slave has a problem, it is temporarily removed from the communication targets, and the master sends an inquiry for restoration every number of cycles specified for [Retry Cycle]. This setting does not affect the communication speed if no problem is occurring on the slave; however, if there is any problem, it does affect the communication speed. When the setting value is small: It will not take a long time before restoration. When the setting value is large: It will take a longer time before restoration.
Multi-Link Baud Rate ♦	4800, 9600, 19200, 38400, 57600, 115 kbps Set the baud rate between S8 series units. The setting must be the same as other S8 series units on the same communication line.
Connect Port	Set the port to be connected to slaves. COM1 (fixed)

## Communication Error

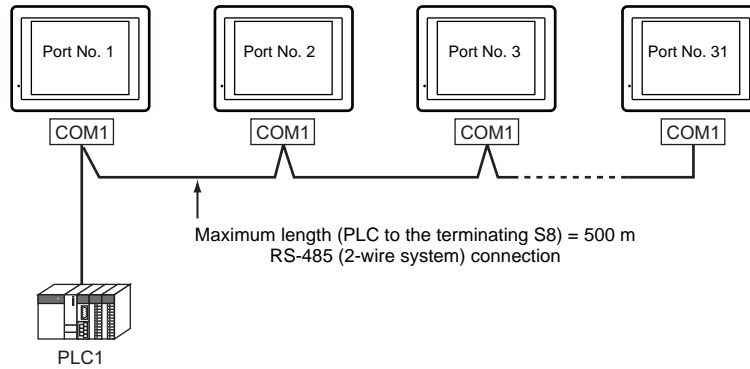
---

- If the master station has a communication error, the master and slave stations do not work, and as a result, "Communication Error Time-Out" is displayed.  
If a slave station becomes faulty, the communication error (check) occurs only on this station.

## Appendix 3.2 Multi-link

- One PLC is connected to a maximum of 31 S8 units\*. The S8, V8, V7, and V6 series can be used together.

\* The terminating resistance of COM1 on S806M10D is always set to ON. If you use S806M10D in multi-link connection, S806M10D is available only in the termination of multi-link.

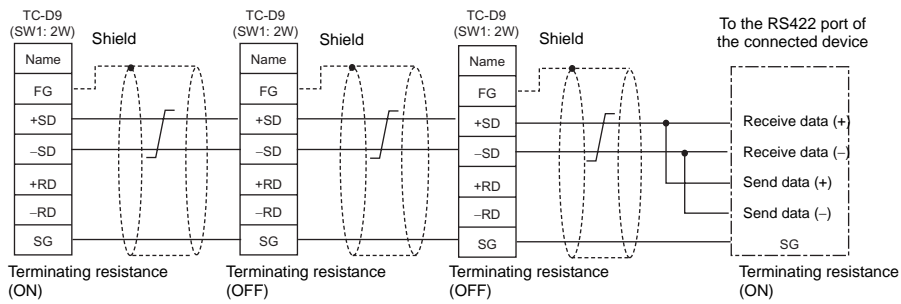


- You can make settings for multi-link in the [Communication Setting] tab window for the logical port PLC1. For the S8, COM1 is available for a communication port. For the V8, however, a communication port is selectable from CN1, MJ1, and MJ2. For the V7 or V6, CN1 is only available.
- Only a PLC for the signal level RS422/RS485 and with a port number is available. For PLCs that support multi-link connection, refer to the list provided at the end of this manual or the chapters on individual manufacturers.
- Wiring type is RS-485 (2-wire system). Use twisted-pair cables of 0.3 mm sq. or greater between terminal blocks.

## Wiring Diagrams

It is convenient to use Hakko Electronics' "TC-D9" (terminal converter) optionally available for this multi-link connection.

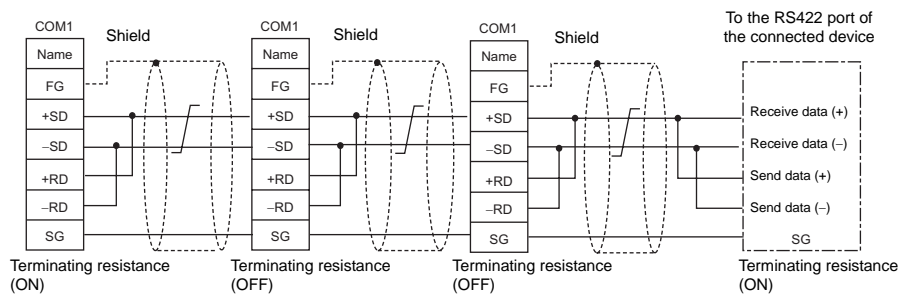
- S8 series with TC-D9:



\* Use shielded twist-pair cables.

\* Jumpers may not be necessary, depending on the connected device.

- S8 series without TC-D9:



\* Use shielded twist-pair cables.

\* Jumpers may not be necessary, depending on the connected device.

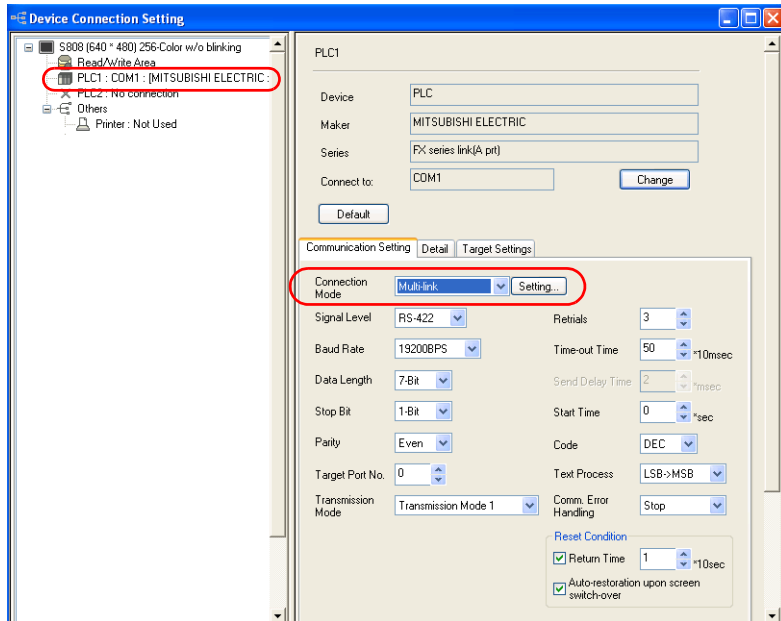
## Setting on the Editor

The settings for Multi-link are covered below. The differences with respect to a 1 : 1 connection and the points where care is required are explained here.

### PLC selection

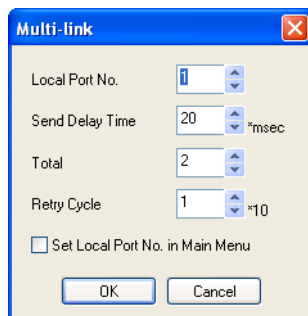
Select the PLC corresponding to the multi-link connection in the [Communication Setting] tab window ([System Setting] → [Device Connection Setting] → [PLC1]).

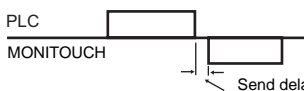
## Communication Setting



### Multi-link

Click the [Setting] button next to [Connection Mode: Multi-link] to display the [Multi-link] dialog, then make the necessary settings in this dialog.



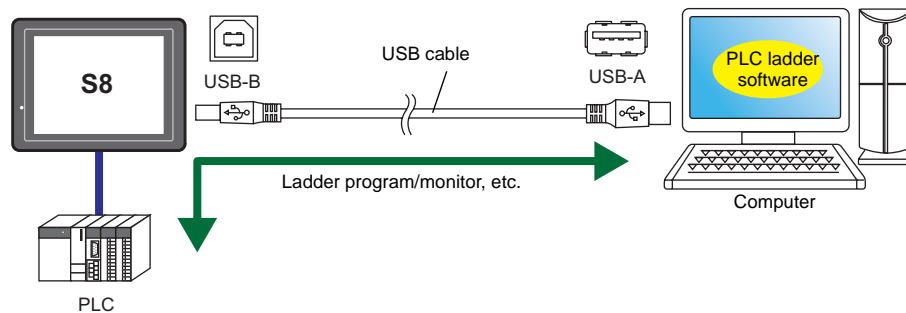
Local Port No.	1 to 32* Specify a port number of the S8 series. Note that if the port number specified is the same as that already set for another S8 unit, the system will not operate correctly.
Send Delay Time	0 to 255 msec (Default setting: 20 msec) Specify a delay time that elapses before S8 sends the next command after receiving data from the PLC. 
Total	2 to 32* Set the total number of S8 series, or V series units to be connected in the multi-link connection. The setting must be the same as other S8 series on the same communication line.

Retry Cycle	1 to 100 (× 10) When the S8 series has a problem, it is temporarily removed from the communication targets, and the master sends an inquiry for restoration every number of cycles specified for [Retry Cycle]. This setting does not affect the communication speed if no problem is occurring; however, if there is any problem, it does affect the communication speed. When the setting value is small: It will not take a long time before restoration. When the setting value is large: It will take a longer time before restoration.
<input type="checkbox"/> Set Local Port No. in Main Menu	<ul style="list-style-type: none"><li>• <u>Unchecked:</u> Set the local port number for screen data.</li><li>• <u>Checked:</u> Set the local port number on MONITOUCH (For the procedures to change the local port No., refer to the page 22-3.)</li></ul>

\* For [Send Delay Time], [Total] and [Retry Cycle], the same values must be set on all the S8 series that are connected in the same communication line.

## Appendix 4 Ladder Transfer Function

When a S8 series is connected to the CPU port of a PLC, debugging has to be carried out by disconnecting and reconnecting two cables alternately: the cable that connects the PC to the PLC and the cable that connects the S8 series and the PLC. However, using the ladder transfer function makes it possible to write the ladder program via the S8 unit with USB port and monitor the PLC without disconnecting and reconnecting the cables.



### Operating Environment

#### Applicable OS

Microsoft Windows 2000/XP

#### Applicable PLC Models

The following PLC models support the ladder transfer function.

Manufacturer	PLC Selection on the Editor *1	CPU	Ladder Communication Program
Fuji Electric FA	MICREX-SX SPH/SPB CPU	NP1Px-xx(SPH) NW0Pxx(SPB)	MicrexSX_U.lcmA
Mitsubishi Electric	QnH (Q) series CPU	Q02(H), Q06H, Q12H, Q25H	MelQHCpQ_U.lcmA
	Q00J/00/01 CPU	Q00J, Q00, Q01	
	QnH (Q) series CPU (multi CPU)	Q02(H), Q06H, Q12H, Q25H	
	QnU series CPU	Q00U, Q02U, Q03UD, Q04UDH, Q06UDH	
Yokogawa Electric	FA-M3	PROGRAMMER port	Yokogawa_U.lcma
	FA-M3R		

**1 : n communication (multi-drop), multi-link communication, and multi-link2 communication cannot be executed.**

## Setting

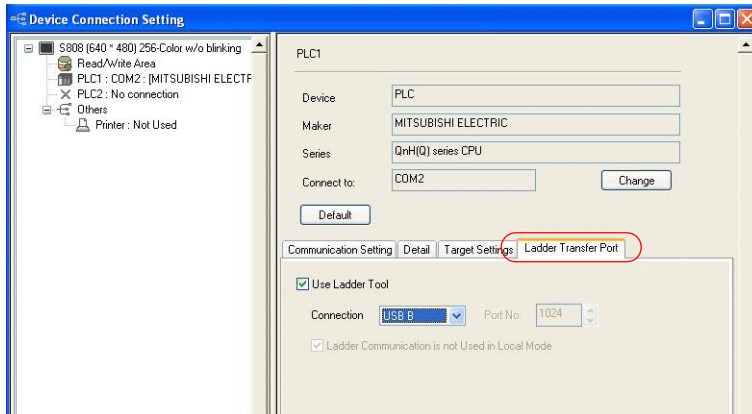
The following settings are necessary to use the ladder transfer via USB.

### Editor

#### Device connection setting

Select [System Setting] → [Device Connection Setting] → [PLC1] → [Ladder Transfer Port]

- \* The [Ladder Transfer Port] tab window is only displayed if a model that is compatible with the ladder transfer function (see page App4-1) has been selected for PLC1.



<input type="checkbox"/> Use Ladder Tool	Checked
Connection	Specify the port where the ladder transfer function is to be used. USB-B (fixed)

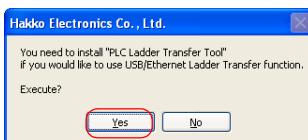
### LadderComOp

This is an application required for the ladder transfer via USB.

#### Installation procedure

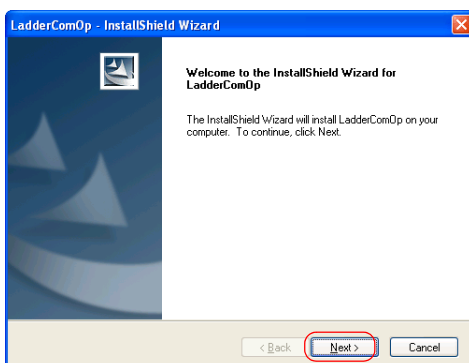
Ladder transfer via USB is available, provided that the dedicated tool, "LadderComOp", is installed on the computer. If you install the "LadderComOp" from the V-SFT-5 CD, perform the procedure below from step 1. If you have downloaded the "LadderComOp" from our website at <http://www.monitouch.com>, double-click the "LadderComOp".exe on your computer and perform the procedure from step 2.

1. When the V-SFT-5 has been installed, the following dialog is displayed\*. Click the [Yes] button.

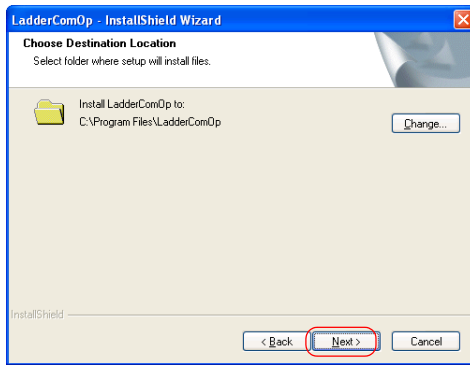


- \* The V-SFT-5 version 5.3.0.0 or later supports the function.

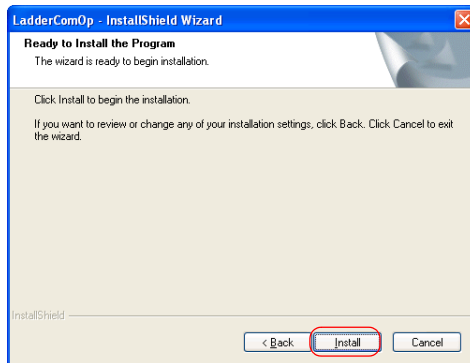
2. Click the [Next] button.



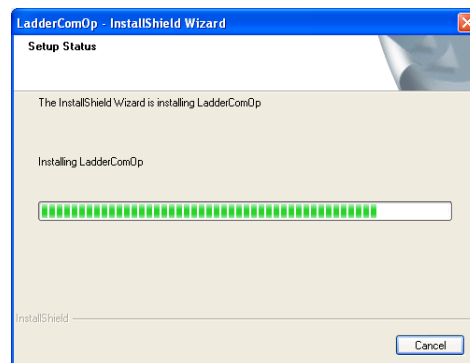
3. Select the location of where to install the tool and click the [Next] button.



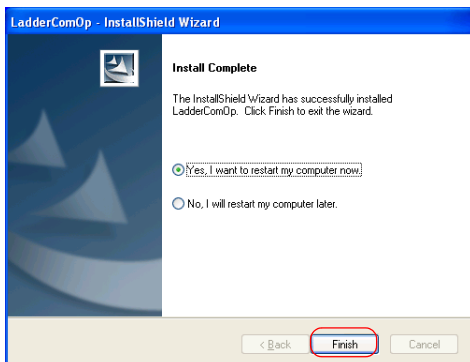
4. Click the [Install] button.



5. Installation starts.



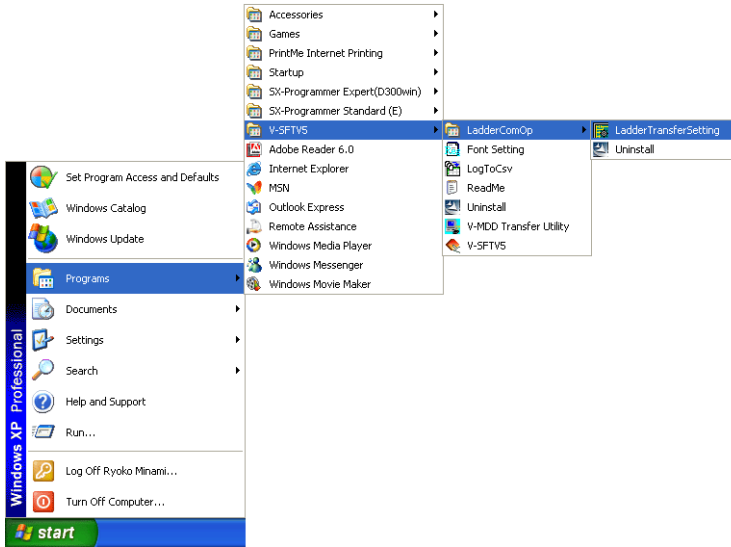
6. Click the [Finish] button. Reboot your computer.



\* Whenever you have installed or uninstalled the “LadderComOp”, reboot your computer. Failure to do so may cause a malfunction.

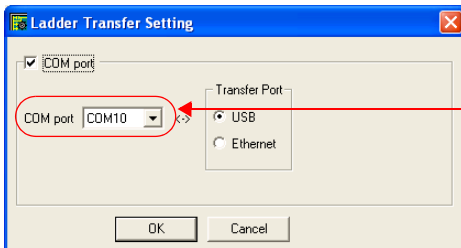


7. "LadderComOp" is added as an option under V-SFT-5.



### Ladder transfer setting

From the [Start] menu of your computer, click [Programs] → [V-SFTV5] → [LadderComOp] → [Ladder Transfer Setting].



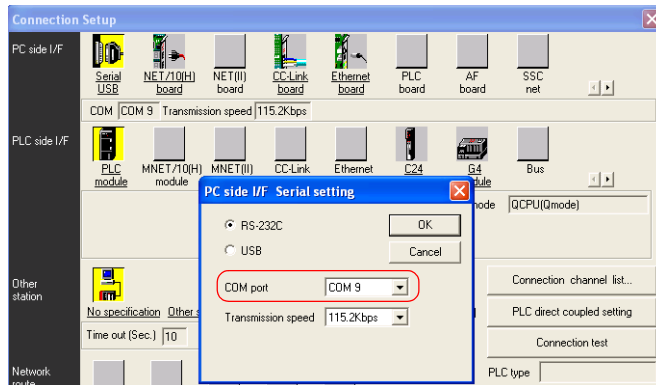
Match the port number to the one set in the ladder software for the PLC.

<input type="checkbox"/> COM port	Checked
COM port	COM1 to COM256 (COM9 as default) Select a COM port which is not used by the software or tools in your computer. Match the port number to the one set in the ladder software for the PLC. For more information, refer to "How to check the COM port setting for the PLC" (page App4-5).
Transfer Port	Select the port where the ladder transfer function is to be used. For S8 series, only USB is available for the transfer port.

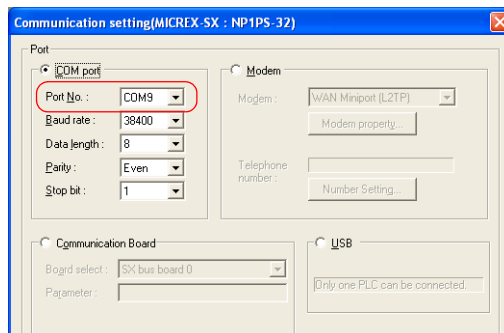
## How to check the COM port setting for the PLC

To see which port must be set for [COM port] in the [Ladder Transfer Setting] dialog, go to the following dialog provided in the PLC ladder software.

- MITSUBISHI ELECTRIC GX Developer



- Fuji Electric SX-Programmer Expert (D300win)



## Notes

- The ladder transfer function can be used with PLC1. It cannot be used with PLC2.
- On-line editing between the editor and the S8 series is not possible. If attempted, communications between the PLC programming software and the PLC will not be performed correctly.
- Communicating statuses with the PLC programming software and the PLC during communications between the editor and the S8 series

Editor	PLC Programming Software
Writing to S8	Communications disconnected (normal communications on completion of writing)
Reading from S8	Normal communications
Comparing with S8	Normal communications

- Baud rate setting  
The [Baud Rate] setting in the [Communication Setting] tab window applies to the baud rate between the S8 series and the PLC. However, if communication with the PLC programming software (monitoring, etc.) starts by means of the ladder transfer function, the baud rate set on the software takes effect. The baud rate stays enabled until the S8 series is turned off and on again. Keeping this in mind, set the PLC programming software baud rate and the [Baud Rate] setting in the [Communication Setting] tab window to the same value.
- With [Use Ladder Tool] checked, it is prohibited to register the devices to be monitored for S8-PLC communication even though the PLC programming software is not started. The screen display speed will decrease somewhat accordingly.
- When the ladder program is transferred in the RUN mode of the S8 series, communications are synchronized; therefore, the performance of both the S8 series and the PLC programming software decreases.
- Ladder transfer is possible only in the RUN mode. When transferring the screen data, be sure to display the Main Menu screen on the S8 series.
- When [ COM port] is checked, every serial communication that uses the COM port you selected will be converted to communication via USB. Therefore, be sure that the COM port selected under [COM port] is not already used for other serial communications. Except when ladder transfer via USB is used, uncheck the box for [ COM port].

MEMO

Please use this page freely.

# Connection Compatibility List

December, 2009

Manufacturer	Models	1 : 1	1 : n Multi-drop	n : 1 Multi-link2	n : 1 Multi-link	
ALLEN BRADLEY	SLC500	○	○	○		
	Micro Logix	○		○		
	Control Logix / Compact Logix	○				
Automation Direct	Direct LOGIC (K-Sequence)	○		○		
	Direct LOGIC (MODBUS RTU)	○	○	○		
EATON Cutler-Hammer	ELC	○	○	○		
FANUC	Power Mate	○		○		
FATEK AUTOMATION	FACON FB series	○	○	○		
Fuji Electric	MICREX-F series	○	○	○	○	
	MICREX-F series V4-compatible	○	○	○		
	SPB (N mode) & FLEX-PC series	○	○	○		
	SPB (N mode) and FLEX-PC CPU	○		○		
	MICREX-SX SPH/SPB series	○		○		
	MICREX-SX SPH/SPB CPU	○		○		
	PYX (MODBUS RTU)	○	○	○		
	PXR (MODBUS RTU)	○	○	○		
	PXG (MODBUS RTU)	○	○	○		
	PXH (MODBUS RTU)	○	○	○		
	PUM (MODBUS RTU)	○	○	○		
	F-MPC04P (loader)	○	○	○		
	F-MPC series / FePSU	○	○	○		
	FVR-E11S (MODBUS RTU)	○	○	○		
	FVR-C11S (MODBUS RTU)	○	○	○		
	FRENIC5000 G11S/P11S (MODBUS RTU)	○	○	○		
	FRENIC5000 VG7S (MODBUS RTU)	○	○	○		
	FRENIC-Mini (MODBUS RTU)	○	○	○		
	FRENIC-Eco (MODBUS RTU)	○	○	○		
	FRENIC-Multi (MODBUS RTU)	○	○	○		
	FRENIC-MEGA (MODBUS RTU)	○	○	○		
	HFR-C9K	○	○	○		
	HFR-C11K	○	○	○		
	PPMC (MODBUS RTU)	○	○	○		
	FALDIC- $\alpha$ series	○	○	○		
	PHR (MODBUS RTU)	○	○	○		
	WA5000	○	○	○		
	APR-N (MODBUS RTU)	○	○	○		
	ALPHA5 (MODBUS RTU)	○	○	○		
	WE1MA (MODBUS RTU)	○	○	○		
	IAI	X-SEL controller	○	○	○	
		PCON/ACON/SCON (MODBUS RTU)	○	○	○	
KEYENCE	KV10/24 CPU	○		○		
	KV-700	○		○		
	KV-1000	○		○		
	KV-3000/5000	○		○		
LS	MASTER-KxxxS	○		○		
	MASTER-KxxxS CNET	○	○	○		
	XGT/XGK series	○	○	○		
	XGT/XGK series CPU	○		○		
MITSUBISHI ELECTRIC	A series link	○	○	○	○	
	QnA series link	○	○	○		
	QnH (Q) series link	○	○	○		
	QnH (Q) series CPU	○		○		
	QnU series CPU	○		○		
	Q00J/00/01 CPU	○		○		
	QnH (Q) series link (multi CPU)	○	○	○		
	QnH (Q) series CPU (multi CPU)	○		○		
	FX2N/1N series CPU	○		○		
	FX series link (A protocol)	○	○	○	○	
	FX-3UC series CPU	○		○		
	FR-*500	○	○	○		
	FR-V500	○	○	○		

Manufacturer	Models	1 : 1	1 : n Multi-drop	n : 1 Multi-link2	n : 1 Multi-link
OMRON	SYSMAC C	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	SYSMAC CS1/CJ1	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
	E5AN/E5EN/E5CN/E5GN	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
	E5AR/E5ER	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
Panasonic Electric Works	FP Series	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
RKC	SR-Mini (MODBUS RTU)	<input type="radio"/>	<input type="radio"/>		
	CB100/CB400/CB500/CB700/CB900 (MODBUS RTU)	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
	SR-Mini (Standard Protocol)	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
	SRV (MODBUS RTU)	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
	MA900/MA901 (MODBUS RTU)	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
	SRZ (MODBUS RTU)	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
SAIA	PCD	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
Siemens	S7-200 PPI	<input type="radio"/>	<input type="radio"/>		
	S7-300/400 MPI	<input type="radio"/>	<input type="radio"/>		
Yamatake	SDC35/36	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
	DMC10	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
	DMC50 (COM)	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
Yaskawa Electric	Memobus	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
	CP9200SH/MP900	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
Yokogawa Electric	FA-M3	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	FA-M3R	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	UT350	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
	UT450	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	
None	MODBUS RTU	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	

### Slave Communication

Manufacturer	Models	Setting	Remarks
None	Universal serial	<input type="radio"/>	
	V-Link	<input type="radio"/>	
	Modbus slave (RTU)	<input type="radio"/>	

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