

› High on **control**
big on reliability



Lx2000 | AC Drive for Elevator

Three Phase 230V (2.2 ~ 37kW)

Three Phase 415V (2.2 ~ 45kW)

Two decades of application knowledge

For over two decades, various industry sectors have been reaping the benefits of L&T's cost-effective, performance-oriented AC Drive solutions. L&T's grasp of the specific needs of each industry enables it to offer application-specific solutions for various industries – such as processing, textile, plastic, ceramic, pharmaceutical, elevator, oil & gas, power, cement and material-handling.



Lx2000 | AC Drive

› The new level of reliability

The Lx2000 is designed specifically to add power to elevator performance. Built to L&T's stringent quality standards, the Lx2000 is tested and certified to meet global benchmarks, thus giving you the assurance of total reliability.



It handles loads up to 45 kW, and is engineered to keep your elevator operating at optimum efficiency, even in the hot, humid and dusty conditions that characterise harsh environment.



➤ Backed by **engineering knowledge** across seven decades

A knowledge-based company, L&T brings you the benefits of over 75 years of engineering experience and expertise, and the richness of its collaborations with technology leaders across the globe.

For 50 years, L&T's low-tension switchgear – India's widest range – has been the preferred option of top industrial houses countrywide.

➤ Meeting your needs, solving your problems

We believe in addressing your needs and not just selling a product. That's why a dedicated Solutions Team first focuses on understanding your application. Then helps you select the drive that best meets your needs. Our advice on installation, maintenance and replacement will ensure that your elevators function at peak productivity. From engineer to repair technician, our people have the knowledge and skill-sets to deliver total peace of mind.







➤ Tested. Certified. Reliable.

L&T is one of the few switchgear manufacturers in India with a dedicated, NABL-certified testing facility. Our products are tested for conformity to standards that exceed minimum requirements, giving you the assurance of high-quality performance. Our focus on continuous improvement ensures that our standards are on par with the best in the world. Repeat orders endorse the value that we deliver.

➤ After-sales service aimed at maximum uptime

A malfunction of the drive can bring an elevator to a halt. To ensure maximum uptime for you, our Rapid Response service team is available to analyze the situation and help you set the problem right. We have set up strategic service centres across the country to provide temporary replacement drives or ready spares to ensure that your business keeps running smoothly.

Rapid Response Service Team





➤ **Training your people to enhance your operations**

At our countrywide Switchgear Training Centres, we can train your operators, electricians and supervisors to increase their effectiveness in the operation and maintenance and trouble-shooting of your drives. We can also conduct in-plant training and workshops at your premises to improve both power management and equipment maintenance skills. This gives you total operational excellence, minimising downtime.

L&T's engineers and channel partners also upgrade their skills through seminars, workshops, training sessions and white papers on electrical practices.

➤ **Features that ensure performance**

- Suitable for geared / gearless machines
- Compatibility with various types of encoders
- Anti-roll-back algorithm
- Load and direction based floor-leveling
- Built-in ARD function

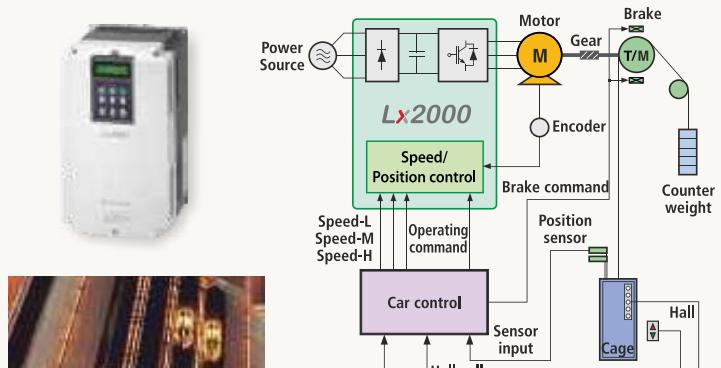


Lx2000

Provides Dedicated Solutions
for Elevator Systems

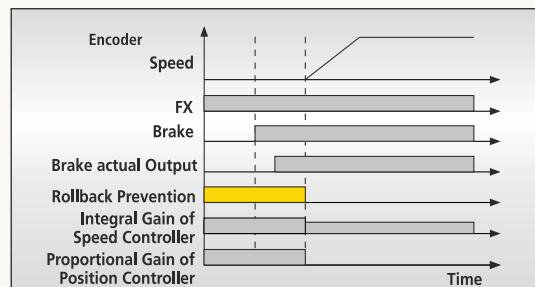
Controls the elevator system
smoothly and efficiently

Lx2000 guarantees stable driving and monitoring of the elevator with both optimum speed pattern and position control.

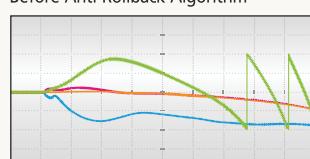


Rollback Prevention:
Anti-Rollback Function
(without external load cell)

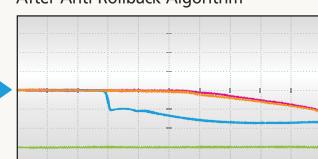
Time Chart for Anti-Rollback Function



Before Anti-Rollback Algorithm



After Anti-Rollback Algorithm



Green : Posion Error between Command & Actual Spd.



Lx2000

LARSEN & TOUBRO



➤ Precise Control

Precise speed control
Accurate control with SIN/COS encoder
PM Sensorless control
Stationary Auto tuning (at standstill)
Brake Control



➤ Auto-tuning

Standstill auto-tuning

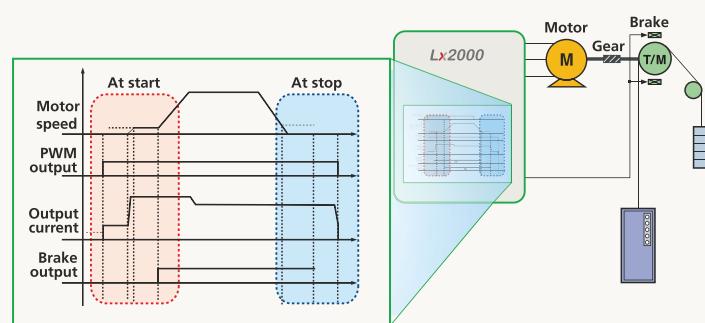
L&T's unique technology allows auto-tuning to be performed even with the motor shaft directly connected to the load. Standstill auto-tuning is useful for elevators because it does not require removal of the brake coupling connected to the motor.

Rotational auto-tuning

Widely used for vector-control drives, this requires the motor shaft to be free from the coupling for proper operation.

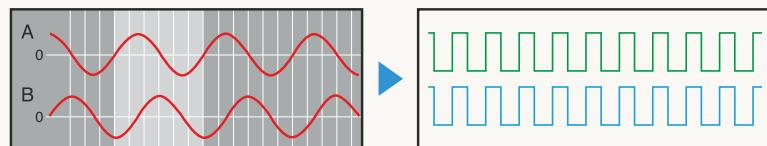
➤ Built-in brake control for safe vertical loading

To minimize risk of the elevator's giving in to the gravitational pull of the earth, brake-control is built in.



➤ Extreme precise control

The SIN/COS encoder option enables more precise control over a normal encoder.

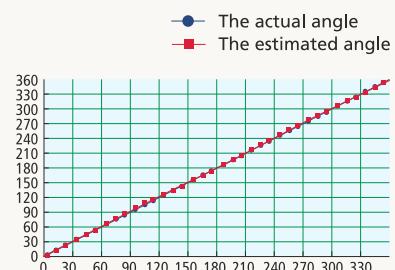
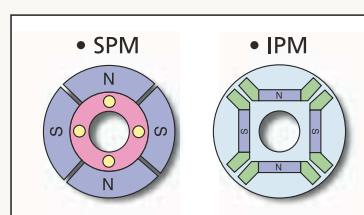


➤ SPM, IPM motor control

SIN/COS encoder option

With synchronous motor initial stimulus position estimation, the Lx2000 perfectly controls the SPM and IPM motor.

- SPM, IPM motor
- 30,000 rpm driving fast response within 100msec



› User-Friendly Interface

Easy-to-use with user-centric keypad and removable terminal blocks

Supports communication devices such as Modbus-RTU, CC-Link

Systematic and efficient system management through DriveConnet 2.0

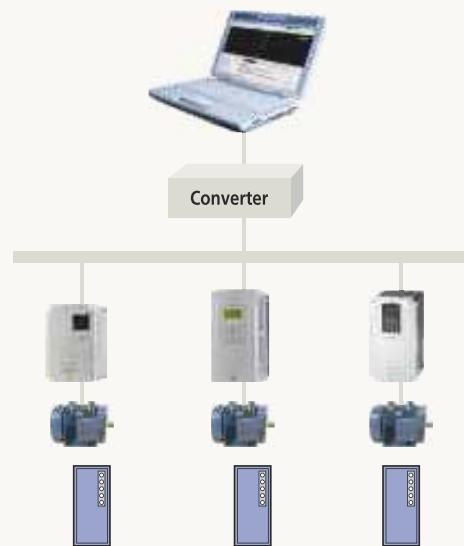


› Easy-to-maintain drive/motor parameter via PC

PC-based Software for Easy Maintenance of Drive and Motor Parameters

DriveConnect software allows drive/system monitoring on a PC and easy maintenance of drive and motor parameters

- Windows-based graphic user interface (GUI)
- Modbus-RTU
- Connecting up to 31 drives
- Integrated control console
- Offline editing function
- Data upload/download
- 4-channel oscilloscope
- Trigger function





>User-Friendly Design



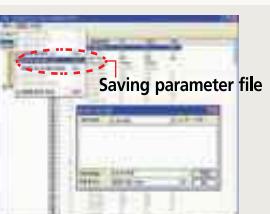
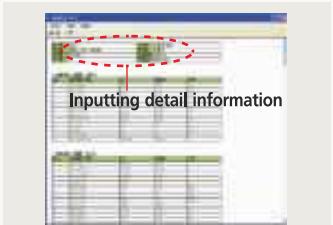
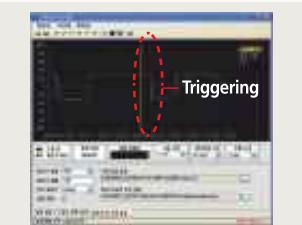
Easy-to-use keypad

By adopting a user-centered operation keypad, parameter setting becomes easier. When applying to the system, the varied information required can be monitored.

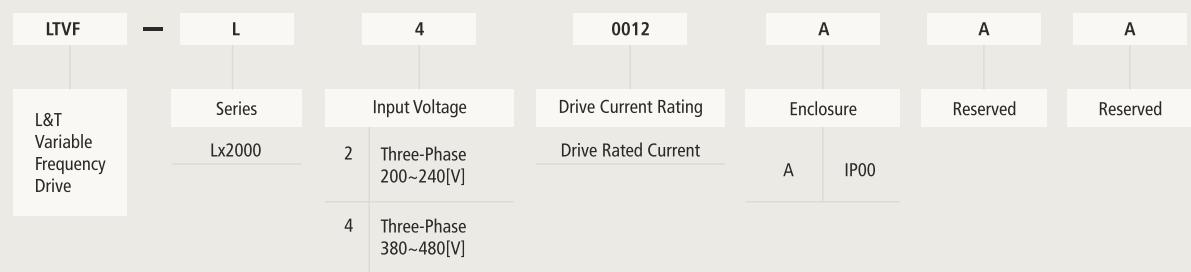


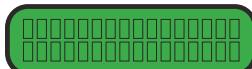
International standard removable terminal block

Wiring and maintenance is made easy by an international standard acquired terminal block.

| | | |
|---|---|---|
| ■ DriveConnect DriveConnect  | ■ Drive integrated console  | ■ Parameter management  Saving parameter file |
| ■ Reporting 1  Reporting | ■ Reporting 2  Inputting detail information | ■ Oscilloscope/Trigger  Triggering |

| Motor rating (Heavy Duty) | Three-Phase 230V | Three-Phase 415V |
|------------------------------|------------------|------------------|
| 2.2kW | LTVF-L20012AAA | LTVF-L40006AAA |
| 3.7kW | LTVF-L20016AAA | LTVF-L40008AAA |
| 5.5kW | LTVF-L20024AAA | LTVF-L40012AAA |
| 7.5kW | LTVF-L20032AAA | LTVF-L40016AAA |
| 11kW | LTVF-L20046AAA | LTVF-L40024AAA |
| 15kW | LTVF-L20059AAA | LTVF-L40030AAA |
| 18.5kW | LTVF-L20074AAA | LTVF-L40039AAA |
| 22kW | LTVF-L20088AAA | LTVF-L40045AAA |
| 30kW | LTVF-L20122AAA | LTVF-L40061AAA |
| 37kW | LTVF-L20146AAA | LTVF-L40075AAA |
| 45kW | - | LTVF-L40091AAA |





- Data and status display

MODE

- Shift between function groups
- Shifting from group code to the upper code



- Function code shift
- Shift to next function code
- Data increase in set up mode



- Reverse run command key
- Only available, with loader operation
- LED is turned ON with reverse run
- Blinks during Acc/Deceleration of reverse run



- Shift to function code
- Shift to previous code
- Data is decreased in set up mode



PROG

- Data set up start

ENT

- Data set up completion

**SHIFT
ESC**

- Decimal point shift
- Only available in case of data setup

FWD

- Forward run command key
- Only available with loader operation
- LED is turned on with forward operation
- Blinks during Acc/Deceleration of forward operation

**STOP
RESET**

- Stop command
- Available with the loader operation
- LED is turned on when drive stops its operation
- Blinks when fault occurs
- Reset
- Fault reset

➤ Digital Operator Instructions

| Classification | Display | Function Name | Function |
|----------------|--------------|---------------------|---|
| KEY | MODE | Mode Key | Shift between groups. Shift from a group code to upper code. |
| | PROG | Program Key | Parameter setting value change. |
| | ENT | Enter Key | Saving altered setting values. |
| | ▲ (up) | Up Key | Shift between codes and increase the parameter value. |
| | ▼ (down) | Down Key | Shift between codes and decrease the parameter value. |
| | Shift/ESC | Shift/ESC Key | In case of set-up mode, it is operated with the shift key. Operation with ESC key in non-set up mode. |
| | REV | Reverse run | Reverse run key. |
| | STOP/RESET | Stop/Reset Key | Stop key when drive is on operation. |
| LED | (REV) | Reverse run key | Turns on at reverse operation. Blinks while the drive is on Acc/Deceleration and then turns on the constant speed operation. |
| | (STOP/RESET) | Stop/Fault display | Turns off when drive stops operation. Blinks when fault occurs. |
| | (FWD) | Forward Run Display | Turns on during forward operation. Acc/Deceleration running modes blink the lamp and it is turned on in the forward operation. |

Input and Output Specification: Input Voltage Three-Phase 230V

| LTVF-L2 □□□□ AAA | | 0012 | 0016 | 0024 | 0032 | 0046 | 0059 | 0074 | 0088 | 0122 | 0146 |
|---|-------------------|-----------------------------------|------|------|------|------|------|------|------|-------------------|------|
| Maximum applicable motor ranges ¹⁾ | HP kW | 3 | 5 | 7.5 | 10 | 15 | 20 | 25 | 30 | 40 | 50 |
| | | 2.2 | 3.7 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 |
| Rated output | Capacity [kVA] | 4.5 | 6.1 | 9.1 | 12.2 | 17.5 | 22.5 | 28.2 | 33.1 | 46 | 55 |
| | Rated current [A] | 12 | 16 | 24 | 32 | 46 | 59 | 74 | 88 | 122 | 146 |
| | Output frequency | 0 - 120 Hz | | | | | | | | | |
| | Output voltage | 0 ~ 200V(230V) ²⁾ | | | | | | | | | |
| Rated input | Voltage | 3Ø 200 ~ 230V (-10% ~ +10%) | | | | | | | | | |
| | Frequency | 50 ~ 60Hz (±5%) | | | | | | | | | |
| Overload Tolerance | | 150% of rated current for 60 sec. | | | | | | | | | |
| Dynamic Braking Unit | | Built-in | | | | | | | | External (option) | |

Input and Output Specification: Input Voltage Three-Phase 415V

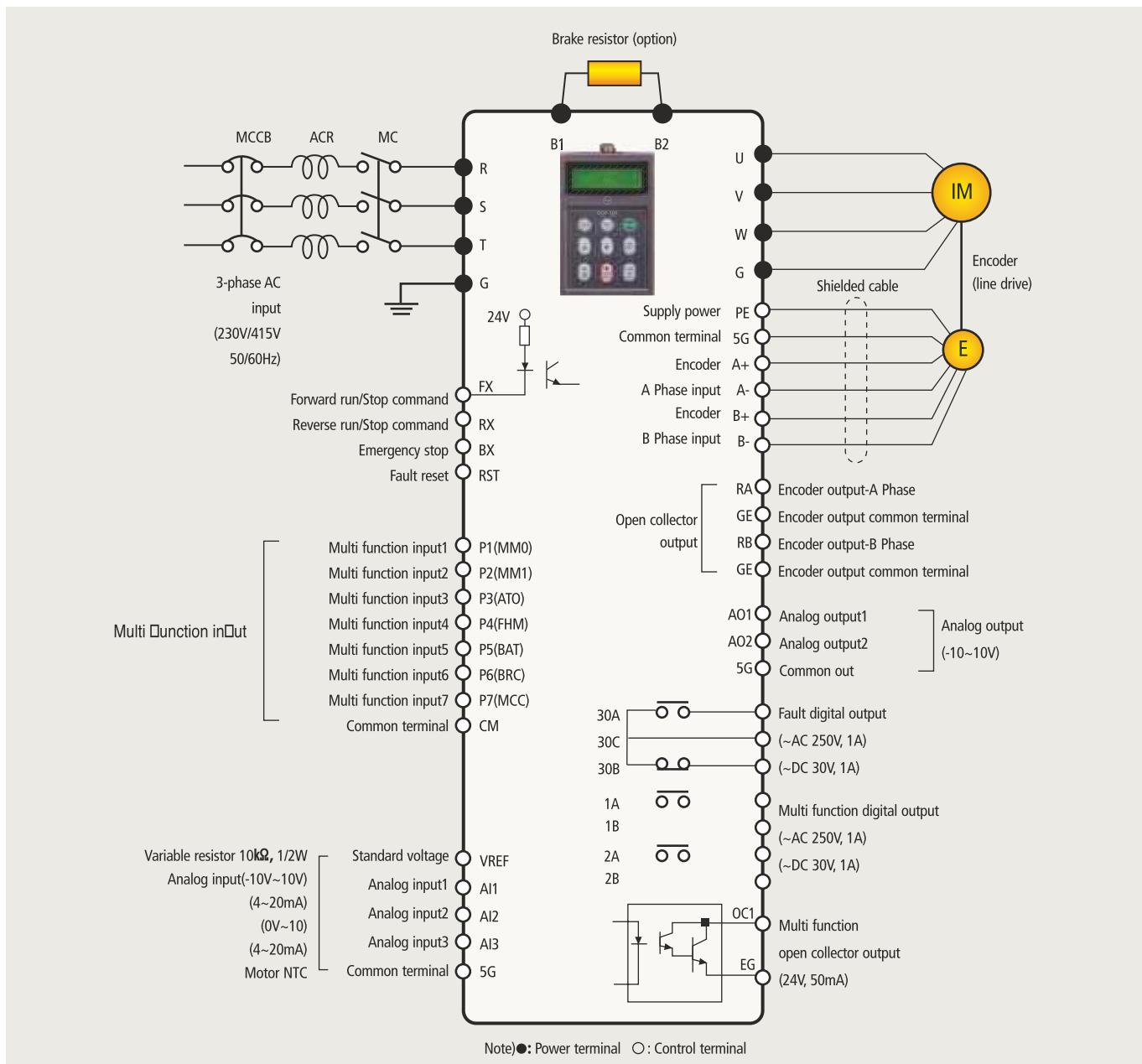
| LTVF-L4 □□□□ AAA | | 0006 | 0008 | 0012 | 0016 | 0024 | 0030 | 0039 | 0045 | 0061 | 0075 | 0091 |
|---|-------------------|-----------------------------------|------|------|------|------|------|------|------|-------------------|------|------|
| Maximum applicable motor ranges ¹⁾ | HP kW | 3 | 5 | 7.5 | 10 | 15 | 20 | 25 | 30 | 40 | 50 | 60 |
| | | 2.2 | 3.7 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 | 45 |
| Rated output | Capacity [kVA] | 4.5 | 6.1 | 9.1 | 12.2 | 18.3 | 22.9 | 29.7 | 34.3 | 46 | 57 | 70 |
| | Rated current [A] | 6 | 8 | 12 | 16 | 24 | 30 | 39 | 45 | 61 | 75 | 91 |
| | Output frequency | 0 - 120 Hz | | | | | | | | | | |
| | Output voltage | 0 ~ 380V (480V) ²⁾ | | | | | | | | | | |
| Rated input | Voltage | 3Ø 380 ~ 480V (-10% ~ +10%) | | | | | | | | | | |
| | Frequency | 50 ~ 60Hz (±5%) | | | | | | | | | | |
| Overload Tolerance | | 150% of rated current for 60 sec. | | | | | | | | | | |
| Dynamic Braking Unit | | Built-in | | | | | | | | External (option) | | |

1) - Indicates the maximum applicable motor capacity when using a 4-pole standard motor.

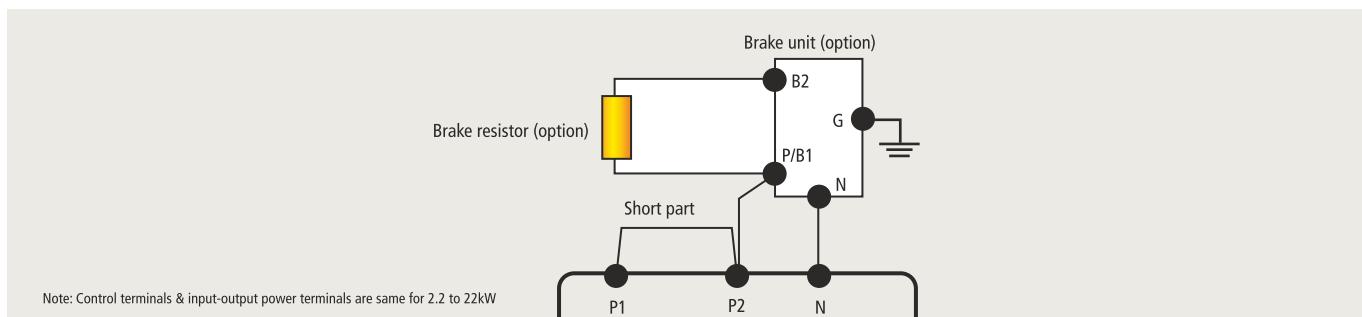
2) - The maximum output voltage cannot be higher than the input voltage and it can be programmable below input voltage.

| Item | | Specification | |
|--------------|--------------------------|---------------------------------|--|
| Circuit type | | IGBT adopted voltage type drive | |
| Control | Control type | | Open Loop Vector, Closed Loop Vector & Closed Loop Vector PM |
| | Frequency / Speed | | Analog: $\pm 0.2\%$ of maximum command speed ($25 \pm 10^\circ\text{C}$) |
| | Control accuracy | | Digital: $\pm 0.01\%$ of maximum command speed ($0 \sim 40^\circ\text{C}$) |
| | Frequency / Speed | | Analog: $\pm 0.05\%$ of maximum command speed |
| | Resolution | | Digital: 0.01% of maximum command speed |
| | Vector | Response speed | 50Hz |
| | | Torque control | 3% |
| | | Torque Boost | Manual torque boost(0~20%), Automatic torque boost |
| | | Time setup | 6000.0 sec (Time unit can be set) |
| | | Combination | 4 combined of Acc/Deceleration time |
| | | Pattern | Linear, S-Curve |
| Braking | Braking type | | Dynamic braking using external resistor |
| | Braking torque | | 150% |
| | Braking resistor | | An external braking resistor is required |
| Input | Speed setting | | Digital setting Multi-step-speed setup by digital input Analog input setting of -10~10V or 4~20mA Setting by options |
| | Analog input | | 3-Channels (AI1, AI2, AI3) -10 ~ 10V, 4 ~ 20mA, 10 ~ 0V, 20 ~ 4mA, motor NTC (selectable) Selectable among 9 different multi-function analog inputs |
| | Digital input | | FX, RX, BX, RST, P1 ~ P7 Multi-function input terminal (P1~P7) can be selected among various functions. |
| | Analog output | | 2-Channel (AO1, AO2) -10 ~ 10V output Selective among 31 multi-function analog output functions |
| | Digital output | | Multi function digital output: 2 channels (1A-1B, 2A-2B) Fault digital output: 1 channel (30A-30C, 30B-30C) |
| Output | Open collector output | | 1 channel (OCI/EG) |
| | Protection function | | Over-current, over/low voltage, drive overheat, drive thermal sensor open, motor over-heat, motor thermal sensor open, over speed, IGBT gate blocking (BX), fuse open, trip by unusual external signal, encoder error, communication error, electronic thermal, stall prevention (V/F), over load(V/F), drive over load. |
| | Installation environment | | Indoor, free of corrosive gas and direct sunlight |
| Environment | Ambient temperature | | -10 ~ 40°C (Non-frozen condition) |
| | Ambient humidity | | Below RH 90% (Dew-free) |
| | Cooling method | | Forced cooling by FAN |
| | Altitude / Vibration | | Below 1000 meters / above sea level 5.9 m/s^2 (=0.6G) |

➤ 2.2~22kW (230/415V)



➤ 30~37kW (230V) & 30~45kW (415V)



▶ Power Terminal

| Display | Name | Description |
|---------|-----------------------------|--|
| R, S, T | AC Input | 3Phase AC input connection 1) 230V: 200~230V, 50/60Hz 2) 415V: 380~480V, 50/60Hz |
| U, V, W | Output | Cable connection of 3 phase induction motor |
| G | Earth | Drive frame earth terminal |
| B1, B2 | Braking resistor | Braking resistor connection |
| P1, P2 | DC reactor and Braking unit | DC reactor, braking unit and DC link common connection terminal |
| P | DC Link(+) terminal | DC Link common connection terminal |
| N | DC Link(-) terminal | Braking unit and DC link common terminal |

▶ Control Circuit Terminals

| Item | Display | Name | Description |
|---------------|---------|----------------------------------|---|
| Digital input | FX | Forward run command | <ul style="list-style-type: none"> ON when tied to CM terminal |
| | RX | Reverse run command | <ul style="list-style-type: none"> Stops when FX and RX are ON/OFF simultaneously |
| Digital input | RST | Fault reset | <ul style="list-style-type: none"> Clears the fault condition only when the fault state is removed |
| | P1(MMO) | | <ul style="list-style-type: none"> Selectable among the following functions: (Multi step speed selection 1/2/3, JOG run, MOP up/down/Save/Clear, analog hold, main drive, speed acc/dec time selection, 3-wire operation, external default signal B contact point, timer input, soft-start cancellation, ASR PI gain selection, ASR P.PI selection, pre-excitation, torque bias) |
| Analog input | CM | Common | <ul style="list-style-type: none"> ON in case of connection between CM and digital |
| | VREF | | |
| Analog input | AI1 | Analog setting power | <ul style="list-style-type: none"> Variable resistor use standard voltage (+10V);10 kΩ Voltage input (-10~10V), current input (4~20mA) |
| | AI2 | Voltage input Current input | <p>The motor NTC input is selectable</p> <ul style="list-style-type: none"> Selectable among following functions; (Speed reference, Torque bias, Torque limit, Process PI control reference, Motor NTC input) Jumper set up use AC voltage input |
| Analog input | AI3 | Voltage input Motor NTC input | <ul style="list-style-type: none"> Jumper set to use as voltage input <p>A1, A2: Open , A3:Left of switch</p> |
| | 5G | COMMON | <ul style="list-style-type: none"> With motor NTC input, switch direction setup <p>A3: Right of switch</p> <ul style="list-style-type: none"> Analog input COMMON terminal |

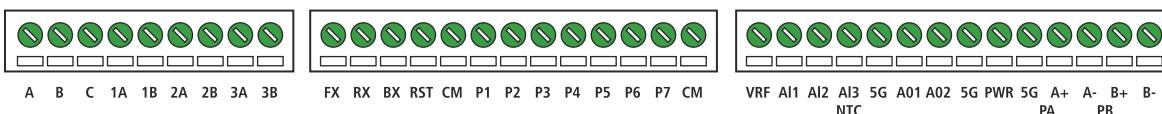
Control Circuit Terminals

| Classification | Display | Name | Description |
|----------------|--|--|---|
| Encoder Input | PE 5G | Encoder power | +5V Line drive power (Jumper set required) 0V |
| | A+ A- | Encoder A phase signal | • A and B phase signals of line drive encoder • To use the line drive type encoder, the 'P5 pin' of I/O PCB JP2 should be shorted and then the JP1 switch should be pulled down to 'LD' direction |
| | B+ B- | Encoder B phase signal | • Jumper set-up (factory default) |
| | PE 5G | Encoder power | +15V Open collector power (Jumper set-up is required) 0V |
| | PA | Encoder A phase signal | • A and B phase signals of complementary and open collector type signals |
| | PB | Encoder B phase signal | • Short the 'P15 pin' of I/O PCB JP2 and then pull up the JP1 switch to 'OC' |
| Encoder output | RA GE RB GE | Encoder output-phase A Encoder output common terminal Encoder output-phase B Encoder output common terminal | • Encoder phase A and B output signal (Open collector type) |
| Analog Output | AO1 | Analog output1 | • Output -10V~+10V • Select from among the following 31 items: (motor speed, speed reference1~2, Torque reference1~2, Torque current volume flux reference, flux reference volume, drive output current, drive output voltage, Motor temperature, DC voltage) |
| | AO2 | Analog output2 | • COMMON terminal for analog output |
| | 5G | COMMON | |
| Digital Output | 1A 1B 2A 2B OC1 EG 30A 30B 30C | Multi-function digital output1 (contact point A) Multi-function digital output2 (contact point B) Multi-function open collector output Fault signal A contact point Fault signal B contact point COMMON | • Select from among the following 14 items: (zero speed detection, speed detection (polarity valid), speed detection (rotation direction invalid), speed reach, speed matching, arbitrary torque detection torque limit feature, motor overheating signal, drive overheating signal, low voltage feature, drive run signal, drive regeneration signal, drive run function, timer output) • Activates when the faults occur • Not available in emergency stop • Common for A and B digital output |

Control Circuit Terminal

Control Terminal Feature

- Control Terminal Panel Arrangement(Standard Type(SIO) - Non insulated type)



➤ Various Optional Cards

Synchronous option, SIN/COS encoder option, expansion I/O, Elevator dedicated I/O, etc.

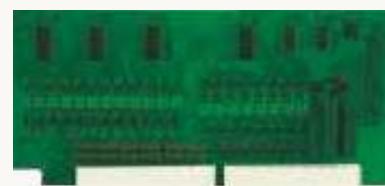
LTCI-CCL-L

- Max. 10 Mbps speed
- Customized LS profile
- CC Link customized cable
- Built-in termination resistor
- Remote I/O : each 32 point
- Remote register : 4 words

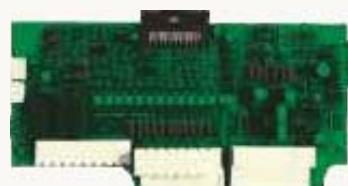


LTEL-EIO-L

- Position sensor/safety switch input
- Car position output
- E/L position and sequence control
- MC/Brake operation signal output
- E/L exclusive connector



SIN/COS ENCODER (LTEN-SCE-L)



LTEN-EDT-L

- Selectable Endat & Sin/Cos Option
- Max. 3,600rpm speed
- Enhanced Comfortable feeling in Car
 - Compatibility with Heidenhain Encoder
 - ECN413, ECN1313, ERN487, ERN1387



Braking resistor specifications

Resistance values in the table shown below are calculated based on the 150% braking torque, 10%ED* standard.

| Input Voltage | Drive Cat. No. | Capacity (10%ED) | |
|------------------|----------------|------------------|------|
| | | [Ω] | [W] |
| Three-Phase 230V | LTVF-L20012AAA | 50 | 800 |
| | LTVF-L20016AAA | 33 | 1200 |
| | LTVF-L20024AAA | 20 | 1600 |
| | LTVF-L20032AAA | 15 | 2400 |
| | LTVF-L20046AAA | 10 | 4800 |
| | LTVF-L20059AAA | 8 | 4800 |
| | LTVF-L20074AAA | 5 | 7200 |
| | LTVF-L20088AAA | 5 | 7200 |
| | | | |
| Three-Phase 415V | LTVF-L40006AAA | 200 | 800 |
| | LTVF-L40008AAA | 130 | 1200 |
| | LTVF-L40012AAA | 85 | 1600 |
| | LTVF-L40016AAA | 60 | 2400 |
| | LTVF-L40024AAA | 40 | 4800 |
| | LTVF-L40030AAA | 30 | 4800 |
| | LTVF-L40039AAA | 20 | 7200 |
| | LTVF-L40045AAA | 20 | 7200 |
| | | | |

* % ED is based on 100sec.

Brake resistor wiring

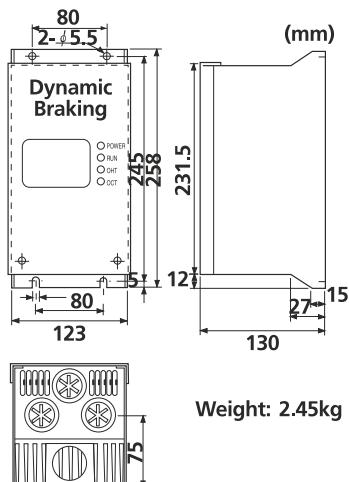
For brake resistor with a temperature detection sensor for fire protection, refer below when in use.

| Brake resistor terminal blocks | Drive terminals | Operation |
|--------------------------------|--|--|
| B1, B2 | P,BR | |
| P7, CM | One of the multi-function input terminals, out of P1~P7, of control terminals board is used as defining 'External trip signal contact B' | The contact is ON in normal temperature and opens in overheat. |

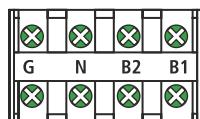
Breaking Unit LED Functions

| Displayed Item | Description |
|----------------|---|
| POWER | Main power in braking unit turns on the POWER LED. Generally the braking unit is wired to the drive, so once the input main power of drive is on, the POWER LED of braking unit turns on. |
| RUN | While braking unit operates its normal operation by the motor regenerative energy, the RUN LED blinks. |
| OHT | During the braking operation, if the braking unit heat sink is overheated and exceeds its limited value, the overheat protection function operates. This blocks the braking unit signal and then turns on the OHT LED. |
| OCT | During the braking operation, if over-current flows in the main circuit of braking unit then the over current protection function is operated in order to prevent the circuit from over current. The TURN ON signal of braking unit is blocked and then turns on the OCT LED. |

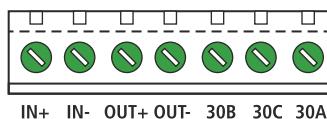
Terminal Block and Braking Unit



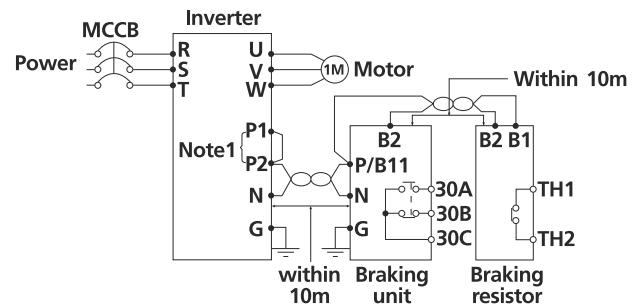
Main circuit terminal block



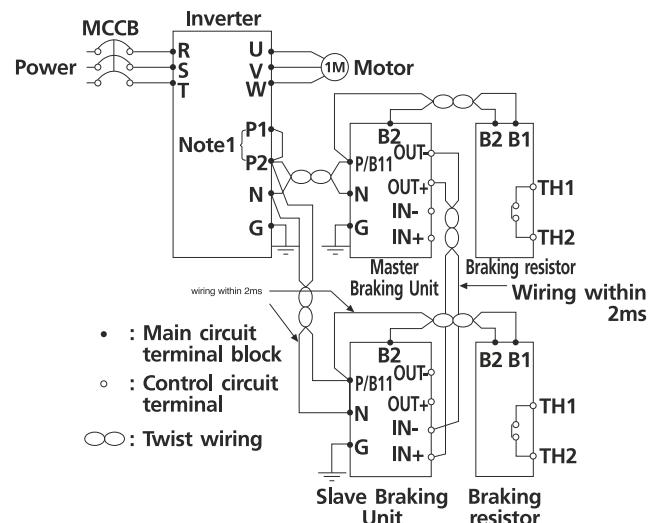
Control circuit terminal



Terminal Block and Braking Unit

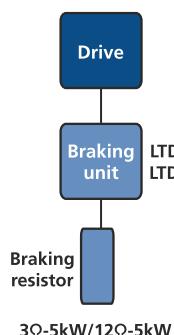


Double use of Braking Unit

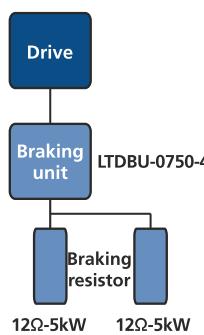


Combination of Braking Units and Braking Resistors

- 30~37kW (230V/415V)



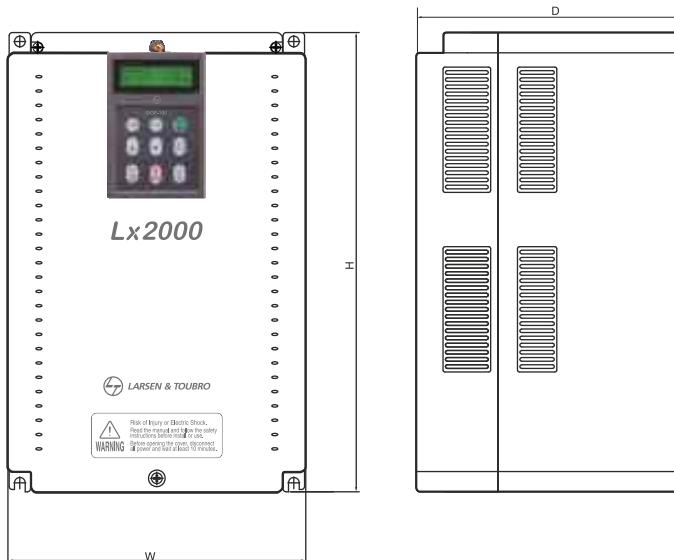
- 45kW (415V)



➤ MCCB (Moulded Case Circuit Breaker) and MC (Magnetic Contactor)

| Input Voltage | Motor (kW) | Drive Cat. No. | MCCB (L&T) | MC (L&T) |
|---------------------|------------|----------------|--------------|----------|
| Three-Phase 230V | 2.2 | LTVF-L20012AAA | DM100/30 | MO 18 |
| | 3.7 | LTVF-L20016AAA | DM100/30 | MO 32 |
| | 5.5 | LTVF-L20024AAA | DM100/50 | MO 50 |
| | 7.5 | LTVF-L20032AAA | DM100/60 | MO 50 |
| | 11 | LTVF-L20046AAA | DN2-250M/100 | MO 70 |
| | 15 | LTVF-L20059AAA | DN2-250M/125 | MO 95 |
| | 18.5 | LTVF-L20074AAA | DN2-250M/160 | MNX 140 |
| | 22 | LTVF-L20088AAA | DN2-250M/160 | MNX 140 |
| | 30 | LTVF-L20122AAA | DN2-250M/250 | MNX 140 |
| | 37 | LTVF-L20146AAA | DN3-400M/320 | MNX 225 |
| | 2.2 | LTVF-L40006AAA | DM16/16 | MO 12 |
| | 3.7 | LTVF-L40008AAA | DM16/16 | MO 18 |
| Three-Phase 415V | 5.5 | LTVF-L40012AAA | DM100/30 | MO 25 |
| | 7.5 | LTVF-L40016AAA | DM100/30 | MO 32 |
| | 11 | LTVF-L40024AAA | DM100/50 | MO 50 |
| | 15 | LTVF-L40030AAA | DM100/60 | MO 50 |
| | 18.5 | LTVF-L40039AAA | DM100/80 | MO 70 |
| | 22 | LTVF-L40045AAA | DN2-250M/100 | MO 70 |
| | 30 | LTVF-L40061AAA | DN2-250M/125 | MO 95 |
| | 37 | LTVF-L40075AAA | DN2-250M/160 | MNX 140 |
| | 45 | LTVF-L40091AAA | DN2-250M/160 | MNX 140 |

➤ **2.2 ~ 22kW (230V/415V)**



| Input Voltage | Drive Cat. No. | W (mm) | H (mm) | D (mm) | Weight (kg) |
|---------------------|----------------|--------|--------|--------|-------------|
| Three-Phase 230V | LTVF-L20012AAA | 200 | 284 | 207 | 6 |
| | LTVF-L20016AAA | 200 | 284 | 207 | 6 |
| | LTVF-L20024AAA | 200 | 284 | 207 | 14 |
| | LTVF-L20032AAA | 200 | 355 | 202 | 14 |
| | LTVF-L20046AAA | 200 | 355 | 202 | 13.7 |
| | LTVF-L20059AAA | 250 | 385 | 221 | 13.7 |
| | LTVF-L20074AAA | 250 | 385 | 221 | 20.3 |
| | LTVF-L20088AAA | 304 | 460 | 254 | 20.3 |
| Three-Phase 415V | LTVF-L40006AAA | 200 | 284 | 207 | 6 |
| | LTVF-L40008AAA | 200 | 284 | 207 | 6 |
| | LTVF-L40012AAA | 200 | 355 | 202 | 14 |
| | LTVF-L40016AAA | 200 | 355 | 202 | 14 |
| | LTVF-L40024AAA | 250 | 385 | 221 | 13.7 |
| | LTVF-L40030AAA | 250 | 385 | 221 | 13.7 |
| | LTVF-L40039AAA | 304 | 460 | 254 | 20.3 |
| | LTVF-L40045AAA | 304 | 460 | 254 | 20.3 |

➤ **30 ~ 37kW (230V/415V)**

| Input Voltage | Drive Cat. No. | W (mm) | H (mm) | D (mm) | Weight (kg) |
|---------------------|----------------|--------|--------|--------|-------------|
| Three-Phase 230V | LTVF-L20122AAA | 350 | 680 | 308.2 | 42 |
| | LTVF-L20146AAA | 350 | 680 | 308.2 | 42 |
| Three-Phase 415V | LTVF-L40061AAA | 350 | 680 | 308.2 | 42 |
| | LTVF-L40075AAA | 350 | 680 | 308.2 | 42 |
| | LTVF-L40091AAA | 375 | 780 | 326 | 63 |

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