



# PowerFlex 700L Liquid-Cooled Adjustable Frequency AC Drive

Frames 2, 3A, and 3B



**Allen-Bradley**

by ROCKWELL AUTOMATION

User Manual

Original Instructions

# Important User Information

Read this document and the documents listed in the additional resources section about installation, configuration, and operation of this equipment before you install, configure, operate, or maintain this product. Users are required to familiarize themselves with installation and wiring instructions in addition to requirements of all applicable codes, laws, and standards.

Activities including installation, adjustments, putting into service, use, assembly, disassembly, and maintenance are required to be carried out by suitably trained personnel in accordance with applicable code of practice.

If this equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

In no event will Rockwell Automation, Inc. be responsible or liable for indirect or consequential damages resulting from the use or application of this equipment.

The examples and diagrams in this manual are included solely for illustrative purposes. Because of the many variables and requirements associated with any particular installation, Rockwell Automation, Inc. cannot assume responsibility or liability for actual use based on the examples and diagrams.

No patent liability is assumed by Rockwell Automation, Inc. with respect to use of information, circuits, equipment, or software described in this manual.

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Throughout this manual, when necessary, we use notes to make you aware of safety considerations.



**WARNING:** Identifies information about practices or circumstances that can cause an explosion in a hazardous environment, which may lead to personal injury or death, property damage, or economic loss.

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**ATTENTION:** Identifies information about practices or circumstances that can lead to personal injury or death, property damage, or economic loss. Attentions help you identify a hazard, avoid a hazard, and recognize the consequence.

---

**IMPORTANT**

Identifies information that is critical for successful application and understanding of the product.

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These labels may also be on or inside the equipment to provide specific precautions.



**SHOCK HAZARD:** Labels may be on or inside the equipment, for example, a drive or motor, to alert people that dangerous voltage may be present.

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**BURN HAZARD:** Labels may be on or inside the equipment, for example, a drive or motor, to alert people that surfaces may reach dangerous temperatures.

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**ARC FLASH HAZARD:** Labels may be on or inside the equipment, for example, a motor control center, to alert people to potential Arc Flash. Arc Flash will cause severe injury or death. Wear proper Personal Protective Equipment (PPE). Follow ALL Regulatory requirements for safe work practices and for Personal Protective Equipment (PPE).

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The following icon may appear in the text of this document.



Identifies information that is useful and can help to make a process easier to do or easier to understand.

Rockwell Automation recognizes that some of the terms that are currently used in our industry and in this publication are not in alignment with the movement toward inclusive language in technology. We are proactively collaborating with industry peers to find alternatives to such terms and making changes to our products and content. Please excuse the use of such terms in our content while we implement these changes.

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**Notes:**



## Summary of Changes

This manual contains new and updated information as indicated in the following table.

Topic	Page
Removed CE (European Conformance Standard) references	Throughout
Updated rated working pressure of the Frame 2 drive	98
Removed 140M self-protected combination motor controllers references	126

This manual provides the basic information needed to install, start-up, and troubleshoot the PowerFlex® 700L Liquid-Cooled AC Drive.

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Rockwell Automation recognizes that some of the terms that are currently used in our industry and in this publication are not in alignment with the movement toward inclusive language in technology. We are proactively collaborating with industry peers to find alternatives to such terms and making changes to our products and content. Please excuse the use of such terms in our content while we implement these changes.

## Who Should Use this Manual?

This manual is intended for qualified personnel. You must be able to install, wire, and operate Adjustable Frequency AC Drive devices. In addition, you must have an understanding of the parameter settings and functions.

## What Is Not in this Manual

This manual is designed to provide only basic installation and start-up information. The following information is **not included**:

### PowerFlex 700L Active Converter Power Module Information

Regenerative PowerFlex 700L drives are equipped with a PowerFlex 700L Active Converter Power Module. For details on active converter I/O wiring, start-up, programming, and other related information, see the PowerFlex 700L Active Converter Power Module User Manual, publication [PFLEX-UM002](#).

## **PowerFlex 700 Vector Control Information (Standard)**

For PowerFlex 700L drives equipped with the standard Vector Control, see the PowerFlex 700 Adjustable Frequency AC Drive User Manual - Series B, publication [20B-UM002](#), which provides I/O wiring, start-up, programming, and vector control encoder information.

## **PowerFlex 700S Phase II Control Information (Optional)**

For PowerFlex 700L drives that are equipped with the optional 700S Phase II Control, see the PowerFlex 700S High Performance AC Drive - Phase II Control User Manual, publication [20D-PM001](#), which provides I/O wiring, start-up, programming, and other related information.

## **HIM (Human Interface Module) Information**

For an overview of the HIM operation, see the PowerFlex 700 Adjustable Frequency AC Drive User Manual - Series B, publication [20B-UM002](#), or the PowerFlex 700S High Performance AC Drive - Phase II Control User Manual, publication [20D-PM001](#).

## **PowerFlex 7-Class Network Communication Adapter Information**

For PowerFlex 700L drives equipped with a network communication adapter, see the adapter User Manuals, publications, 20COMM-UMXXX, <http://www.rockwellautomation.com/literature/>, for information on configuring and using I/O and explicit messaging over the network.

## **PowerFlex 700L Service Information**

For Frame 2 drive service information, see the PowerFlex 700L Liquid-Cooled Adjustable Frequency AC Drive Frame 2 Hardware Service Manual, publication [20L-TG002](#).

For Frame 3A and 3B drive service information, see the PowerFlex 700L Liquid-Cooled Adjustable Frequency AC Drive Frames 3A and 3B Hardware Service Manual, publication [20L-TG001](#).

## Manual Conventions

- In this manual, we also refer to the PowerFlex 700L Liquid-Cooled AC Drive as drive, PowerFlex 700L, or PowerFlex Drive.
- To help differentiate parameter names and LCD display text from other text, the following conventions are used:
  - Parameter Names appear in [brackets] – example: [DC Bus Voltage].
  - Display Text appears in “quotes” – example: “Enabled.”
- The following words are used throughout the manual to describe an action.

Word	Meaning
Can	Possible, able to do something
Cannot	Not possible, not able to do something
May	Permitted, allowed
Must	Unavoidable, you must do this
Shall	Required and necessary
Should	Recommended
Should Not	Not recommended

## General Precautions



**ATTENTION:** This drive contains electrostatic discharge (ESD) sensitive parts and assemblies. Static control precautions are required when installing, testing, servicing, or repairing this assembly. Component damage can result if ESD control procedures are not followed. If you are not familiar with static control procedures, see Guarding Against Electrostatic Damage, publication [8000-4.5.2](#), or any other applicable ESD protection handbook.



**ATTENTION:** An incorrectly applied or installed drive can result in component damage or a reduction in product life. Wiring or application errors, such as undersizing the motor, incorrect or inadequate AC supply, or excessive ambient temperatures can result in malfunction of the system.



**ATTENTION:** Only qualified personnel familiar with adjustable frequency AC drives and associated machinery should plan or implement the installation, start-up, and subsequent maintenance of the system. Failure to comply can result in personal injury and/or equipment damage.



**ATTENTION:** To avoid an electric shock hazard, verify that the voltage on the bus capacitors has discharged completely before servicing. After removing power to the drive, wait 5 minutes for the bus capacitors to discharge. Measure the DC bus voltage at the DC+ and DC- TESTPOINT sockets on the drive or power module. See [Figure 18](#) for Frame 2, [Figure 47](#) for Frame 3A, or [Figure 49](#) for Frame 3B. The voltage must be zero.



**ATTENTION:** Risk of injury or equipment damage exists. DPI host products must not be directly connected together via 1202 cables. Unpredictable behavior can result if two or more devices are connected in this manner.

# Catalog Number Explanation

1-3	4	5-7	8	9	10	11	12	13	14	15	16	17	18
<b>20L</b>	<b>E</b>	<b>800</b>	<b>A</b>	<b>O</b>	<b>E</b>	<b>N</b>	<b>N</b>	<b>A</b>	<b>N</b>	<b>1</b>	<b>O</b>	<b>W</b>	<b>A</b>
a	b	c	d	e	f	g	h	i	j	k	l	m	n

Position

**a**

Drive	
Code	Type
20L	PowerFlex 700L

**b**

Voltage Rating		
Code	Voltage	Ph.
C	400V AC	3
D	480V AC	3
E	600V AC	3
F	690V AC	3

**c1**

ND Rating			
400V, 60 Hz Input			
Code	Amps	Hp (KW)	Frame
360	360	268 (200)	2
650	650	500 (370)	3A
1K2	1250	960 (715)	3B

**c2**

ND Rating			
480V, 60 Hz Input			
Code	Amps	Hp (KW)	Frame
360	360	300 (224)	2
650	650	600 (445)	3A
1K2	1250	1150 (860)	3B

**c3**

ND Rating			
600V, 60 Hz Input			
Code	Amps	Hp (KW)	Frame
425	425	465 (345)	3A
800	800	870 (650)	3B
1K1 <sup>(1)</sup>	1175	1275 (950)	3B

(1) Must operate at 2 kHz PWM only, and only as a stand-alone inverter module ("K" in position 13).

**c4**

ND Rating			
690V, 60 Hz Input			
Code	Amps	Hp (KW)	Frame
380	380	475 (355)	3A
705	705	881 (657)	3B
1K0 <sup>(1)</sup>	1050	1310 (980)	3B

(1) Must operate at 2 kHz PWM only, and only as a stand-alone inverter module ("K" in position 13).

**d**

Enclosure		
Code	Type	Conformal Coating
A <sup>(1)</sup>	NEMA/UL Type 1, IP20	Yes
N <sup>(2)</sup>	Open-Chassis Style/IP00	Yes

(1) Frame 3 complete drive.  
 (2) Frame 2 drive and Frame 3 input filter and power modules.

**e**

HIM	
Code	Operator Interface
0	No HIM/Blank Cover
3 <sup>(1)</sup>	Full Numeric LCD
C <sup>(2)</sup>	Door-Mounted Full Numeric LCD

(1) Frame 2 and Frame 3 power modules.  
 (2) Frame 3 complete drive only.

**f**

Documentation		
Code	Documents	Ship Carton
E	English Doc Set	Yes
N	No Documentation	Yes
Q	No Documentation	No

**g**

Brake	
Code	w/Brake IGBT
N	No

**h**

Brake Resistor	
Code	w/Resistor
N	No

**i**

Equipment Type		
Code	Description	Frame
A	Complete Regenerative Drive - Std. Interrupt Rating	2, 3A, and 3B
C	Input Filter	3A and 3B
E	Combined Active Converter/ Inverter Power Module	3A only
G	Active Converter Power Module	3B only
J	Inverter Power Module - Coupled Version	3B only
K	Inverter Power Module - Common DC Bus Version	3B only
L	Dual Inverter Power Module	3A only
P	Active Converter Power Module - Stand Alone Version	3B only
X <sup>(1)</sup>	Spare Power Module	3A and 3B

(1) No control cassettes.

**j**

Comm Slot		
Code	Communication Option	DPI User-Installed Kit Cat. No. <sup>(1)</sup>
N	None	N
C <sup>(2)</sup>	ControlNet <sup>®</sup> (Coax) - DPI	20-COMM-C
D <sup>(2)</sup>	DeviceNet - DPI	20-COMM-D
E <sup>(2)</sup>	EtherNet/IP <sup>™</sup> - DPI	20-COMM-E
1 <sup>(3)(4)</sup>	DriveLogix Comm Option, ControlNet (Coax)	—
2 <sup>(3)(4)</sup>	DriveLogix Comm Option, ControlNet Redundant (Coax)	—
3 <sup>(3)(4)</sup>	DriveLogix Comm Option, ControlNet (Fiber)	—
4 <sup>(3)(4)</sup>	DriveLogix Comm Option, ControlNet Redundant (Fiber)	—
5 <sup>(3)(4)</sup>	DriveLogix Comm Option, DeviceNet (Open Connection)	—
6 <sup>(3)(4)</sup>	DriveLogix Comm Option, DeviceNet (Twisted Pair)	—

(1) For 700S Phase II Control with DriveLogix5730, comm. slot option selections are mutually exclusive. For two communication adapters, (DPI and DriveLogix), select the DriveLogix comm. slot option and order the DPI user installed kit catalog number separately.  
 (2) 700 Vector Control uses DPI comm. slot options only.  
 (3) DriveLogix comm. slot options require 700S Phase II Control with DriveLogix5730.  
 (4) No longer available as a factory installed option.

1-3			4	5-7		8	9	Position			10	11	12	13	14	15	16	17	18
<b>20L</b>			<b>E</b>	<b>800</b>		<b>A</b>	<b>O</b>	<b>E</b>	<b>N</b>	<b>N</b>	<b>A</b>	<b>N</b>	<b>1</b>	<b>0</b>	<b>W</b>	<b>A</b>			
<i>a</i>			<i>b</i>	<i>c</i>		<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>	<i>h</i>	<i>i</i>	<i>j</i>	<i>k</i>	<i>l</i>	<i>m</i>	<i>n</i>			

**k**

Control Option				
Code	Control	Cassette	Logic Expansion	Synch Link
1	700VC 24V I/O	Base	N/A	N/A
2	700VC 115V I/O	Base	N/A	N/A
A	700S Ph. II	Expanded	No	No
B	700S Ph. II	Expanded	No	Yes
C <sup>(1)</sup>	700S Ph. II	Expanded	Yes	No
D <sup>(1)</sup>	700S Ph. II	Expanded	Yes	Yes
W <sup>(2)</sup>	None	N/A	N/A	N/A

(1) Requires DriveLogix5730.

(2) Frame 3 input filter, Active Converter Power Modules, and spare power modules.

**l**

Feedback		
Code	Control Option	Type
0	All	None
1	700VC	Encoder 5V/12V
A <sup>(1)(2)</sup>	700S Ph. II	Resolver
B <sup>(1)(2)</sup>	700S Ph. II	Hi-Res. Stegmann Encoder
C <sup>(1)(2)(3)</sup>	700S Ph. II	Multi-Device Interface
E <sup>(1)</sup>	700S Ph. II	2nd Encoder
S <sup>(1)(4)</sup>	700S Ph. II	Safe Torque Off (w/2nd Encoder)

(1) Requires expanded cassette.

(2) No longer available as a factory installed option.

(3) Multi-Device Interface allows the connection of the Stegmann and Temposonics linear sensors. The Temposonics sensor cannot be used to close motor control or speed loops.

(4) PowerFlex 700L drives with Safe Torque Off manufactured before 09/25/2020 are TUV certified. Only applies to option S.

**m**

Additional 700S Configuration		
Code	Logix Option	Embedded Comm.
W	None	—
E	Phase II Control	No
K	Phase II Control with DriveLogix5730	No
L <sup>(1)</sup>	Phase II Control with DriveLogix5730	EtherNet/IP

(1) No longer available as a factory installed option.

**n**

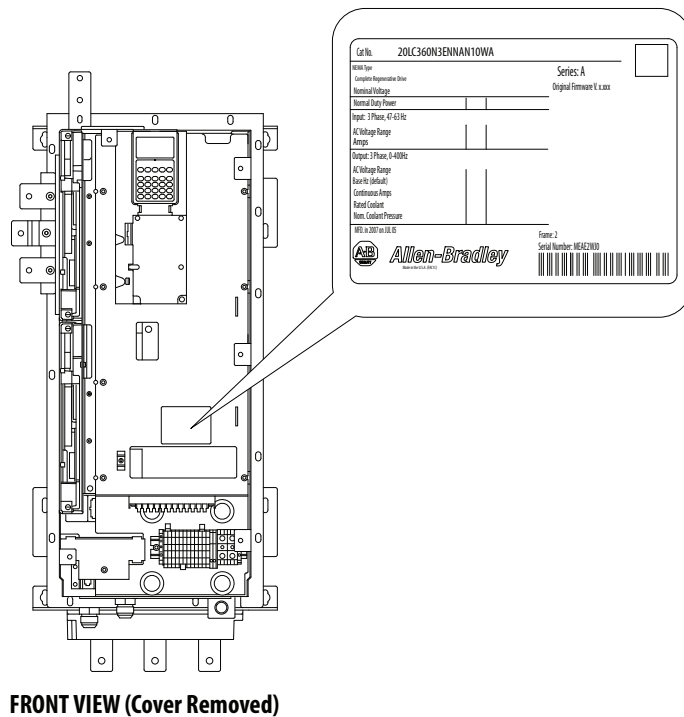
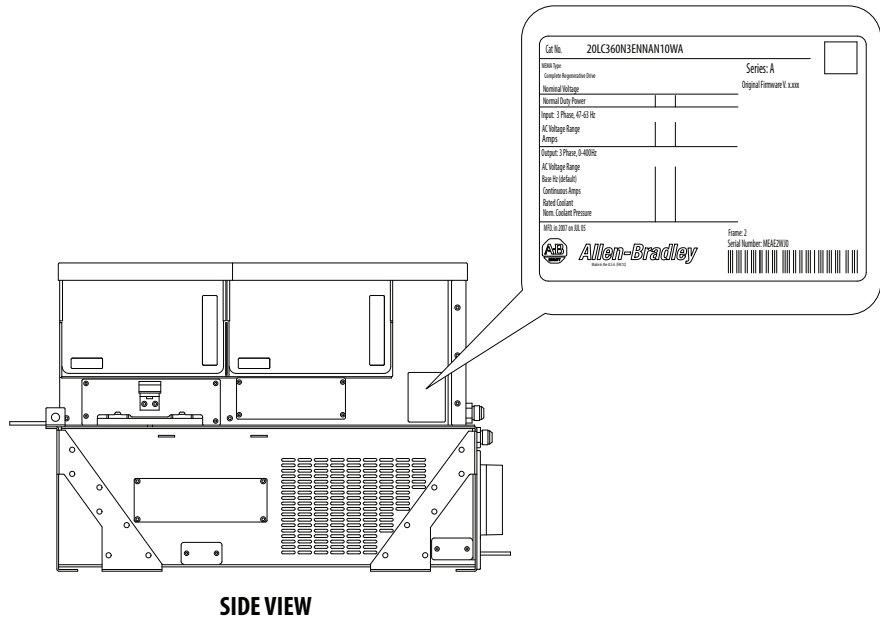
Coolant Type		
Code	Coolant	Frame
N	None	3 Input Filter only
A	Water	All

# Complete Drive Data Nameplate Locations

## Frame 2 Drives

Figure 1 shows multiple data nameplate locations for Frame 2 drives. The data and agency markings are different for equipment type. For example, the complete drive is UL listed component; and the Power Modules are UL recognized.

Figure 1 - Frame 2 Drive Data Nameplate Locations



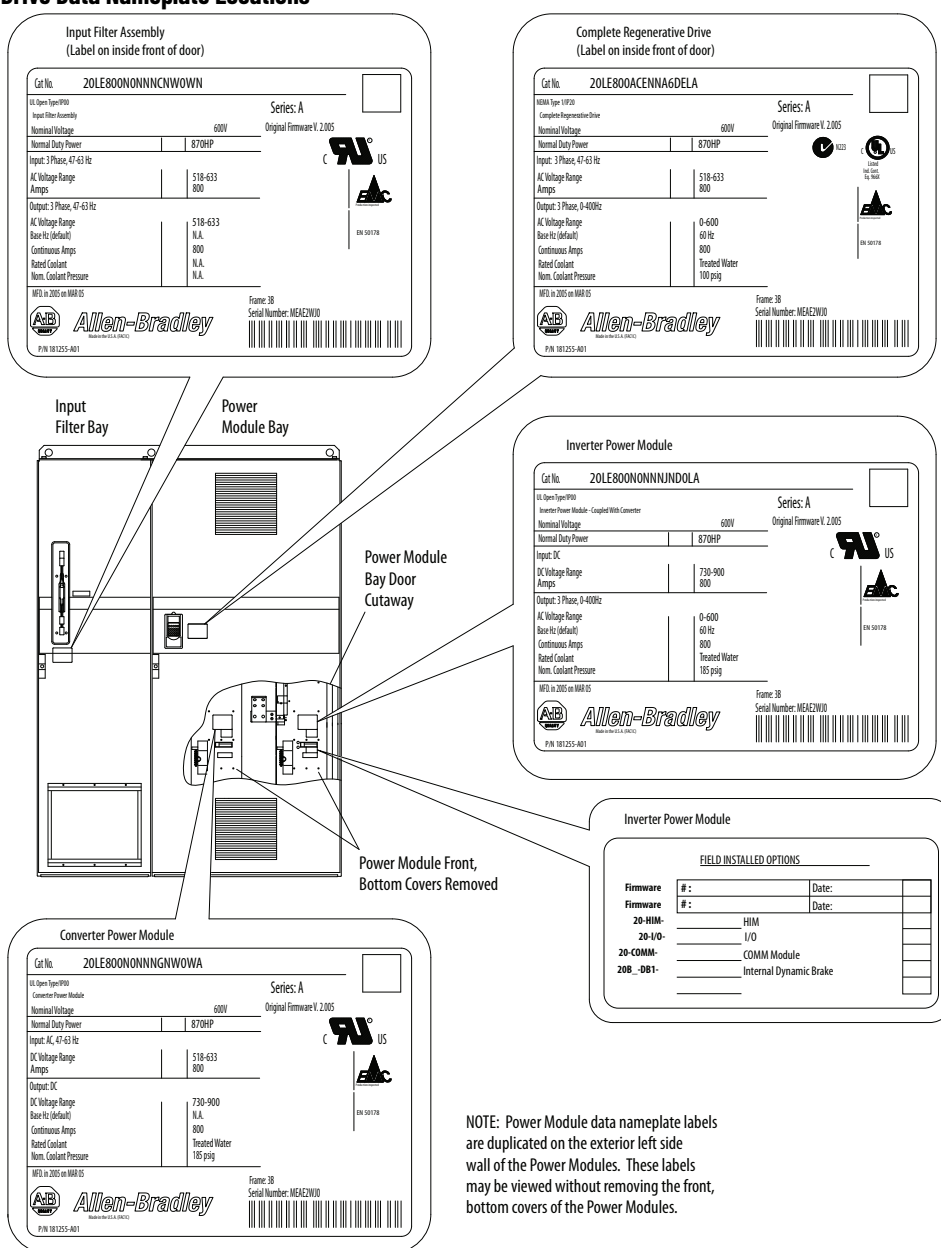
## Frames 3A and 3B Drives

**Figure 2** shows multiple data nameplate locations for complete Frame 3A/ 3B drives. The data and agency markings are different for equipment type. For example, except for 690V AC input, the complete drive is UL listed component; and the Input Filter and Power Modules are UL recognized.

Base Power Module catalog numbers do not reflect the position 14 and position 16 options actually installed inside the Inverter Power Module. When ordering a replacement Inverter Power Module for use in a complete drive, inform Rockwell Customer Service of both the Inverter Power Module catalog string, and the position 14 and position 16 factory-installed options shown on the Factory Installed Options label.

**TIP** PowerFlex 700L drives with Safe Torque Off manufactured before 09/25/2020 are TUV certified. Only applies to option S.

**Figure 2 - Complete Frame 3A and 3B Drive Data Nameplate Locations**



NOTE: Power Module data nameplate labels are duplicated on the exterior left side wall of the Power Modules. These labels may be viewed without removing the front, bottom covers of the Power Modules.

## Additional Resources

These documents contain additional information concerning related products from Rockwell Automation.

Title	Publication
Wiring and Grounding Guidelines for Pulse Width Modulated (PWM) AC Drives	<a href="#">DRIVES-IN001</a>
Preventive Maintenance of Industrial Control and Drive System Equipment	<a href="#">DRIVES-TD001</a>
PowerFlex 70EC/700VC Reference Manual	<a href="#">PFLEX-RM004</a>
Safety Guidelines for the Application, Installation, and Maintenance of Solid State Control	<a href="#">SGI-1.1</a>
Guarding Against Electrostatic Damage	<a href="#">8000-4.5.2</a>

The following publications provide specific feedback card information for PowerFlex 700L drives with Optional 700S Phase II Control.

Title	Publication
Hi-Resolution (Stegmann) Feedback Option Card Installation Instructions for PowerFlex 700S Drives	<a href="#">20D-IN001</a>
Resolver Feedback Option Card Installation Instructions for PowerFlex 700S Drives	<a href="#">20D-IN002</a>
Multi-Device Interface Option Card Installation Instructions for PowerFlex 700S Drives	<a href="#">20D-IN004</a>
Second Encoder Option Card for PowerFlex 700S Drives with Phase II Control	<a href="#">20D-IN009</a>
DriveGuard® Safe Torque Off Option for PowerFlex 700S Phase II and PowerFlex 700L Drives	<a href="#">20D-UM007</a>

Title	Publication
DriveLogix™ 5730 Controller User Manual <sup>(1)</sup>	<a href="#">20D-UM003</a>
PowerFlex 700S AC Drive with Phase II Control Programming Manual <sup>(2)</sup>	<a href="#">20D-PM001</a>
PowerFlex 700 AC Drives – Frames 0...10, Vector Control Firmware 4.001 and Up <sup>(3)</sup>	<a href="#">20B-UM002</a>

(1) This publication provides information that is necessary when applying the 700S Phase II Control DriveLogix 5730 Controller.

(2) This publication provides information that is necessary in applications where the PowerFlex 700L drive has the PowerFlex 700S phase II control option.

(3) This publications provides information that is necessary in applications where the PowerFlex 700L drive has the PowerFlex 700 vector control option.

The following publications provide information that is useful when planning and installing communication networks.

Title	Publication
ControlNet Coax Tap Installation Instructions	<a href="#">1786-IN007</a>
ControlNet Coax Media Planning and Installation Manual	<a href="#">1786-6.2.1</a>
ControlNet Fiber Media Planning and Installation Guide	<a href="#">CNET-IN001</a>
DeviceNet Media Design and Installation Guide	<a href="#">DNET-UM072</a>
DeviceNet Starter Kit User Manual	<a href="#">DNET-UM003</a>
EtherNet/IP Media Planning and Installation Manual <sup>(1)</sup>	ODVA Pub. 148
EtherNet/IP Network Infrastructure Guidelines <sup>(1)</sup>	ODVA Pub. 35
SynchLink™ Design Guide	<a href="#">1756-TD008</a>

(1) Use this link to the ODVA EtherNet/IP library for these publications: <https://www.odva.org/technology-standards/document-library/>

You can view or download publications at [rok.auto/literature](http://rok.auto/literature).



## General Installation Information

This chapter provides general information on mounting and wiring PowerFlex® 700L Liquid-Cooled AC Drives.

Topic	Page
Enclosure Ratings	17
AC Supply Source Considerations	17
Power Wiring	20
Using Input/Output Contactors	24

### Enclosure Ratings

PowerFlex 700L Liquid-Cooled AC drives have the following enclosure ratings:

- Open-Chassis Style (IP00) - Frame 2: Intended to be installed in an enclosure. Frame 3: Input filter and power modules, when purchased individually, are intended to be mounted in an enclosure.
- Type 1 (IP20) - Frame 3: Drive is mounted in a separate NEMA/UL Type 1 enclosure to obtain this rating.

PowerFlex 700L Liquid-Cooled AC drives must be placed in an enclosure. See the catalog string on page [12](#) for fully assembled NEMA/UL Type 1 drive options.

### AC Supply Source Considerations

PowerFlex 700L Liquid-Cooled AC drives are suitable for use on a circuit capable of delivering up to a maximum of 200,000 rms symmetrical amperes. For the PowerFlex 700L Frame 3A or 3B complete drive, a circuit breaker with shunt trip with the appropriate kAIC rating must always be used upstream of the power module. See [Table 1](#) for details.

PowerFlex 700L Liquid Cooled AC drives should not be used on undersized or high-impedance supply systems. The supply system kVA should be equal to or greater than the drive-rated kW, and the system impedance should be less than 10%. Operation outside these limits could cause instability resulting in drive shutdown.

$$\text{System Impedance} = (\text{PowerFlex 700L kVA} \div \text{Transformer kVA}) \times \text{Transformer \% Impedance}$$

The kVA of all PowerFlex 700L drives on the distribution system and the system impedance of upstream transformers should be taken into account.



**ATTENTION:** To guard against personal injury and/or equipment damage caused by improper circuit breaker selection, use only the recommended circuit breakers specified in [Table 1](#).

## Unbalanced, Ungrounded or Resistive Grounded Distribution Systems

If phase-to-ground voltage will exceed 125% of nominal or the supply system is ungrounded, see Wiring and Grounding Guidelines for Pulse Width Modulated (PWM) AC Drives, publication [DRIVES-INO01](#), for more information.



**ATTENTION:** PowerFlex 700L Liquid Cooled Frame 2, 3A, and 3B drives contain protective MOVs and a common mode capacitor that are referenced to ground. (The protective MOVs and common mode capacitor in Frame 3A and 3B drives are mounted in the Input Filter Bay.) These devices must be disconnected if the drive is installed on a resistive grounded distribution system or an ungrounded distribution system.

Drive Frame Size	See Ungrounded or Resistive Grounded Installations on...
2	page <a href="#">37</a>
3A or 3B	page <a href="#">72</a>

## Input Power Conditioning

Certain events on the power system supplying a drive can cause component damage or shortened product life. These events include the following:

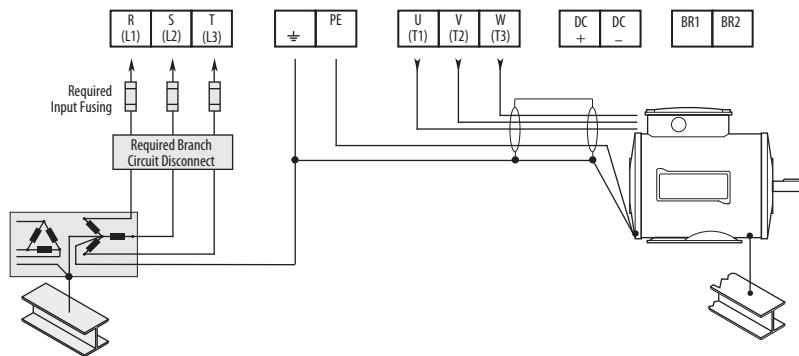
- The power system has power factor correction capacitors switched in and out of the system, either by the user or by the power company.
- The power source has intermittent voltage spikes in excess of 6000 volts. These spikes could be caused by other equipment on the line or by events such as lightning strikes.
- The power source has frequent interruptions.

## General Grounding Requirements

**The drive Safety Ground - PE must be connected to system ground.** Ground impedance must conform to the requirements of national and local industrial safety regulations and/or electrical codes. The integrity of all ground connections should be periodically checked.

For installations within a cabinet, a single safety ground point or ground bus bar connected directly to building steel should be used. All circuits including the AC input ground conductor should be grounded independently and directly to this ground point or ground bus bar.

**Figure 3 - Typical Grounding**



### Safety Ground - PE

This is the safety ground for the drive that is required by code. This point must be connected to adjacent building steel (girder or joist), a floor ground rod, or bus bar (Figure 3). Grounding points must comply with national and local industrial safety regulations and/or electrical codes.

### Shield Termination - SHLD

The Shield terminal provides a grounding point for the motor cable shield. It must be connected to an earth ground by a separate continuous lead. The **motor cable** shield should be connected to this terminal on the drive (drive end) and the motor frame (motor end). Use a shield terminating or EMI clamp to connect shield to this terminal.

When shielded cable is used for **control and signal wiring**, the shield should be grounded at the source end only.

## Wiring Requirements for the Drive

Certain drive requirements should be checked before continuing with the drive installation. Wire sizes, branch circuit protection, encoder feedback, and wiring to disable the drive are all areas that need to be evaluated.

Operation of the drive can be disabled in two locations. The Gate Enable terminal block on the front of the power structure can be used to disable the firing of inverter IGBTs. When the Gate Enable signal is opened, inverter IGBTs are disabled independent of any software control. As a result, the Active Converter Power Module is also turned off, but this is done via software operation. The firing of IGBTs in the Active Converter Power Module can be disabled independently of any software control by opening the connection between terminals 13 and 14 on the Active Converter Power Module control cassette PCB assembly terminal block P1. This action also generates a fault in the Inverter Power Module to enunciate this condition.

## Input Line Branch Circuit Protection



**ATTENTION:** Most codes require that upstream branch circuit protection be provided to protect input power wiring.

The PowerFlex 700L Frame 2 drive does not provide input power short circuit protection. Specifications for the recommended fuse or circuit breaker to provide Frame 2 drive input power protection against short circuits are provided in [Table 23](#) and [Table 24](#).

Frame 3A and 3B complete drives include an input power circuit breaker. The value of the circuit breaker provided with the drive is listed in [Table 1](#).

**Table 1 - AC Input Circuit Breaker Values for Frame 3A and 3B Complete Drives**

Frame Size	Input Voltage	Circuit Breaker Provided	Shunt Trip Rating
3A	400...480V AC	800 A	65 kAIC
	575...690V AC	800 A	35 kAIC
3B	400...480V AC	1500 A	100 kAIC
	575...690V AC	1500 A	35 kAIC

## Power Wiring

Because most start-up difficulties are the result of incorrect wiring, take every precaution to verify that the wiring is correct. Read and understand all items in this section before beginning installation.



**ATTENTION:** The following information is merely a guide for proper installation. Rockwell Automation cannot assume responsibility for the compliance or noncompliance to any code, national, local, or otherwise for the proper installation of this drive or associated equipment. A risk of personal injury and/or equipment damage exists if codes are ignored during installation.

## Cable Types Acceptable for 400...690 Volt Installations



**ATTENTION:** National Codes and standards (NEC, VDE, BSI, and so forth) and local codes outline provisions for safely installing electrical equipment. Installation must comply with specifications regarding wire types, conductor sizes, branch circuit protection, and disconnect devices. Failure to do so can result in personal injury and/or equipment damage.

A variety of cable types are acceptable for drive installations. For many installations, unshielded cable is adequate, provided it can be separated from sensitive circuits. As an approximate guide, allow a spacing of 0.3 meters (1 foot) for every 10 meters (32.8 feet) of length. In all cases, long parallel runs must be avoided. Do not use cable with an insulation thickness less than or equal to 15 mils (0.4mm/0.015 in.). **Use Copper wire only.** Wire gauge requirements and recommendations are based on 75 °C (167 °F). Do not reduce wire gauge when using higher temperature wire.

### *Unshielded Cable*

THHN, THWN, or similar wire is acceptable for drive installation in dry environments provided adequate free air space and/or conduit fill rate limits are used. **Do not use THHN or similarly coated wire in wet areas.** Any wire chosen must have a minimum insulation thickness of 15 mils (0.4mm/0.015 in.) and should not have large variations in insulation concentricity.

### *Shielded Cable*

Shielded cable contains all of the general benefits of multi-conductor cable with the added benefit of a copper braided shield that can contain much of the noise generated by a typical AC Drive. Strong consideration for shielded cable should be given in installations with sensitive equipment such as weigh scales, capacitive proximity switches, and other devices that can be affected by electrical noise in the distribution system. Applications with large numbers of drives in a similar location, imposed EMC regulations, or a high degree of communication/networking are also good candidates for shielded cable.

Shielded cable can also help reduce shaft voltage and induced bearing currents for some applications. In addition, the increased impedance of shielded cable can help extend the distance the motor can be located from the drive without the addition of motor protective devices such as terminator networks. See Chapter 5, "Reflected Wave" in Wiring and Grounding Guidelines for Pulse Width Modulated (PWM) AC Drives, publication [DRIVES-IN001](#).

Consideration should be given to all of the general specifications dictated by the environment of the installation, including temperature, flexibility, moisture characteristics, and chemical resistance. Additionally, a braided shield should be included and specified by the cable manufacturer as having coverage of at least 75%. An additional foil shield can greatly improve noise containment.

A good example of recommended cable is Belden 29528 ... 29532 (AWG-1 ... AWG-410). This cable has three XLPE insulated conductors plus ground with a spiral copper shield surrounded by a PVC jacket.

Other types of shielded cable are available, but the selection of these types can limit the allowable cable length. Particularly, some of the newer cables twist 4 conductors of THHN wire and wrap them tightly with a foil shield. This construction can greatly increase the cable charging current required, and reduce the overall drive performance. These cables are not recommended.

### Armored Cable

Cable with continuous aluminum armor is often recommended in drive system applications or specific industries. It offers most of the advantages of standard shielded cable and also combines considerable mechanical strength and resistance to moisture. It can be installed in concealed and exposed manners and removes the requirement for conduit (EMT) in the installation. It can also be directly buried or embedded in concrete.

Because noise containment can be affected by incidental grounding of the armor to building steel when the cable is mounted, we recommend that the armor cable have an overall PVC jacket. For details, see Chapter 2, "Wire Types" in Wiring and Grounding Guidelines for Pulse Width Modulated (PWM) AC Drives, publication [DRIVES-IN001](#).

Interlocked armor is acceptable for shorter cable runs, but continuous welded armor is preferred.

Best performance is achieved with three spaced ground conductors, but acceptable performance for drives below 200 HP is provided by way of a single ground conductor.

**Table 2 - Recommended Shielded or Armored Wire**

Location	Rating/Type	Description
Standard (Option 1)	1000V, 90 °C (194 °F) XHHW2/RHW-2 Anixter B29528-B29532, Belden 29528-29532, or equivalent	<ul style="list-style-type: none"> <li>• Four tinned copper conductors with XLPE insulation.</li> <li>• Copper braid/aluminum foil combination shield and tinned copper drain wire.</li> <li>• PVC jacket.</li> </ul>
Standard (Option 2)	Tray rated 1000V, 90 °C (194 °F) RHH/RHW-2 Anixter 0LFLEX-76xxx03 or equivalent	<ul style="list-style-type: none"> <li>• Three tinned copper conductors with XLPE insulation.</li> <li>• Corrugated copper tape with three bare copper grounds in contact with shield.</li> <li>• PVC jacket.</li> </ul>
Class I & II; Division I & II	Tray rated 1000V, 90 °C (194 °F) RHH/RHW-2 Anixter 7VFD-xxxx or equivalent	<ul style="list-style-type: none"> <li>• Three bare copper conductors with XLPE insulation and impervious corrugated continuously welded aluminum armor.</li> <li>• Black sunlight resistant PVC jacket overall.</li> <li>• Three copper grounds.</li> </ul>

## Cable Trays and Conduit

If cable trays or large conduits are to be used, see the guidelines in Wiring and Grounding Guidelines for Pulse Width Modulated (PWM) AC Drives, publication [DRIVES-IN001](#).



**ATTENTION:** To avoid a possible shock hazard caused by induced voltages, unused wires in the conduit must be grounded at both ends. For the same reason, if a drive sharing a conduit is being serviced or installed, all drives using this conduit should be disabled. This helps to minimize the possible shock hazard from “cross coupled” motor leads.

## General Notes

- Without additional external filtering, PowerFlex 700L Liquid-Cooled AC drives satisfy the 2nd Environment high-frequency emission limits of EN61800-3. Without external mitigation, PowerFlex 700L Liquid-Cooled drives are not intended to be used on a low-voltage public network which supplies residential or office premises; radio frequency interference is expected if used in such an environment.
- The drive motor cabling should be kept as short as possible to minimize electromagnetic emission and capacitive currents.
- Use of line filters in ungrounded systems is not recommended.
- Conformity of the drive with EMC requirements does not guarantee an entire machine or installation complies with EMC requirements. Many factors can influence total machine/installation compliance.
- Non-regenerative PowerFlex 700L Liquid-Cooled AC drives generate conducted low frequency disturbances (harmonic emissions) on the AC supply system which may require mitigation in some applications. More information regarding harmonic emissions can be found in the PowerFlex 70/700 Reference Manual, [PFLEX-RM001](#).
- When operated on a public supply system, it is the responsibility of the installer or user to make sure, by consultation with the distribution network operator and Rockwell Automation, if necessary, that applicable requirements have been met.

## Using Input/Output Contactors

### Input Contactor Precautions

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**ATTENTION:** A contactor or other device that routinely disconnects and reapplies the AC line to the drive to start and stop the motor can cause drive hardware damage. The drive is designed to use control input signals that will start and stop the motor. If an input device is used, operation must not exceed one cycle per minute or drive damage will occur.



**ATTENTION:** The drive start/stop/enable control circuitry includes solid-state components. If hazards due to accidental contact with moving machinery, or unintentional flow of liquid, gas, or solids exist, an additional hard-wired stop circuit may be required to remove the AC line to the drive. An auxiliary braking method can be required.

---

### Output Contactor Precaution

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**ATTENTION:** To guard against drive damage when using output contactors, the following information must be read and understood. One or more output contactors can be installed between the drive and motor(s) for the purpose of disconnecting or isolating certain motors/loads. If a contactor is opened while the drive is operating, power will be removed from the respective motor, but the drive will continue to produce voltage at the output terminals. In addition, reconnecting a motor to an active drive (by closing the contactor) could produce excessive current that can cause the drive to fault. If any of these conditions are determined to be undesirable or unsafe, an auxiliary contact on the output contactor should be wired to a drive digital input that is programmed as "Enable." This will cause the drive to execute a coast-to-stop (cease output) whenever an output contactor is opened.

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## Frame 2 Installation

Topic	Page
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Equipment Lifting	28
Mounting Requirements	30
Verifying the Drive's Watts Loss Rating	31
Removing the Drive Cover	31
Removing the Active Converter Control Cassette	32
Removing the Inverter Control Cassette	33
Determining Wire Routing for Control, Ground, Drive Input, and Motor Output	35
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Power Wiring	38
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DPI Connections for Frame 2 Drives	48
Coolant Loop Connections	48

Because most start-up difficulties are the result of incorrect wiring, take every precaution to verify that the wiring is completed as instructed. Read and understand all items before starting actual installation.



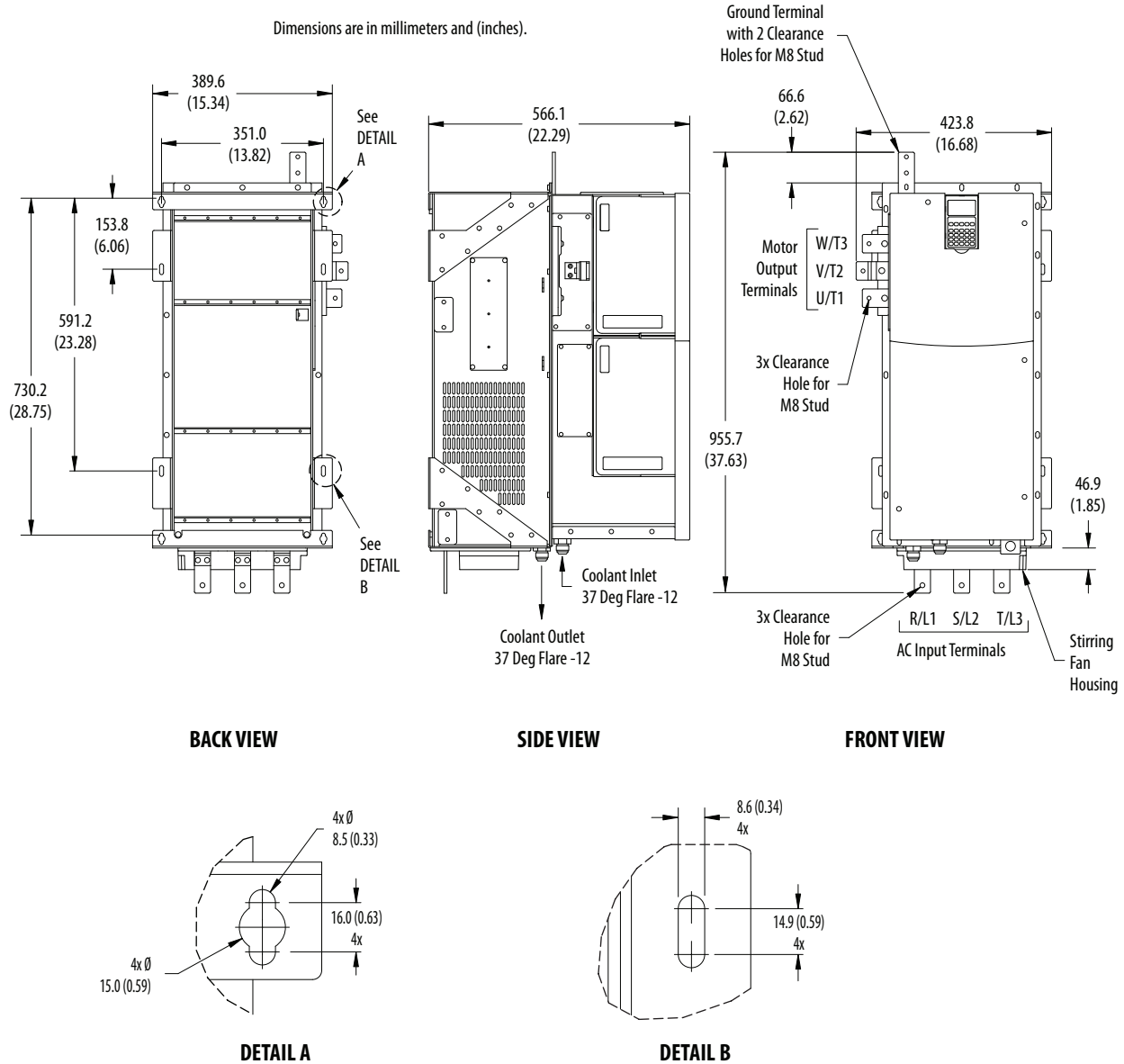
**ATTENTION:** The following information is merely a guide for proper installation. Rockwell Automation does not assume responsibility or liability for the compliance or noncompliance to any code, national, local or otherwise for the proper installation of this drive or associated equipment. A hazard of personal injury and/or equipment damage exists if codes are ignored during installation.

### Mounting Considerations

### Total Area Required for Drive Installation

Overall drive dimensions are shown in [Figure 4](#) as an aid in calculating the total area required for installing Frame 2 drives.

Figure 4 - Frame 2 Drive Installation Dimensions

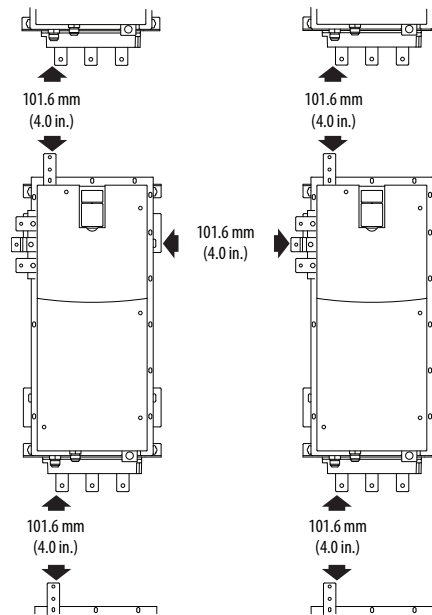


**Approximate Weight**

186 kg (410 lb)

**Recommended Mounting Clearances**

Specified vertical clearance requirements (Figure 5) are intended to be from drive to drive. Other objects can occupy this space; however, reduced air flow can cause protection circuits to fault the drive. In addition, inlet air temperature must not exceed the product specification.

**Figure 5 - Frame 2 Drive Minimum Mounting Clearances**

### Verifying Drive Input Ratings Match Supplied Power

It is important to verify that plant power meets the input power requirements of the PowerFlex® 700L Frame 2 drive circuitry. See [Appendix A](#) for input power rating specifications. Be sure input power to the drive corresponds to the drive nameplate voltage and frequency.

## Equipment Lifting

This section explains how to lift the drive.



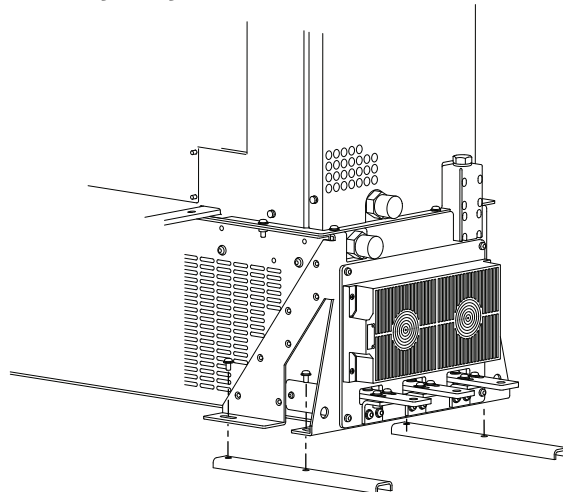
**ATTENTION:** To guard against possible personal injury and/or equipment damage, observe the following:

- Do not allow any part of the drive or lifting mechanism to make contact with electrically charged conductors or components.
- At no time should a person or their limbs be directly underneath the items being lifted.
- Do not subject the load to high rates of acceleration or deceleration.
- Inspect all lifting hardware for proper attachment before lifting any drive unit.

### Attaching the Lifting Feet to the Drive

1. Remove the four shipping bolts that hold the drive to the skid.
2. Attach the two lifting feet provided with the drive to the bottom drive mounting holes as shown in [Figure 6](#).

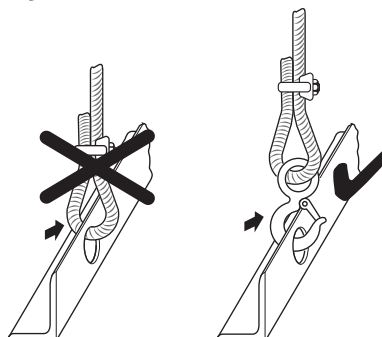
**Figure 6 - Attaching Lifting Feet to the Drive**



### Attaching the Lifting Hardware to the Drive

Apply lifting hooks (see [Figure 7](#)). Take precautions to verify that there are lifting hooks secured in all four locations ([Figure 8](#)) on the drive.

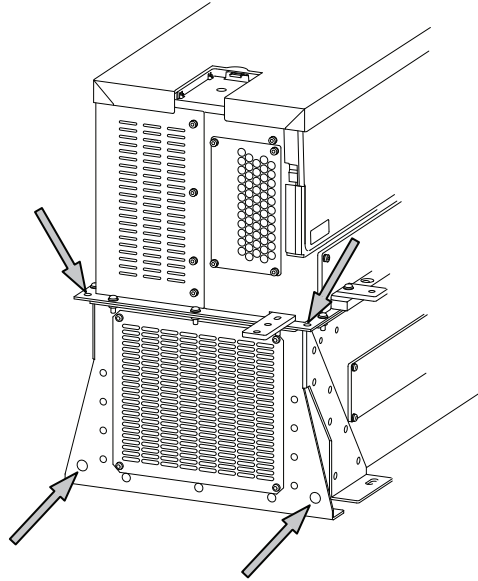
**Figure 7 - Attaching Lifting Hardware to the Frame 2 Drive**



## Connecting Lifting Hooks to Proper Locations

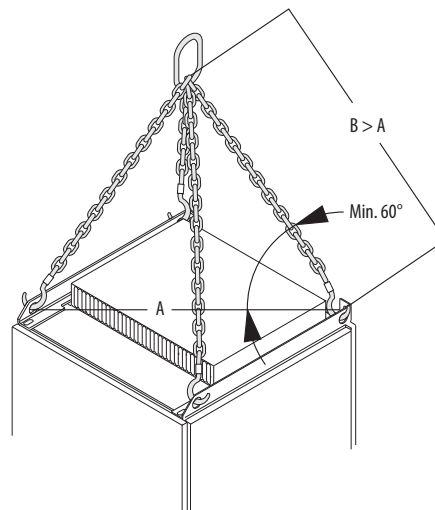
Locate all four lifting features on the drive (see [Figure 8](#)). All four locations must be used to maintain the drive center of gravity when lifting.

**Figure 8 - Lifting Locations on the Frame 2 Drive**



## Applying Strap Angles

**TIP** To ensure that this angle is greater than  $60^\circ$ , make the length of chain or cable between the center and the corners (B) longer than the distance between the opposite corners (A).

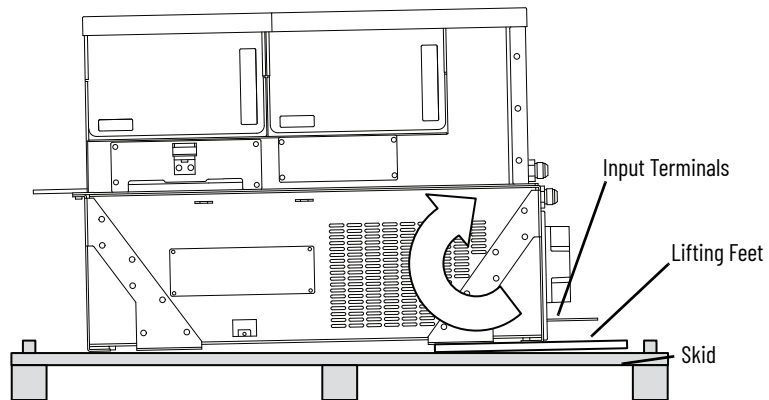


## Rotating the Drive About the Board

[Figure 9](#) shows the drive, with the lifting feet attached, on a skid. To avoid damage to the drive input terminals when lifting the drive to a vertical position, do the following.

1. After the straps are in place (see [Applying Strap Angles on page 29](#)), carefully lift the drive to rotate it 90° to a vertical position.
2. Remove the lifting feet before installing the drive into the enclosure.

**Figure 9 - Frame 2 Drive on Skid**



## Mounting Requirements

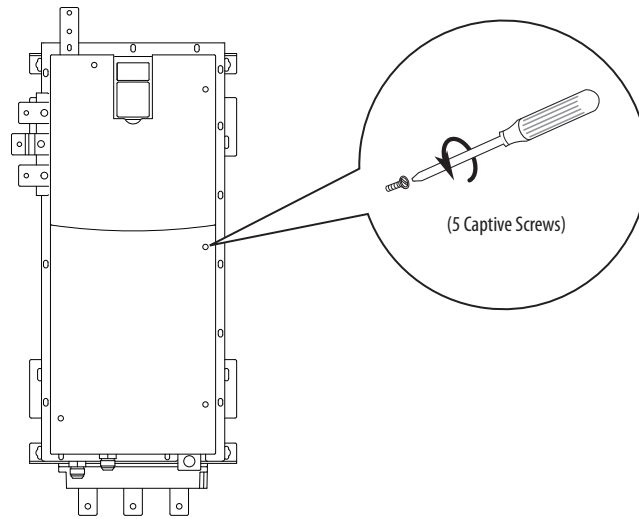
The PowerFlex700L Frame 2 drive is a single integrated assembly consisting of a filter section and a power section. The filter section provides the mounting feet and represents greater than 50% of the approximate 186 kg (410 lb) total weight. Follow these mounting requirement guidelines.

1. Mount the Frame 2 drive into an enclosure that is designed according to Electrical Equipment Pollution Degree 2 requirements.
2. Size and fasten any enclosure mounting panel appropriately to accommodate for the weight of the drive.
3. The Frame 2 drive is designed to use eight M8 x 1.25 fasteners in mounting slots shown in Detail A and Detail B of [Figure 4](#).
4. The M8 x 1.25 fasteners must be class 5.8 or greater.
5. Use a lock washer or similar mechanism to prevent the fasteners from loosening after mounting.
6. All M8 x 1.25 fastener threads must engage a steel panel with 6 to 7 full threads or a permanent backing nut such as a weld nut or a self-clinching PEM nut with 4 full threads.
7. Tighten the M8 x 1.25 fasteners to  $11.3 \pm 2.8$  N·m ( $100 \pm 25$  lb·in) unless the lock washer mechanism requires a different torque. If this is the case, the holding force must be equivalent.

## Verifying the Drive's Watts Loss Rating

When mounting the drive inside of an enclosure, determine the watts loss rating of the drive from [Table 22 on page 125](#). This table lists the typical full load power loss watts value at 4 kHz (rated carrier frequency). Make sure that the enclosure is adequately ventilated with 0...50 °C (32...122 °F) ambient air based on the drive's watts loss rating.

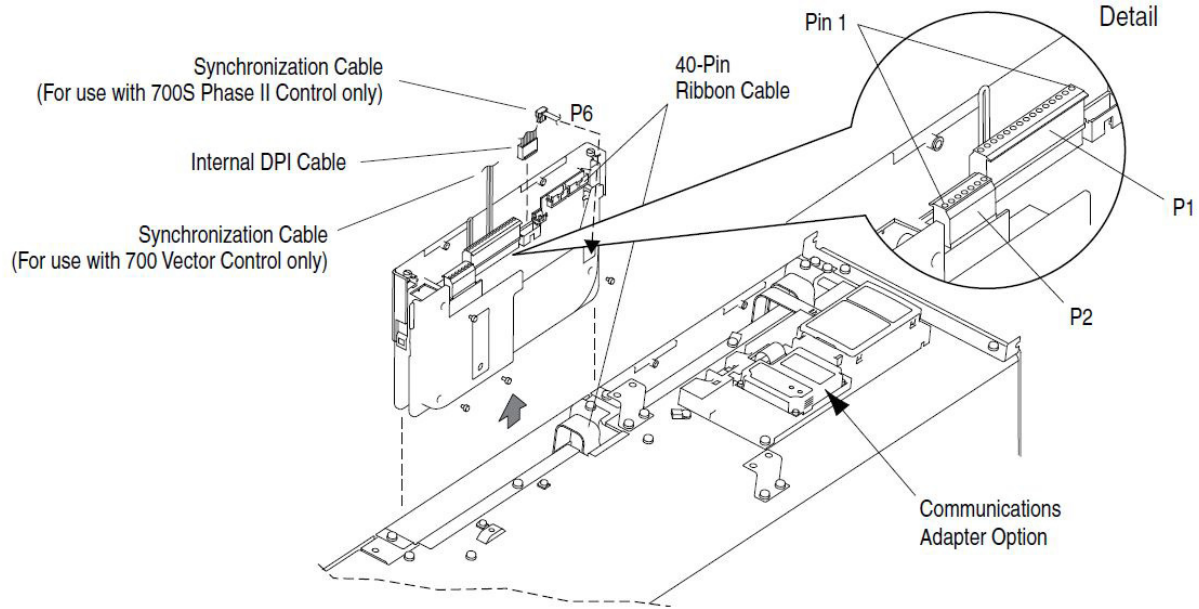
## Removing the Drive Cover



## Removing the Active Converter Control Cassette

The Frame 2 regenerative-type drive is equipped with an Active Converter control cassette. [Figure 10](#) shows the location and removal of this cassette to access its terminal blocks for control wiring. See the PowerFlex 700 Active Converter Power Module User Manual, publication [PFLEX-UM002](#), for control wiring details.

**Figure 10 - Removing the Frame 2 Active Converter Control Cassette**





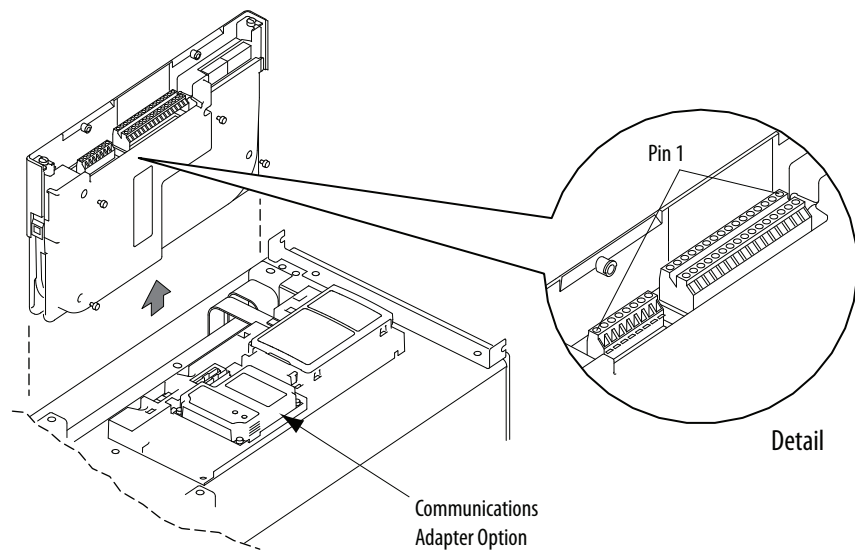
## Removing the Inverter Control Cassette

For Frame 2 drives, the Inverter is equipped with either the standard PowerFlex 700 Vector Control cassette or the optional PowerFlex 700S Phase II Control cassette. In either case, the cassette is removed in the same way.

### PowerFlex 700 Vector Control Cassette (standard)

[Figure 11](#) shows the location and removal of the drive's standard PowerFlex 700 Vector Control cassette to access its terminal blocks for control wiring. See the PowerFlex 700 Adjustable Frequency AC Drive User Manual - Series B, publication [20B-UM002](#), for control wiring details.

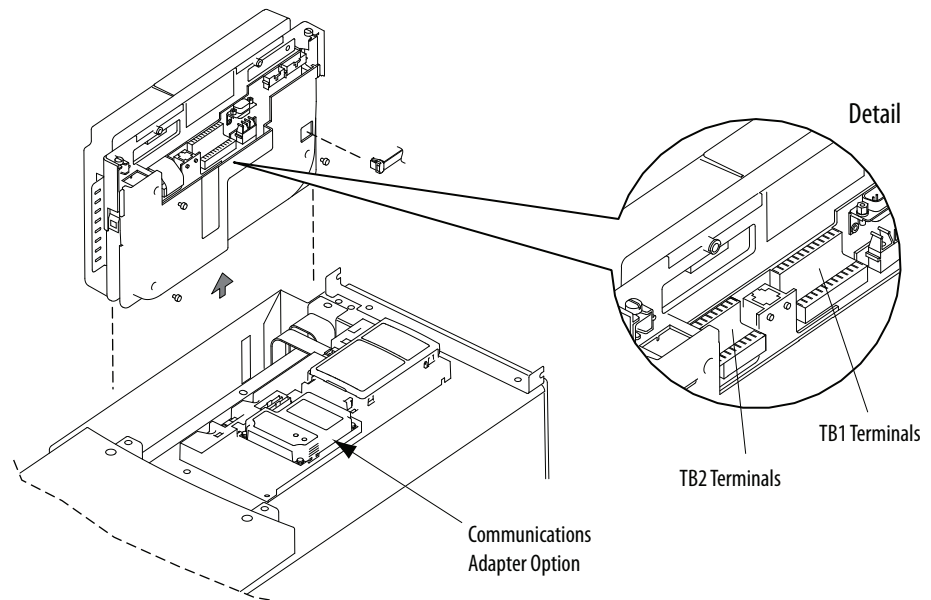
**Figure 11 - Removing the Standard PowerFlex 700 Vector Control Cassette**



## PowerFlex 700S Phase II Control Cassette (optional)

Figure 12 shows the location and removal of the drive's optional PowerFlex 700S Phase II Control cassette to access its terminal blocks for control wiring. See the PowerFlex 700S High Performance AC Drive - Phase II Control User Manual, publication [20D-PM001](#), for control wiring details.

Figure 12 - Removing the Optional PowerFlex 700S Phase II Control Cassette



## Determining Wire Routing for Control, Ground, Drive Input, and Motor Output

All wiring should be installed in conformance with the applicable local, national, and international codes (for example, NEC/CEC). Signal wiring, control wiring, and power wiring must be routed in separate conduits to prevent interference with drive operation. When hubs are not provided, use grommets to guard against wire chafing.



**ATTENTION:** Do not route signal and control wiring with power wiring in the same conduit. This can cause interference with drive operation. Failure to observe this precaution can result in damage to, or destruction of, the equipment.

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Do not route more than three sets of motor leads through a single conduit. This minimizes cross-talk that can reduce the effectiveness of noise reduction methods. If more than three drive/motor connections per conduit are required, shielded cable must be used. If possible, each conduit should contain only one set of motor leads.

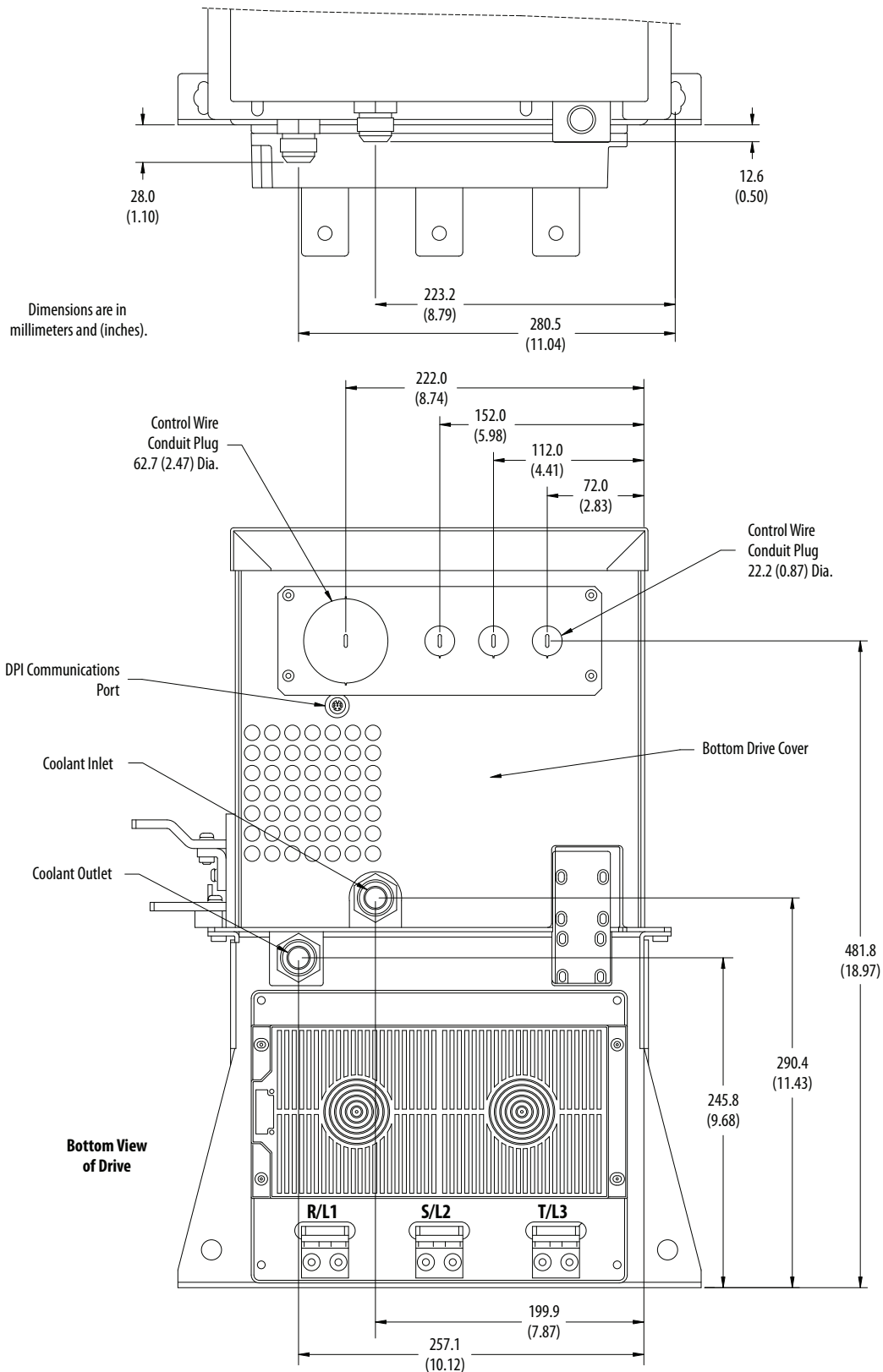


**ATTENTION:** Unused wires in conduit must be grounded at both ends to avoid a possible shock hazard caused by induced voltages. Also, if a drive sharing a conduit is being serviced or installed, disable all drives using this conduit to eliminate the possible shock hazard from cross-coupled motor leads. Failure to observe these precautions can result in bodily injury.

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[Figure 13](#) shows locations for Frame 2 control wire routing, ground, drive input, motor output, DPI communication ports/cable routing, and coolant connections.

**Figure 13 - Frame 2 Drive Locations for Control Wire Routing, DPI Communication Port, and Coolant Connections**



## Grounding the Drive



**ATTENTION:** The user is responsible for conforming with all applicable local, national, and international codes. Failure to observe this precaution can result in damage to, or destruction of, the equipment.

The customer must supply a grounding conductor between the ground lug of the drive and the ground lug in the cabinet. For PE ground terminal location, see [Figure 18](#). Tighten the ground connection to the recommended torque shown in [Table 4](#).

## Ungrounded or Resistive Grounded Installations

PowerFlex 700L Frame 2 drives are equipped with a common mode input filter capacitor and MOV that are referenced to ground. If the drive is installed on a resistive ground or ungrounded distribution system, disconnect this capacitor and MOV to prevent drive damage.

### Disconnecting the Common Mode Capacitor

To disconnect the 1  $\mu$ F common mode capacitor from the circuit, see [Figure 14](#) and perform the following steps.

1. Disconnect the Faston wire from the 1  $\mu$ F common mode capacitor.
2. Insulate the wire end by applying a wire nut or electrical tape.
3. Tie wrap the disconnected wire to keep it away from any electrical connections.

### Disconnecting the MOV from Ground

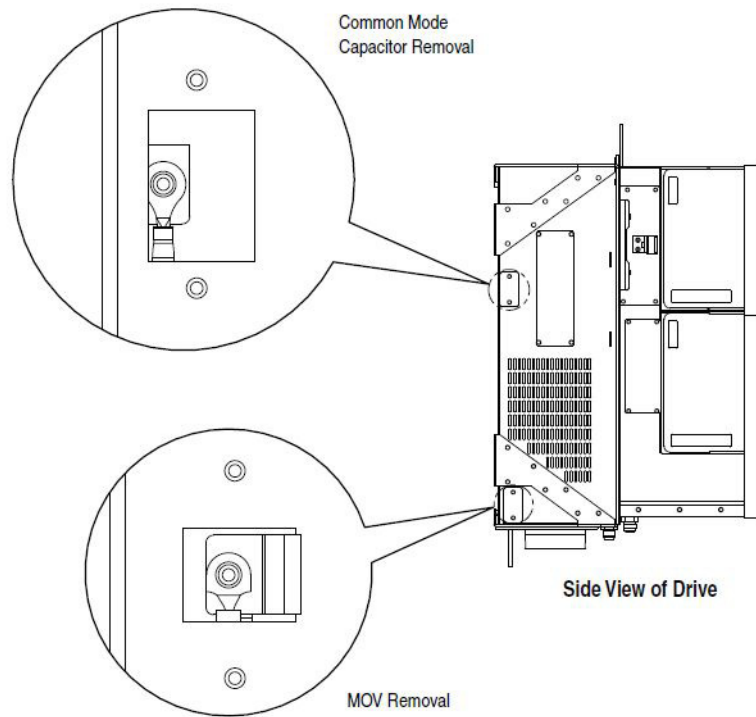
To disconnect the MOV from ground, see [Figure 14](#) and perform the following steps.

1. Unbolt the ground wire lug from the MOV's ground connection point.
2. Screw the bolt back into the panel.
3. Cut the lug off the disconnected ground wire and apply a wire nut to its end.
4. Tie wrap the disconnected ground wire to keep it away from any electrical connections.

For more information on ungrounded distribution systems, see *Wiring and Grounding Guidelines for Pulse Width Modulated (PWM) AC Drives*, publication [DRIVES-IN001](#).

**Note:** Removing the Common Mode capacitor and input MOVs makes the drive more vulnerable to high voltage line spikes.

**Figure 14 - Removing Common Mode Capacitor and MOV**



## Power Wiring

This section describes incoming line components and how to install them, and provides instructions on wiring input power, output contactors, motor overload protection, and output wiring to the motor.

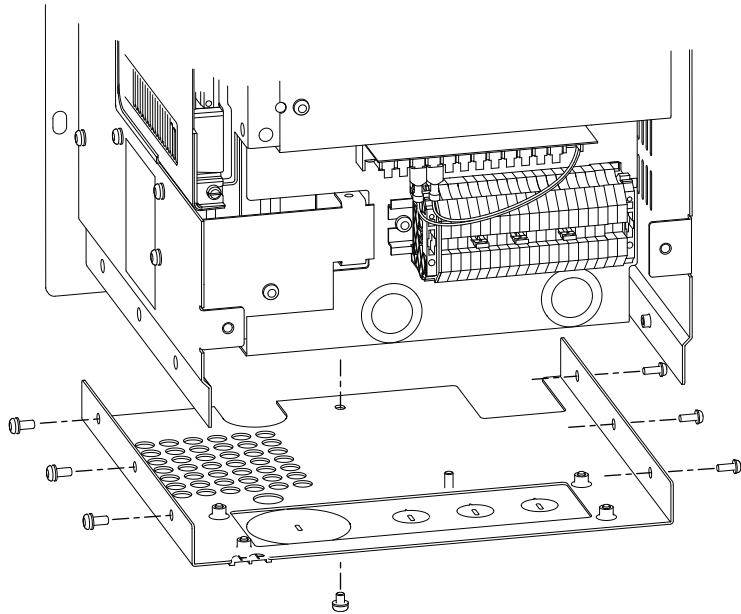
### Installing Transformers and Reactors (Not Recommended)

Frame 2 drives may be used on distribution systems with 200,000 amps or less symmetrical fault current capacity. The drive input components consist of a 3% line reactor and a harmonic line filter. Additional input inductance is not recommended.

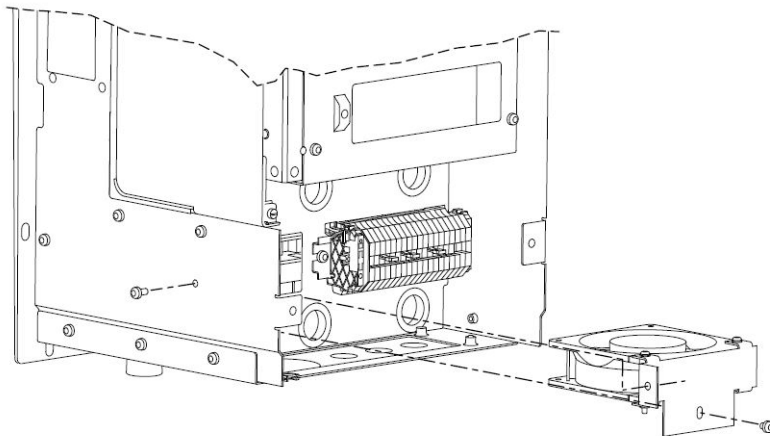
### Selecting and Verifying Control Transformer Voltage

A control transformer is used to match the input line voltage of the drive to the 115V control voltage. If your line voltage is different than the voltage class specified on the drive nameplate, it may be necessary to change transformer taps as described in the following steps.

1. Unfasten seven screws and remove the bottom drive cover ([Figure 15](#)).

**Figure 15 - Removing the Bottom Drive Cover**

2. Remove the power section stirring fan.
  - a. Unfasten two bracket screws.
  - b. Disconnect the fan power leads (two fastons).
  - c. Lift the fan from the drive ([Figure 16](#)).

**Figure 16 - Removing the Power Section Stirring Fan**

3. Depending on the supplied AC line voltage used to power the drive, see [Table 3](#) to determine which transformer tap to use.

**Table 3 - Control Transformer Tap Usage**

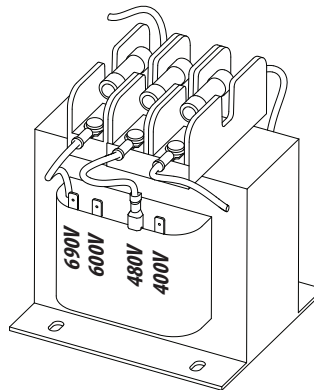
AC Line Voltage	Transformer Tap To Use
380V AC	400V
400V AC	
440V AC	
460V AC	480V
480V AC	

- Pull the faston from the present tap and push it onto the appropriate tap.

Verify that the faston is fully seated on the tap.

**TIP** Do not bend the faston. A straight blade screwdriver helps to remove the faston by carefully prying on the bottom edge of the faston.

**Figure 17 - Control Transformer Voltage Taps**



- Reinstall the power section stirring fan.
- Before fastening the two bracket screws, connect power to the fan power leads.
- Reinstall the bottom drive cover by fastening the six screws.



## Installing Input Power Wiring to the Drive

Use the following steps to connect AC input power to the drive.



**ATTENTION:** Do not route signal and control wiring with power wiring in the same conduit. This can cause interference with drive operation. Failure to observe this precaution can result in damage to, or destruction of, the equipment.

1. Connect the three-phase AC input power leads (three-wire 380-480V AC) to the R/L1, S/L2, and T/L3 input power terminals on the Frame 2 drive.

For terminal locations, see [Figure 18](#).

2. Tighten the AC input power terminal connections to the recommended torque as shown in [Table 4](#).

**Table 4 - Frame 2 Drive Power Terminal Specifications**

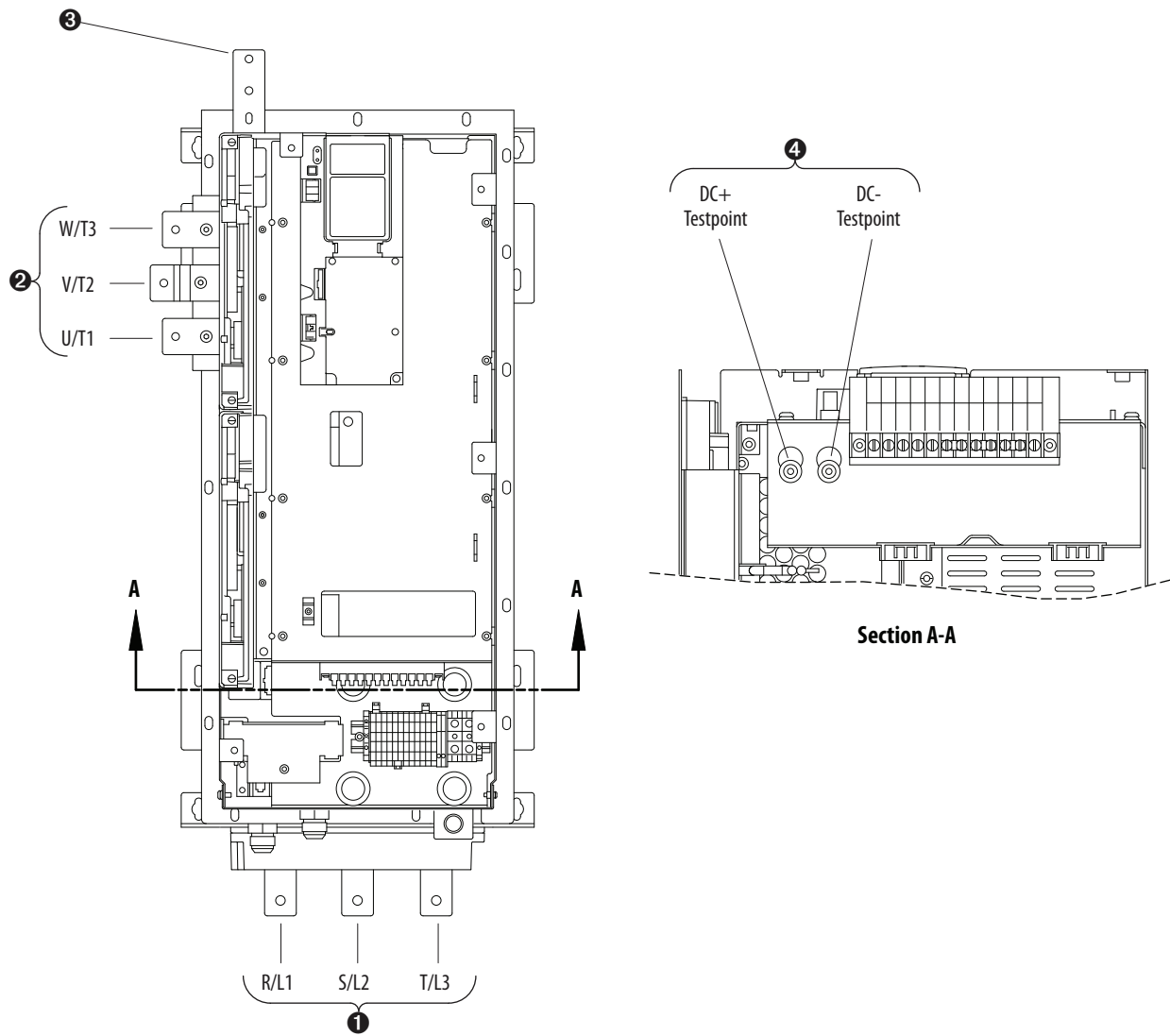
Item	Name	Description	Recommended Tightening Torque ( $\pm 10\%$ )	Terminal Bolt Size <sup>(3)</sup>
①	Input Power Bus Bar <sup>(1)</sup> R/L1, S/L2, T/L3	Input power	40 N·m (354 lb·in)	M8
②	Output Power Bus Bar <sup>(1)</sup> U/T1, V/T2, W/T3	Motor connections	40 N·m (354 lb·in)	M8
③	PE, Motor Ground Bus Bar <sup>(1)</sup>	Terminating point for wiring shields and grounds	40 N·m (354 lb·in)	M8
④	DC Bus Test Point Socket <sup>(2)</sup> (2 Terminals; DC+, DC-)	4 mm socket for DC bus voltage measurement only	—	—

(1) These connections are bus bar type terminations and require the use of lug connectors.

(2) Use only to verify that DC bus capacitors are discharged before servicing the Power Module. No other external use is permitted.

(3) Apply counter torque to the nut on the other side of terminations when tightening or loosening the terminal bolt to avoid damage to the terminal.

Figure 18 - Frame 2 Drive Power Terminal Locations



### Installing Mechanical Motor Overload Protection (Optional)

To provide the motor with overload protection, local, national, and international codes (for example, NEC/CEC) can require one of the following items:

- A motor thermostat be installed internal to the motor.
- A mechanical thermal motor overload relay, sized to protect the motor, be installed between the motor and the drive's output terminals.

In multiple motor applications (only V/Hz regulation), each motor must have its own user-supplied overload and branch circuit protection.

## Installing Output Wiring from the Drive Output Terminals to the Motor

---

**IMPORTANT** See the Wiring and Grounding Guidelines for Pulse Width Modulated (PWM) AC Drives Installation Instructions, publication [DRIVES-IN001](#), for details on maximum motor cable lengths.

---

Follow these steps to connect the AC output power wiring from the drive to the motor.

1. Route the three-phase AC output power motor leads to the drive power module.

Do not route more than three sets of motor leads through a single conduit. This minimizes cross-talk that can reduce the effectiveness of noise reduction methods. If more than three drive/motor connections per conduit are required, shielded cable must be used. If possible, each conduit should contain only one set of motor leads.



**ATTENTION:** Do not route signal and control wiring with power wiring in the same conduit. This can cause interference with drive operation. Failure to observe these precautions can result in damage to, or destruction of, the equipment



**ATTENTION:** Unused wires in conduit must be grounded at both ends to avoid a possible shock hazard caused by induced voltages. Also, if a drive sharing a conduit is being serviced or installed, disable all drives using this conduit to eliminate the possible shock hazard from cross-coupled motor leads. Failure to observe these precautions can result in bodily injury.

---

2. Connect the three-phase AC power motor leads to the U/T1, V/T2, and W/T3 output power terminals.

For terminal locations, see [Figure 18](#).

3. Tighten the AC output power terminal connections to the proper torque as shown in [Table 4](#).

## Control Wiring

This section provides details on control wiring to the drive.



**ATTENTION:** Risk of equipment damage exists. Do not use drive terminal blocks TB5-1 and TB5-3 to connect any type of power wiring for auxiliary equipment. These terminals are only for low amperage control wiring.



**ATTENTION:** Do not route signal and control wiring with power wiring in the same conduit. This can cause interference with drive operation. Failure to observe this precaution can result in damage to, or destruction of, the equipment.

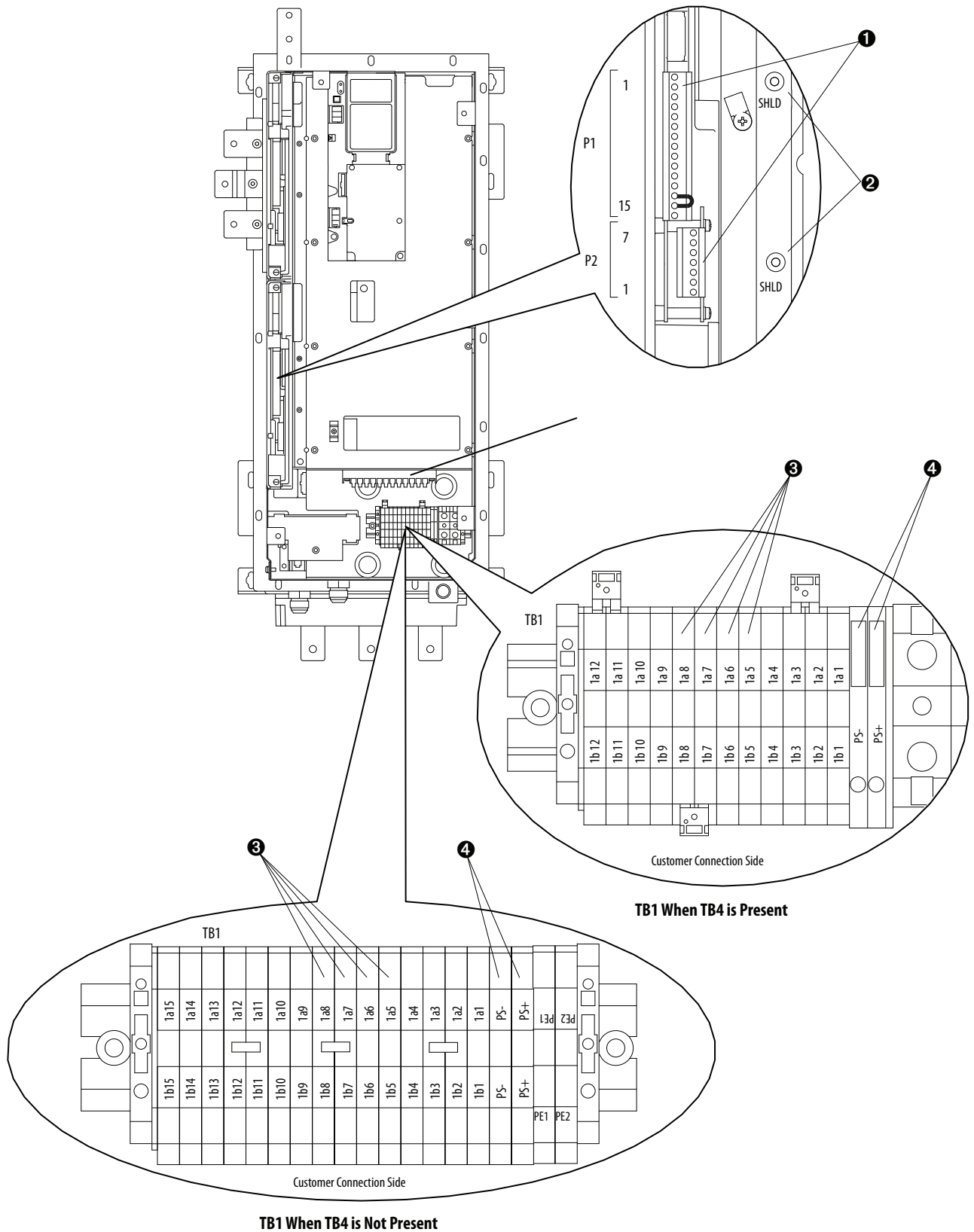
Connect wiring to terminals in accordance with [Table 5](#), [Figure 19](#), and the Frame 2 drive schematic on page [130](#).

**Table 5 - Frame 2 Drive Control Wiring Terminal Specifications**

Item	Name	Description	Wire Size Range <sup>(1)</sup>		Recommended Tightening Torque ( $\pm 10\%$ )	Wire Strip Length
			Maximum	Minimum		
1	Active Converter Cassette Terminal Blocks—P1 and P2	Active Converter AC power and control wiring	3.3 mm <sup>2</sup> (#12 AWG)	0.3 mm <sup>2</sup> (#22 AWG)	0.8 N·m (7 lb·in)	8 mm (0.31 in.)
2	SHLD Terminal	Terminating point for control wiring shields on the drive	2.1 mm <sup>2</sup> (#14 AWG)	0.3 mm <sup>2</sup> (#22 AWG)	1.4 N·m (12 lb·in)	10 mm (0.39 in.)
3	Terminal Block—TB1	Drive control wiring: Output dry contact (12V DC/24V DC, 2 Amps max.) indicating the drive is powered and has completed precharge.	4.0 mm <sup>2</sup> (#10 AWG)	0.2 mm <sup>2</sup> (#24 AWG)	0.9 N·m (8 lb·in)	8 mm (0.31 in.)
	1b 5: +12/+24V Cooling Loop					
	1b 6: Cooling Loop Return					
	1b 7: +24V (digin)	Drive-supplied +24V DC				
	1b 8: Gate Enable	Enables the firing of the IGBTs. Factory-installed jumper from terminal 1b 7 to terminal 1b 8 allows firing of the IGBTs.				
4	PS- Terminal PS+ Terminal	300V DC Auxiliary Control voltage	4.0 mm <sup>2</sup> (#12 AWG)	0.5 mm <sup>2</sup> (#22 AWG)	0.6 N·m (5.3 lb·in)	10 mm (0.39 in.)

(1) Maximum/minimum sizes that the terminals will accept - these are not recommendations.

Figure 19 - Frame 2 Drive Control Wiring Terminal Locations



## Synchronization Connections

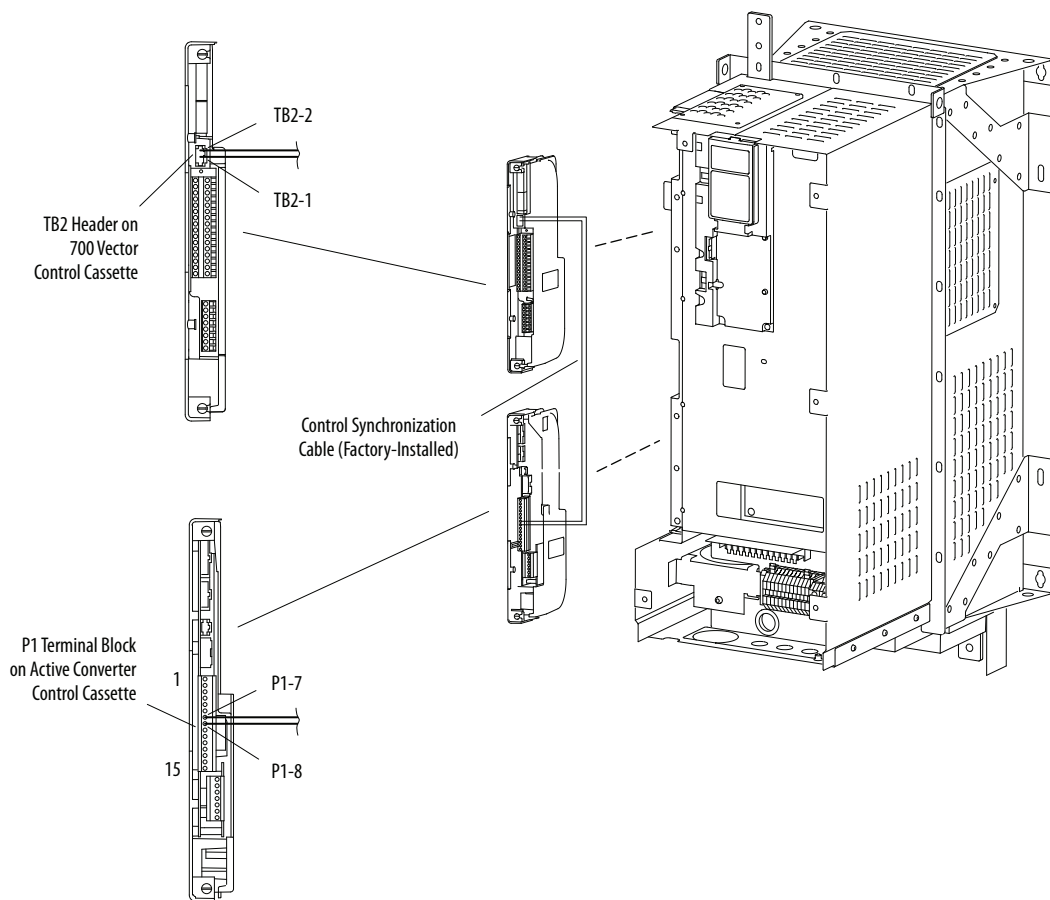
### Coupled Power Modules

Frame 2 combined Converter/Inverter Power Modules are configured only as coupled power modules. Coupling the Converter and Inverter is achieved by using two factory-installed cables: a control synchronization cable and an inverter-to-converter DPI communication cable. The two cables are described in the next two subsections.

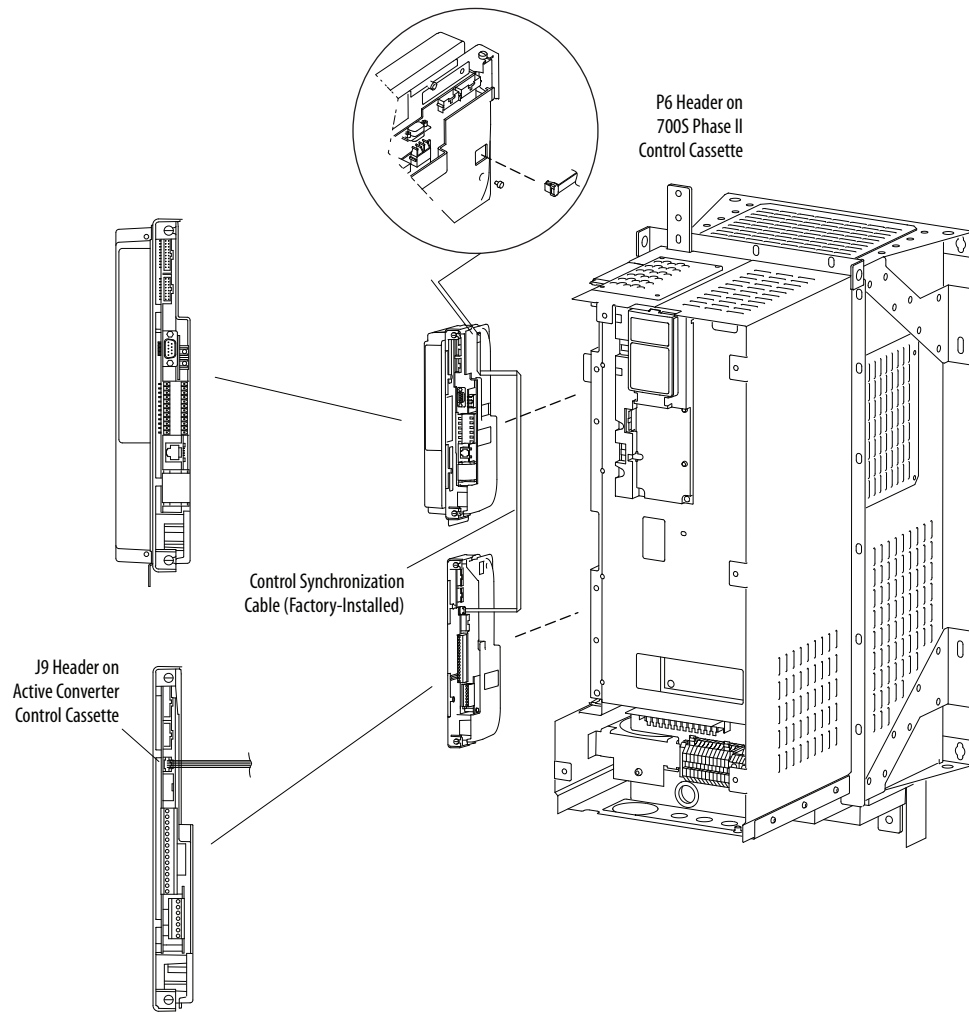
### Control Synchronization Cable

To enable synchronization between the Inverter control board and the Converter control board, a factory-installed control synchronization cable connects each board. No user connection is required. However, the connection method is different for PowerFlex 700L drives with 700 Vector Control than for 700S Phase II Control. The 700 Vector Control synchronization cable connection is shown in [Figure 20](#). The 700S Phase II Control synchronization cable connection is shown in [Figure 21](#).

**Figure 20 - Frame 2 700 Vector Control Synchronization Cable Connection**



**Figure 21 - Frame 2 700S Phase II Control Synchronization Cable Connection**



### **Inverter-to-Converter DPI Communication Cable**

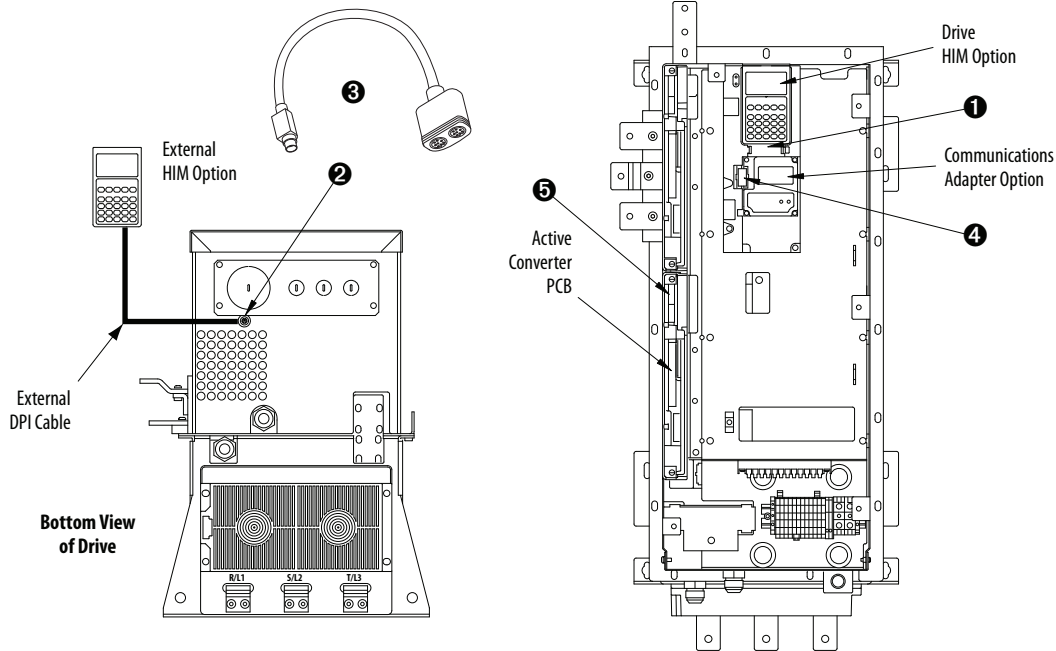
To enable the Inverter and Converter section of the Frame 2 drive to communicate with each other, a factory-installed DPI communication cable is used. No user connection is required.

## DPI Connections for Frame 2 Drives

### Drive Connection Points

The PowerFlex 700L Frame 2 drive provides a number of cable connection points as shown in [Figure 22](#). If an additional external HIM is required for the application, the HIM can be connected to the DPI port on the bottom of the drive. Only one additional external HIM device can be connected. The use of two external HIM devices is not supported. If multiple external HIM devices are required, then install a user-supplied splitter cable or splitter box.

**Figure 22 - Frame 2 Drive DPI Connection Points**



Item	Connector	Description
1	DPI Port 1	HIM connection when installed in the drive.
2	DPI Port 2	Cable connection for handheld and remote options.
3	DPI Port 3 or 2	Splitter cable connection to DPI Port 2 provides additional port.
4	DPI Port 5	Cable connection for communications adapter.
5	DPI Port 6	Internal DPI connection to Active Converter pcb.

### External Door-Mounted HIM Connection (optional)

For a Frame 2 drive installed in a user-supplied enclosure, an optional external door-mounted HIM may be connected as an alternative to the external HIM option. The cable supplied with the door-mount HIM option kit connects to the DPI port on the bottom of the drive (see [Figure 22](#)). For additional installation information, see the instructions provided with the door-mount HIM option kit.

## Coolant Loop Connections

See [Chapter 4, Cooling Loop Application Guidelines](#) for details.



## Frame 3A and 3B Installation

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Removing the Inverter Power Module Control Cassette	63
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Because most start-up difficulties are the result of incorrect wiring, take every precaution to verify that the wiring is completed as instructed. Read and understand all items before beginning actual installation.



**ATTENTION:** The following information is merely a guide for proper installation. Rockwell Automation does not assume responsibility or liability for the compliance or noncompliance to any code, national, local or otherwise for the proper installation of this drive or associated equipment. A hazard of personal injury and/or equipment damage exists if codes are ignored during installation.

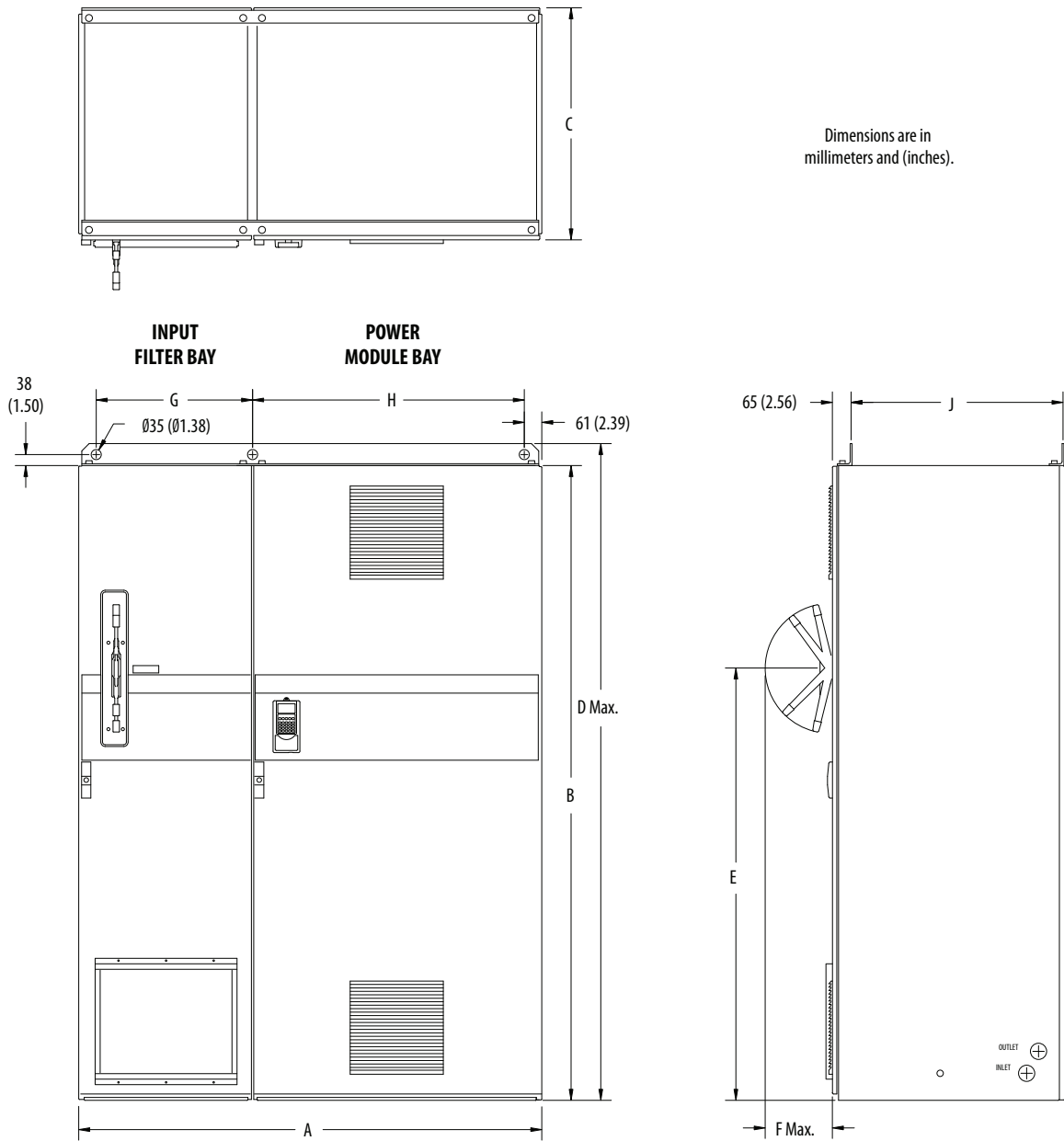
### Drive Components

Frame 3A and 3B complete drives are comprised of an Input Filter Bay and a Power Module Bay. For Frame 3A drives, the Power Module Bay contains a combined Converter/Inverter Power Module. For Frame 3B drives, the Power Module Bay contains separate Converter and Inverter Power Modules.

### Total Area Required for Drive Installation

Overall drive dimensions are shown in [Figure 23](#) as an aid in calculating the total area required for installing Frame 3A and 3B drives.

**Figure 23 - Frame 3 Complete Drive Installation Dimensions**



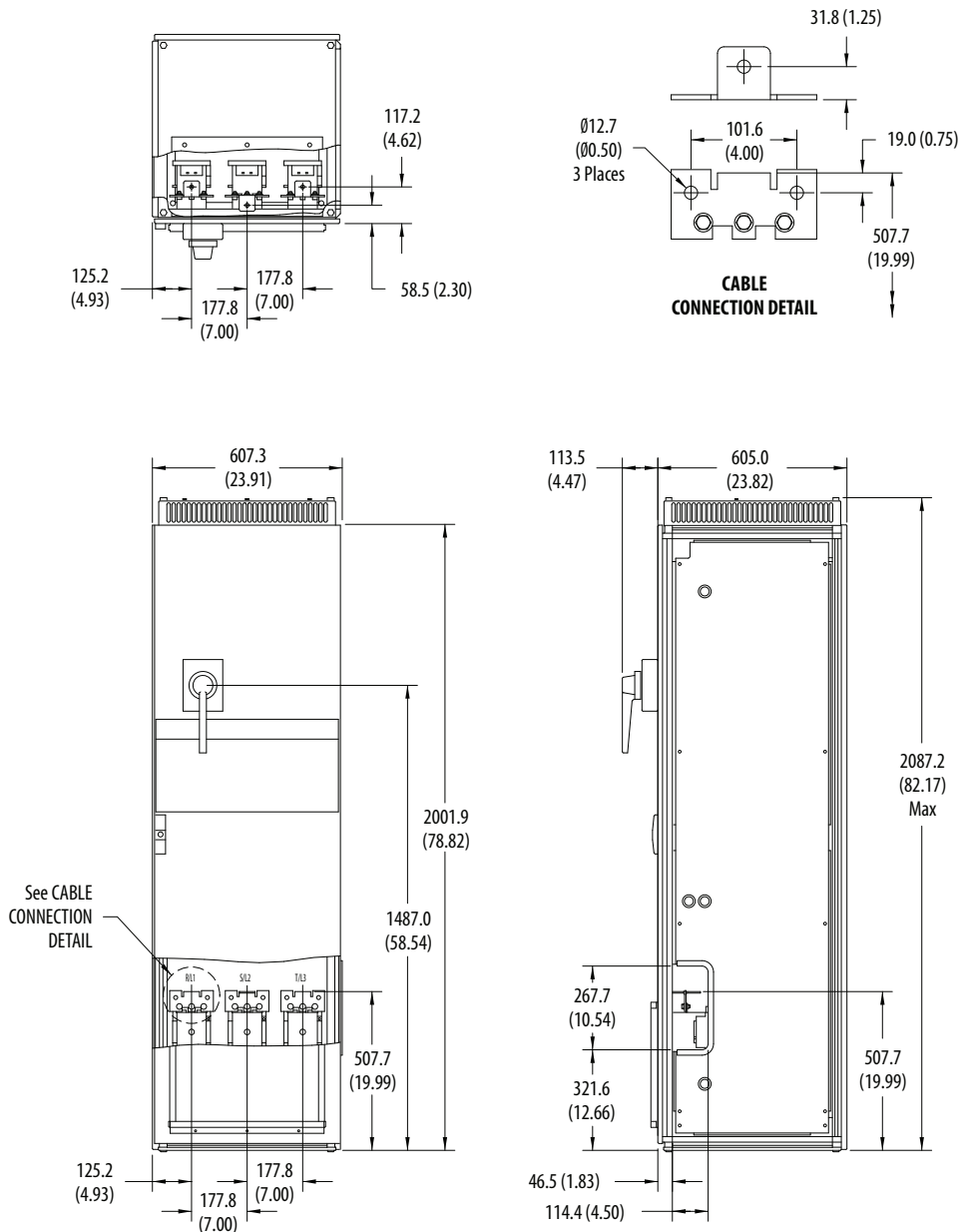
Frame Size	Dimensions mm (in.)									Approximate Weight of Complete Drive
	A	B	C	D	E	F	G	H	J	
3A	1200 (47.2)	2000 (78.7)	600 (23.6)	2078 (81.9)	1500 (59.1)	233 (9.2)	542 (21.3)	542 (21.3)	535 (21.1)	950 kg (2090 lb)
3B	1600 (63.0)	2200 (86.6)	800 (31.5)	2278 (89.8)	1500 (59.1)	233 (9.2)	542 (21.3)	942 (37.1)	735 (28.9)	1361 kg (3000 lb)

## Recommended Air Flow Clearances for Complete Drive

Verify that there is adequate clearance for air circulation around the drive enclosures. A 15 cm (6 in.) minimum clearance is required wherever vents in the cabinet are located.

**Figure 24 - Frame 3A Input Filter Bay Power Wiring and Installation Dimensions**

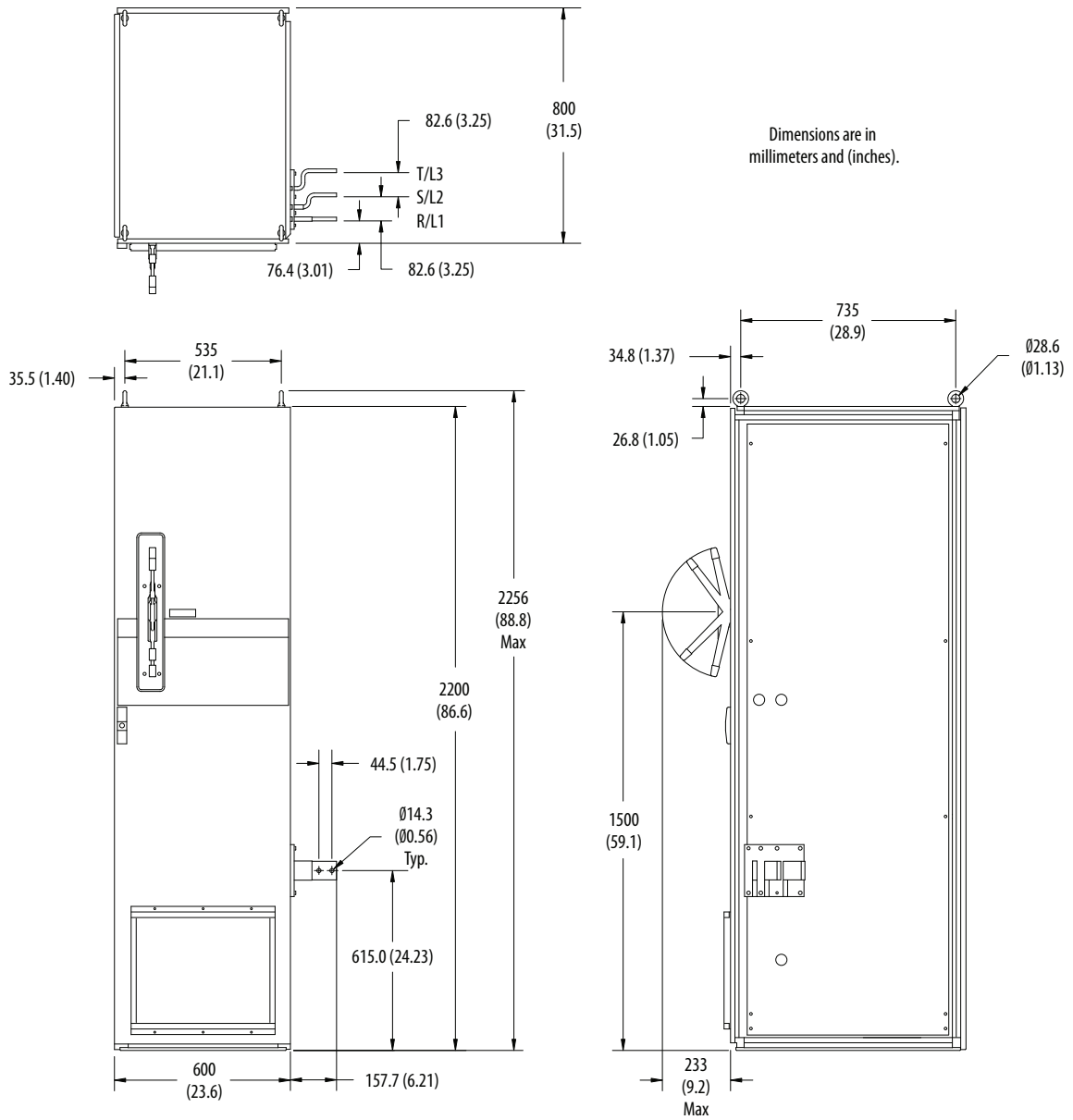
Dimensions are in millimeters and (inches).



**Approximate Weight of  
Frame 3A Input Filter Assembly**

695 kg (1530 lb)

**Figure 25 - Frame 3B Input Filter Bay Power Wiring and Installation Dimensions**




---

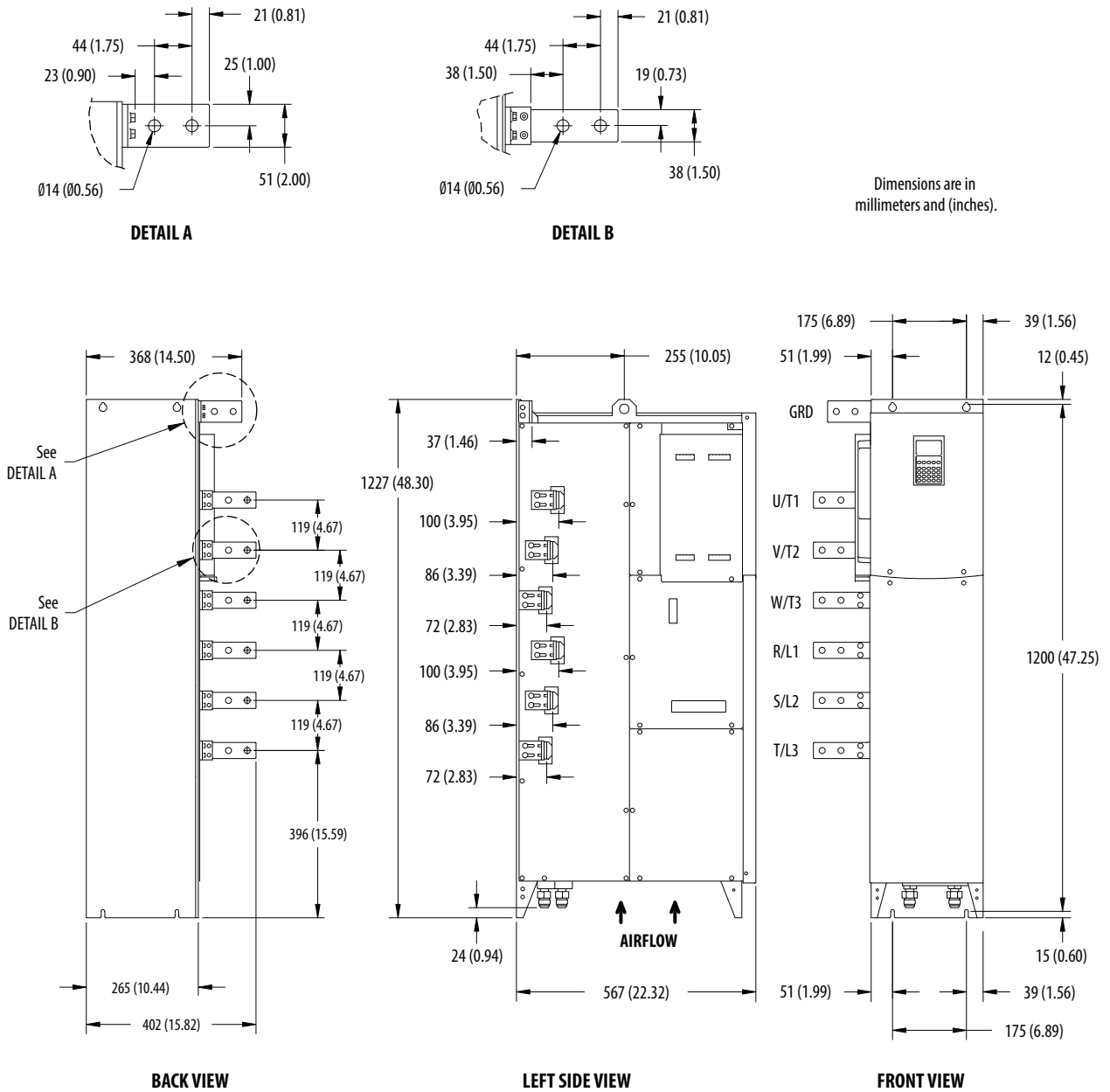
**Approximate Weight of  
Frame 3B Input Filter Assembly**

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861.8 kg (1900 lb)

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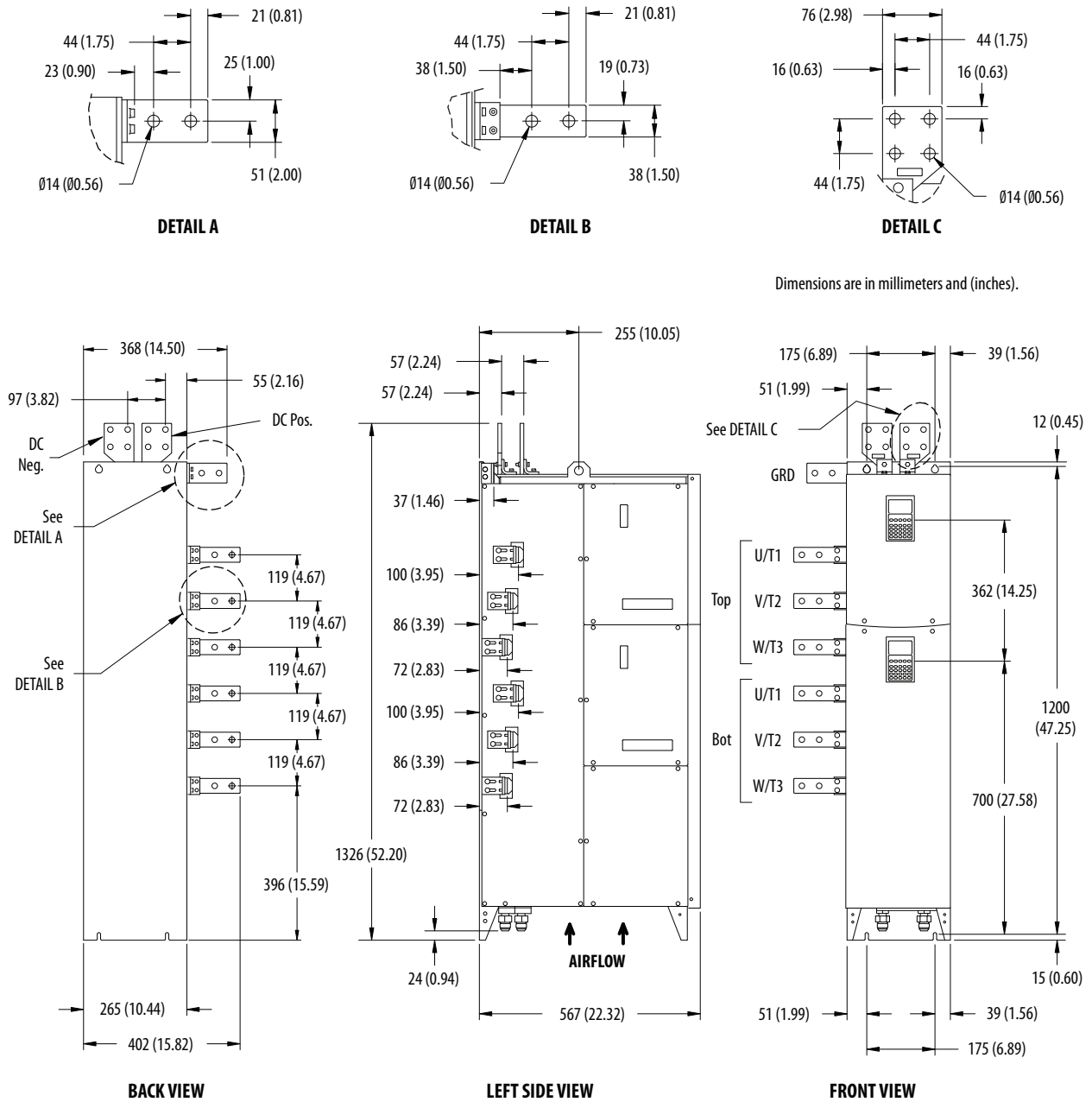
**Figure 26 - Frame 3A Converter/Inverter Power Module Installation Dimensions**



**Approximate Weight**

Power Module	Power Module and Packaging
112 kg (247 lb)	144 kg (317 lb)

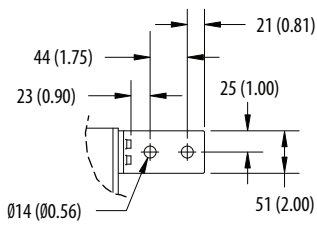
Figure 27 - Frame 3A Dual Inverter Power Module Installation Dimensions



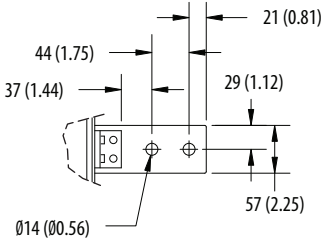
**Approximate Weight**

Power Module	Power Module and Packaging
113.9 kg (251 lb)	145.6 kg (321 lb)

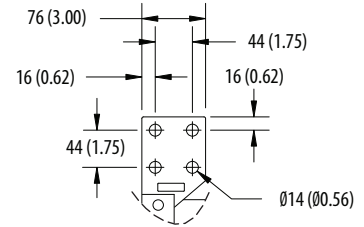
**Figure 28 - Frame 3B Power Module Installation Dimensions**



**DETAIL A**

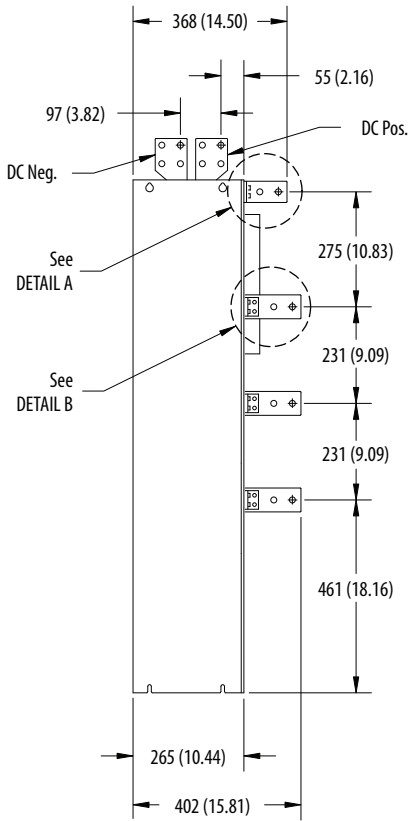


**DETAIL B**

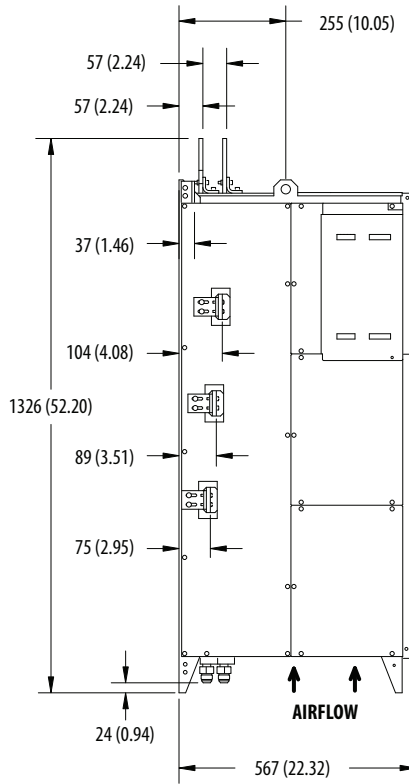


**DETAIL C**

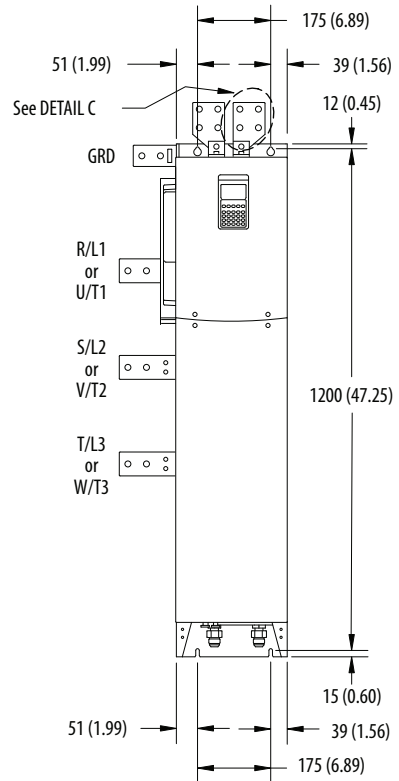
Dimensions are in millimeters and (inches).



**BACK VIEW**



**LEFT SIDE VIEW**



**FRONT VIEW**

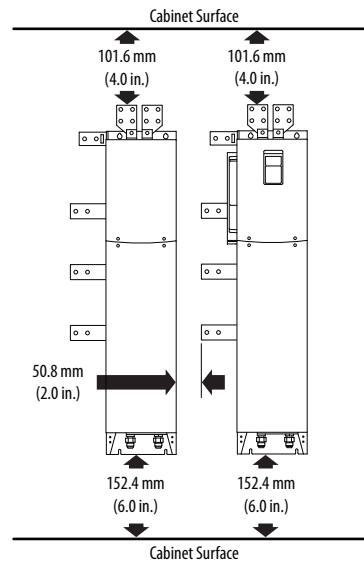
**Approximate Weight**

Power Module	Power Module and Packaging
132 kg (290 lb)	166 kg (365 lb)

## Recommended Mounting Clearances for Power Modules

Specified vertical clearance requirements (Figure 29) are intended to be from power module to cabinet surface. Other objects can occupy this space; however, reduced air flow can cause protection circuits to fault the module. In addition, inlet air temperature must not exceed the product specification.

Figure 29 - Frame 3A and 3B Power Module Minimum Mounting Clearances



## Verifying Power Module Input Ratings Match Supplied Power

It is important to verify that plant power will meet the input power requirements of the PowerFlex® 700L drive's Power Module circuitry. See Appendix A for input power rating specifications. Make sure input power to the drive corresponds to the drive nameplate voltage and frequency.

## Equipment Lifting

This section explains how to lift the equipment.



**ATTENTION:** To guard against possible personal injury and/or equipment damage, observe the following:

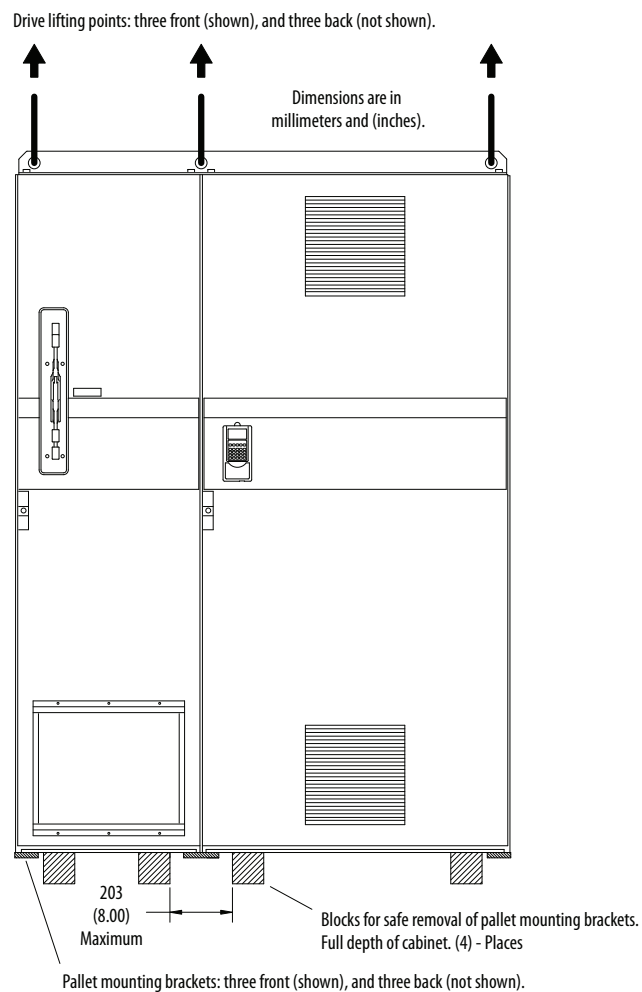
- Do not allow any part of the drive or lifting mechanism to make contact with electrically charged conductors or components.
- At no time should a person or their limbs be directly underneath the items being lifted.
- Do not subject the load to high rates of acceleration or deceleration.
- Inspect all lifting hardware for proper attachment before lifting any drive unit.



## Lifting the Complete Drive

For the complete drive equipment, always hoist the cabinet using the lifting angles provided with the equipment (see [Figure 30](#)). Prior to placing the complete drive equipment at its installation site, remove both the pallet and the pallet mounting brackets. For safety when removing the pallet mounting brackets, place blocks under the hoisted cabinet ([Figure 31](#)). The blocks provide a measure of safety while the six M12 screws are unfastened under the cabinet to remove the pallet mounting brackets. After the complete drive equipment is placed at its installation position, remove the lifting angles to permit the installation of the vented top cover over the input filter bay. Assembly instructions are provided with the vented top cover. If the complete drive equipment must be moved for any reason, remove the vented top cover, and then reinstall the lifting angles to hoist the cabinet.

**Figure 30 - Frame 3 Complete Drive Lifting Instructions**



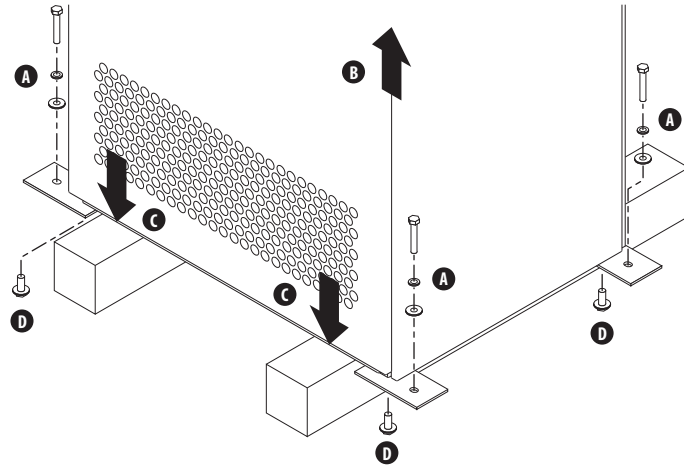
**ATTENTION:** To guard against possible personal injury and/or equipment damage, block the cabinet while removing the pallet mounting brackets.

Removing the Pallet and Pallet Mounting Brackets



**ATTENTION:** To guard against personal injury and equipment damage, do not work under the drive unless the drive is securely mounted on appropriate blocks.

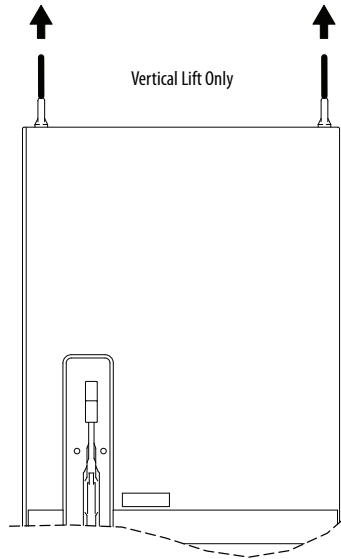
Figure 31 - Frame 3 Complete Drive Pallet/Mounting Bracket Removal Instructions



Task	Description
A	Using a 15 mm wrench, remove the hardware which secures the drive to the pallet.
B	Lift the drive off the pallet.
C	Place the drive on proper blocks on a hard, level surface. The blocks should be approximately 10 cm (4 inches) high.
D	Using a 17 mm wrench, remove the hardware which secures the pallet mounting brackets to the drive and remove the brackets.

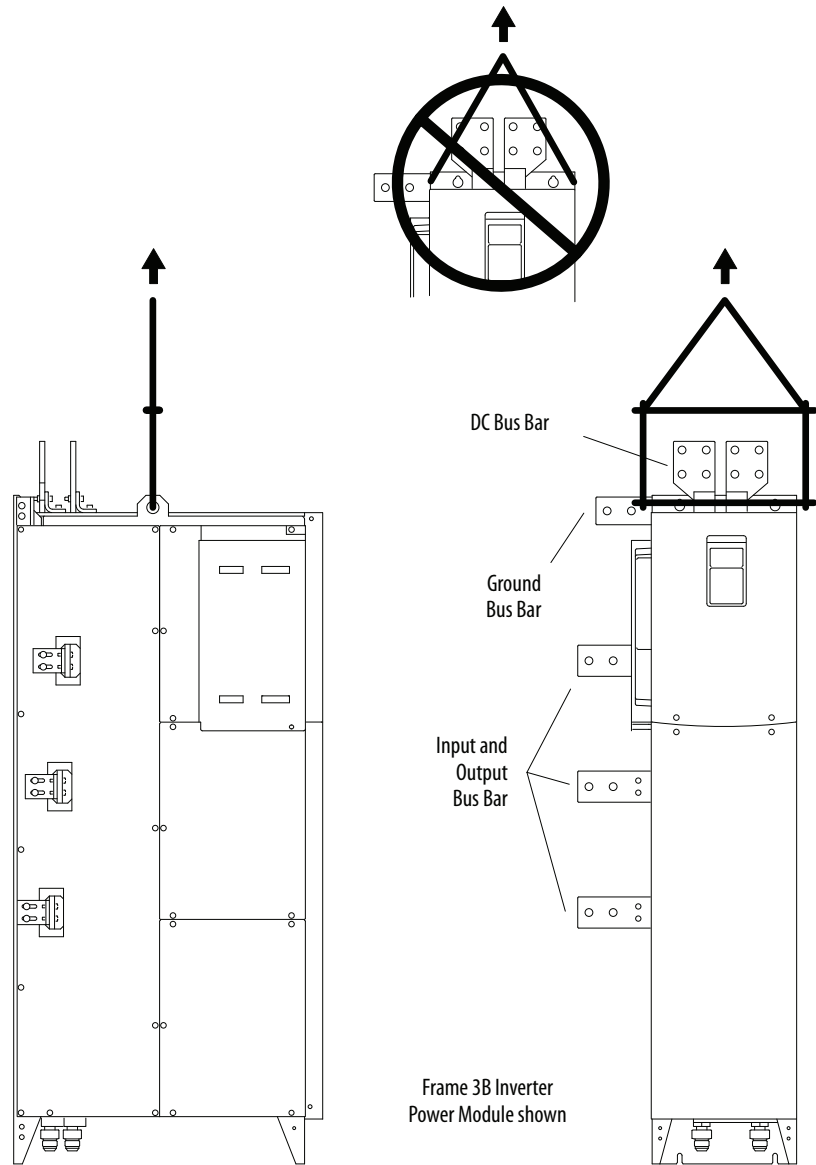
## Lifting the Input Filter Bay

**Figure 32 - Frame 3 Input Filter Bay Lifting Instructions**



## Lifting the Power Module

Figure 33 - Frame 3 Power Module Lifting Instructions



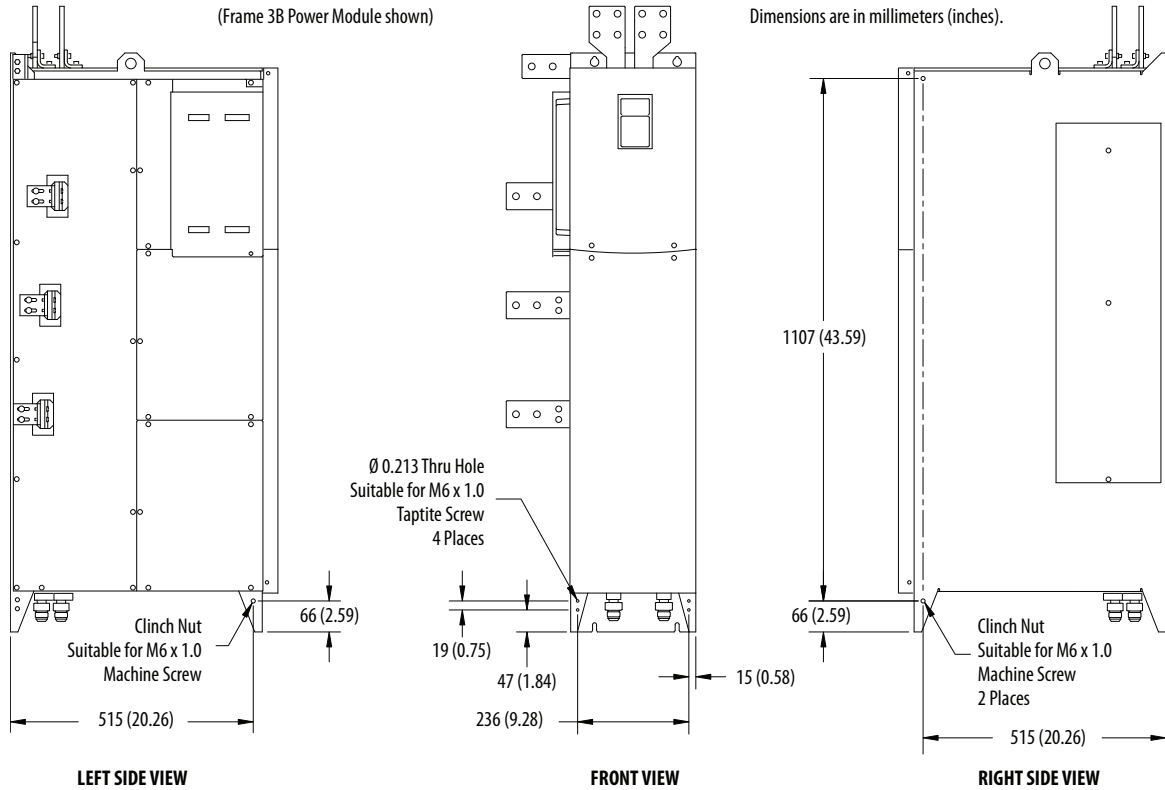
**ATTENTION:** Risk of equipment damage exists. Do not use input, output, ground, or DC bus bars for lifting or handling.

Mechanically support conductors to minimize mechanical load on the input and output bus bars.

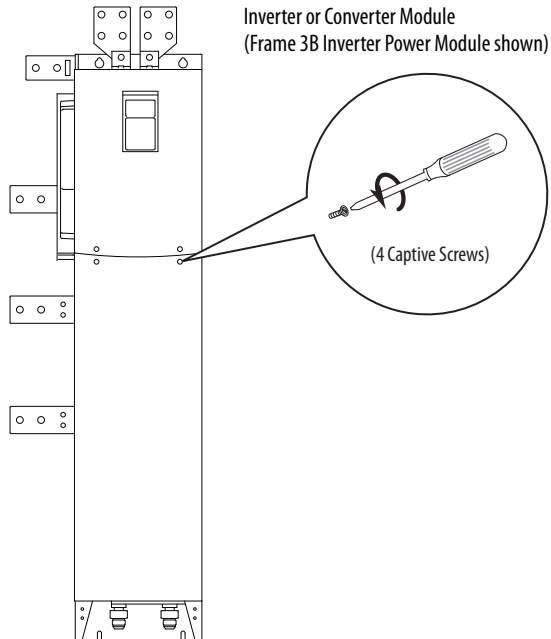
# Supporting the Power Module

The Frame 3 power module has features for attaching support brackets with screws. The support brackets are required to prevent mechanical damage to the AC input, DC, and AC output bus bars. The feature locations, feature size, and screw type are shown in [Figure 34](#).

**Figure 34 - Frame 3 Power Module Support Locations**



## Removing the Power Module Covers

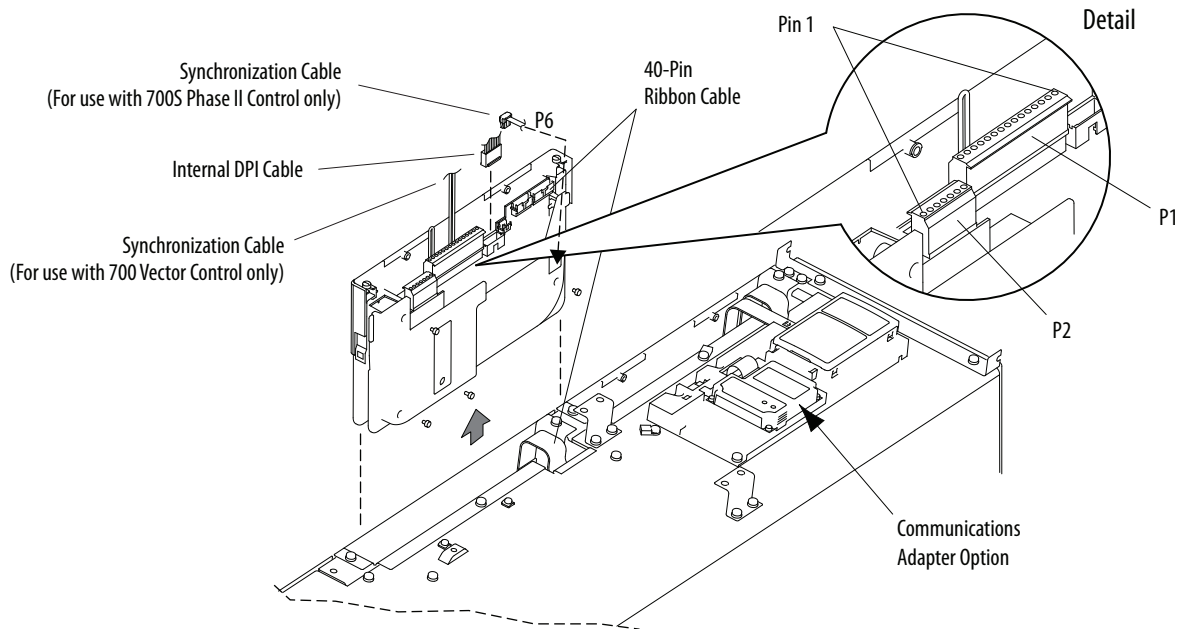


## Removing the Active Converter Power Module Control Cassette

### Frame 3A Drives

For Frame 3A regenerative-type drives, the combined Active Converter/Inverter Power Module is equipped with an Active Converter control cassette. [Figure 35](#) shows the location and removal of this cassette to access its terminal blocks for control wiring. See the PowerFlex 700 Active Converter Power Module User Manual, publication [PFLEX-UM002](#), for control wiring details.

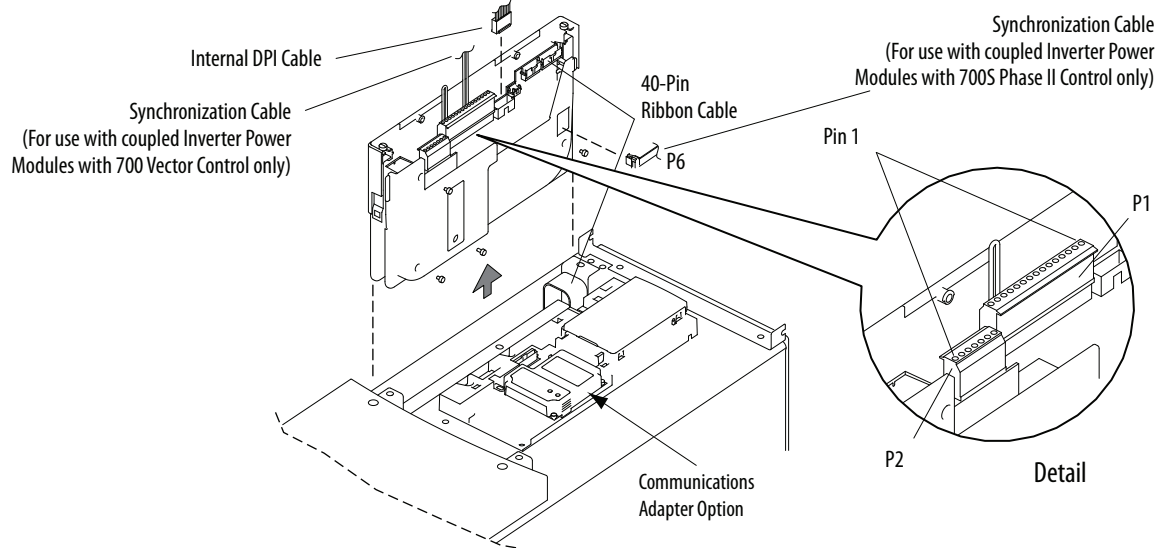
**Figure 35 - Removing the Frame 3A Active Converter Control Cassette**



## Frame 3B Drives

For Frame 3B regenerative-type drives, the separate Active Converter Power Module is equipped with a control cassette. [Figure 36](#) shows the location and removal of this cassette to access its terminal blocks for control wiring. See the PowerFlex 700 Active Converter Power Module User Manual, publication [PFLEX-UM002](#), control wiring details.

**Figure 36 - Removing the Frame 3B Active Converter Control Cassette**



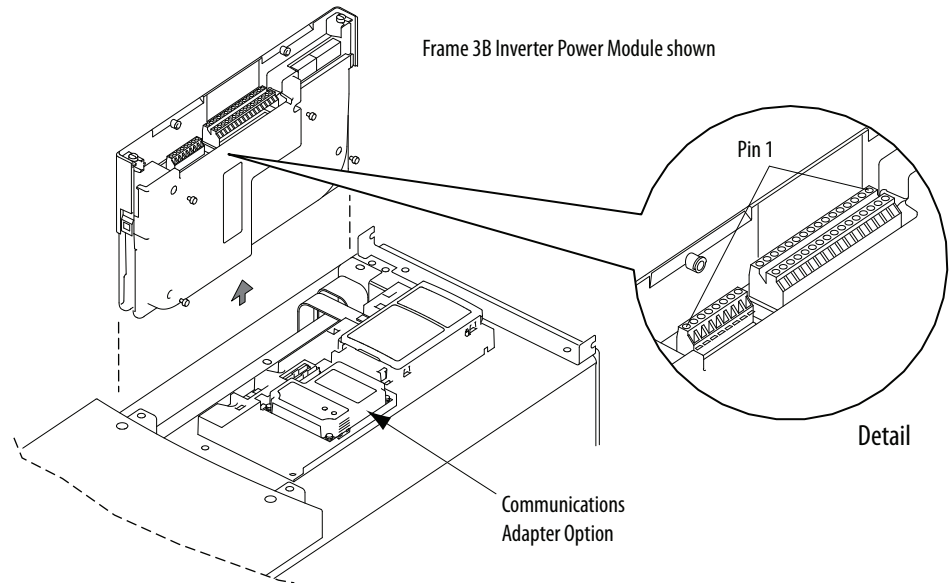
## Removing the Inverter Power Module Control Cassette

For Frame 3A drives (with a combined Active Converter/Inverter Power Module) or Frame 3B drives (with a separate Inverter Power Module), the Inverter is equipped with either the standard PowerFlex 700 Vector Control cassette or an optional PowerFlex 700S Phase II Control cassette. In either case, the cassette is removed in the same way.

## PowerFlex 700 Vector Control Cassette (standard)

[Figure 37](#) shows the location and removal of the Inverter Power Module's standard PowerFlex 700 Vector Control cassette to access its terminal blocks for control wiring. See the PowerFlex 700 Adjustable Frequency AC Drive User Manual - Series B, publication [20B-UM002](#), for control wiring details.

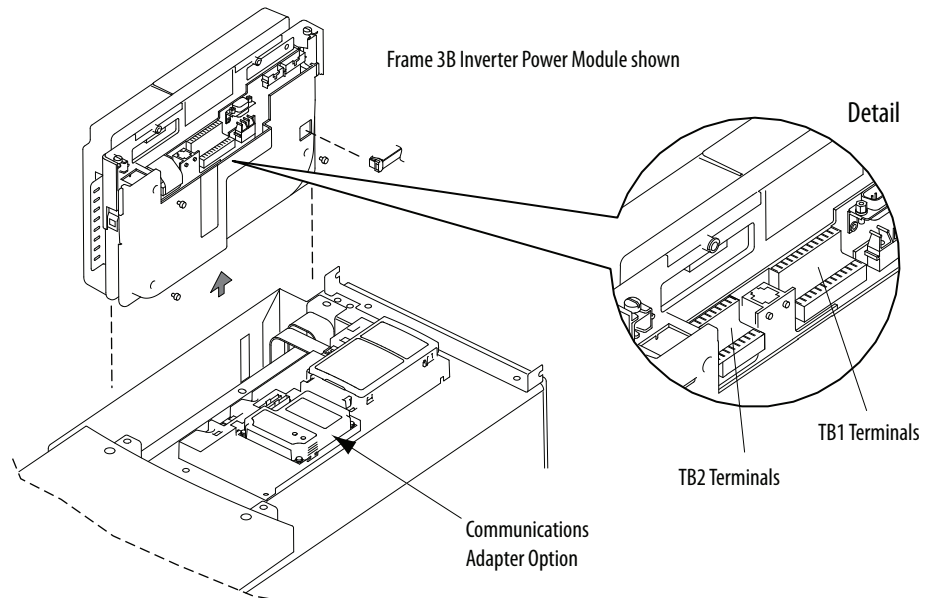
**Figure 37 - Removing the Standard PowerFlex 700 Vector Control Cassette**



### **PowerFlex 700S Phase II Control Cassette (optional)**

[Figure 38](#) shows the location and removal of the Inverter Power Module's optional PowerFlex 700S Phase II Control cassette to access its terminal blocks for control wiring. See the PowerFlex 700S High Performance AC Drive - Phase II Control User Manual, publication [20D-PM001](#), for control wiring details.

**Figure 38 - Removing the Optional PowerFlex 700S Phase II Control Cassette**





## Verifying the Drive's Watts Loss Rating

When mounting the drive inside of an enclosure, determine the watts loss rating of the drive from [Table 22 on page 125](#). This table lists the typical full load power loss watts value at 4 kHz (rated carrier frequency). Make sure that the enclosure is adequately ventilated with 0...40 °C (32...105 °F) ambient air based on the drive's watts loss rating.

## Installing the Vented Top Cover

---

**IMPORTANT** Install the vented top cover for PowerFlex 700L Frame 3A and 3B complete drives before routing input wiring. See the vented top cover installation instructions, publication [20L-IN002](#), for more information.

---

## Determining Wire Routing for Control, Ground, Drive Input, and Motor Output

All wiring should be installed in conformance with the applicable local, national, and international codes (for example, NEC/CEC). Signal wiring, control wiring, and power wiring must be routed in separate conduits to prevent interference with drive operation. When hubs are not provided, use grommets to guard against wire chafing.



**ATTENTION:** Do not route signal and control wiring with power wiring in the same conduit. This can cause interference with drive operation. Failure to observe this precaution can result in damage to, or destruction of, the equipment.

---

Do not route more than three sets of motor leads through a single conduit. This minimizes cross-talk that can reduce the effectiveness of noise reduction methods. If more than three drive/motor connections per conduit are required, shielded cable must be used. If possible, each conduit should contain only one set of motor leads.



**ATTENTION:** Unused wires in conduit must be grounded at both ends to avoid a possible shock hazard caused by induced voltages. Also, if a drive sharing a conduit is being serviced or installed, disable all drives using this conduit to eliminate the possible shock hazard from cross-coupled motor leads. Failure to observe these precautions can result in bodily injury.

---

## Frame 3A Drives

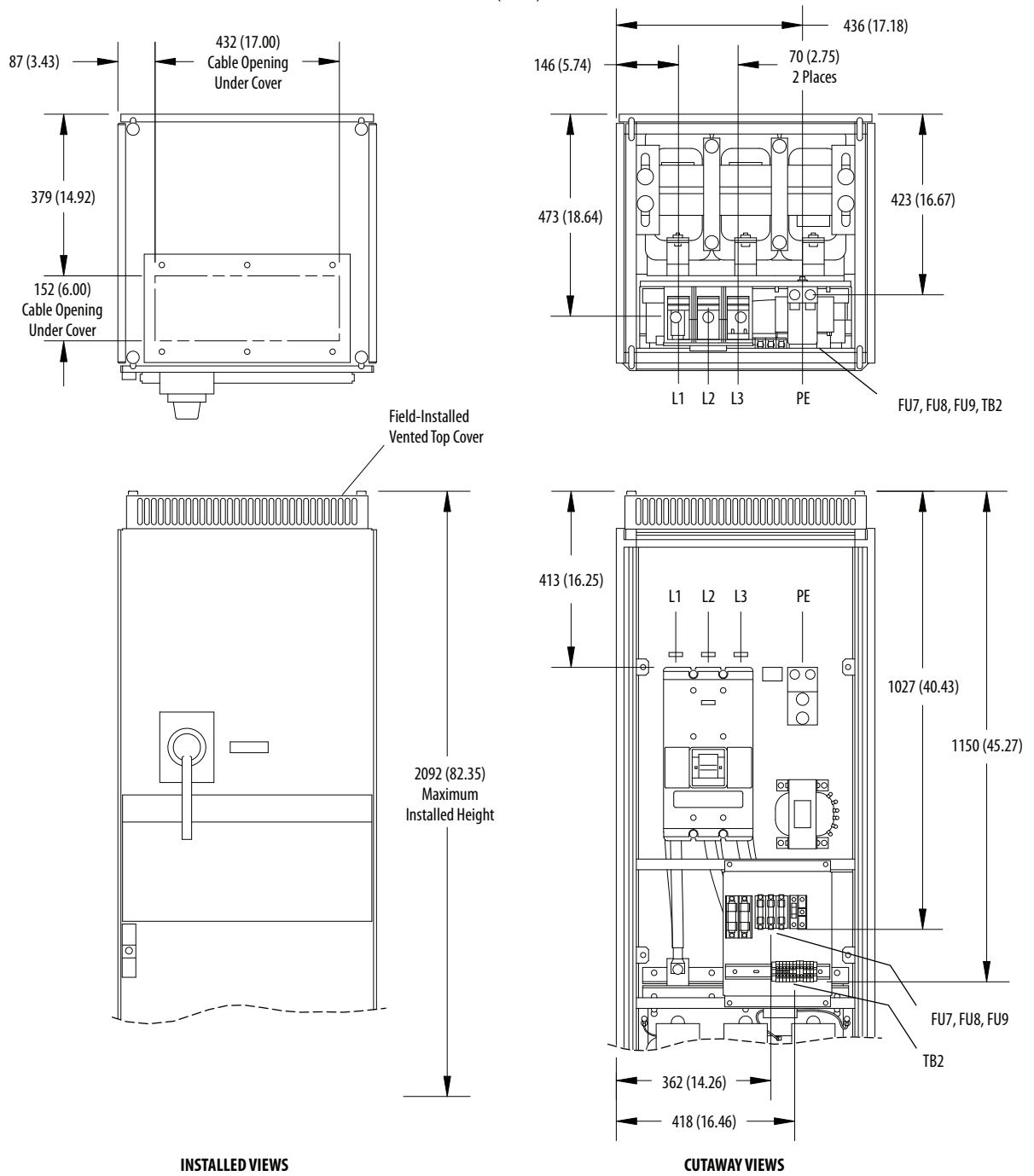
[Figure 39](#) shows the location of Frame 3A Input Filter Bay wire routing. [Figure 42](#) shows locations for Frame 3A Power Module control wire routing, DPI communication ports/cable routing, and coolant connections. [Figure 40](#) shows locations of Frame 3A complete drive control, ground, drive input, motor output, and coolant connections.

## Frame 3B Drives

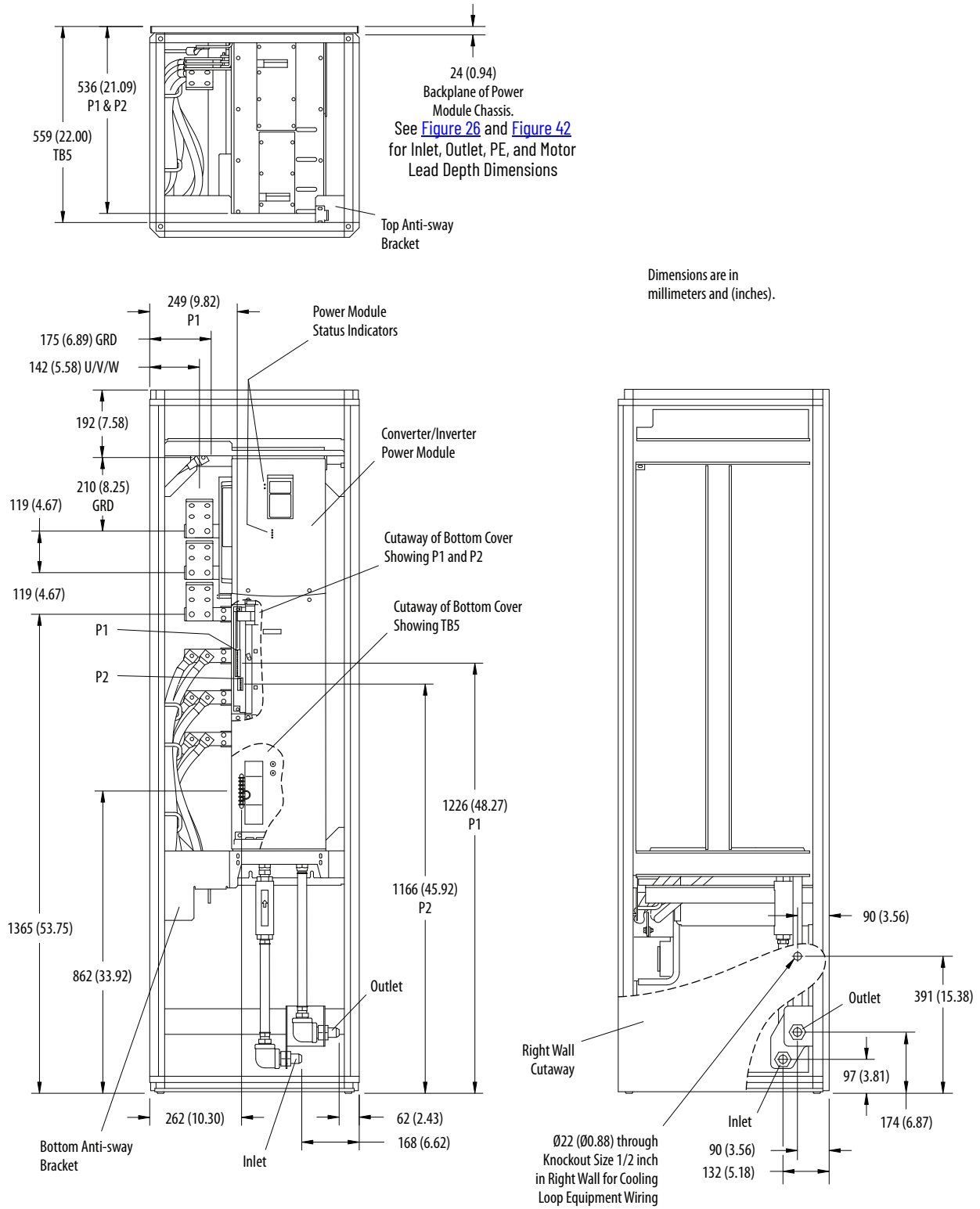
[Figure 41](#) shows the location of Frame 3B Input Filter Bay wire routing. [Figure 42](#) shows locations for Frame 3B Power Module control wire routing, DPI communication ports/ cable routing, and coolant connections. [Figure 43](#) shows locations of Frame 3B complete drive control, ground, drive input, motor output, and coolant connections.

**Figure 39 - Location of Frame 3A Input Filter Bay Wire Routing**

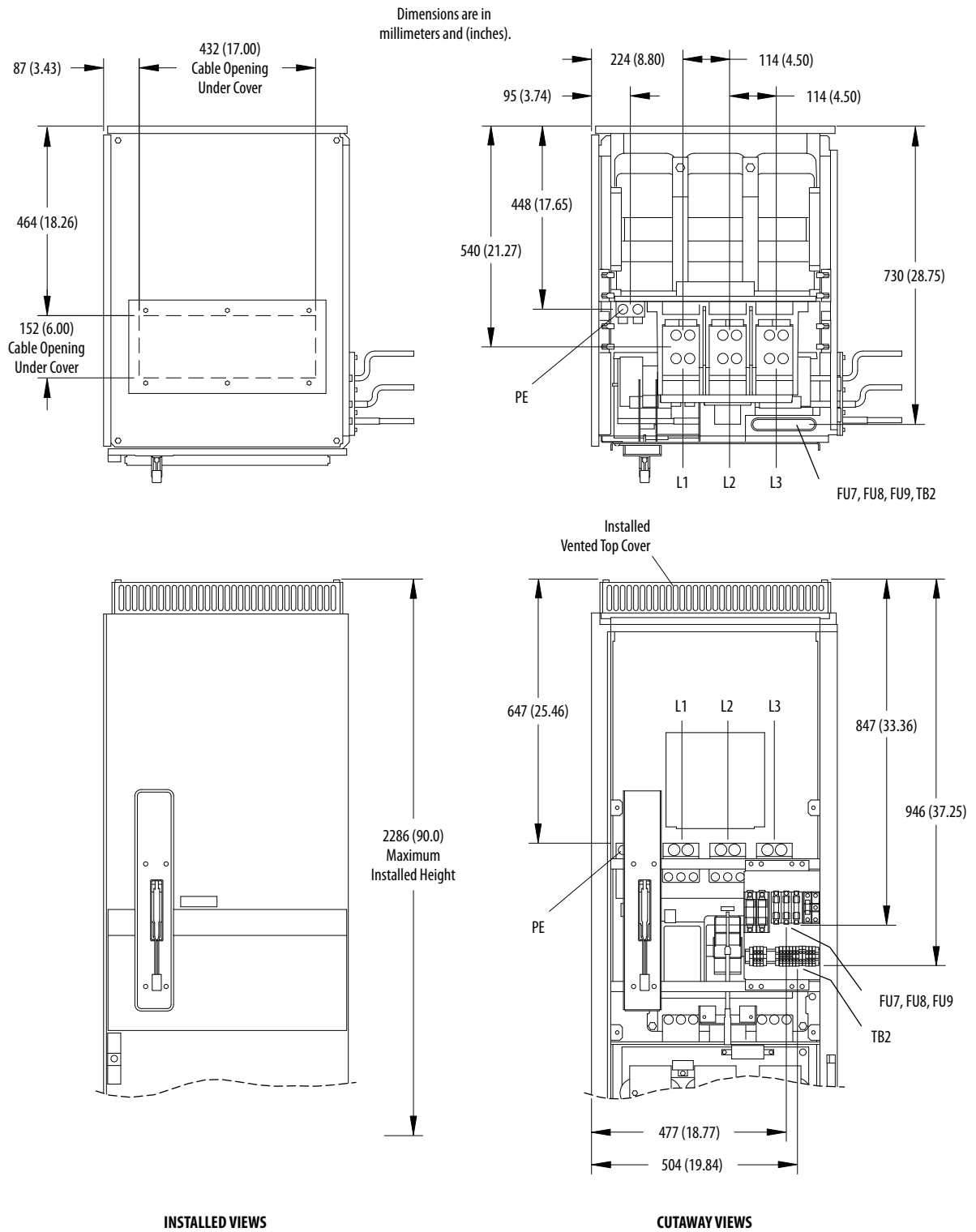
Dimensions are in millimeters and (inches).



**Figure 40 - Locations for Frame 3A Complete Drive Power Module Bay Control, Ground, Motor Output, and Coolant Connections**



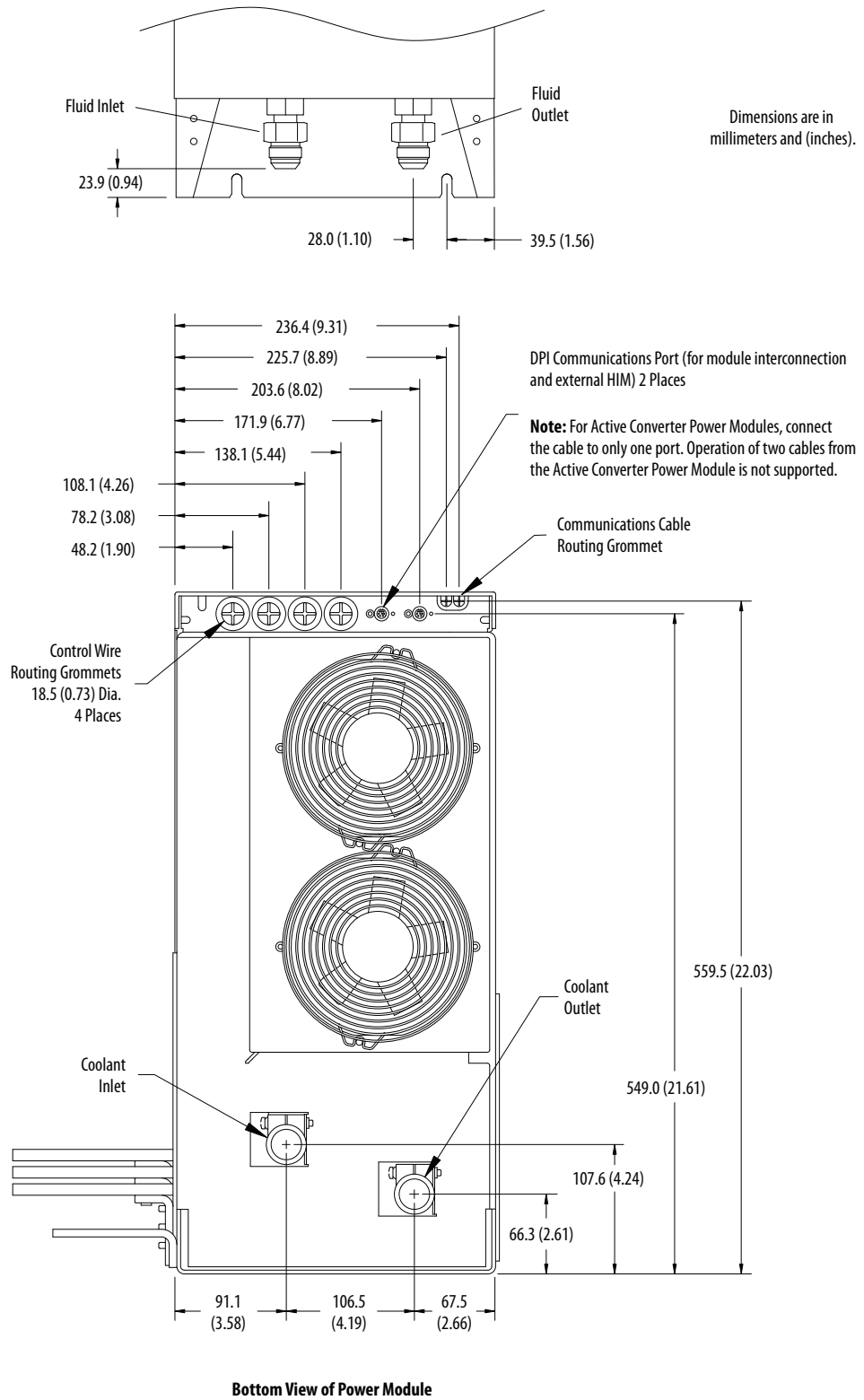
**Figure 41 - Location of Frame 3B Input Filter Bay Wire Routing**



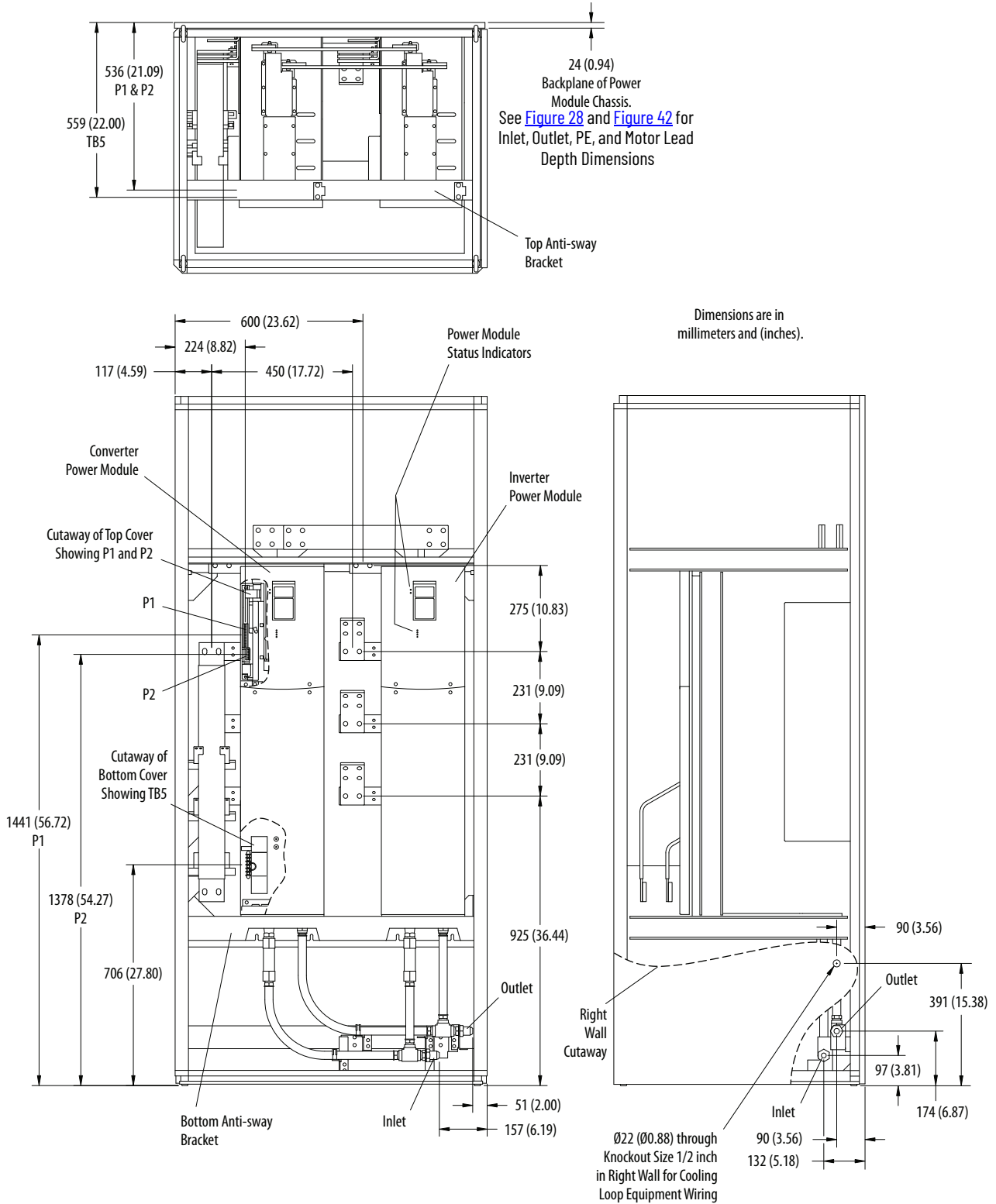
**INSTALLED VIEWS**

**CUTAWAY VIEWS**

**Figure 42 - Frame 3A and 3B Power Module Locations for Control Wire Routing, DPI Communication Ports/Cable Routing, and Coolant Connections**



**Figure 43 - Locations for Frame 3B Complete Drive Control, Ground, Drive Input, Motor Output, and Coolant Connections**



## Grounding the Power Module



**ATTENTION:** The user is responsible for conforming with all applicable local, national, and international codes. Failure to observe this precaution could result in damage to, or destruction of, the equipment.

Complete drives consist of an Input Filter Bay and a Power Module Bay (see [Figure 23](#)). Complete drives purchased from Rockwell Automation are furnished with a grounding conductor between the ground lug of the Inverter Power Module and the ground lug in the Input Filter Bay. However, when power modules are purchased separately and mounted in a customer's cabinet, the customer must supply a grounding conductor as follows:

- Frame 3A—between the ground lug of the combined Converter/Inverter Power Module (or the ground lug of the Dual Inverter Power Module) and the ground lug in the Input Filter Bay (see [Figure 45](#)).
- Frame 3B—between the ground lugs of each separate Power Module and the ground lug in the Input Filter Bay (see [Figure 46](#)).

## Ungrounded or Resistive Grounded Installations

PowerFlex 700L Frame 3A and 3B drives are equipped with a common mode capacitor and MOV that are referenced to ground. If the drive is installed on a resistive ground or ungrounded distribution system, disconnect this capacitor and MOV to guard against drive damage.



**ATTENTION:** The PowerFlex 700L Liquid-Cooled AC Drive has not been designed to be used on IT (insulated terra) or corner-grounded power networks above 600V (phase-to-phase voltage). Operation on such a network can cause a hazardous failure of the insulation system of the drive.

## Disconnecting the Input Filter Common Mode Capacitor

To disconnect the 1  $\mu$ F common mode capacitor from the circuit, see [Figure 44](#) and perform the following steps.

1. Disconnect the Faston wire from the 1  $\mu$ F common mode capacitor.
2. Insulate the wire end by applying a wire nut or electrical tape.
3. Tie wrap the disconnected wire to keep it away from any electrical connections.



## Disconnecting the MOV from Ground

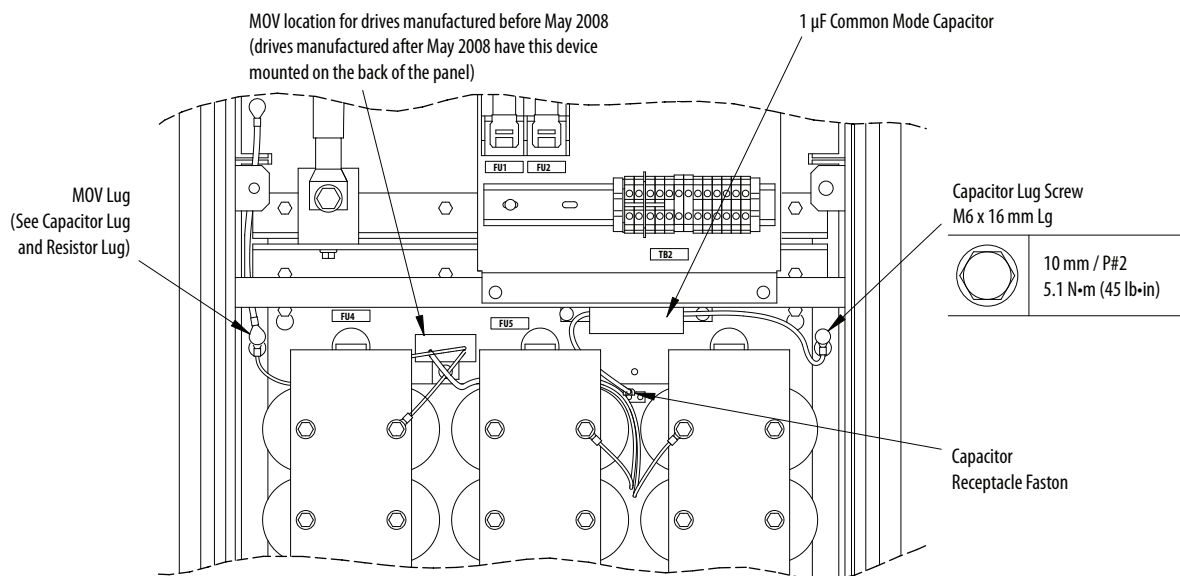
To disconnect the MOV from ground, see [Figure 44](#) and perform the following steps.

1. Unbolt the ground wire lug from the MOV's ground connection point.
2. Screw the bolt back into the panel.
3. Cut the lug off the disconnected ground wire and apply a wire nut to its end.
4. Tie wrap the disconnected ground wire to keep it away from any electrical connections.

For more information on ungrounded distribution systems, see *Wiring and Grounding Guidelines for Pulse Width Modulated (PWM) AC Drives*, publication [DRIVES-IN001](#).

**Note:** Removing the Common Mode capacitor and input MOVs makes the drive more vulnerable to high voltage line spikes.

**Figure 44 - Removing Common Mode Capacitor and MOV**



# Installing Input Power Wiring

This section describes incoming line components and how to install them.

## Installing Transformers and Reactors (Not Recommended)

Frame 3A and 3B drives can be used on distribution systems with 200,000 amps or less symmetrical fault current capacity. The Drive Input components consist of a 3% line reactor and a harmonic line filter. Additional input inductance is not recommended.

## Selecting and Verifying Control Transformer Voltage

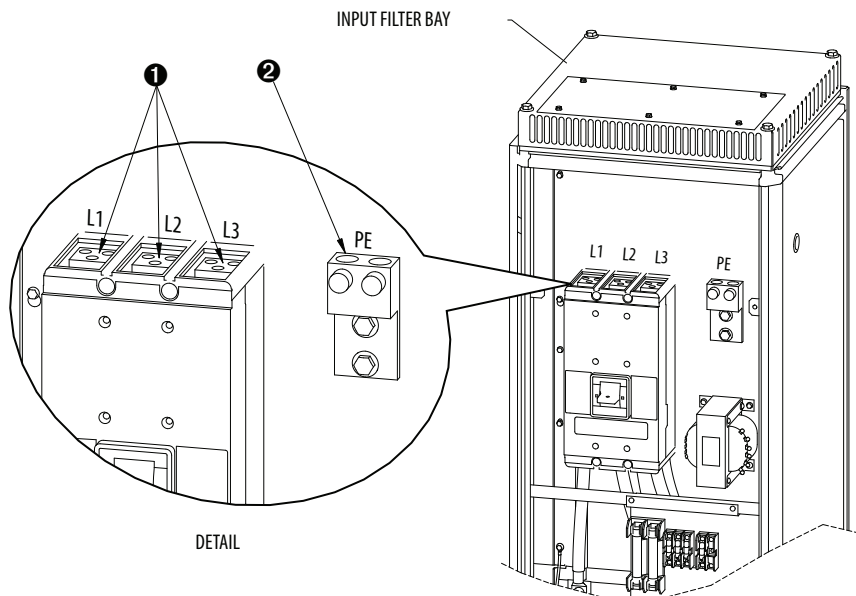
A control transformer in the input filter bay of the drive is used to match the input line voltage of the drive to the 115V control voltage. If your line voltage is different than the voltage class specified on the drive nameplate, it may be necessary to change transformer taps as described below.

Depending on the supplied AC line voltage used to power the drive, connect FU1 and FU2 to TB1 in accordance with [Table 6](#). See [Figure 51](#) or [Figure 52](#) for fuse and terminal block locations.

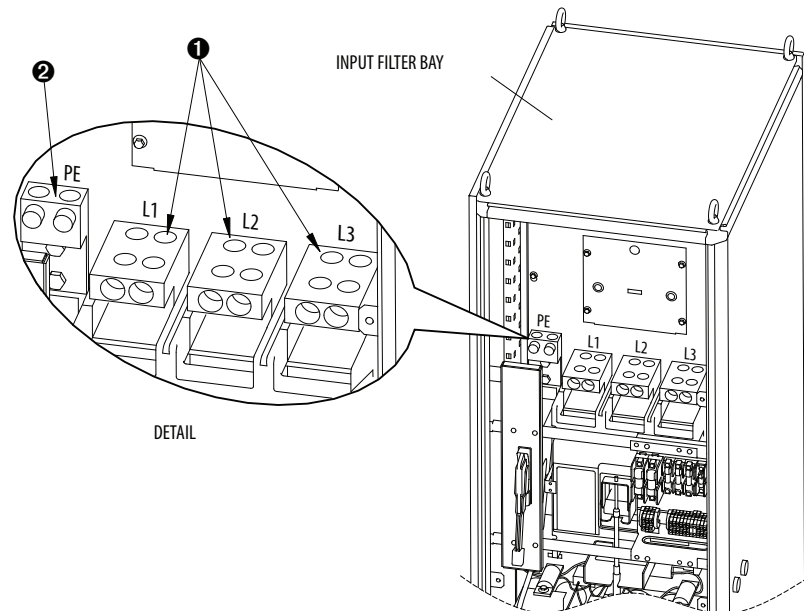
**Table 6 - Input Voltage Setting for Control Transformer**

Supplied Input Voltage		From	To
50 Hz	60 Hz		
For all input voltages		FU1	TB1-1
360...380V	370...440V	FU2	TB1-2
400...460V	440...500V	FU2	TB1-3
520...580V	540...610V	FU2	TB1-4
620...690V	640...690V	FU2	TB1-5

**Figure 45 - Frame 3A Regenerative Drive Input Power and PE Wiring**



**Figure 46 - Frame 3B Regenerative Drive Input Power and PE Wiring**



**Table 7 - Frame 3 Power Terminal Specifications**

Item	Name	Description	Frame Size	Wire Size Range <sup>(1)</sup>		Recommended Tightening Torque (±10%)
				Maximum	Minimum	
❶	Input Power Wire Lugs R/L1, S/L2, T/L3	Input power connections on drive	3A	400 MCM	3/0	42 N•m (375 lb•in)
			3B	1000 MCM	500 MCM	62 N•m (550 lb•in)
❷	PE Wire Lug	Terminating point for ground wires	3A or 3B	600 MCM	#2 AWG	34 N•m (300 lb•in)

(1) Maximum/minimum sizes that the terminals will accept - these are not recommendations.

### Installing an External/Separate Input Disconnect

An input disconnect can be installed in the line before the drive input terminals in accordance with local, national, and international codes (for example, NEC/CEC). Size the disconnect according to the in-rush current as well as any additional loads the disconnect might supply. Coordinate the trip rating for the inrush current (10...12 times full load current) with that of the input isolation transformer, if used. See [Installing Transformers and Reactors \(Not Recommended\) on page 74](#) for additional information.

### Installing Power Wiring from Input Filter Bay to the Power Module Bay

Use the following steps to connect AC input power to the drive.



**ATTENTION:** Do not route signal and control wiring with power wiring in the same conduit. This can cause interference with drive operation. Failure to observe this precaution can result in damage to, or destruction of, the equipment.

1. Connect the three-phase AC input power leads (three-wire 380...480V AC or three-wire 600...690V AC, depending on drive nameplate voltage rating) to the R/L1, S/L2, and T/L3 input power terminals on the drive:
  - Frame 3A Combined Converter/Inverter Power Module (for terminal locations, see [Figure 24](#), [Figure 40](#), and [Figure 47](#)).
  - Frame 3A Dual Inverter Power Module (for terminal locations, see [Figure 24](#), [Figure 40](#), and [Figure 48](#)).
  - Frame 3B Separate Converter Power Module (for terminal locations, see [Figure 25](#), [Figure 43](#), and [Figure 49](#)).
2. Tighten the AC input power terminal connections to the recommended torque as shown in [Table 8](#).

**Table 8 - Power Module Terminal Specifications**

Item	Name	Description	Recommended Tightening Torque ( $\pm 10\%$ )	Terminal Bolt Size <sup>(1)</sup>
1	Input Power Bus Bar <sup>(2)</sup> R/L1, S/L2, T/L3	Input power	62 N•m (550 lb•in)	M12
2	Output Power Bus Bar <sup>(2)</sup> U/T1, V/T2, W/T3	Motor connections	62 N•m (550 lb•in)	M12
3	PE, Motor Ground Bus Bar <sup>(2)</sup>	Terminating point for wiring shields	11 N•m (100 lb•in)	M8
4	DC Bus Test Point Socket <sup>(3)</sup> (2 Terminals; DC+, DC-)	4 mm socket for DC bus voltage measurement only	—	—
5	DC Power Bus Bar <sup>(2)(4)</sup> (2 Terminals; DC+, DC-)	DC power from Converter Power Module to Inverter Power Module (Frame 3B only)	62 N•m (550 lb•in)	M12

- (1) Apply counter torque to the nut on the other side of terminations when tightening or loosening the terminal bolt to avoid damage to the terminal.
- (2) These connections are bus bar type terminations and require the use of lug connectors.
- (3) Use only to verify that DC bus capacitors are discharged before servicing the Power Module. No other external use is permitted.
- (4) Size DC power conductors for current carrying capacity as follows: 400/480V, 1000 Amps; 600/690V, 800 Amps.

**Figure 47 - Frame 3A Converter/Inverter Power Module Terminal Locations**

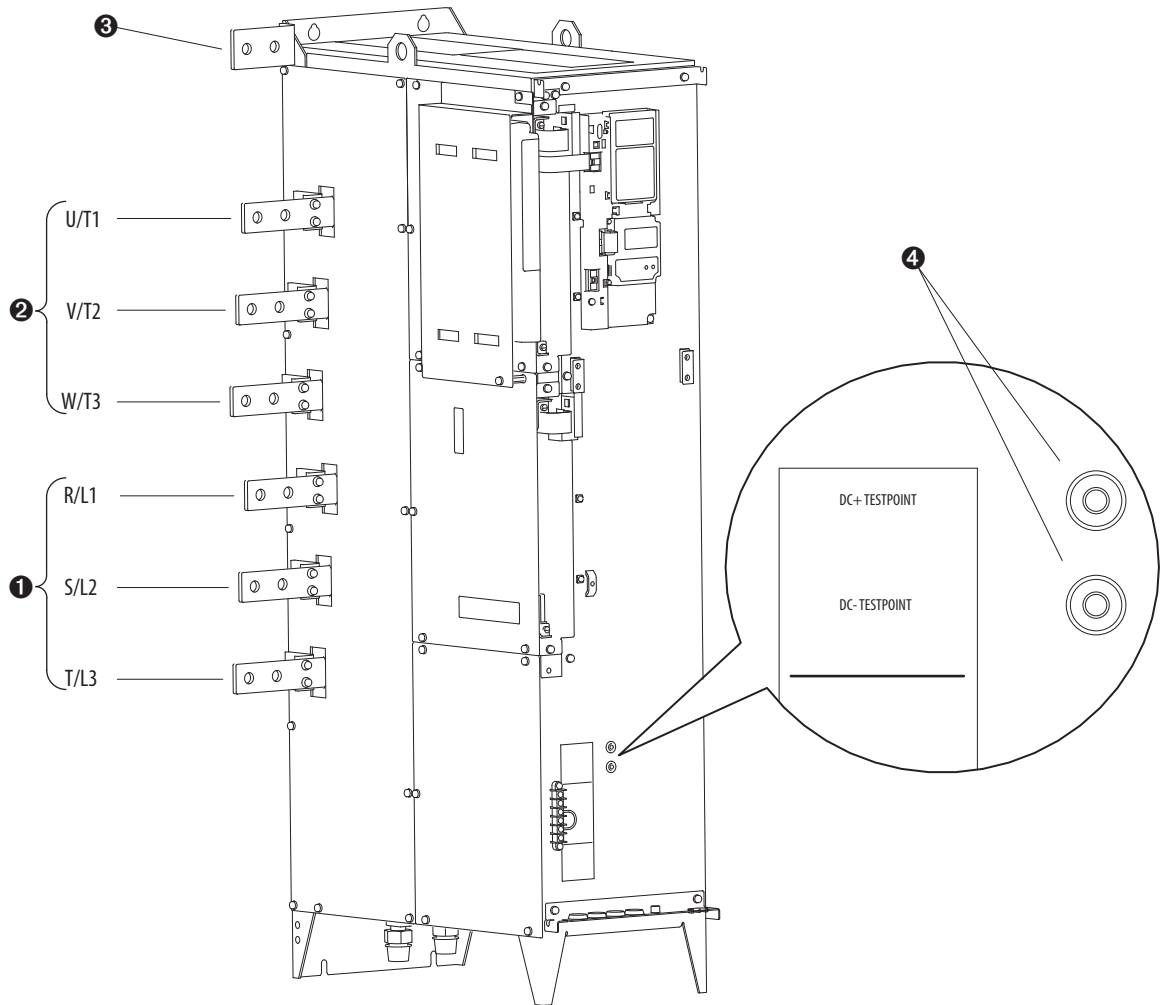
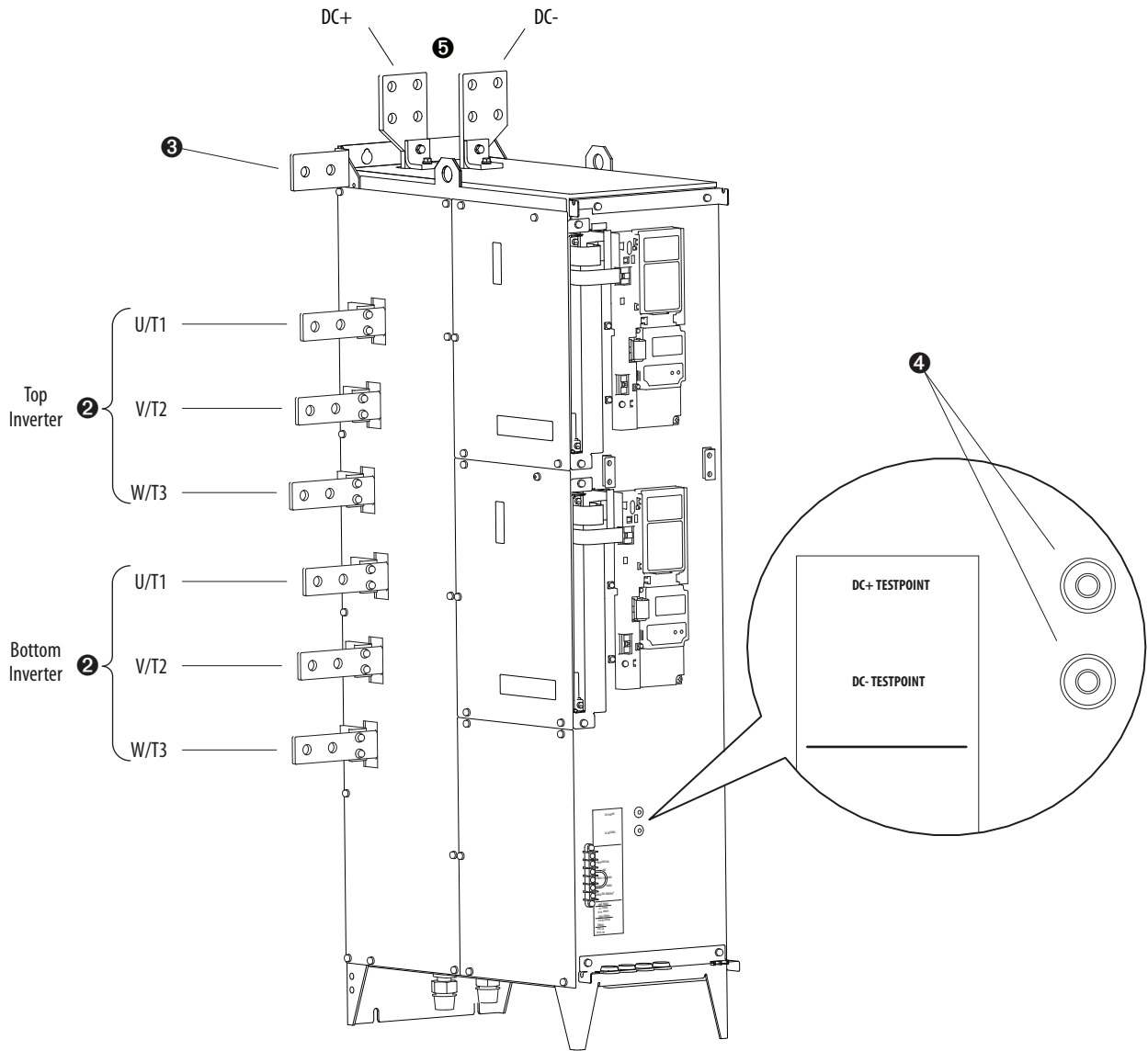
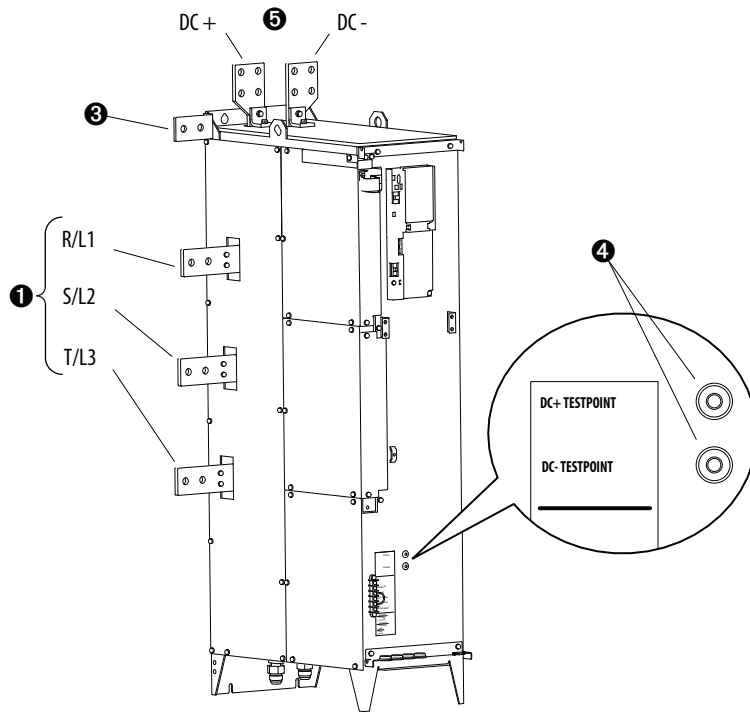


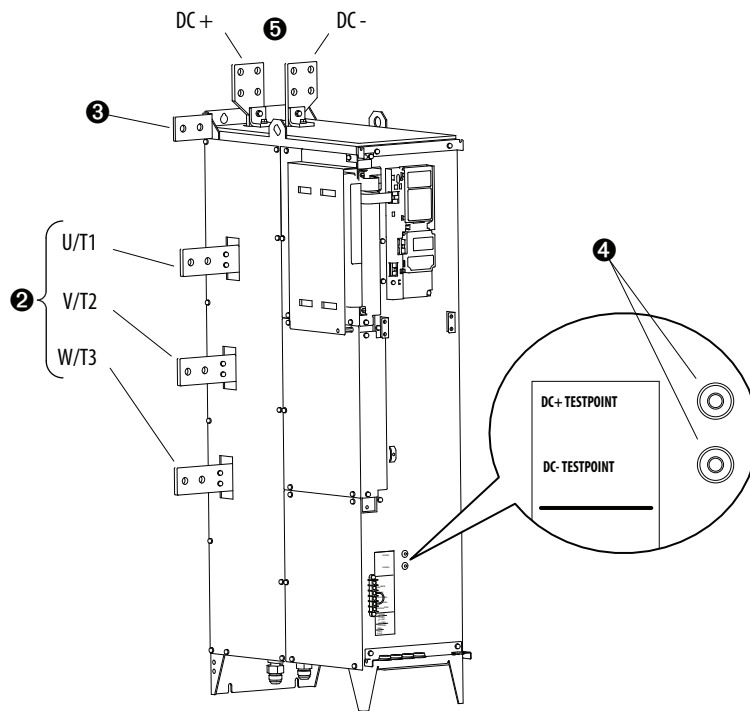
Figure 48 - Frame 3A Dual Inverter Power Module Terminal Locations



**Figure 49 - Frame 3B Active Converter Power Module Terminal Locations**



**Figure 50 - Frame 3B Inverter Power Module Terminal Locations**



## Installing Output Power Wiring

This section provides instructions on wiring output contactors, motor overload protection, and output wiring to the motor.

### Installing Mechanical Motor Overload Protection (Optional)

To provide the motor with overload protection, local, national, and international codes (for example, NEC/CEC) can require one of the following items:

- A motor thermostat be installed internal to the motor.
- A mechanical thermal motor overload relay, sized to protect the motor, be installed between the motor and the drive's output terminals.

In multiple motor applications (V/Hz regulation only), each motor must have its own user-supplied overload and branch circuit protection.

### Installing Output Wiring from the Drive Output Terminals to the Motor

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**IMPORTANT** See the Wiring and Grounding Guidelines for Pulse Width Modulated (PWM) AC Drives, Installation Instructions, publication [DRIVES-IN001](#), for details on maximum motor cable lengths.

---

Follow these steps to connect the AC output power wiring from the drive to the motor.

1. Route the three-phase AC output power motor leads to the drive power module.

Do not route more than three sets of motor leads through a single conduit. This minimizes cross-talk that can reduce the effectiveness of noise reduction methods. If more than three drive/motor connections per conduit are required, shielded cable must be used. If possible, each conduit should contain only one set of motor leads.



**ATTENTION:** Do not route signal and control wiring with power wiring in the same conduit. This can cause interference with drive operation. Failure to observe these precautions can result in damage to, or destruction of, the equipment.



**ATTENTION:** Unused wires in conduit must be grounded at both ends to avoid a possible shock hazard caused by induced voltages. Also, if a drive sharing a conduit is being serviced or installed, disable all drives using this conduit to eliminate the possible shock hazard from cross-coupled motor leads. Failure to observe these precautions can result in bodily injury.

---

2. Connect the three-phase AC power motor leads to the U/T1, V/T2, and W/T3 output power terminals on the drive:
  - Frame 3A Combined Converter/Inverter Power Module (for terminal locations, see [Figure 40](#) and [Figure 47](#)).
  - Frame 3A Dual Inverter Power Module (for terminal locations, see [Figure 40](#) and [Figure 48](#)).



- Frame 3B Separate Converter Power Module (for terminal locations, see [Figure 43](#) and [Figure 49](#)).
3. Tighten the AC output power terminal connections to the proper torque as shown in [Table 8](#).

## Installing Control Wiring from the Input Filter Bay to the Power Module Bay

This section provides details on control wiring between the Input Filter Bay and the Power Module Bay. When a Frame 3A or 3B Complete Drive is ordered, wiring from the Input Filter Bay to the Power Module Bay is completed at the factory. In this case, this section can be used as verification or reference for installation or maintenance.



**ATTENTION:** Risk of equipment damage exists. Do not use power module terminal blocks TB5-1 and TB5-3 to connect any type of power wiring for auxiliary equipment. These terminals are for only low amperage control wiring.



**ATTENTION:** Do not route signal and control wiring with power wiring in the same conduit. This can cause interference with drive operation. Failure to observe this precaution can result in damage to, or destruction of, the equipment.

### Frame 3A Drives

Connect wiring to terminals in accordance with [Table 9](#), [Table 6](#), [Table 10](#), [Figure 51](#), and the Frame 3A drive schematic on [page 136](#) or [page 138](#).

## Frame 3B Drives

Connect wiring to terminals in accordance with [Table 9](#), [Table 6](#), [Table 10](#), [Figure 52](#), and the Frame 3B drive schematic on [page 144](#) or [page 146](#).

**Table 9 - Power Module Control Wiring Terminal Specifications**

Item	Name	Description	Wire Size Range <sup>(1)</sup>		Recommended Tightening Torque (±10%)	Wire Strip Length	Wire Terminal
			Maximum	Minimum			
❶	400/480V Line Voltage Fuses FU7, FU8, and FU9	Input filter AC power	21.1 mm <sup>2</sup> (#4 AWG)	2.1 mm <sup>2</sup> (#14 AWG)	4 N•m (35 lb•in)	(2)	(2)
	600/690V Line Voltage Fuses FU7, FU8, and FU9		21.1 mm <sup>2</sup> (#4 AWG)	2.1 mm <sup>2</sup> (#14 AWG)	4 N•m (35 lb•in)	6 mm (0.25 in.)	not applicable
❷	Terminal Blocks—TB2	Input filter control signals	3.3 mm <sup>2</sup> (#12 AWG)	0.3 mm <sup>2</sup> (#22 AWG)	1.5 N•m (13 lb•in)	13 mm (0.51 in.)	not applicable
❸	Active Converter Cassette Terminal Blocks—P1 and P2	Active Converter AC power and control wiring	3.3 mm <sup>2</sup> (#12 AWG)	0.3 mm <sup>2</sup> (#22 AWG)	0.8 N•m (7 lb•in)	8 mm (0.31 in.)	not applicable
❹	SHLD Terminal	Terminating point for control wiring shields on Power Module	2.1 mm <sup>2</sup> (#14 AWG)	0.3 mm <sup>2</sup> (#22 AWG)	1.4 N•m (12 lb•in)	10 mm (0.39 in.)	not applicable
❺	Terminal Blocks—TB5 and TB6	Power Module control wiring	4.0 mm <sup>2</sup> (#10 AWG)	0.2 mm <sup>2</sup> (#24 AWG)	1.4 N•m (12 lb•in)	8 mm (0.31 in.)	not applicable
❻	Fan—M6	Power Module Bay cooling fan	4.0 mm <sup>2</sup> (#10 AWG)	0.3 mm <sup>2</sup> (#22 AWG)	0.8 N•m (7 lb•in)	8 mm (0.31 in.)	not applicable

(1) Maximum/minimum sizes that the terminals will accept - these are not recommendations.

(2) For 400/480V applications, terminate wires with #10 spade tongue terminal. Maximum terminal width is 11 mm (0.43 in.). Wire strip length per terminal manufacturers recommendation.

Wire the Input Filter Bay to the Power Module Bay in accordance with [Table 10](#) and drive schematics in [Appendix C](#).

**Table 10 - Input Filter-to-Power Module Bay Wiring**

From	To	Comments
FU7	PMC P2-1	PMC = Power Module, Converter
FU8	PMC P2-4	
FU9	PMC P2-7	
TB2-1	PMC P1-9	
TB2-1	PMC TB5-1	
TB2-3	M6-N	M6 = Power Module Bay Door Fan
TB2-4	PMC TB5-3	
TB2-5	PMC P1-10	
TB2-6	PMC TB5-2	
TB2-6	M6-L1	
TB2-7	M6-PE	
TB2-9	PMC TB5-4	
TB2-10	PMC TB5-7	
TB2-11	PMC TB5-5	
PMC TB5-4	PMC TB5-6	Factory-installed jumper

**Figure 51 - Frame 3A Complete Drive Control Wiring Terminal Locations**

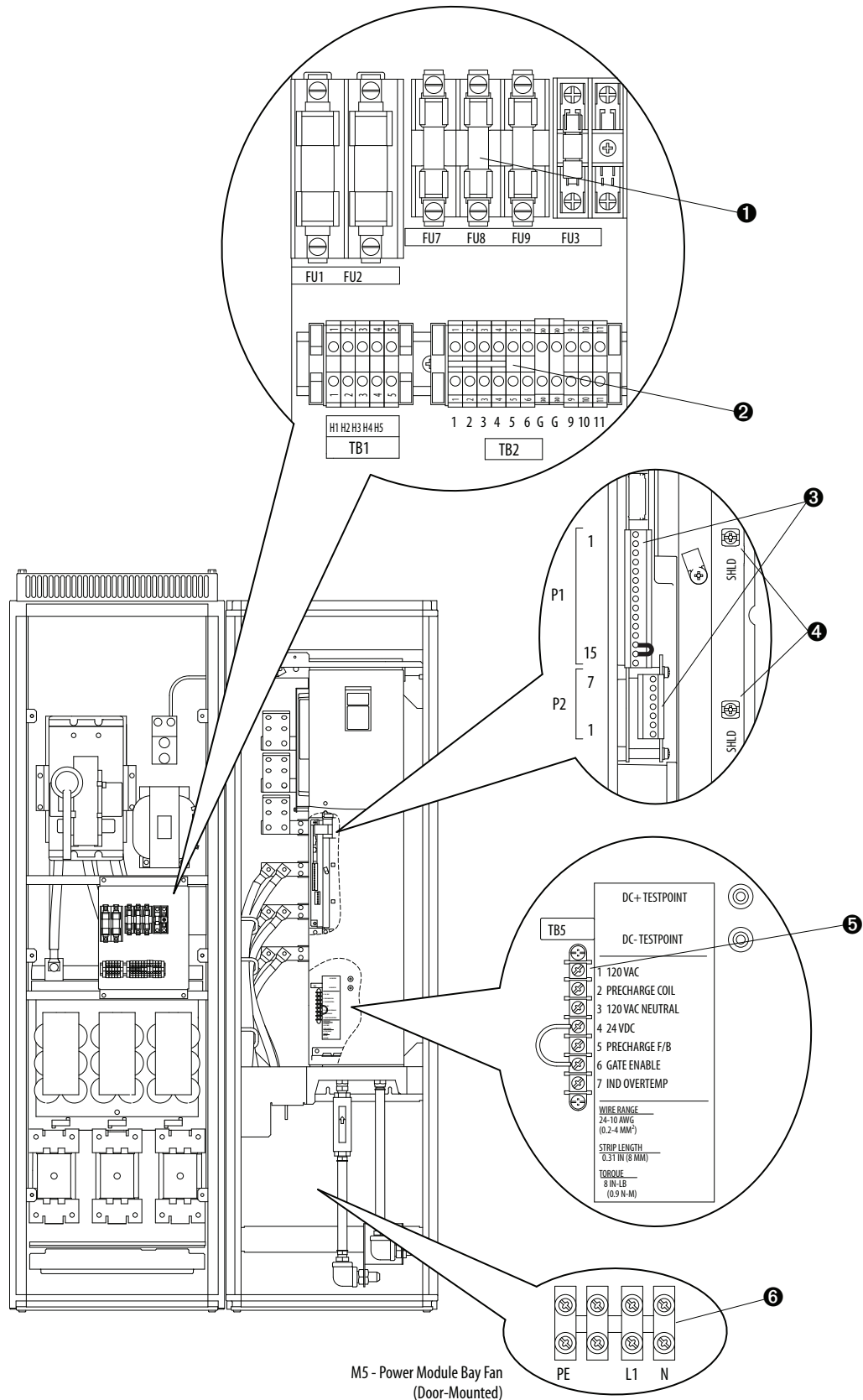
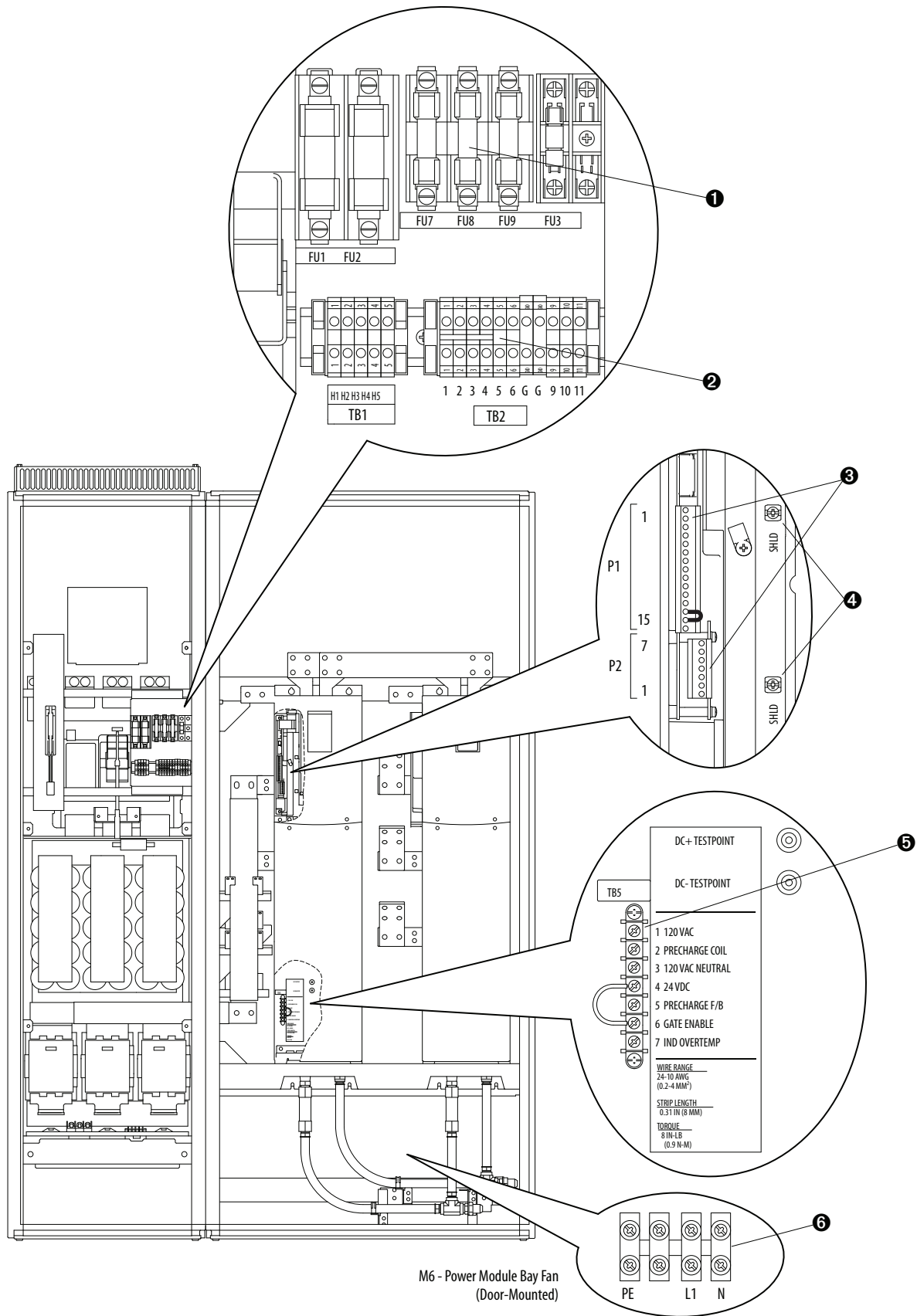


Figure 52 - Frame 3B Complete Drive Control Wiring Terminal Locations



# Synchronization Connections for Frame 3A

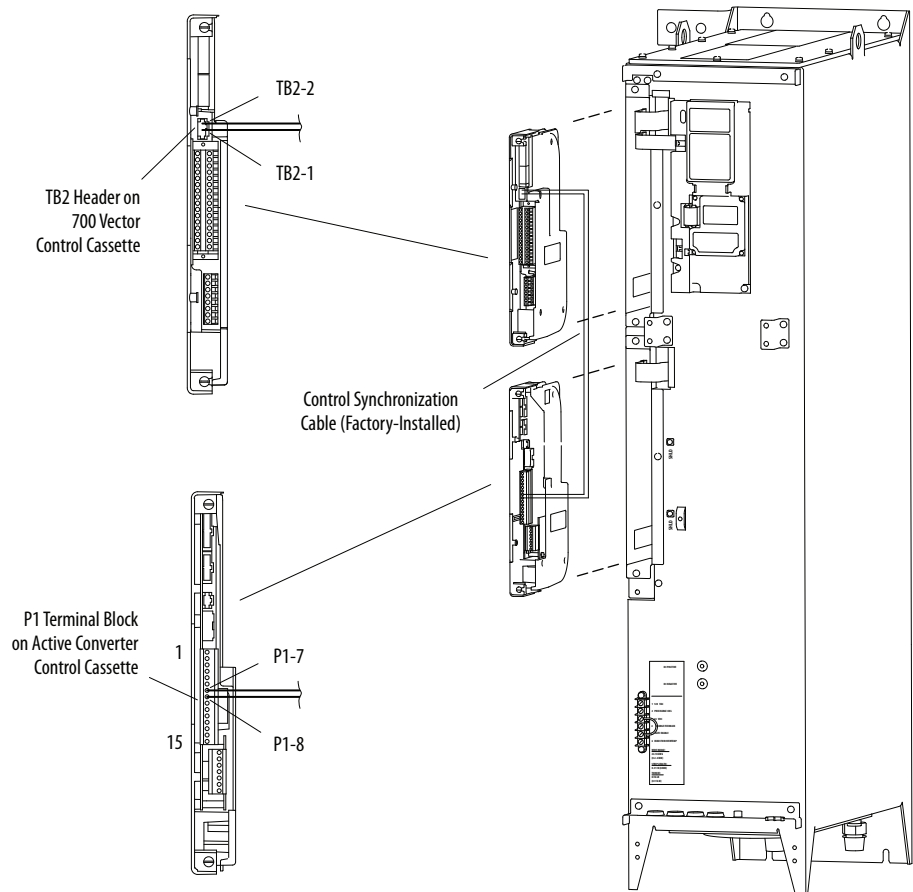
## Coupled Power Modules

Frame 3A combined Converter/Inverter Power Modules are configured only as coupled power modules. Coupling the Converter and Inverter is achieved by using two factory-installed cables: a control synchronization cable and an inverter-to-converter DPI communication cable. The two cables are described in the next two subsections.

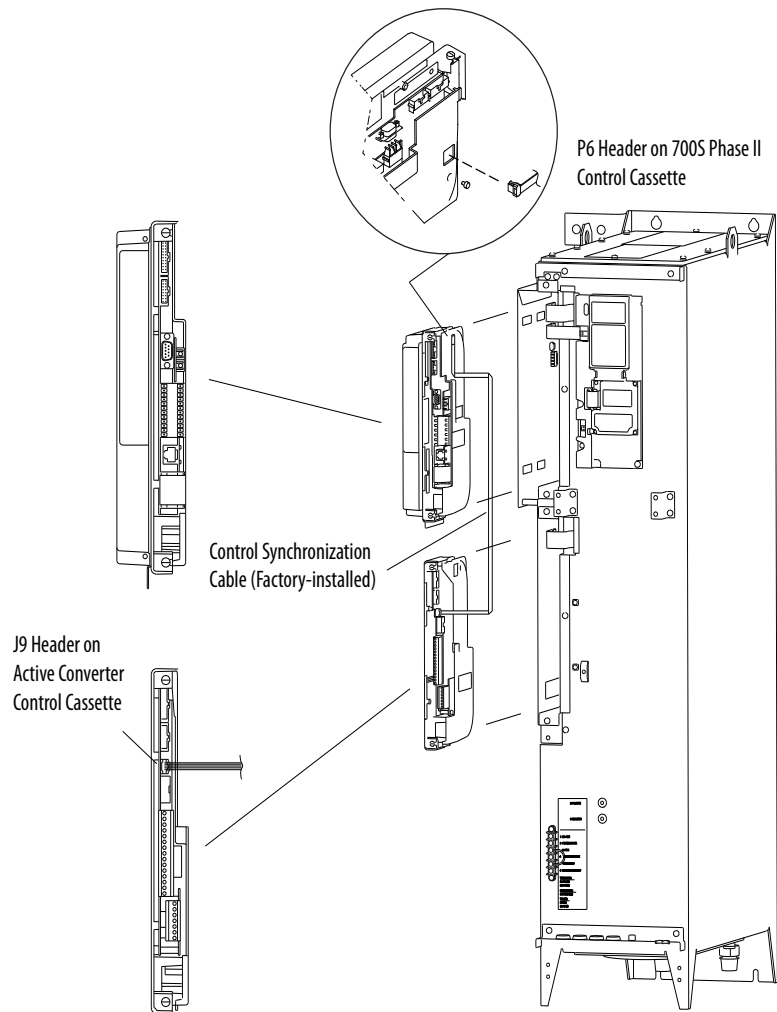
## Control Synchronization Cable

To enable synchronization between the Inverter control board and the Converter control board, a factory-installed control synchronization cable connects each board. No user connection is required. However, the connection method is different for PowerFlex 700L drives with 700 Vector Control than for 700S Phase II Control. The 700 Vector Control synchronization cable connection is shown in [Figure 53](#). The 700S Phase II Control synchronization cable connection is shown in [Figure 54](#).

**Figure 53 - Frame 3A 700 Vector Control Synchronization Cable Connection**



**Figure 54 - Frame 3A 700S Phase II Control Synchronization Cable Connection**



### **Inverter-to-Converter DPI Communication Cable**

To enable the Inverter and Converter section of the Frame 3A Power Module to communicate with each other, a factory-installed DPI communication cable is used. No user connection is required.

## **Synchronization Connections for Frame 3B**

### **Coupled or Stand-Alone Inverter Power Modules**

Frame 3B Inverter Power Modules can be configured in two ways. One way is an Inverter Power Module coupled with a Converter Power Module. The coupling is achieved by using two cables: a control synchronization cable and an inverter-to-converter DPI connection cable. The other way is a stand-alone Inverter Power Module. In this case, synchronization and DPI connection cables are not needed to connect the Inverter Power Module to the Converter Power Module. The two cables for coupling are described in the next two subsections.

## Control Synchronization Cable

To enable synchronization between the Inverter control board and the Converter control board, you must connect a synchronization cable to each board. The connection method is different for PowerFlex 700L drives with 700 Vector Control than for 700S Phase II Control. The 700 Vector Control synchronization cable connection is shown in [Figure 55](#). The 700S Phase II Control synchronization cable connection is shown in [Figure 56](#). The appropriate version of the cable is provided in a plastic bag with each Inverter Power Module. Only one Inverter Power Module may be coupled to a Converter Power Module.

**Figure 55 - Frame 3B 700 Vector Control Synchronization Cable Connection**

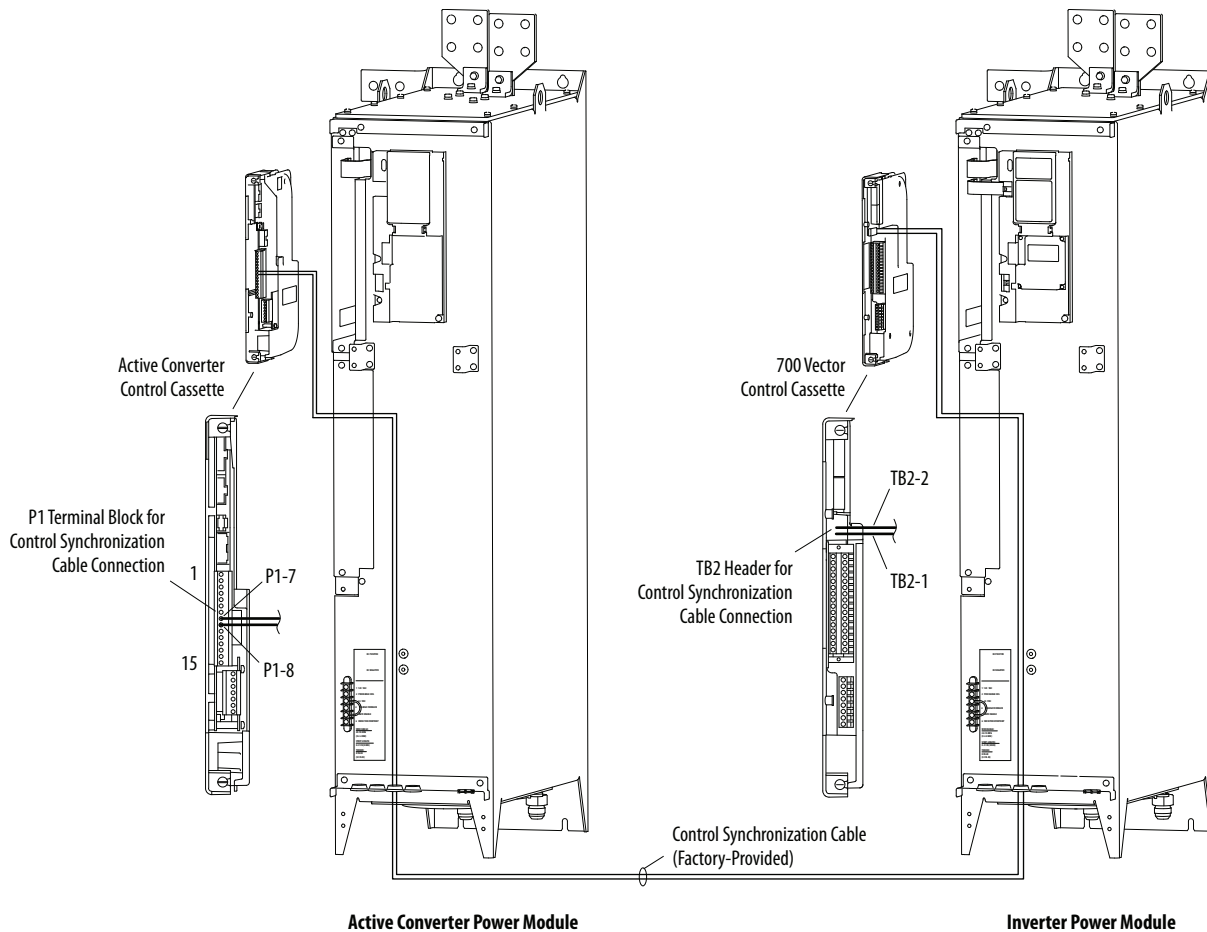
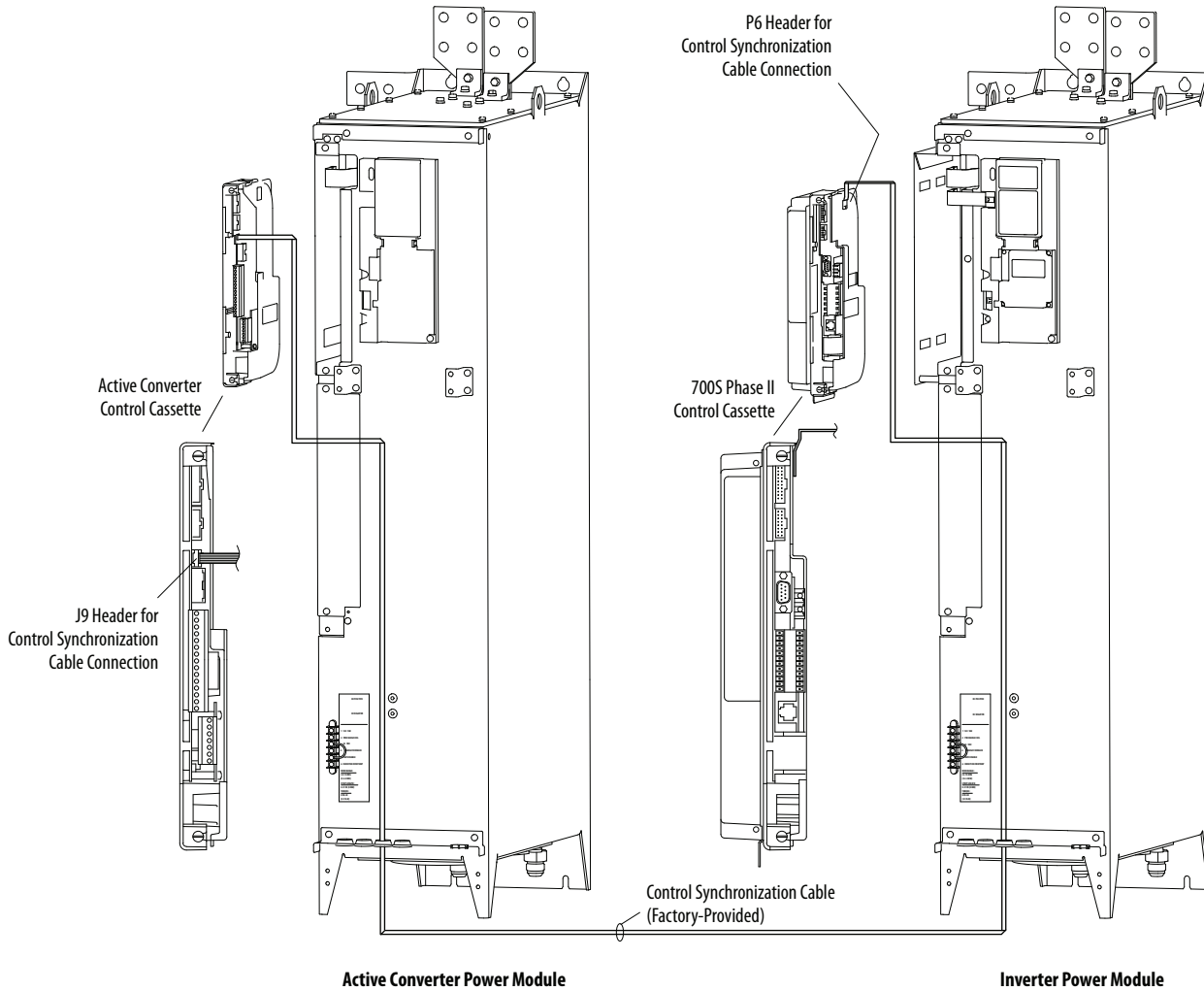


Figure 56 - Frame 3B 700S Phase II Control Synchronization Cable Connection



### Inverter-to-Converter DPI Communication Cable

To enable the Frame 3B Inverter and Converter Power Modules to communicate with each other, you must connect one DPI port on the bottom of the Converter to a DPI port on the bottom of the Inverter with a DPI communication cable (see [Figure 58](#)).



## DPI Connections for Frame 3A and 3B Drives

## Drive Connection Points

The PowerFlex 700L provides a number of cable connection points as shown in [Figure 57](#) and [Figure 58](#). If an additional external HIM is required for the application, the HIM can be connected to the DPI port on the bottom of the Power Module. Only one additional external HIM device can be connected. The use of two external HIM devices is not supported. If multiple external HIM devices are required, then install a user-supplied splitter cable or splitter box.

**Figure 57 - Frame 3A DPI Connection Points**

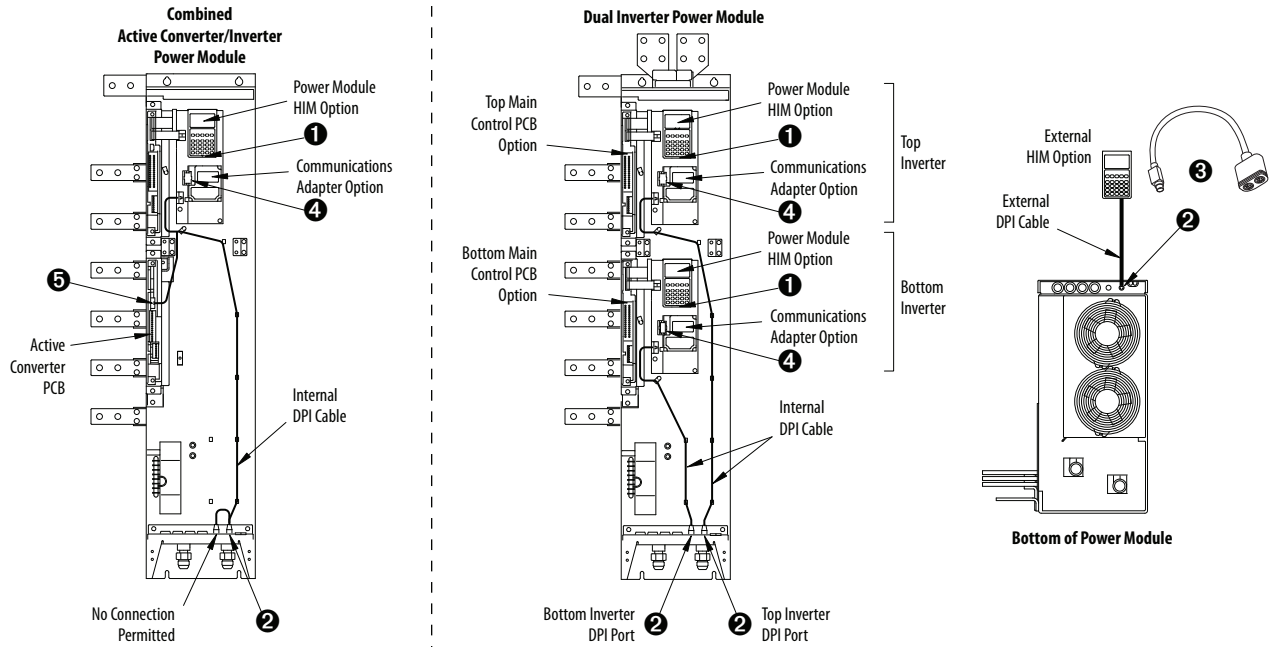
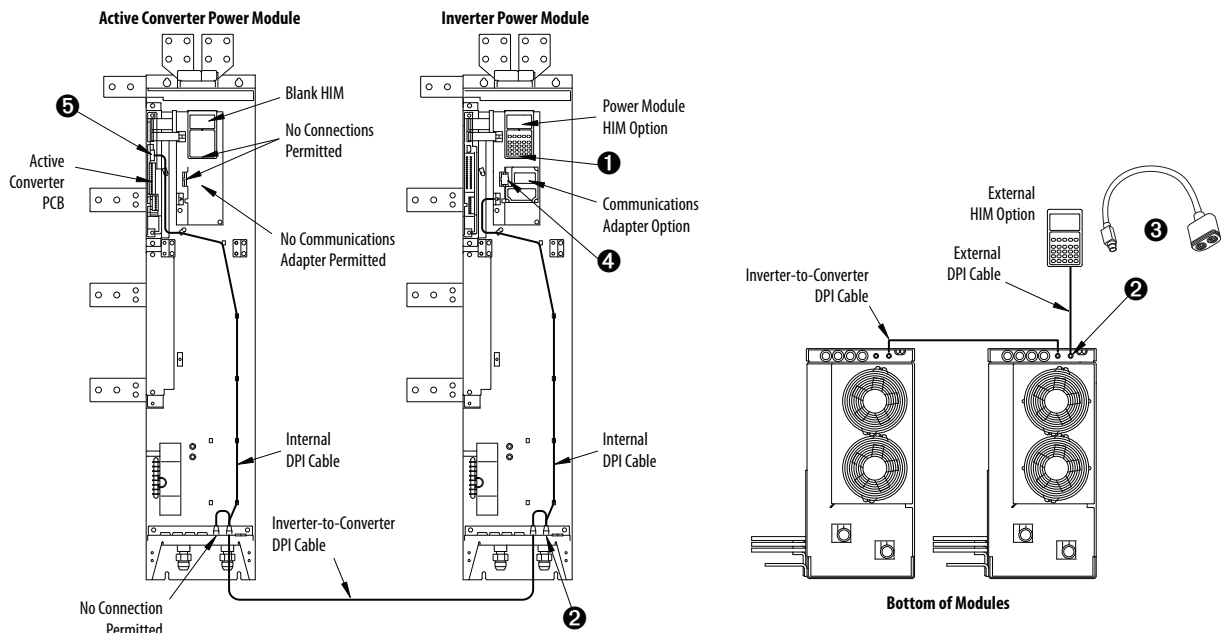


Figure 58 - Frame 3B DPI Connection Points



Item	Connector	Description
❶	DPI Port 1	HIM connection when installed in Power Module.
❷	DPI Port 2	Cable connection for handheld and remote options.
❸	DPI Port 3 or 2	Splitter cable connected to DPI Port 2 provides an additional port.
❹	DPI Port 5	Cable connection for communications adapter.
❺	DPI Port 6	Internal DPI connection to Active Converter PCB.

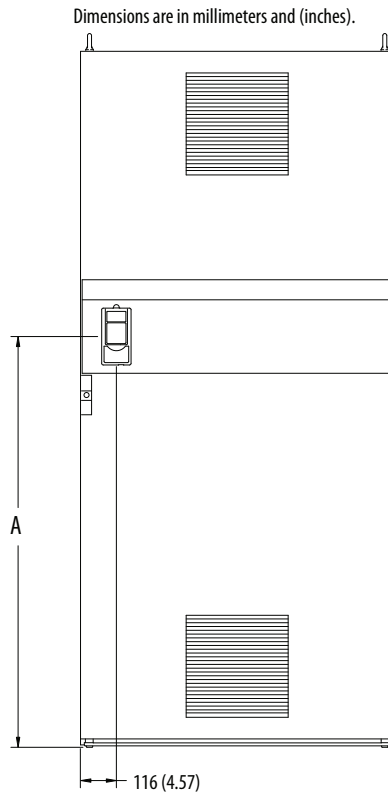
### External Door-Mounted HIM Connection (Optional)

For complete drives, the door-mounted HIM is standard equipment.

[Figure 59](#) shows the location for the door mount bezel in the door of the Power Module Bay.

For power modules installed in user-supplied enclosures, an optional external door-mounted HIM can be connected as an alternative to the external HIM option. The cable supplied with the door-mount HIM option kit connects to the DPI port on the bottom of the Power Module (see [Figure 57](#) for Frame 3A or [Figure 58](#) for Frame 3B). For additional installation information, see the instructions provided with the door-mount HIM option kit.

**Figure 59 - Complete Drive External Door-Mounted HIM Location**



Frame Size	Dimensions mm (in.)
	A
3A	1206 (47.49)
3B	1301 (51.21)

## Coolant Loop Connections

See [Chapter 4, Cooling Loop Installation](#) for details.

**Notes:**

## Cooling Loop Installation

Proper liquid cooling is critical to drive operation and reliability. This chapter provides information about the types of drive cooling loops, drive coolant requirements, and cooling loop connections for the PowerFlex® 700L Liquid-Cooled drive power structure.

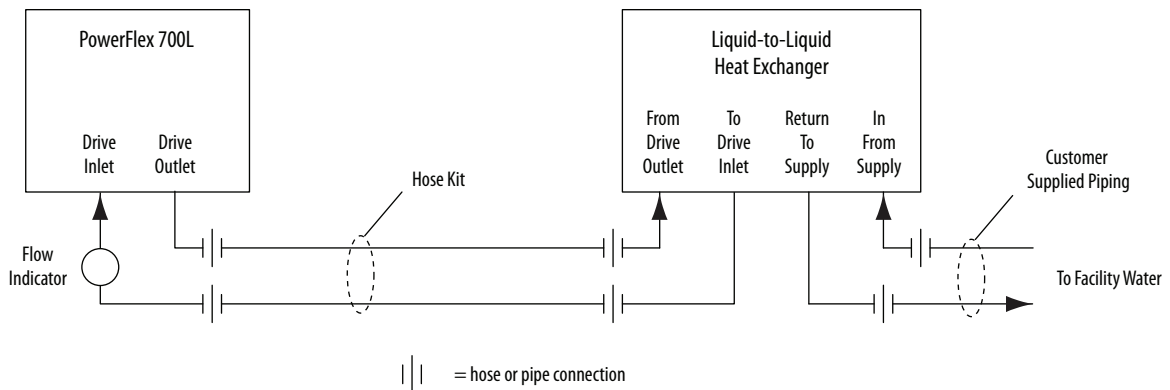
Topic	Page
Explanation of Cooling Loop Types	93
Cooling Loop Application Guidelines	97
Drive Coolant Connections	98
Drive Coolant Requirements	101

### Explanation of Cooling Loop Types

#### Liquid-to-Liquid Heat Exchanger

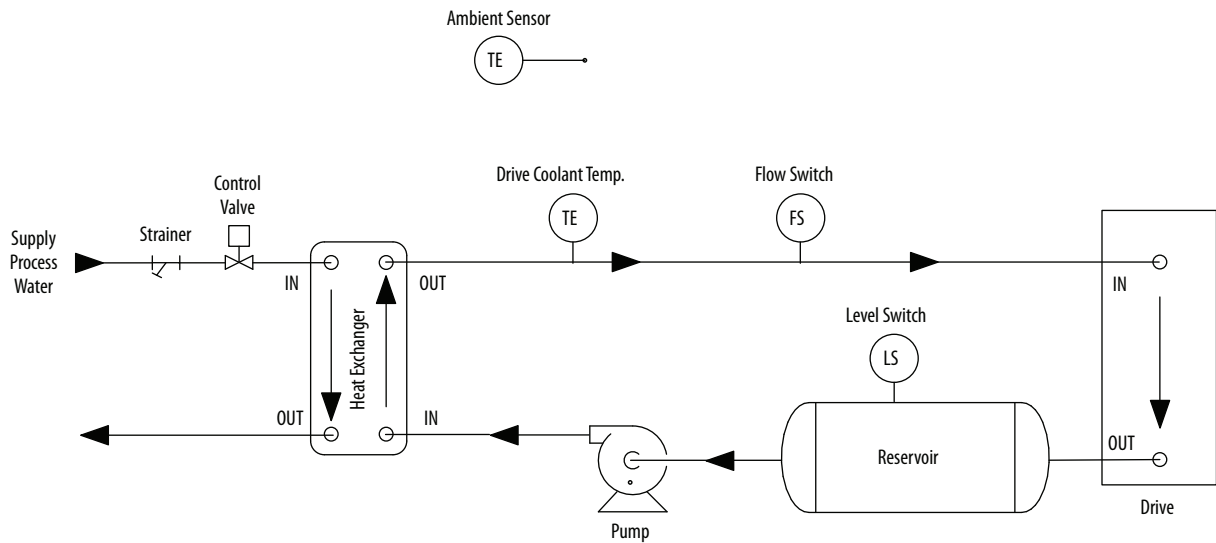
The liquid-to-liquid heat exchanger uses a heat transfer plate to transfer heat from one liquid to another. This method requires a stable water supply from the user.

**Figure 60 - Drive and Liquid-to-Liquid Heat Exchanger Plumbing Arrangement**



[Figure 61](#) shows a cooling loop diagram for a typical liquid-to-liquid heat exchanger.

Figure 61 - Liquid-to-Liquid Heat Exchanger Plumbing Diagram



The main components of the liquid-to-liquid heat exchanger cooling loop are listed below.

Part	Description
Strainer	Filters particles from the supply water.
Control Valve	Controls the supply loop water flow.
Heat Exchanger Plate	Transfers heat from the drive loop to the supply loop.
Ambient Sensor	Senses the ambient temperature used for the dew point control.
Drive Coolant Temperature Sensor	Senses the drive coolant temperature used for the dew point control.
Drive Coolant Flow Switch	Measures the drive coolant flow rate.
Level Switch	Senses the level of coolant in the reservoir.
Reservoir	Stores drive coolant.
Pump and Motor	Circulates drive coolant.

## Liquid-to-Air Heat Exchanger

The liquid-to-air heat exchanger uses radiator technology to transfer heat from a liquid to surrounding air. This is a simple closed loop system—it does not require a water supply from the user. However, this system requires surrounding air that is 5...10 °C below the maximum operating temperature of the drive.

**Figure 62 - Drive and Liquid-to-Air Heat Exchanger Plumbing Arrangement**

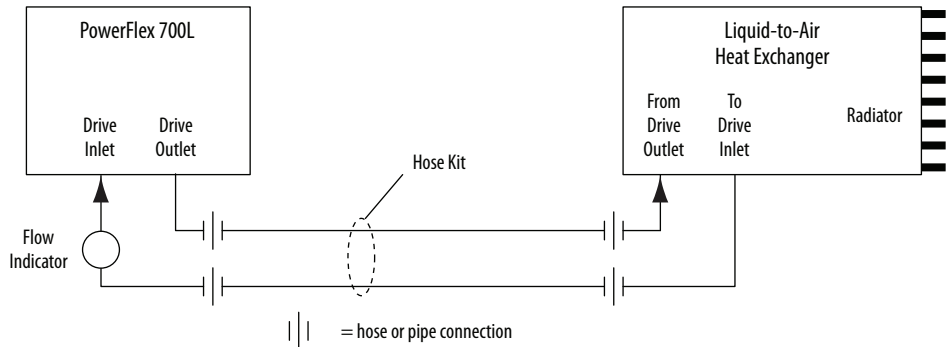
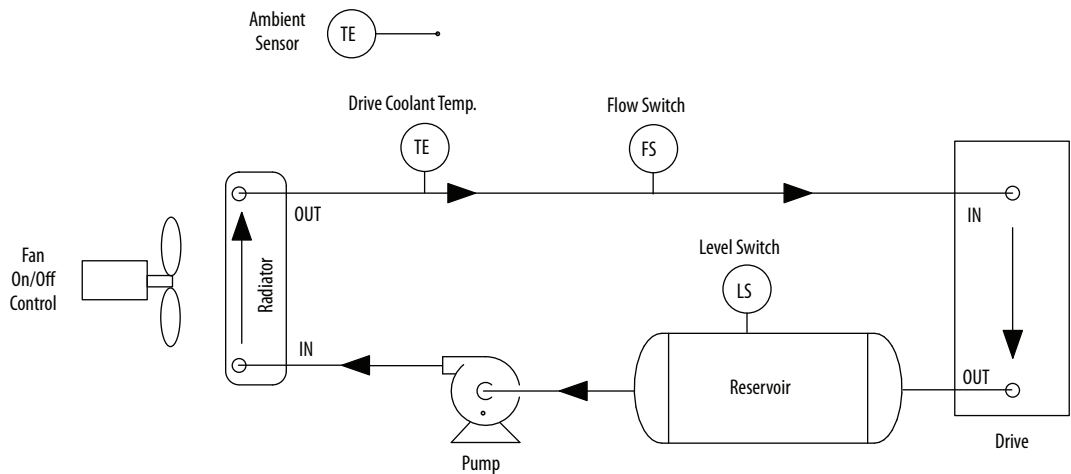


Figure 63 shows a cooling loop diagram for a typical liquid-to-air heat exchanger.

**Figure 63 - Liquid-to-Air Heat Exchanger Plumbing Diagram**



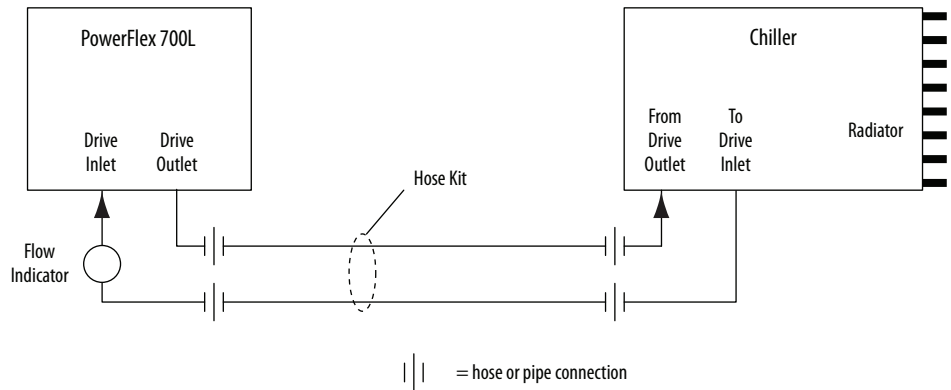
The main components of the liquid-to-air heat exchanger cooling loop are listed below.

Part	Description
Fan	Blows air across the radiator.
Radiator	Transfers heat from liquid to air.
Ambient Sensor	Senses the ambient temperature used for the dew point control.
Drive Coolant Temperature Sensor	Senses the drive coolant temperature used for the dew point control.
Drive Coolant Flow Switch	Measures the drive coolant flow rate.
Level Switch	Senses the level of coolant in the reservoir.
Reservoir	Allows for expansion of coolant.
Pump and Motor	Circulates drive coolant.

## Chiller

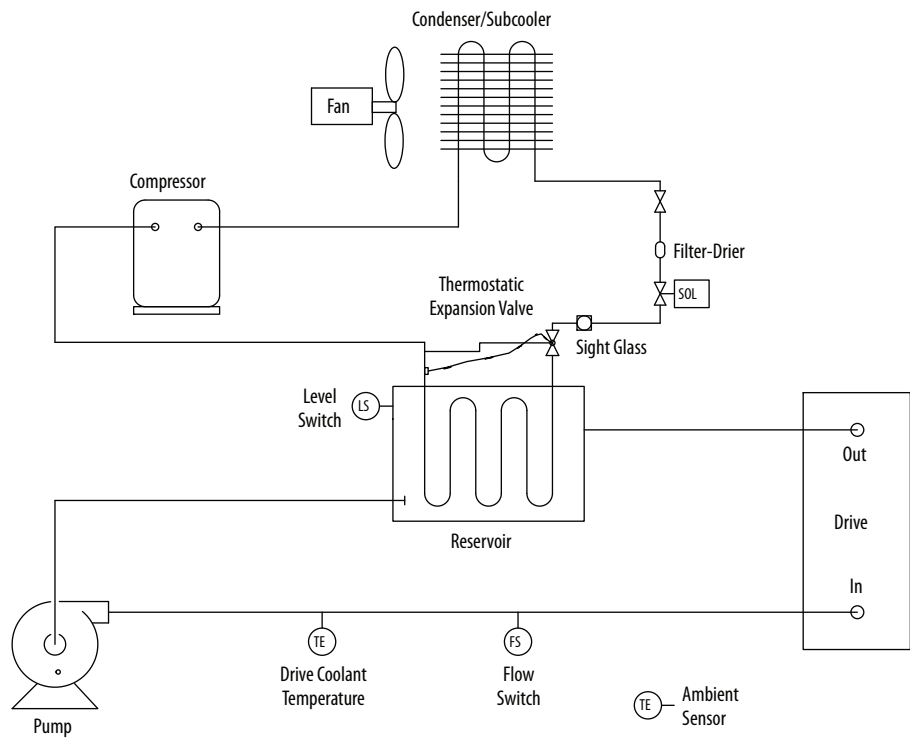
The chiller uses refrigerant to transfer heat from a liquid to air. This is a simple closed loop system—it does not require a water supply from the user. A chiller can achieve almost any coolant temperature required. Coolant temperature should be at or above ambient temperature to avoid condensation on drive components.

**Figure 64 - Drive and Chiller Plumbing Arrangement**



[Figure 65](#) shows a cooling loop diagram for a typical chiller.

**Figure 65 - Chiller Plumbing Diagram**





The main components of the chiller cooling loop are listed below.

Part	Description
Compressor	Forces the refrigerant into a smaller space.
Fan	Blows air across the condenser/subcooler.
Condenser/Subcooler	Cools the refrigerant.
Filter-Drier	Filters the refrigerant.
Sight Glass	Allows viewing of the level of drive coolant in the reservoir.
Thermostatic Expansion Valve	Allows for expansion of the refrigerant.
Level Switch	Senses the level of coolant in the reservoir.
Reservoir	Allows for expansion of coolant.
Pump and Motor	Circulates drive coolant.
Drive Coolant Temperature Sensor	Senses the drive coolant temperature used for the dew point control.
Drive Coolant Flow Switch	Measures the drive coolant flow rate.
Ambient Sensor	Senses the ambient temperature used for the dew point control.

## Cooling Loop Application Guidelines



**ATTENTION:** Risk of equipment damage exists. Do not use ferrous and plated-ferrous materials for pipe-treated water to the power modules and drive. Use of ferrous materials degrades the performance of the power module chillplate.

This section is intended to provide guidelines for applying the cooling loops.

1. The allowable drive coolant temperature range is listed below:

- Frame 2 Drives: 0...50 °C (32...122 °F)
- Frame 3A and 3B Drives: 0...40 °C (32...105 °F)

When using coolant at a temperature below the dew point of the surrounding air, condensation can accumulate on the drive heatsink and/or circuit boards, which can damage the drive. In this situation, install a coolant flow regulating device and tube/hose insulation. A flow regulating device modulates the coolant flow rate to a level that permits the drive heatsink temperature to rise above the dew point. Insulation for customer side tube or hose can be closed-cell foam insulation with a minimum 12.7 mm (0.50 in.) wall thickness.

2. Include a flow switch in the cooling loop on the connection to the drive inlet to turn off the drive if coolant flow drops below the minimum flow required by the drive (see [Table 12](#)).
3. Circulate coolant through the drive only when the drive is also powered. Failure to do this can result in condensation accumulating on the drive heatsink and/or circuit boards, which could damage the drive.
4. Use an interlock from the cooling loop to stop the drive when the cooling loop is faulted.
5. For applications requiring a closed loop coolant system, vent the system to remove air that can otherwise degrade the performance of the drive heatsink.

6. Install a flow measuring device at the inlet of each Converter and each Inverter Power Module. Note that flow measuring devices are included in the PowerFlex 700L Frame 3A and 3B Complete Drive cabinets (13th position in catalog number = A). The coolant flow rate (GPM) must meet the requirements in [Table 12](#).
7. We recommend the following types of pipe for cooling loop connections:
  - Copper tubing, type L
  - Brass pipe
  - Stainless steel, 300 series

---

**IMPORTANT** Do not use galvanized pipe.

---

8. Provide a method in the cooling loop for draining and replacing the coolant.

## Drive Coolant Connections **Frame 2 Drive or Frame 3A or 3B Power Module**

For locations of the coolant inlet and outlet connections on PowerFlex 700L Frame 2 drives, see [Figure 13](#). For locations on Frame 3A and 3B Power Modules, see [Figure 42](#).

The rated working pressure of the Frame 2 drive is 1.72 bar (25 psi) and the maximum tested working pressure is 8.76 bar (127psi). Size coolant supply and return lines for 76 LPM (20 gpm) / 6.89 bar (100 psi) service with a maximum operating temperature of 50 °C (122 °F). The required operating flow rate and pressure drop is specified in [Table 12](#).

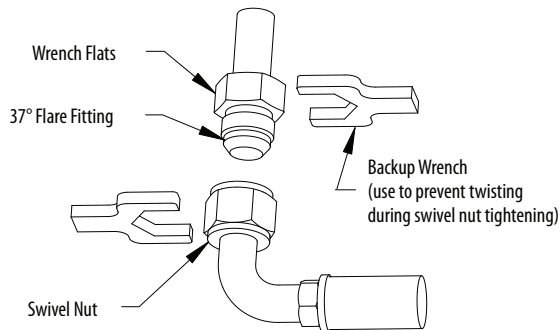
The rated working pressure of the Frame 3A or 3B Power Module is 12.76 bar (185 psi). Size coolant supply and return lines for 38 LPM (10 gpm) / 12.76 bar (185 psi) service with a maximum operating temperature of 40 °C (105 °F). The required operating flow rate and pressure drop is specified in [Table 12](#).

Coolant connections for Frame 2 drives and Frame 3A and 3B Power Modules are made using 37 degree flare fittings which have a:

- 3/4-inch nominal size
- "-12" SAE dash size
- 1-1/16-12 UN/UNF-2B external thread size

The mating connection is shown in [Figure 66](#). To make the mating coolant connection, follow these steps.

1. Assemble the mating version of the fitting (with swivel nut) to each fluid fitting, and tighten to a wrench resistance of approximately 3.4 N•m (30 lb•in).
2. Using a backup wrench on the Power Module fitting, tighten the swivel nut fitting by either of the following two methods:
  - Hex flats from wrench resistance method (recommended): one and one-quarter (1¼) hex flat from wrench resistance.
  - Torque method: 69...77 N•m (51...57 lb•ft).

**Figure 66 - Power Module Mating Coolant Connection**

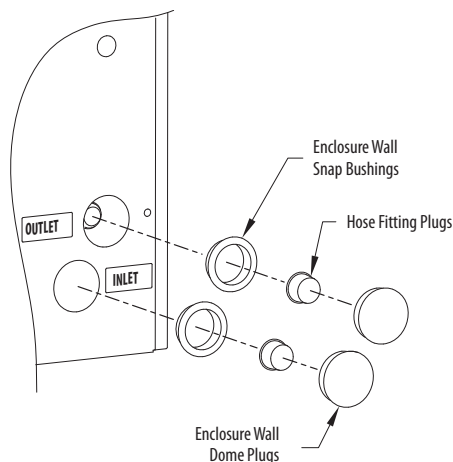
## Frame 3A or 3B Complete Drive

For locations of the coolant inlet and outlet connections on PowerFlex 700L Frame 3A Complete Drives, see [Figure 40](#) (front and side views). For locations on Frame 3B Complete Drives, see [Figure 43](#) (front and side views).

The rated working pressure of the Frame 3A and 3B Complete Drive is 6.89 bar (100 psi). Size coolant supply and return lines for 76 LPM (20 gpm) / 6.89 bar (100 psi) service with a maximum operating temperature of 40 °C (105 °F). The required operating flow rate is specified in [Table 12](#).

Before connecting the coolant hoses to the Complete Drive hose fittings located at the lower-right back corner of the drive enclosure, see [Figure 67](#) and perform these steps.

1. Remove the factory-installed hose fitting plugs and the enclosure wall dome plugs.
2. Install the factory-supplied snap bushings to the enclosure wall.

**Figure 67 - Frame 3A and 3B Complete Drive Coolant Connection Components**

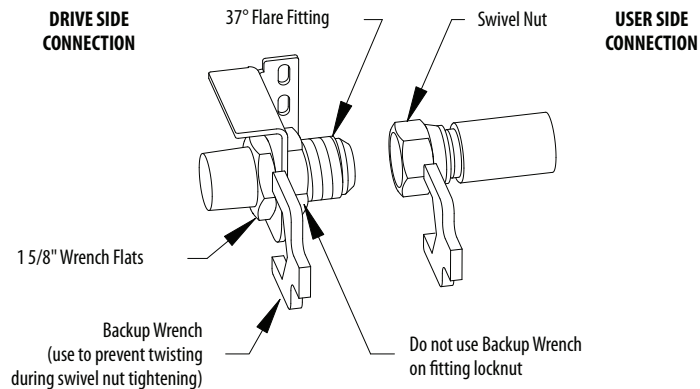
Frame 3A and Frame 3B Complete Drive coolant connections are made using 37 degree flare fittings which have a:

- 1-inch nominal size
- “-16” SAE dash size
- 1-5/16-12 UN/UNF-2B external thread size

The mating connection is shown in [Figure 68](#). To make the mating coolant connection, follow these steps.

1. Assemble the mating version of the fitting (with swivel nut) to each fluid fitting, and tighten to a wrench resistance of approximately 3.4 N•m (30 lb•in).
2. Using a backup wrench on the Complete Drive fitting, tighten the swivel nut fitting by either of the following two methods:
  - Hex flats from wrench resistance method (recommended): one (1) hex flat from wrench resistance.
  - Torque method: 103...109 N•m (76...81 lb•ft).

**Figure 68 - Frame 3A and 3B Complete Drive Mating Coolant Connection**



Depending on the location of the heat exchanger or chiller relative to the drive, the following drive cooling loop hose kits are available.

**Table 11 - Drive Cooling Loop Hose Kits**

Hose Length	Hoses in Kit	Drive Side <sup>(1)</sup> Coupling Size	Heat Exchanger Side Coupling Size	Used With	Hose Kit <sup>(2)</sup> Catalog Number
3 m (10 ft)	2	0.75 inch	0.75 inch	Frame 2	20L-GH10-B1
9.1 m (30 ft)	2	0.75 inch	0.75 inch	Frame 2	20L-GH30-B1
3 m (10 ft)	2	1 inch	1 inch with 90° elbow	Frame 3A	20L-GH10-A2
9.1 m (30 ft)	2	1 inch	1 inch with 90° elbow	Frame 3A	20L-GH30-A2
3 m (10 ft)	2	1 inch	1 inch	Frame 3B	20L-GH10-A1
9.1 m (30 ft)	2	1 inch	1 inch	Frame 3B	20L-GH30-A1

(1) All drive side hose kit fittings are 37 degree flare.

(2) Each hose kit contains two (2) hoses and the appropriate connectors.

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## Drive Coolant Requirements

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**IMPORTANT** Since coolant performance slowly degrades over time, we recommend replacing the drive loop coolant every two years and whenever the loop is drained for servicing.

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For the drive coolant, we recommend that you use a 50/50 pre-mix of either ethylene or propylene glycol and water with a corrosion inhibitor for the wet drive loop materials. The levels of corrosion inhibitor need to be maintained according to the manufacturer's instructions.

If a pre-mix is not used, the drive coolant must be 50/50 mix of ethylene or propylene glycol mix to **distilled** water with an appropriate corrosion inhibitor for the wet drive loop materials. **Deionized water is prohibited.** The water must have less than 50 ppm concentrations of these chemical compounds:

- Sulfate and chloride
- Hard water ions such as Mg<sup>++</sup> and Ca<sup>++</sup>

**Use of common silicate-containing, automotive-type ethylene glycol solutions are prohibited as they can damage the heat exchanger and drive and cooling module equipment.**



**ATTENTION:** The pH level, maintenance interval, and adjustment level must be followed according to the coolant and inhibitor manufacturer's recommendation. A pH level outside the range of 4...8 can cause significant damage to wetted aluminum surfaces.

---

Regardless of whether you use pre-mixed or not, the drive coolant and corrosion inhibitor must be compatible with the following materials:

- Copper
- Brass
- Aluminum
- Arimid fiber gasket with nitrile binder (Garlock, Inc. Blue-Gard 3000)
- Synthetic rubber hose (Parker Hannifan Corp 801 General Purpose Hose)
- Viton seal (only Complete Drive)

## Biocide

A biocide may be needed to control biological growth. Use of a biocide is permitted. For specific recommendations, consult a reputable water treatment company.

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**IMPORTANT** Do not mix different brands or types of coolants. The coolant, corrosion inhibitor, and any biocide used must be compatible.

---

## Drive Cooling Loop Specifications

Inhibited ethylene glycol or propylene glycol must contain a corrosion inhibitor compatible with the cooling loop material.

**Table 12 - Coolant Requirements for One Frame 2, 3A, or 3B Drive**

Drive Frame Size	Coolant Temperature Range	Minimum Coolant Flow Rate	Maximum Coolant Flow Rate	Pressure Drop <sup>(2)</sup> From Drive Inlet to Drive Outlet at Minimum Coolant Flow Rate	Coolant Type
2	0...50 °C (32...122 °F)	30.3 LPM (8 gpm)	45.4 LPM (12 gpm)	1.58 bar (23 psi)	WEG50 <sup>(3)</sup> or WPG50 <sup>(4)</sup>
3A	0...40 °C (32...104 °F)	30.3 LPM (8 gpm)	45.4 LPM (12 gpm)	0.35 bar (5 psi)	
3B	0...40 °C (32...104 °F)	56.8 LPM (15 gpm) <sup>(1)</sup>	94.6 LPM (25 gpm)	0.48 bar (7 psi) <sup>(1)</sup>	

- (1) Frame 3B includes separate converter and inverter power modules. A single inverter or converter power module requires a minimum flow rate of 30.3 LPM (8 gpm) at 0.35 bar (5 psi).
- (2) Pressure drop does not include any system connections such as hoses or piping. Cooling systems must be sized to provide minimum flow considering entire system pressure drop.
- (3) WEG50 equals good quality or distilled water with approved **inhibited\*** ethylene glycol, 50% glycol by volume.
- (4) WPG50 equals good quality or distilled water with approved **inhibited\*** propylene glycol, 50% glycol by volume.

[Table 13](#) lists the estimated amount of coolant needed for the drive loop based on the drive frame size. For recommended drive loop coolants, see [Table 12](#).

**Table 13 - Estimated Coolant Amount for the Drive Loop**

Drive Size	Estimated Amount of Coolant <sup>(1)</sup>
Frame 2	15.1 liters (4 gal)
Frame 3A	19 liters (5 gal)
Frame 3B	19 liters (5 gal)

- (1) The estimated amount of coolant is based on the heat exchanger using 1.2 m (4 ft) hoses. Longer hoses require more coolant. The maximum hose length of 9.1 m (30 ft) would require up to an additional 2.8 liters (3/4 gal).

## Programming and Parameters

This chapter provides information about specific 700 Vector Control parameters and specific 700S Phase II Control parameters that are affected when used in a PowerFlex® 700L Liquid-Cooled drive power structure.

Topic	Page
Affected 700 Vector Control Parameters	103
Affected 700S Phase II Control Parameters	107

### Affected 700 Vector Control Utility File Parameters

For the following Utility file parameters, Bit 20 is set when there is an alarm present in the Active Converter.

File	Group	No.	Parameter Name & Description	Values																																																														
<b>UTILITY</b>	<b>Diagnostic</b>	211	<p><b>[Drive Alarm 1]</b> Displays alarm conditions that presently exist in the drive.</p> <p>"Prof SetHome" will be set if the alarm is configured in [Alarm Config 1], "Prof/Indexer" is configured in [Speed/Torque Mod] and the homing routine has not been successfully completed.</p> <table border="1" style="width: 100%; border-collapse: collapse; margin-bottom: 10px;"> <thead> <tr> <th style="text-align: left;">Bit Definition</th> <th style="text-align: center;">Ground Warn</th> <th style="text-align: center;">Load Loss</th> <th style="text-align: center;">In PhaseLoss</th> <th style="text-align: center;">Motor Therm</th> <th style="text-align: center;">Waking</th> <th style="text-align: center;">Decel Inhibit</th> <th style="text-align: center;">Drv OL Lvl 2</th> <th style="text-align: center;">Drv OL Lvl 1</th> <th style="text-align: center;">IntDBRes OH</th> <th style="text-align: center;">Anlg in Loss</th> <th style="text-align: center;">Str At PwrUp</th> <th style="text-align: center;">Power Loss</th> <th style="text-align: center;">UnderVoltage</th> <th style="text-align: center;">Prechrg Actv</th> </tr> </thead> <tbody> <tr> <td>Default</td> <td style="text-align: center;">x</td> <td style="text-align: center;">0</td> <td style="text-align: center;">0</td> <td style="text-align: center;">0</td> <td style="text-align: center;">0</td> <td style="text-align: center;">0</td> <td style="text-align: center;">0</td> <td style="text-align: center;">0</td> <td style="text-align: center;">x</td> <td style="text-align: center;">0</td> <td style="text-align: center;">0</td> <td style="text-align: center;">0</td> <td style="text-align: center;">0</td> <td style="text-align: center;">0</td> </tr> <tr> <td>Bit</td> <td style="text-align: center;">15</td> <td style="text-align: center;">14</td> <td style="text-align: center;">13</td> <td style="text-align: center;">12</td> <td style="text-align: center;">11</td> <td style="text-align: center;">10</td> <td style="text-align: center;">9</td> <td style="text-align: center;">8</td> <td style="text-align: center;">7</td> <td style="text-align: center;">6</td> <td style="text-align: center;">5</td> <td style="text-align: center;">4</td> <td style="text-align: center;">3</td> <td style="text-align: center;">2</td> <td style="text-align: center;">1</td> <td style="text-align: center;">0</td> </tr> </tbody> </table> <p style="margin-left: 20px;">1 = Condition True 0 = Condition False x = Reserved</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left;">Bit Definition</th> <th style="text-align: center;">Active Cnvtr</th> <th style="text-align: center;">PTC HW</th> <th style="text-align: center;">Prof SetHome</th> <th style="text-align: center;">Adj Volt Ref</th> </tr> </thead> <tbody> <tr> <td>Default</td> <td style="text-align: center;">x</td> <td style="text-align: center;">x</td> <td style="text-align: center;">x</td> <td style="text-align: center;">x</td> </tr> <tr> <td>Bit</td> <td style="text-align: center;">31</td> <td style="text-align: center;">30</td> <td style="text-align: center;">29</td> <td style="text-align: center;">28</td> </tr> </tbody> </table> <p style="margin-left: 20px;">1 = Condition True 0 = Condition False x = Reserved</p>	Bit Definition	Ground Warn	Load Loss	In PhaseLoss	Motor Therm	Waking	Decel Inhibit	Drv OL Lvl 2	Drv OL Lvl 1	IntDBRes OH	Anlg in Loss	Str At PwrUp	Power Loss	UnderVoltage	Prechrg Actv	Default	x	0	0	0	0	0	0	0	x	0	0	0	0	0	Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Bit Definition	Active Cnvtr	PTC HW	Prof SetHome	Adj Volt Ref	Default	x	x	x	x	Bit	31	30	29	28	Read Only
		Bit Definition	Ground Warn	Load Loss	In PhaseLoss	Motor Therm	Waking	Decel Inhibit	Drv OL Lvl 2	Drv OL Lvl 1	IntDBRes OH	Anlg in Loss	Str At PwrUp	Power Loss	UnderVoltage	Prechrg Actv																																																		
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File	Group	No.	Parameter Name & Description	Values																																													
UTILITY	Diagnostic	229	<p><b>[Alarm 1 @ Fault]</b> Captures and displays [Drive Alarm 1] at the time of the last fault.</p> <table border="1"> <thead> <tr> <th>Bit Definition</th> <th>Ground Warn</th> <th>Load Loss</th> <th>In PhaseLoss</th> <th>Motor Therm</th> <th>Waking</th> <th>Decel Inhibit</th> <th>Drv OL Lvl 2</th> <th>Drv OL Lvl 1</th> <th>IntDBRes OH</th> <th>Anlg in Loss</th> <th>Str At PwrUp</th> <th>Power Loss</th> <th>Under Voltage</th> <th>Prechrg Actv</th> </tr> </thead> <tbody> <tr> <td>Default</td> <td>x</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>x</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> </tr> <tr> <td>Bit</td> <td>15</td> <td>14</td> <td>13</td> <td>12</td> <td>11</td> <td>10</td> <td>9</td> <td>8</td> <td>7</td> <td>6</td> <td>5</td> <td>4</td> <td>3</td> <td>2</td> </tr> </tbody> </table> <p>1 = Condition True 0 = Condition False x = Reserved</p>	Bit Definition	Ground Warn	Load Loss	In PhaseLoss	Motor Therm	Waking	Decel Inhibit	Drv OL Lvl 2	Drv OL Lvl 1	IntDBRes OH	Anlg in Loss	Str At PwrUp	Power Loss	Under Voltage	Prechrg Actv	Default	x	0	0	0	0	0	0	0	x	0	0	0	0	0	Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	Read Only
		Bit Definition	Ground Warn	Load Loss	In PhaseLoss	Motor Therm	Waking	Decel Inhibit	Drv OL Lvl 2	Drv OL Lvl 1	IntDBRes OH	Anlg in Loss	Str At PwrUp	Power Loss	Under Voltage	Prechrg Actv																																	
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UTILITY	Alarms	259	<p><b>[Alarm Config 1]</b> Enables/disables alarm conditions that will initiate an active drive alarm.</p> <table border="1"> <thead> <tr> <th>Bit Definition</th> <th>Ground Warn</th> <th>Load Loss</th> <th>In PhaseLoss</th> <th>Motor Therm</th> <th>Waking</th> <th>Decel Inhibit</th> <th>Drv OL Lvl 2</th> <th>Drv OL Lvl 1</th> <th>IntDBRes OH</th> <th>Anlg in Loss</th> <th>Str At PwrUp</th> <th>Power Loss</th> <th>Under Voltage</th> <th>Prechrg Actv</th> </tr> </thead> <tbody> <tr> <td>Default</td> <td>x</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>x</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> </tr> <tr> <td>Bit</td> <td>15</td> <td>14</td> <td>13</td> <td>12</td> <td>11</td> <td>10</td> <td>9</td> <td>8</td> <td>7</td> <td>6</td> <td>5</td> <td>4</td> <td>3</td> <td>2</td> </tr> </tbody> </table> <p>1 = Condition True 0 = Condition False x = Reserved</p>	Bit Definition	Ground Warn	Load Loss	In PhaseLoss	Motor Therm	Waking	Decel Inhibit	Drv OL Lvl 2	Drv OL Lvl 1	IntDBRes OH	Anlg in Loss	Str At PwrUp	Power Loss	Under Voltage	Prechrg Actv	Default	x	0	0	0	0	0	0	0	x	0	0	0	0	0	Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	Read / Write
		Bit Definition	Ground Warn	Load Loss	In PhaseLoss	Motor Therm	Waking	Decel Inhibit	Drv OL Lvl 2	Drv OL Lvl 1	IntDBRes OH	Anlg in Loss	Str At PwrUp	Power Loss	Under Voltage	Prechrg Actv																																	
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Default	x	x	x	x																																													
Bit	31	30	29	28																																													



## Communication File

For the following Communication file parameters, Bit 6 is available and is set when DPI port 6 is indicated.

File	Group	No.	Parameter Name & Description	Values																																																		
				Default:	Options:																																																	
COMMUNICATION	Comm Control	274	<b>[DPI Port Sel]</b> Selects which DPI port reference value will appear in [DPI Port Value].	1	"DPI Port 1" "DPI Port 1 - 6"																																																	
		276	<b>[Logic Mask]</b> Determines which ports can control the drive when [Write Mask Act], bit 15 is set to "1." If the bit for a port is set to "0," the port will have no control functions except for stop.  <table border="1"> <thead> <tr> <th>Bit Definition</th> <th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th> <th>DPI Port 6</th> <th>DPI Port 5</th> <th>DPI Port 4</th> <th>DPI Port 3</th> <th>DPI Port 2</th> <th>DPI Port 1</th> <th>Digital In</th> </tr> </thead> <tbody> <tr> <td>Default</td> <td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td> <td>1</td><td>1</td><td>1</td><td>1</td><td>1</td><td>1</td><td>1</td> </tr> <tr> <td>Bit</td> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td> <td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> </tbody> </table> 1 = Control Permitted 0 = Control Masked x = Reserved	Bit Definition										DPI Port 6	DPI Port 5	DPI Port 4	DPI Port 3	DPI Port 2	DPI Port 1	Digital In	Default	x	x	x	x	x	x	x	x	x	1	1	1	1	1	1	1	Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	Bit Definition										DPI Port 6	DPI Port 5	DPI Port 4	DPI Port 3	DPI Port 2	DPI Port 1	Digital In																																					
	Default	x	x	x	x	x	x	x	x	x	1	1	1	1	1	1	1																																					
	Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																																					
	277	<b>[Start Mask]</b> Controls which adapters can issue start commands.	See [Logic Mask]																																																			
	278	<b>[Jog Mask]</b> Controls which adapters can issue jog commands.	See [Logic Mask]																																																			
	279	<b>[Direction Mask]</b> Controls which adapters can issue forward/reverse commands.	See [Logic Mask]																																																			
	280	<b>[Reference Mask]</b> Controls which adapters can select an alternate reference; [Speed Ref A, B Sel] or [Preset Speed 1-7].	See [Logic Mask]																																																			
	281	<b>[Accel Mask]</b> Controls which adapters can select [Accel Time 1, 2].	See [Logic Mask]																																																			
	282	<b>[Decel Mask]</b> Controls which adapters can select [Decel Time 1, 2].	See [Logic Mask]																																																			
	283	<b>[Fault Clr Mask]</b> Controls which adapters can clear a fault.	See [Logic Mask]																																																			
	284	<b>[MOP Mask]</b> Controls which adapters can issue MOP commands to the drive.	See [Logic Mask]																																																			
	285	<b>[Local Mask]</b> Controls which adapters are allowed to take exclusive control of drive logic commands (except stop). Exclusive "local" control can only be taken while the drive is stopped.	See [Logic Mask]																																																			
288	<b>[Stop Owner]</b> Adapters that are presently issuing a valid stop command.  <table border="1"> <thead> <tr> <th>Bit Definition</th> <th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th> <th>DPI Port 6</th> <th>DPI Port 5</th> <th>DPI Port 4</th> <th>DPI Port 3</th> <th>DPI Port 2</th> <th>DPI Port 1</th> <th>Digital In</th> </tr> </thead> <tbody> <tr> <td>Default</td> <td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td> <td>1</td><td>1</td><td>1</td><td>1</td><td>1</td><td>1</td><td>1</td> </tr> <tr> <td>Bit</td> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td> <td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> </tbody> </table> 1 = Issuing Command 0 = No Command x = Reserved	Bit Definition										DPI Port 6	DPI Port 5	DPI Port 4	DPI Port 3	DPI Port 2	DPI Port 1	Digital In	Default	x	x	x	x	x	x	x	x	x	1	1	1	1	1	1	1	Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Read Only	
Bit Definition										DPI Port 6	DPI Port 5	DPI Port 4	DPI Port 3	DPI Port 2	DPI Port 1	Digital In																																						
Default	x	x	x	x	x	x	x	x	x	1	1	1	1	1	1	1																																						
Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																																						
289	<b>[Start Owner]</b> Adapters that are presently issuing a valid start command.	See [Stop Owner]																																																				
290	<b>[Jog Owner]</b> Adapters that are presently issuing a valid jog command.	See [Stop Owner]																																																				

File	Group	No.	Parameter Name & Description	Values
COMMUNICATION	Masks & Owners	291	<b>[Direction Owner]</b> Adapter that presently has exclusive control of direction changes.	See [Stop Owner]
		292	<b>[Reference Owner]</b> Adapter that has the exclusive control of the command frequency source selection.	See [Stop Owner]
		293	<b>[Accel Owner]</b> Adapter that has exclusive control selecting [Accel Time 1, 2].	See [Stop Owner]
		294	<b>[Decel Owner]</b> Adapter that has exclusive control selecting [Decel Time 1, 2].	See [Stop Owner]
		295	<b>[Fault Clr Owner]</b> Adapter that is presently clearing a fault.	See [Stop Owner]
		296	<b>[MOP Owner]</b> Adapters that are presently issuing increases or decreases in MOP command frequency.	See [Stop Owner]
		297	<b>[Local Owner]</b> Adapter that has requested exclusive control of all drive logic functions. If an adapter is in local lockout, all other functions (except stop) on all other adapters are locked out and non-functional. Local control can only be obtained when the drive is not running.	See [Stop Owner]
		595	<b>[Port Mask Act]</b> Bits 0-6 indicate status for DPI port communications. Bit 15 indicates when security software is controlling the parameter.	Read Only
		596	<b>[Write Mask Cfg]</b> Enables/disables write access (parameters, links, etc.) for DPI ports. Changes to this parameter only become effective when power is cycled, the drive is reset, or bit 15 of [Write Mask Actv] transitions from "1" to "0."	Read / Write
		597	<b>[Write Mask Act]</b> Status of write access for DPI ports. When bit 15 is set, network security is controlling the write mask instead of [Write Mask Cfg].	Read Only
598	<b>[Logic Mask Act]</b> Indicates status of the logic mask for DPI ports. When bit 15 is set, network security is controlling the logic mask instead of [Logic Mask].	Read Only		

Bit Definition	Security									DPI Port 6	DPI Port 5	DPI Port 4	DPI Port 3	DPI Port 2	DPI Port 1	Host
Default	0	x	x	x	x	x	x	x	x	1	1	1	1	1	1	1
Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

1 = Active  
0 = Not Active  
x = Reserved

Bit Definition										DPI Port 6	DPI Port 5	DPI Port 4	DPI Port 3	DPI Port 2	DPI Port 1	
Default	x	x	x	x	x	x	x	x	x	1	1	1	1	1	1	x
Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

1 = Write Permitted  
0 = Read Only  
x = Reserved

Bit Definition	Security									DPI Port 6	DPI Port 5	DPI Port 4	DPI Port 3	DPI Port 2	DPI Port 1	
Default	0	x	x	x	x	x	x	x	x	1	1	1	1	1	1	x
Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

1 = Write Permitted  
0 = Read Only  
x = Reserved

Bit Definition	Security									DPI Port 6	DPI Port 5	DPI Port 4	DPI Port 3	DPI Port 2	DPI Port 1	Digital In
Default	0	x	x	x	x	x	x	x	x	1	1	1	1	1	1	1
Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

1 = Control Permitted  
0 = Control Masked  
x = Reserved

## Affected 700S Phase II Control Parameters

When a PowerFlex 700L Liquid-Cooled drive is present, the following 700S Phase II Control functions are affected:

- Supports DPI communication ports 1 through 6.
- Supports DPI Type III communication with an active converter.
- Supports the power structure fault latch and multiple NTCs.
- Supports IT (Junction Temperature Calculation) mode.
- Bus regulator mode is disabled when an active converter is present.
- Fast Flux-up current is limited to 40% of motor nameplate current instead of 70% (PowerFlex 700S).

## Utility File

In the Utility file - Diagnostics group, the following parameters are available when a PowerFlex 700L Liquid-Cooled AC drive is present.

No.	Name Description	Values																																																																																																		
332	<p><b>700L EventStatus</b></p> <p>Indicates the presence of certain drive anomalies for the PowerFlex 700L Liquid-Cooled drive.</p> <p>Bit 0 [Dsat Phs U1] indicates that the primary structure detected a Dsat on phase U.</p> <p>Bit 1 [Dsat Phs V1] indicates that the primary structure detected a Dsat on phase V.</p> <p>Bit 2 [Dsat Phs W] indicates that the primary structure detected a Dsat on phase W.</p> <p>Bit 3 [Ovr Current1] indicates that the primary structure detected an over current.</p> <p>Bit 4 [Ovr Volt1] indicates that the primary structure detected an over voltage.</p> <p>Bit 5 [Asym Dclink1] indicates that the primary structure detected an unbalanced DC Link.</p> <p>Bit 6 [Pwr Suply1] indicates that the primary structure detected a power supply failure.</p> <p>Bit 7 [HW Disable1] indicates that the primary structure detected a hardware disable.</p> <p>Bit 8 [Latch Err1] indicates that the primary structure fault was generated but no indicating bit was set.</p> <p>Bit 9 [Fan Fail1] indicates</p> <p>Bit 12 [NonCnfgAlarm] indicates</p> <p>Bit 13 [Cnv Faulted] indicates</p> <p>Bit 14 [Cnv NotLogin] indicates the converter was expected but none logged in.</p> <p>Bit 15 [Cnv NotStart] indicates the converter was commanded to start but did not become active.</p> <p>Bit 16 [Dsat Phs U2] indicates the second structure detected a Dsat on phase U.</p> <p>Bit 17 [Dsat Phs V2] indicates the second structure detected a Dsat on phase V.</p> <p>Bit 18 [Dsat Phs W2] indicates the second structure detected a Dsat on phase W.</p> <p>Bit 19 [Ovr Current2] indicates the second structure detected an over current.</p> <p>Bit 20 [Ovr Volt2] indicates the second structure detected an over voltage.</p> <p>Bit 21 [Asym Dclink2] indicates the second structure detected an unbalanced DC Link.</p> <p>Bit 22 [Pwr Suply2] indicates the second structure detected a power supply failure.</p> <p>Bit 23 [HW Disable2] indicates the second structure detected a hardware disable.</p> <p>Bit 24 [Latch Err2] indicates the second structure fault was generated but no indicating bit was set.</p> <p>Bit 25 [Fan Fail2] indicates</p> <p>Note: This parameter was added for firmware version 2.03.</p>	Read Only																																																																																																		
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Bit Definition	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Fan Fail2	Latch Err2	HW Disable2	Pwr Suply2	Asym Dclink2	Ovr Volt2	Ovr Current2	Dsat Phs W2	Dsat Phs V2	Dsat Phs U2	Cnv NotStart	Cnv NotLogin	Cnv Faulted	NonCnfgAlarm	Reserved	Reserved	Fan Fail1	Latch Err1	HW Disable1	Pwr Suply1	Asym Dclink1	Ovr Volt1	Ovr Current1	Dsat Phs W1	Dsat Phs V1	Dsat Phs U1																																																																				
Default	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0																																																																					
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333	<p><b>700L FaultStatus</b></p> <p>Indicates the occurrence of exception events that have been configured as fault conditions for the PowerFlex 700L Liquid-Cooled drive.</p> <p>Bit 0 [Dsat Phs U1] indicates that the primary structure detected a Dsat on phase U.</p> <p>Bit 1 [Dsat Phs V1] indicates that the primary structure detected a Dsat on phase V.</p> <p>Bit 2 [Dsat Phs W1] indicates that the primary structure detected a Dsat on phase W.</p> <p>Bit 3 [Ovr Current1] indicates that the primary structure detected an over current.</p> <p>Bit 4 [Ovr Volt1] indicates that the primary structure detected an over voltage.</p> <p>Bit 5 [Asym DcLink1] indicates that the primary structure detected an unbalanced DC Link.</p> <p>Bit 6 [Pwr Suply1] indicates that the primary structure detected a power supply failure.</p> <p>Bit 7 [HW Disable1] indicates that the primary structure detected a hardware disable.</p> <p>Bit 8 [Latch Err1] indicates that the primary structure fault was generated but no indicating bit was set.</p> <p>Bit 9 [Fan Fail1] indicates</p> <p>Bit 12 [NonCnfgAlarm] indicates</p> <p>Bit 13 [Cnv Faulted] indicates</p> <p>Bit 14 [Cnv NotLogin] indicates that the converter expected but none logged in.</p> <p>Bit 15 [Cnv NotStart] indicates that the converter commanded to start but did not become active.</p> <p>Bit 16 [Dsat Phs U2] indicates that the second structure detected a Dsat on phase U.</p> <p>Bit 17 [Dsat Phs V2] indicates that the second structure detected a Dsat on phase V.</p> <p>Bit 18 [Dsat Phs W2] indicates that the second structure detected a Dsat on phase W.</p> <p>Bit 19 [Ovr Current2] indicates that the second structure detected an over current.</p> <p>Bit 20 [Ovr Volt2] indicates that the second structure detected an over voltage.</p> <p>Bit 21 [Asym DcLink2] indicates that the second structure detected an unbalanced DC Link.</p> <p>Bit 22 [Pwr Suply2] indicates that the second structure detected a power supply failure.</p> <p>Bit 23 [HW Disable2] indicates that the second structure detected a hardware disable.</p> <p>Bit 24 [Latch Err2] indicates that the second structure fault was generated but no indicating bit was set.</p> <p>Bit 25 [Fan Fail2] indicates</p> <p>Note: This parameter was added for firmware version 2.03.</p>	Read Only																																																																																																		
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No.	Name Description	Values																																																																																																		
334	<p><b>700L AlarmStatus</b></p> <p>Indicates the occurrence of exception events that have been configured as alarm conditions for the PowerFlex 700L Liquid-Cooled drive.</p> <p>Bit 0 [NonCnfgFault] Not configured as alarm.                      Bit 1 [NonCnfgFault] Not configured as alarm.                      Bit 2 [NonCnfgFault] Not configured as alarm.                      Bit 3 [NonCnfgFault] Not configured as alarm.                      Bit 4 [NonCnfgFault] Not configured as alarm.                      Bit 5 [NonCnfgFault] Not configured as alarm.                      Bit 6 [NonCnfgFault] Not configured as alarm.                      Bit 7 [NonCnfgFault] Not configured as alarm.                      Bit 8 [NonCnfgFault] Not configured as alarm.                      Bit 9 [NonCnfgFault] Not configured as alarm.                      Bit 10 [NonCnfgFault] Not configured as alarm.                      Bit 11 [NonCnfgFault] Not configured as alarm.                      Bit 12 [Cnv Alarm]                      Bit 13 [NonCnfgFault] Not configured as alarm.                      Bit 14 [Cnv NotLogin]                      Bit 15 [NonCnfgFault] Not configured as alarm.                      Bit 16 [NonCnfgFault] Not configured as alarm.                      Bit 17 [NonCnfgFault] Not configured as alarm.                      Bit 18 [NonCnfgFault] Not configured as alarm.                      Bit 19 [NonCnfgFault] Not configured as alarm.                      Bit 20 [NonCnfgFault] Not configured as alarm.                      Bit 21 [NonCnfgFault] Not configured as alarm.                      Bit 22 [NonCnfgFault] Not configured as alarm.                      Bit 23 [NonCnfgFault] Not configured as alarm.                      Bit 24 [NonCnfgFault] Not configured as alarm.                      Bit 25 [NonCnfgFault] Not configured as alarm.                      Bit 26 [NonCnfgFault] Not configured as alarm.                      Bit 27 [NonCnfgFault] Not configured as alarm.                      Bit 28 [NonCnfgFault] Not configured as alarm.                      Bit 29 [NonCnfgFault] Not configured as alarm.                      Bit 30 [NonCnfgFault] Not configured as alarm.                      Bit 31 [NonCnfgFault] Not configured as alarm.</p> <p>Note: This parameter was added for firmware version 2.03.</p>	Read Only																																																																																																		
	<table border="1"> <thead> <tr> <th>Bit Definition</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>Cnv Alarm</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> <th>NonCnfgFault</th> </tr> </thead> <tbody> <tr> <td>Default</td> <td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td> </tr> <tr> <td>Bit</td> <td>31</td><td>30</td><td>29</td><td>28</td><td>27</td><td>26</td><td>25</td><td>24</td><td>23</td><td>22</td><td>21</td><td>20</td><td>19</td><td>18</td><td>17</td><td>16</td><td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> </tbody> </table>	Bit Definition	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	Cnv Alarm	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	NonCnfgFault	Default	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Bit	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	0 = False 1 = True
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No.	Name Description	Values																																																									
420	<p><b>Pwr Strct Mode</b></p> <p>Displays the power structure used in the drive. This is an identifier to the firmware for power structure control.</p> <p>Bit 0 = PowerFlex 700S Frame 1 to 6 (Lo Pwr Strct)</p> <p>Bit 1 = PowerFlex 700S above Frame 6 (Hi Pwr Strct)</p> <p>Bit 2 = PowerFlex 700L</p> <p>Bit 3 = PowerFlex 700S Frame 12</p> <p><b>NOTE:</b> Bit 3 [Parallel Drv] was added for firmware version 3.01.</p> <table border="1" data-bbox="214 499 824 659"> <thead> <tr> <th data-bbox="214 499 293 583">Bit Definition</th> <th data-bbox="293 499 321 583">Reserved</th> <th data-bbox="321 499 349 583">Reserved</th> <th data-bbox="349 499 376 583">Reserved</th> <th data-bbox="376 499 404 583">Reserved</th> <th data-bbox="404 499 431 583">Reserved</th> <th data-bbox="431 499 459 583">Reserved</th> <th data-bbox="459 499 487 583">Reserved</th> <th data-bbox="487 499 514 583">Reserved</th> <th data-bbox="514 499 542 583">Reserved</th> <th data-bbox="542 499 570 583">Reserved</th> <th data-bbox="570 499 597 583">Reserved</th> <th data-bbox="597 499 625 583">Reserved</th> <th data-bbox="625 499 652 583">Reserved</th> <th data-bbox="652 499 680 583">Reserved</th> <th data-bbox="680 499 708 583">Parallel Drv</th> <th data-bbox="708 499 735 583">PF 700L</th> <th data-bbox="735 499 763 583">Hi Pwr Strct</th> <th data-bbox="763 499 790 583">Lo PwrStrct</th> </tr> </thead> <tbody> <tr> <td data-bbox="214 583 293 619">Default</td> <td data-bbox="293 583 321 619">0</td> <td data-bbox="321 583 349 619">0</td> <td data-bbox="349 583 376 619">0</td> <td data-bbox="376 583 404 619">0</td> <td data-bbox="404 583 431 619">0</td> <td data-bbox="431 583 459 619">0</td> <td data-bbox="459 583 487 619">0</td> <td data-bbox="487 583 514 619">0</td> <td data-bbox="514 583 542 619">0</td> <td data-bbox="542 583 570 619">0</td> <td data-bbox="570 583 597 619">0</td> <td data-bbox="597 583 625 619">0</td> <td data-bbox="625 583 652 619">0</td> <td data-bbox="652 583 680 619">0</td> <td data-bbox="680 583 708 619">0</td> <td data-bbox="708 583 735 619">0</td> <td data-bbox="735 583 763 619">0</td> <td data-bbox="763 583 790 619">0</td> </tr> <tr> <td data-bbox="214 619 293 655">Bit</td> <td data-bbox="293 619 321 655">15</td> <td data-bbox="321 619 349 655">14</td> <td data-bbox="349 619 376 655">13</td> <td data-bbox="376 619 404 655">12</td> <td data-bbox="404 619 431 655">11</td> <td data-bbox="431 619 459 655">10</td> <td data-bbox="459 619 487 655">9</td> <td data-bbox="487 619 514 655">8</td> <td data-bbox="514 619 542 655">7</td> <td data-bbox="542 619 570 655">6</td> <td data-bbox="570 619 597 655">5</td> <td data-bbox="597 619 625 655">4</td> <td data-bbox="625 619 652 655">3</td> <td data-bbox="652 619 680 655">2</td> <td data-bbox="680 619 708 655">1</td> <td data-bbox="708 619 735 655">0</td> <td data-bbox="735 619 763 655">0</td> <td data-bbox="763 619 790 655">0</td> </tr> </tbody> </table> <p data-bbox="834 619 911 667">0 = False 1 = True</p>	Bit Definition	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Parallel Drv	PF 700L	Hi Pwr Strct	Lo PwrStrct	Default	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	0	0	Read Only
Bit Definition	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Parallel Drv	PF 700L	Hi Pwr Strct	Lo PwrStrct																																									
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## Troubleshooting

This chapter provides information to guide you in troubleshooting the PowerFlex® 700L Liquid-Cooled AC drive. Included is a listing and description of faults (with possible solutions, when applicable) and alarms.

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### Faults and Alarms

A fault is a condition that stops the drive. There are two fault types. Refer to documentation for the control option installed for specific fault and alarm information. Refer to [Additional Resources](#) for a list of publications.

Type	Fault Description	
1	Reserved for future.	
2	Non-Resettable	This type of fault normally requires drive or motor repair. The cause of the fault must be corrected before the fault can be cleared. The fault will be reset on power up after repair.
3	User Configurable	These faults can be enabled/disabled to annunciate or ignore a fault condition.

An alarm is a condition that, if left untreated, can stop the drive. There are two alarm types.

Type	Fault Description	
1	User Configurable	These alarms can be enabled/disabled through [Alarm Config 1].
2	Non-Configurable	These alarms are always enabled.

### Drive Status

The condition or state of your drive is constantly monitored. Any changes will be indicated through the LEDs and/or the HIM (if present).

## Frame 2 Drive LED Indicators

Status indicators for Frame 2 drives are located near the top and front of the drive (see [Figure 4](#)). For drive status indications, see [Table 14](#).

## Accessing Status Indicators of Powered Frame 3A and 3B Complete Drives

Status indicators (shown in [Table 14](#)) for Frame 3A and 3B complete drives are inside the power module bay. To access the status indicators, follow the instructions below.

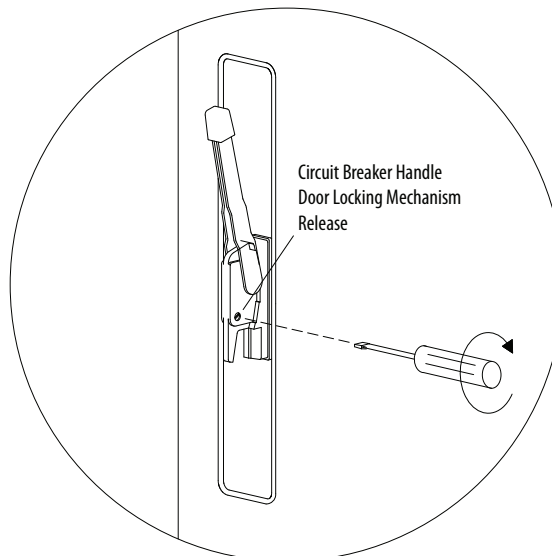


**ATTENTION:** Risk of injury or death exists. Only qualified electricians should use this procedure. Bypassing the interlock mechanism exposes the user to dangerous high voltage live components. Failure to comply can result in personal injury and/or death.

*To Open:*

1. Unlock the input filter bay door and the power module bay door by using the key provided with the drive.
2. Turn the circuit breaker handle door locking mechanism release with a flat head screwdriver ([Figure 69](#)) to unlatch the input filter bay door.

**Figure 69 - Releasing Door Locking Mechanism**



3. Swing open the input filter bay several inches until the door interlock mechanism unlatches from the power module bay door.
4. Swing open the power module bay door to view the status indicators on the power module(s).



To Close:

1. Close and lock the power module bay door.
2. Close and lock the input filter bay door.

**Table 14 - Status Indications**

Item	Name	Color	State	Description
1	PWR	Green	Steady	Illuminates when power is applied to the drive.
2	STS (Status)	Green	Flashing	Drive ready, but not running and no faults are present.
			Steady	Drive running, no faults are present.
		Yellow	Flashing, Drive Stopped	A type 2 alarm condition exists, the drive cannot be started. Check parameter 211 [Drive Alarm 2].
			Flashing, Drive Running	An intermittent type 1 alarm condition is occurring. Check parameter 211 [Drive Alarm 1].
			Steady, Drive Running	A continuous type 1 alarm condition exists. Check parameter 211 [Drive Alarm 1].
		Red	Flashing	Fault has occurred. Check [Fault x Code] or Fault Queue.
Steady	A non-resettable fault has occurred.			
3	PORT	See the 20-COMM-x Communication Adapter User Manual.		Status of DPI port internal communications (if present).
	MOD			Status of communications module (when installed).
	NET A			Status of network (if connected).
	NET B			Status of secondary network (if connected).


## HIM Indication

The LCD HIM also provides visual notification of a fault or alarm condition.

Condition	Display
<p><b>Drive is indicating a fault.</b></p> <p>The LCD HIM immediately reports the fault condition by displaying the following information:</p> <ul style="list-style-type: none"> <li>• "Faulted" appears in the status line</li> <li>• Fault number</li> <li>• Fault name</li> <li>• Time that has passed since fault occurred</li> </ul> <p>Press ESC to regain HIM control.</p>	
<p><b>Drive is indicating an alarm.</b></p> <p>The LCD HIM immediately reports the alarm condition by displaying the following information:</p> <ul style="list-style-type: none"> <li>• Alarm name (Type 2 alarms only)</li> <li>• Alarm bell graphic</li> </ul>	

## Manually Clearing Faults


To manually clear faults, follow these steps.

1. Press the  (Escape) key to acknowledge the fault.

The fault information is removed so that you can use the HIM.

2. Address the condition that caused the fault.

The cause must be corrected before the fault can be cleared.

3. After corrective action has been taken, clear the fault by using **one** of these methods:
  - Press the  (Stop) key.
  - Cycle drive power.
  - Set parameter 240- [Fault Clear] to "1" (Clear Faults) - for the PowerFlex 700 vector control.
  - "Clear Faults" on the HIM Diagnostic menu.

## Converter Faults

When a fault is generated in the Converter, that fault is passed to the Inverter so all the faults are recorded in the Inverter fault queue. Faults in the converter are numbered 1 to 99.

When using PowerFlex 700 Vector Control, the fault from the Converter is added to a base number of 300, so all the Converter faults are numbered 301 to 399. The pop-up window on the HIM alerts the user to look at the fault log in the PF700AC to get the specific fault text.

<p>- Fault - F 340                  F340 See PF700AC                  Time Since Fault                  00000:00:01</p>
---

When using PowerFlex 700S Phase II Control, the faults from the Converter are all combined into one fault code (F110) in the Inverter. The pop-up window on the HIM alerts the user to look at the fault log in the PF700AC to get the specific fault text.

<p>- Fault - F 110                  700L Cnv Faulted                  Time Since Fault                  00000:00:01</p>
---

For a complete listing of Converter faults, descriptions, and actions, see the PowerFlex 700L Active Converter User Manual, publication [PFLEX-UM002](#).

# 700 Vector Control Fault Descriptions

**Table 15 - 700 Vector Control Fault Types, Descriptions, and Actions**

Fault	No.	Type <sup>(1)</sup>	Description	Action
Port 6 Adapter	F76		Communication adapter on DPI port 6 reported a fault.	Check communication cable and check adapter fault queue for information about the fault.
Port 6 DPI Loss	F86		DPI Communications to port 6 was lost.	If adapter was not intentionally disconnected, check wiring. Replace wiring, port expander, or Main Control Board as needed. Check HIM connection.
700L Dsat U	F170		Phase U Dsat fault on 700L power structure.	Contact Technical Support.
700L Dsat V	F171		Phase V Dsat fault on 700L power structure.	Contact Technical Support.
700L Dsat W	F172		Phase W Dsat fault on 700L power structure.	Contact Technical Support.
700L OvrCurnt	F173		Over current on 700L power structure.	Check programming. Check for cause of excessive current.
700L OvrVolt	F174		Over voltage on 700L power structure.	Check programming. Check for cause of excessive voltage.
700L Asym Vdc	F175		Asymmetrical voltage on the 700L power structure dc link.	Verify load balance resistors.
700L PwrSply	F176		Power supply failed on 700L power structure.	Replace power supply if problem persists.
700L HW Disable	F177		Hardware disable asserted on 700L power structure.	Verify drive enable is present.
700L Latch Err	F178		Fault reporting failure on 700L power structure.	Contact Technical Support.
700L Fan Loss	F179		Fan failure on 700L power structure.	Verify internal circulating fans are turning.
700L Dsat U	F180		Phase U Dsat fault on secondary 700L power structure.	Contact Technical Support.
700L Dsat V	F181		Phase V Dsat fault on secondary 700L power structure.	Contact Technical Support.
700L Dsat W	F182		Phase W Dsat fault on secondary 700L power structure.	Contact Technical Support.
700L OvrCurnt	F183		Over current on secondary 700L power structure.	Check programming. Check for cause of excessive current.
700L OvrVolt	F184		Over voltage on secondary 700L power structure.	Check programming. Check for cause of excessive voltage.
700L Asym Vdc	F185		Asymmetrical voltage on secondary 700L power structure dc link.	Verify load balance resistors.
700L PwrSply	F186		Power supply failed on secondary 700L power structure.	Replace power supply if problem persists.
700L HW Disable	F187		Hardware disable asserted on secondary 700L power structure.	Verify drive enable is present.
700L Latch Err	F188		Fault reporting failure on secondary 700L power structure.	Contact Technical Support.
700L Fan Loss	F189		Fan failure on secondary 700L power structure.	Verify internal circulating fans are turning.
Cnvtr Not Login	F190		Active converter did not begin communication.	Check DPI connection. Check for proper versions.
Cnvtr Not Start	F191		Active converter did not start when requested.	Check start inhibits. Check parameter 214 - [Start Inhibit].
700L NTC Open	F192		Thermal sensor failed on 700L power structure.	Contact Technical Support.

(1) See [page 111](#) for a description of fault types.

## 700S Phase II Control Fault Descriptions

Table 16 - 700S Phase II Control Fault Types, Descriptions, and Actions

Fault	No.	Type <sup>(1)</sup>	Description	Action
700L Dsat Phs U1	F097		Phase U Dsat fault on 700L power structure.	Contact Technical Support.
700L Dsat Phs V1	F098		Phase V Dsat fault on 700L power structure.	Contact Technical Support.
700L Dsat Phs W1	F099		Phase W Dsat fault on 700L power structure.	Contact Technical Support.
700L Ovr Current1	F100		Over current on 700L power structure.	Check programming. Check for cause of excessive current.
700L Ovr Volt1	F101		Over voltage on 700L power structure.	Check programming. Check for cause of excessive voltage.
700L AsymDcLink1	F102		Asymmetrical voltage on the 700L power structure dc link.	Verify load balance resistors.
700L Pwr Suply1	F103		Power supply failed on 700L power structure.	Replace power supply if problem persists.
700L HW Disable1	F104		Hardware disable asserted on 700L power structure.	Verify drive enable is present.
700L Latch Err1	F105		Fault reporting failure on 700L power structure.	Contact Technical Support.
700L Fan Fail1	F106		Fan failure on 700L power structure.	Verify internal circulating fans are turning.
700L Cnv Faulted	F110		Active converter has faulted.	Check active converter fault log.
Cnv NotLogin	F111		Active converter did not begin communication.	Check DPI connection. Check for proper versions.
Cnv NotStart	F112		Active converter did not start when requested.	Check start inhibits. Check parameter 214 - [Start Inhibits].
700L Dsat Phs U2	F113		Phase U Dsat fault on secondary 700L power structure.	Contact Technical Support.
700L Dsat Phs V2	F114		Phase V Dsat fault on secondary 700L power structure.	Contact Technical Support.
700L Dsat Phs W2	F115		Phase W Dsat fault on secondary 700L power structure.	Contact Technical Support.
700L Ovr Current2	F116		Over current on secondary 700L power structure.	Check programming. Check for cause of excessive current.
700L Ovr Volt2	F117		Over voltage on secondary 700L power structure.	Check programming. Check for cause of excessive voltage.
700L AsymDcLink2	F118		Asymmetrical voltage on secondary 700L power structure dc link.	Verify load balance resistors.
700L Pwr Suply2	F119		Power supply failed on secondary 700L power structure.	Replace power supply if problem persists.
700L HW Disable2	F120		Hardware disable asserted on secondary 700L power structure.	Verify drive enable is present.
700L Latch Err2	F121		Fault reporting failure on secondary 700L power structure.	Contact Technical Support.
700L Fan Fail2	F122		Fan failure on secondary 700L power structure.	Verify internal circulating fans are turning.

(1) See [page 111](#) for a description of fault types.

## Clearing Alarms

Alarms are automatically cleared when the condition that caused the alarm is no longer present.

## Alarm Descriptions (only 700S Phase II Control)

The following alarm can occur when the PowerFlex 700L Liquid-Cooled AC drive is equipped with the optional 700S Phase II Control cassette.

**Table 17 - 700S Phase II Control Alarm Descriptions**

Alarm	No.	Type <sup>(1)</sup>	Description
700L Cnv Alarm	A109	Á	Indicates an alarm in the Active Converter control has occurred. See the Active Converter User Manual for alarm descriptions.

(1) See [page 111](#) for a description of alarm types.

## Replacement of Door Filter of the Input Filter Cabinet (Frames 3A and 3B)



**ATTENTION:** Only qualified personnel familiar with adjustable frequency AC drives and associated machinery should plan or implement the installation, start-up, and subsequent maintenance of the system. Failure to comply can result in personal injury and/or equipment damage.

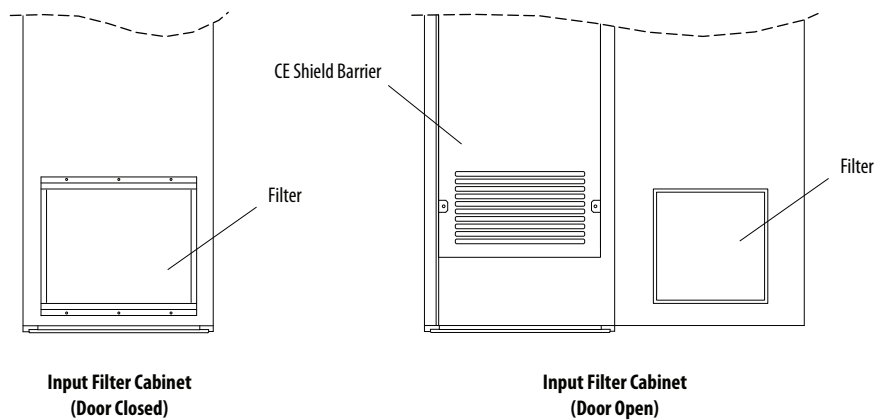


**ATTENTION:** To avoid an electric shock hazard, verify that the voltage on the bus capacitors has discharged completely before servicing. After removing power to the drive, wait 5 minutes for the bus capacitors to discharge. Measure the DC bus voltage at the DC+ and DC- TESTPOINT sockets on the front of the power module ([Figure 36](#) or [Figure 49](#)). The voltage must be zero.

When the door filter of the Input Filter Cabinet requires replacement, remove the dirty filter and replace it with an equivalent clean filter.

**IMPORTANT** If the CE Shield Barrier has been removed for servicing, it must be reinstalled to restore the casual touch protection this barrier provides.

**Figure 70 - Input Filter Cabinet Door Filter Replacement**



**Notes:**

## Supplemental Drive Information

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Watts Loss	125
Fuse and Circuit Breaker Ratings	125

### Specifications

Category	Specification
	Frame 2 Frames 3A and 3B
<b>Agency Certification</b>	<p>Listed to UL508C and CAN/CSA-C274. UL Listing for frame 2 is applicable up to 480V AC. UL Listing for frame 3A and 3B is applicable up to 600V AC.</p> <p>Australian Communications and Media Authority In conformity with the following: Radiocommunications Act: 1992 (including Amendments up to 2018) Radiocommunications (Electromagnetic Compatibility) Standard 2017 Radiocommunications Labeling (Electromagnetic Compatibility) Notice 2017 Standards applied: EN61800-3</p> <p>These drives are also designed to meet the following specifications: NFPA 70 - US National Electrical Code NEMA ICS 3.1 - Safety standards for Construction and Guide for Selection, Installation and Operation of Adjustable Speed Drive Systems. IEC 146 - International Electrical Code. CMAA Specification #70 (Crane Manufacturers of America Association)</p>

Resource	Description
<a href="#">PowerFlex Certifications</a> website	Provides declarations of conformity, certificates, and other certification details.

Unless otherwise noted, the following specifications pertain to drives equipped with 700 Vector Control or 700S Phase II Control.

### Derating Guidelines

#### Altitude

Above 1000 m (3280 ft), derate the output current by 1% for every 100 additional meters (328 additional feet). This is applicable to filters and power modules. PowerFlex 700L 600/690V drives cannot be used in altitudes above 2000 m (6562 ft) due to voltage spacing requirements.

Category	Specification						
		Frame 2		Frames 3A and 3B			
<b>Protection</b>		<b>400V</b>	<b>480V</b>	<b>400V</b>	<b>480V</b>	<b>600V</b>	<b>690V</b>
	AC Input Overvoltage Trip:	528V AC	528V AC	528V AC	528V AC	760V AC	760V AC
	AC Input Undervoltage Trip:	340V AC	340V AC	340V AC	340V AC	340V AC	340V AC
	Bus Overvoltage Trip:	815V DC	815V DC	815V DC	815V DC	1168V DC	1168V DC
	Bus Undervoltage Shutoff/Fault:	305V DC	305V DC	305V DC	305V DC	382V DC	382V DC
	Nominal Bus Voltage:	600V DC	700V DC	600V DC	700V DC	900V DC	1000V DC
	Heat Sink Thermistor:	Monitored by microprocessor overtemp trip					
	Drive Overcurrent Trip Software Overcurrent Trip: Hardware Overcurrent Trip:	200% of rated current (typical) 220...300% of rated current (dependent on drive rating)					
	Line Transients:	Up to 6000 volts peak per IEEE C62.41-1991					
	Control Logic Noise Immunity:	Showering arc transients up to 1500V peak					
<b>Protection (continued)</b>	Logic Control Ride-Thru Vector Control:	0.5 seconds minimum, 2 seconds typical					
	700S Phase II Control:	0.25 seconds, drive not running					
	Ground Fault Trip:	Phase-to-ground on drive output					
	Short Circuit Trip:	Phase-to-phase on drive output					
	<b>Environment</b>	Altitude:	1000 m (3280 ft) at rated current. See <a href="#">Derating Guidelines on page 119</a> for operation above 1000 m (3280 ft).				
Maximum Surrounding Air Temperature w/o Derating: IP20, NEMA/UL Type 1:	0...50 °C (32...122 °F)		0...40 °C (32...104 °F)				
Storage Temperature (all constructions):	-40...85 °C (-40...185 °F)						
Atmosphere:	<p style="text-align: center;"><b>IMPORTANT</b> Drive must not be installed in an area where the ambient atmosphere contains volatile or corrosive gas, vapors or dust. If the drive is not going to be installed for a period of time, it must be stored in an area where it will not be exposed to a corrosive atmosphere.</p>						
Relative Humidity:	5...95% non-condensing						
Shock:	10 g peak for 11 milliseconds duration (± 1.0 ms), three shocks in each direction, in each axis						
Vibration:	<ul style="list-style-type: none"> <li>• 2 mm (0.07 in.) displacement, 1 g peak amplitude</li> <li>• 1 mm (0.04 in.) displacement from 2...13.2 Hz</li> <li>• 0.7 g acceleration at 13.2 Hz to 1.0 g acceleration at 55 Hz</li> <li>• 1 g acceleration from 55 ...512 Hz</li> </ul> Duration: Ten logarithmic sine sweep cycles per axis, at sweep rate of one octave per minute, sequentially performed in each of the three mutually perpendicular axes.						
Sound:	Frame 2: Not available at time of publication.		Frame 3A: 78 dB		Frame 3B: 76 dB		
	Note: Sound pressure level is measured at 1 meter.						



Category	Specification		
		Frame 2	Frames 3A and 3B
<b>Electrical</b>	Voltage Tolerance		
	Vector Control:	For full power and operating range, see the PowerFlex® 700 Adjustable Frequency AC Drive—Series B User Manual, publication <a href="#">20B-UM002</a> , Appendix C.	
	700S Phase II Control:	For full power and operating range, see the PowerFlex 700S High Performance AC Drive—Phase II Control User Manual, publication <a href="#">20D-PM001</a> , Appendix C.	
	Input Frequency Tolerance:	47...63 Hz.	
	Input Phases:	Three-phase input provides full rating for all drives.	
	Displacement Power Factor:	0.98 across entire speed range.	
	Efficiency:	96.2% at rated amps, nominal line volts.	97.5% at rated amps, nominal line volts.
	Maximum Short Circuit Current Rating:	To match specified circuit breaker capability, ≤ 200,000 Amps	
	Actual Short Circuit Rating:	Determined by AIC rating of installed circuit breaker.	
Motor Lead Lengths:	Refer to Wiring and Grounding for Pulse Width Modulated (PWM) AC Drives, publication <a href="#">DRIVES-IN001</a>		
<b>Control</b>	Method:	Sine coded PWM with programmable carrier frequency.	
	Carrier Frequency:	2, 4, or 8 kHz. Drive rating based on 4 kHz. <a href="#">Derating Guidelines on page 119</a> for more information.	2 or 4 kHz. Drive rating based on 4 kHz.
	Output Voltage Range:	0 to rated motor voltage	
	Output Frequency Range		
	Vector Control:	0...420 Hz	
	700S Phase II Control:	0...400 Hz	
	Frequency Accuracy (Vector Control only)		
Digital Input:	Within ± 0.01% of set output frequency.		
Analog Input:	Within ± 0.4% of maximum output frequency		

Category	Specification		
		Frame 2	Frames 3A and 3B
<b>Control (continued)</b>	Frequency Control (Vector Control only):	Speed Regulation - w/Slip Compensation (Volts per Hertz Mode) 0.5% of base speed across 40:1 speed range 40:1 operating range 10 rad/sec bandwidth Speed Regulation - w/Slip Compensation (Sensorless Vector Mode) 0.5% of base speed across 80:1 speed range 80:1 operating range 20 rad/sec bandwidth	
	Speed Control Vector Control:	Speed Regulation - without feedback (Vector Control Mode) 0.1% of base speed across 120:1 speed range 120:1 operating range 50 rad/sec bandwidth Speed Regulation - with feedback (Vector Control Mode) 0.001% of base speed across 120:1 speed range 1000:1 operating range 250 rad/sec bandwidth	
	700S Phase II Control:	Speed Regulation - without feedback 0.1% of base speed across 120:1 speed range 120:1 operating range 50 rad/sec bandwidth Speed Regulation - with feedback 0.001% of base speed across 120:1 speed range 1000:1 operating range 740 rad/sec bandwidth	
	Torque Regulation Vector Control:	Torque regulation without Feedback; $\pm 5\%$ , 600 rad/sec bandwidth Torque regulation with Feedback; $\pm 2\%$ , 2500 rad/sec bandwidth	
	700S Phase II Control:	Torque regulation without Feedback; $\pm 10\%$ , 600 rad/sec bandwidth Torque regulation with Feedback; $\pm 5\%$ , 4400 rad/sec bandwidth	
	Selectable Motor Control Vector Control:	Sensorless Vector with full tuning. Standard V/Hz with full custom capability and Vector Control with Force Technology (with and without feedback).	
	700S Phase II Control:	Vector Control with Force Technology (with and without feedback), V/Hz Control, and permanent magnet motor control.	
	Stop Modes Vector Control:	Multiple programmable stop modes including Ramp, Coast, DC-Brake, Ramp-to-Hold, and S-curve.	
	700S Ph. II Control:	Multiple programmable stop modes including Ramp, Coast, and Current Limit.	
	Accel/Decel Vector Control:	Two independently programmable accel and decel times. Each time can be programmed from 0...3600 seconds in 0.1 second increments.	
	700S Phase II Control:	Independently programmable accel and decel times, adjustable from 0...6553.5 seconds in 0.01 second increments.	
	Intermittent Overload:	110% Overload capability for up to 1 minute 150% Overload capability for up to 3 seconds	
Current Limit Capability Vector Control:	Proactive Current Limit programmable from 20 to 160% of rated output current. Independently programmable proportional and integral gain.		
700S Phase II Control:	Independent Motoring and Regenerative Power Limits programmable to 800% of rated output current.		
Electronic Motor Overload Protection:	Class 10 motor overload protection according to NEC article 430 and motor over-temperature protection according to NEC article 430.126 (A)(2). UL File E59272.		

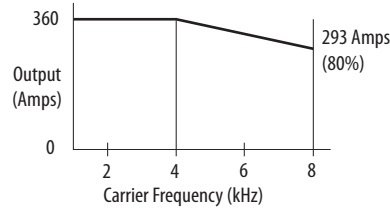
Category	Specification		
		Frame 2	Frames 3A and 3B
<b>Encoder (Vector Control only)</b>	Type:	Incremental, dual channel	
	Supply:	12V or 5V, 250 mA. 12V or 5V, 10 mA minimum inputs isolated with differential transmitter, 250 kHz maximum.	
	Quadrature:	90°, ± 27° at 25 °C	
	Duty Cycle:	50%, ± 10%	
	Requirements:	Encoders must be line driver type, quadrature (dual channel) or pulse (single channel), 8...15V DC output (3.5...6V DC for 5V encoder), single-ended or differential, and capable of supplying a minimum of 10 mA per channel. Maximum input frequency is 250 kHz. The Encoder Interface Board accepts 12V DC or 5V DC square-wave with a minimum high state of 7.0V DC (12 volt encoder) or 3.1V DC (5 volt encoder). Maximum low state voltage is 0.4V DC.	
<b>Feedback (700S Phase II Control only)</b>	Encoder Input:	Dual Channel Plus Marker, Isolated with differential transmitter Output (Line Drive) Incremental, Dual Channel Quadrature type	
	Encoder Voltage Supply:	5V DC or 12V DC (5V DC requires an external power supply), 320 mA/channel	
	Maximum Input Freq:	400 kHz	
	Stegmann Hi-Resolution Option		
	Encoder Voltage Supply:	11.5V DC @ 130 mA	
Hi-Resolution Feedback:	Sine/Cosine 1V P-P Offset 2.5		
Maximum Cable Length:	182 m (600 ft.)		
RS-485 Interface:	Hi-Resolution Feedback Option card obtains the following information via the Hiperface RS-485 interface shortly after power-up: Address, Command Number, Mode, Number of Turns, Number of Sine/Cos cycles, and Checksum.		
Resolver Option			
Excitation Frequency:	2400 Hz		
Excitation Voltage:	4.25...26V rms		
Operating Freq. Range:	1...10 kHz		
Resolver Fdbk. Voltage:	2V ± 300 mV		
Maximum Cable Length:	304.8 m (1000 ft)		
<b>DriveLogix (700S Phase II Control only)</b>	User Available Memory Base:	1.5 megabytes	
	Battery:	1756-BA1 (Allen-Bradley® PN 94194801) 0.59g lithium	
	Serial Cable:	1756-CP3 directly to controller 1747-CP3 directly to controller Category 3 (2)	
	Compact I/O Connection:	Up to (30) modules	
	Cable:	20D-DL2-CL3 or 20D-DL2-CR3	

## Ambient

Frame 2 drives have a maximum ambient of 50 °C (122 °F). Frame 3A and 3B drives have a maximum ambient of 40 °C (104 °F). PowerFlex 700L drives cannot be derated to operate at higher temperatures.

## Carrier Frequency

For Frame 2 drives, see the carrier frequency derating table below. PowerFlex 700L Frame 3A and 3B drives cannot be run above 4 kHz.



## Horsepower/Current Ratings

The following tables provide normal duty and heavy duty drive ratings (including continuous, 1 minute, and 3 second).

**Table 18 - 400V AC Ratings (AC Input/AC Output)**

Drive Catalog Number	Frame	PWM Freq. (kHz)	Output Power		Output Current (with 400V AC Induction Motor) <sup>(1)</sup>					
			HP (kW)		Cont.	110% 1 min.	150% 3 secs.	Cont.	150% 1 min.	200% 3 secs.
			ND	HD	ND	ND	ND	HD	HD	HD
20LC360	2	4	268 (200)	200 (150)	360	396	540	264	396	540
20LC650	3A	4	500 (370)	365 (270)	650	715	975	475	715	975
20LC1K2	3B	4	960 (715)	700 (525)	1250	1375	1875	915	1375	1875

(1) Frame 2 ratings are based on 50 °C ambient and 50 °C coolant.  
Frame 3A and 3B ratings are based on 40 °C ambient and 40 °C coolant.

**Table 19 - 480V AC Ratings (AC Input/AC Output)**

Drive Catalog Number	Frame	PWM Freq. (kHz)	Output Power		Output Current (with 480V AC Induction Motor) <sup>(1)</sup>					
			HP (kW)		Cont.	110% 1 min.	150% 3 secs.	Cont.	150% 1 min.	200% 3 secs.
			ND	HD	ND	ND	ND	HD	HD	HD
20LD360	2	4	300 (224)	235 (175)	360	396	540	264	396	540
20LD650	3A	4	600 (445)	440 (325)	650	715	975	475	715	975
20LD1K2	3B	4	1150 (860)	845 (630)	1250	1375	1875	915	1375	1875

(1) Frame 2 ratings are based on 50 °C ambient and 50 °C coolant. Frame 3A and 3B ratings are based on 40 °C ambient and 40 °C coolant.

**Table 20 - 600V AC Ratings (AC Input/AC Output)**

Drive Catalog Number	Frame	PWM Freq. (kHz)	Output Power		Output Current (with 600V AC Induction Motor) <sup>(1)</sup>					
			HP (kW)		Cont.	110% 1 min.	150% 3 secs.	Cont.	150% 1 min.	200% 3 secs.
			ND	HD	ND	ND	ND	HD	HD	HD
20LE425	3A	4	465 (345)	345 (255)	425	470	640	315	470	640
20LE800	3B	4	870 (650)	640 (480)	800	885	1200	590	885	1200
20LE1K1	3B	2 <sup>(2)</sup>	1275 (955)	935 (695)	1175	1295	1765	860	1295	1765

(1) Frame 3A and 3B ratings are based on 40 °C ambient and 40 °C coolant.  
(2) Must operate at only 2 kHz PWM, and only as a stand-alone inverter module ("K" in catalog string position 13).

**Table 21 - 690V AC Ratings (AC Input/AC Output)**

Drive Catalog Number	Frame	PWM Freq. (kHz)	Output Power		Output Current (with 690V AC Induction Motor) <sup>(1)</sup>					
			HP (kW)		Cont.	110% 1 min.	150% 3 secs.	Cont.	150% 1 min.	200% 3 secs.
			ND	HD	ND	ND	ND	HD	HD	HD
20LF380	3A	4	475 (355)	350 (260)	380	420	570	280	420	570
20LF705	3B	4	881 (657)	650 (485)	705	780	1060	520	780	1060
20LF1K0	3B	2 <sup>(2)</sup>	1315 (980)	965 (720)	1050	1155	1575	770	1155	1575

(1) Frame 3A and 3B ratings are based on 40 °C ambient and 40 °C coolant.

(2) Must operate at only 2 kHz PWM, and only as a stand-alone inverter module ("K" in catalog string position 13).

## Watts Loss

**Table 22 - Watts Loss @ Rated Load, Speed, and PWM Carrier Frequency**

Frame Size	Voltage	PWM Freq.	Watts Loss					
			Filter Section	Power Section			Complete Drive	
			Into Air	Into Air	Into Liquid	Total	Total Air	Total Liquid
2	400V	4 kHz	Not Applicable				1500	7900
	480V	4 kHz	Not Applicable				1500	7900
3A	400V	4 kHz	4000	1000	10,500	11,500	5000	10,500
	480V	4 kHz	4000	1000	11,500	12,500	5000	11,500
	600V	4 kHz	4000	1200	10,500	11,700	5200	10,500
	690V	4 kHz	4000	1200	12,000	13,200	5200	12,000
3B <sup>(1)</sup>	400V	4 kHz	7800	2000	21,000	23,000	9800	21,000
	480V	4 kHz	7800	2000	23,000	25,000	9800	23,000
	600V	4 kHz	7800	2400	21,000	23,400	10,200	21,000
	690V	4 kHz	7800	2400	24,000	26,400	10,200	24,000

(1) Frame 3B power section consists of two power modules. Each module dissipates half (½) of the watts shown in this table.

## Fuse and Circuit Breaker Ratings

The tables on the following pages provide recommended AC line input fuse and circuit breaker information. See below for UL and IEC requirements. Sizes listed are the recommended sizes based on 40 °C (104 °F) and the U.S. NEC. Other country, state or local codes can require different ratings. Tables with DC link fuse recommendations for DC input drives are also provided.

### Fusing

The recommend fuse types are listed below. If available current ratings do not match the tables provided, the next higher fuse rating should be chosen.

- IEC – BS88 (British Standard) Parts 1 & 2, EN60269-1, Parts 1 & 2 <sup>(1)</sup>, type gG fuses or equivalent should be used.
- UL – UL Class T, J or L fuses should be used.

(1) Typical designations include, but may not be limited to the following; Parts 1 & 2: AC, AD, BC, BD, CD, DD, ED, EFS, EF, FF, FG, GF, GG, GH.

## Circuit Breakers

The “non-fuse” listings in the following tables include inverse time circuit breakers and instantaneous trip circuit breakers (motor circuit protectors). If one of these is chosen as the desired protection method, the following requirements apply.

- IEC – Both types of circuit breakers are acceptable for IEC installations.
- UL – Only inverse time circuit breakers are acceptable for UL installations.

**Table 23 - 400 Volt AC Input Protection Devices**

Drive Catalog Number	Frame	HP (kW) Rating		Input Rating	Dual Element Time Delay Fuse		Non-Time Delay Fuse		Circuit Breaker <sup>(3)</sup>	Motor Circuit Protector <sup>(5)</sup>
		ND	HD	Amps	Min. <sup>(1)</sup>	Max. <sup>(2)</sup>	Min.	Max.	Max. <sup>(4)</sup>	Max.
20LC360	2	268 (200)	—	360	500	750	500	900	900	600
		—	200 (150)	264	400	650	450	900	900	400

- (1) Minimum protection device size is the lowest rated device that supplies maximum protection without nuisance tripping.  
 (2) Maximum protection device size is the highest rated device that supplies drive protection. For US NEC, minimum size is 125% of motor FLA. Ratings shown are maximum.  
 (3) Circuit Breaker - inverse time breaker. For US NEC, minimum size is 125% of motor FLA. Ratings shown are maximum  
 (4) Maximum allowable rating by US NEC. Exact size must be chosen for each installation.  
 (5) Motor Circuit Protector - instantaneous trip circuit breaker. For US NEC minimum size is 125% of motor FLA. Ratings shown are maximum

**Table 24 - 480 Volt AC Input Protection Devices**

Drive Catalog Number	Frame	HP (kW) Rating		Input Rating	Dual Element Time Delay Fuse		Non-Time Delay Fuse		Circuit Breaker <sup>(3)</sup>	Motor Circuit Protector <sup>(5)</sup>
		ND	HD	Amps	Min. <sup>(1)</sup>	Max. <sup>(2)</sup>	Min.	Max.	Max. <sup>(4)</sup>	Max.
20LD360	2	300 (224)	—	360	500	750	500	900	900	600
		—	235 (175)	264	400	650	450	900	900	400

- (1) Minimum protection device size is the lowest rated device that supplies maximum protection without nuisance tripping.  
 (2) Maximum protection device size is the highest rated device that supplies drive protection. For US NEC, minimum size is 125% of motor FLA. Ratings shown are maximum.  
 (3) Circuit Breaker - inverse time breaker. For US NEC, minimum size is 125% of motor FLA. Ratings shown are maximum  
 (4) Maximum allowable rating by US NEC. Exact size must be chosen for each installation.  
 (5) Motor Circuit Protector - instantaneous trip circuit breaker. For US NEC minimum size is 125% of motor FLA. Ratings shown are maximum

**Table 25 - 540 Volt DC Input Fusing**

Drive Catalog Number	Frame	HP (kW) Rating		DC Input Rating	Bussmann Fuse	
		ND	HD	Amps	Amps	Catalog No.
20LC650	3A	500 (370)	365 (270)	1250 <sup>(1)</sup>	2000	170M6621 <sup>(2)</sup>
20LC1K2	3B	960 (715)	700 (525)	1250	2000	170M6621 <sup>(2)</sup>

- (1) Only the Dual Inverter for PowerFlex 700L Frame 3A is available as a DC input inverter.  
 (2) Two 1000A Bussmann 170M6614 fuses per phase can also be used.

**Table 26 - 650 Volt DC Input Fusing**

Drive Catalog Number	Frame	HP (kW) Rating		DC Input Rating	Bussmann Fuse	
		ND	HD	Amps	Amps	Catalog No.
20LD650	3A	600 (445)	440 (325)	1250 <sup>(1)</sup>	2000	170M6621 <sup>(2)</sup>
20LD1K2	3B	1150 (860)	845 (630)	1250	2000	170M6621 <sup>(2)</sup>

- (1) Only the Dual Inverter for PowerFlex 700L Frame 3A is available as a DC input inverter.

(2) Two 1000A Bussmann 170M6614 fuses per phase can also be used.

**Table 27 - 810 Volt DC Input Fusing**

Drive Catalog Number	Frame	HP (kW) Rating		DC Input Rating	Bussmann Fuse	
		ND	HD	Amps	Amps	Catalog No.
20LE425	3A	465 (345)	345 (255)	850 <sup>(1)</sup>	1400	170M6701 <sup>(2)</sup>
20LE800	3B	870 (650)	640 (480)	800	1250	170M6700 <sup>(3)</sup>
20LE1K1	3B	1275 (955)	935 (695)	1175	900 (2 per phase)	170M6697

(1) Only the Dual Inverter for PowerFlex 700L Frame 3A is available as a DC input inverter.

(2) Two 700A Bussmann 170M6695 fuses per phase can also be used.

(3) Two 630A Bussmann 170M6694 fuses per phase can also be used.

**Table 28 - 932 Volt DC Input Fusing**

Drive Catalog Number	Frame	HP (kW) Rating		DC Input Rating	Bussmann Fuse	
		ND	HD	Amps	Amps	Catalog No.
20LF380	3A	475 (355)	350 (260)	760 <sup>(1)</sup>	1250	170M6700 <sup>(2)</sup>
20LF705	3B	881 (657)	650 (485)	705	1100	170M6699 <sup>(3)</sup>
20LF1K0	3B	1315 (980)	965 (720)	1050	800 (2 per phase)	170M6696

(1) Only the Dual Inverter for PowerFlex 700L Frame 3A is available as a DC input inverter.

(2) Two 630A Bussmann 170M6694 fuses per phase can also be used.

(3) Two 550A Bussmann 170M6693 fuses per phase can also be used.

**Notes:**

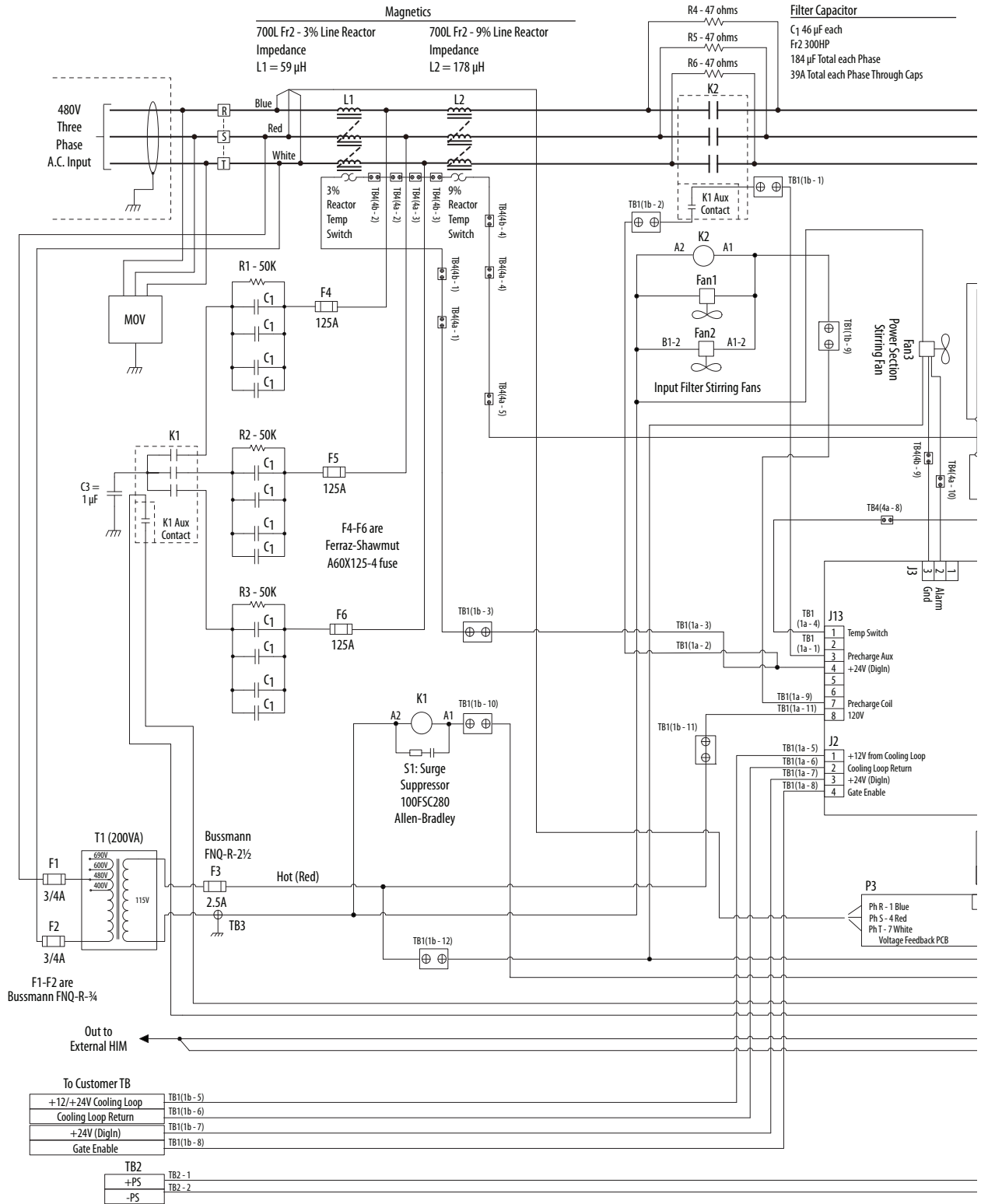


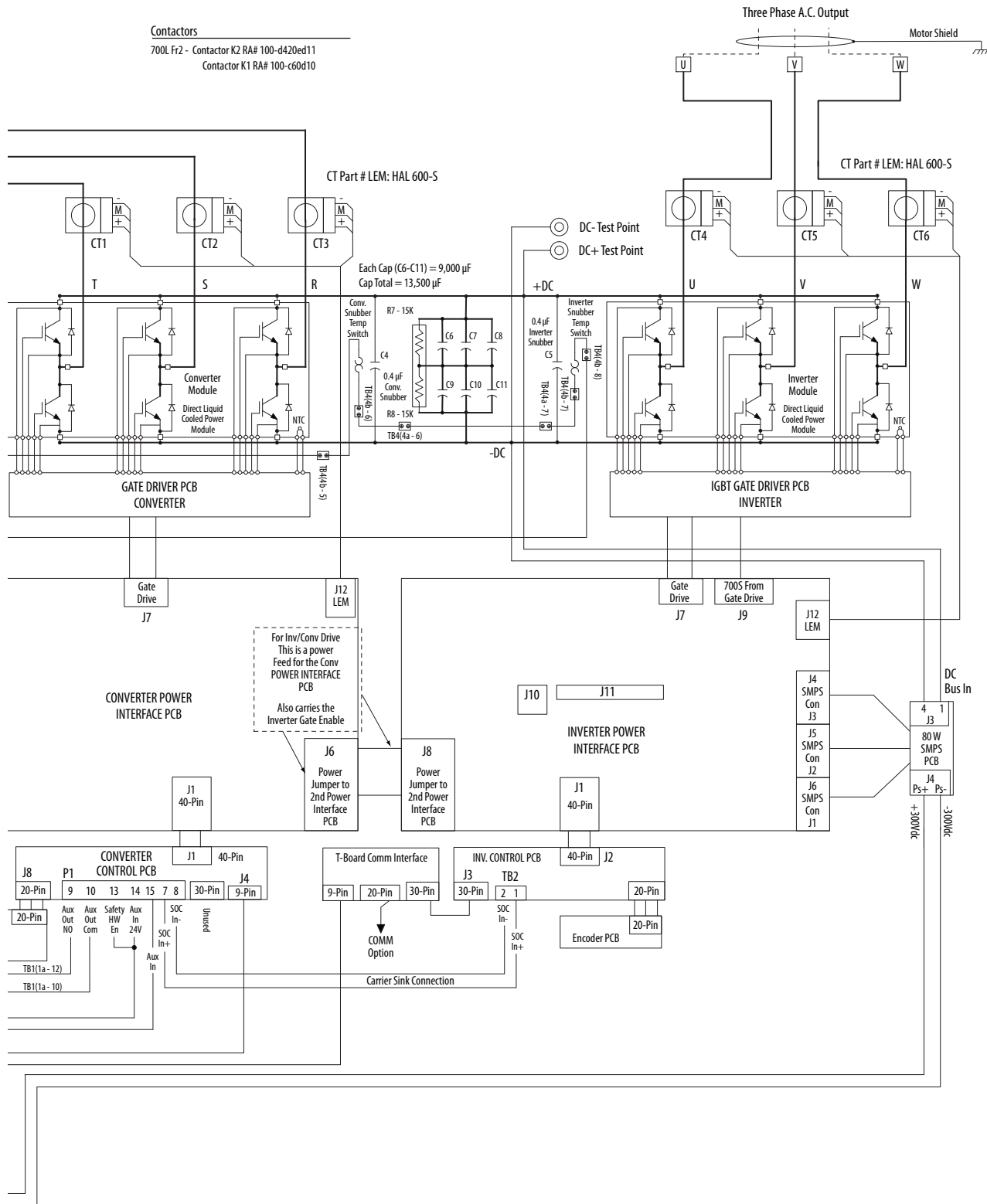
## Frame 2 Schematics

The schematics on the following pages illustrate the PowerFlex® 700L Frame 2 Liquid-Cooled drives.

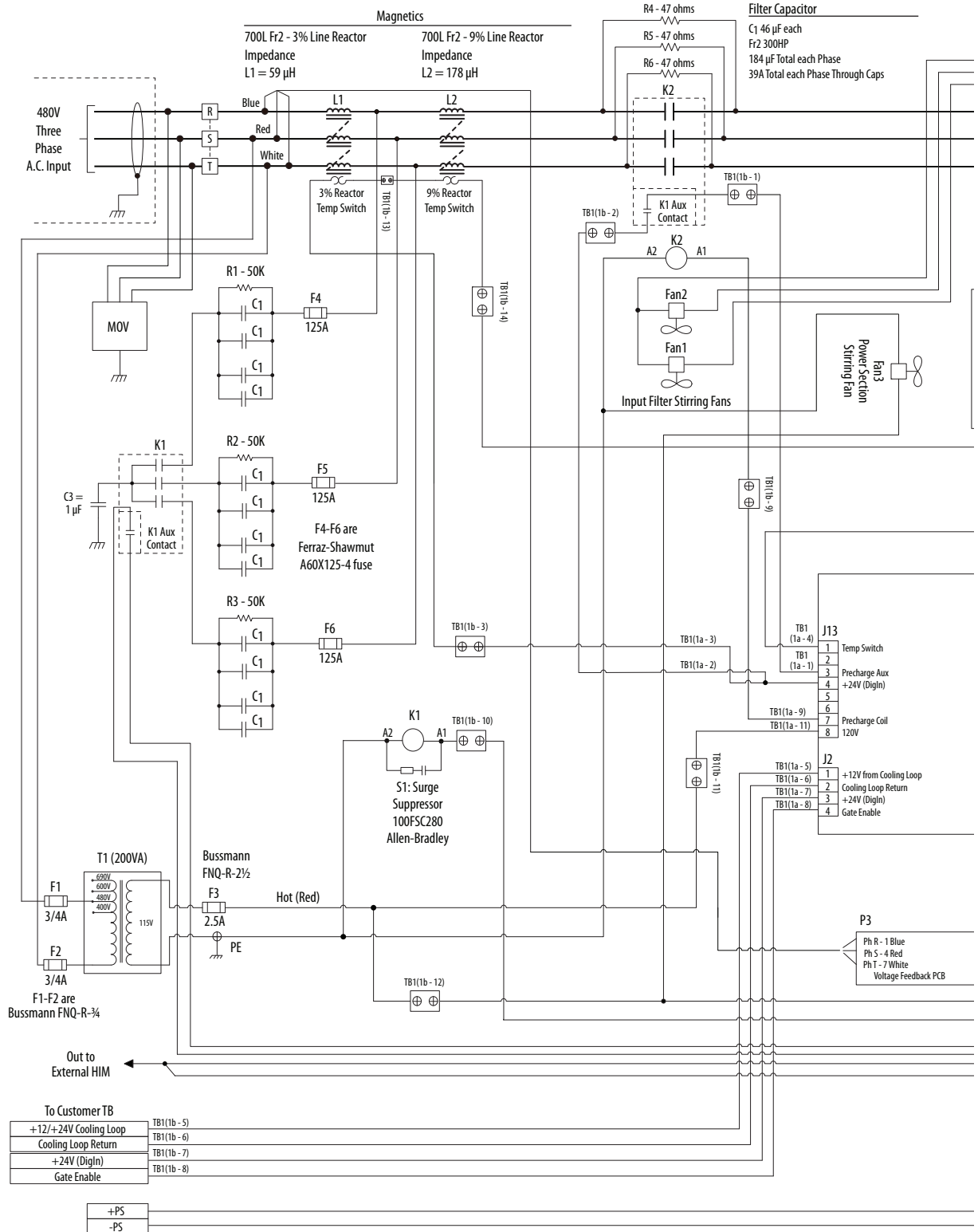
<b>Topic</b>	<b>Page</b>
Regenerative Drive Wiring Diagram with TB4 Connections - 400/480V, 3 Phase	130
Regenerative Drive Wiring Diagram without TB4 Connections - 400/480V, 3 Phase	132

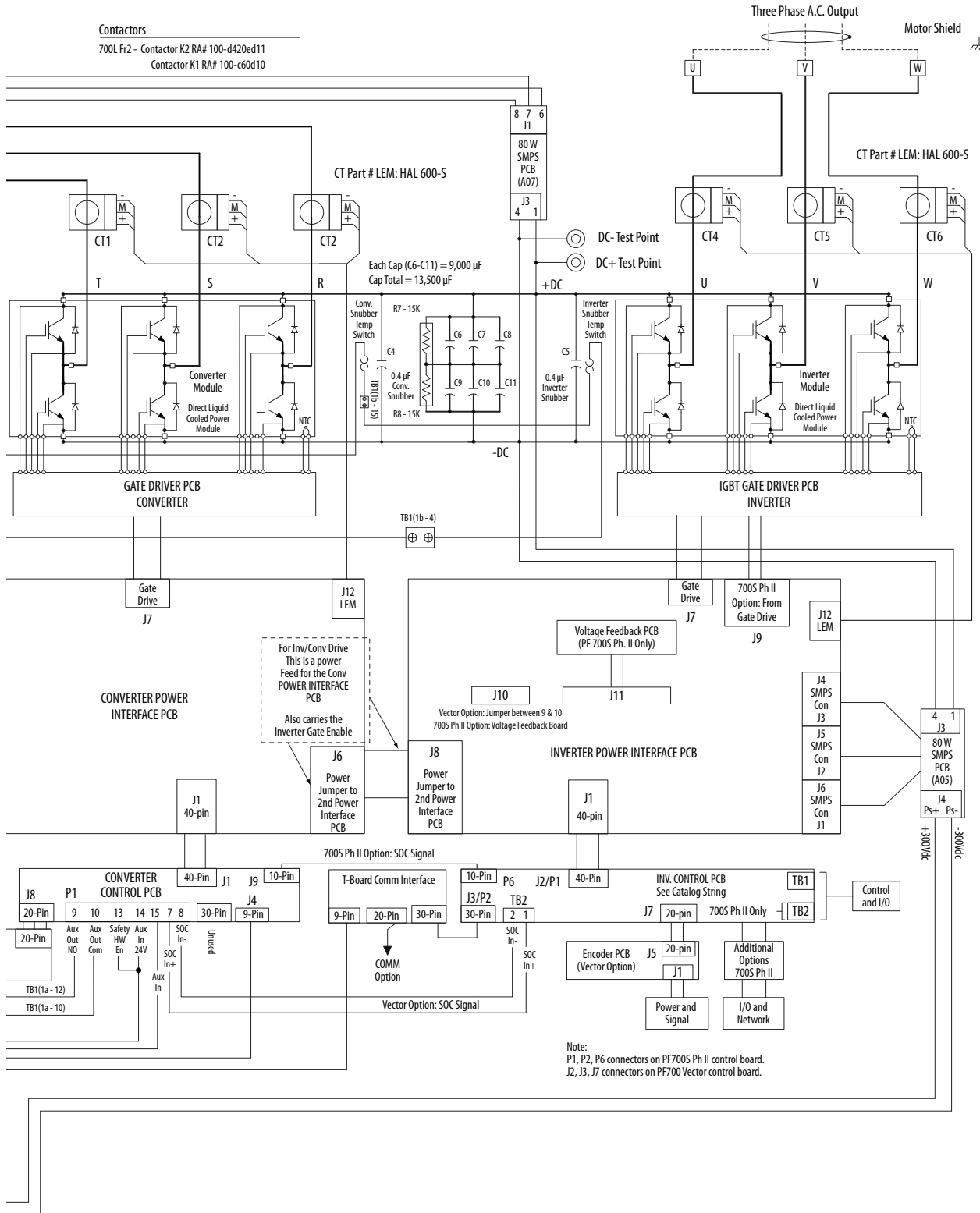
# Regenerative Drive Wiring Diagram with TB4 Connections - 400/480V, 3 Phase





# Regenerative Drive Wiring Diagram without TB4 Connections - 400/480V, 3 Phase





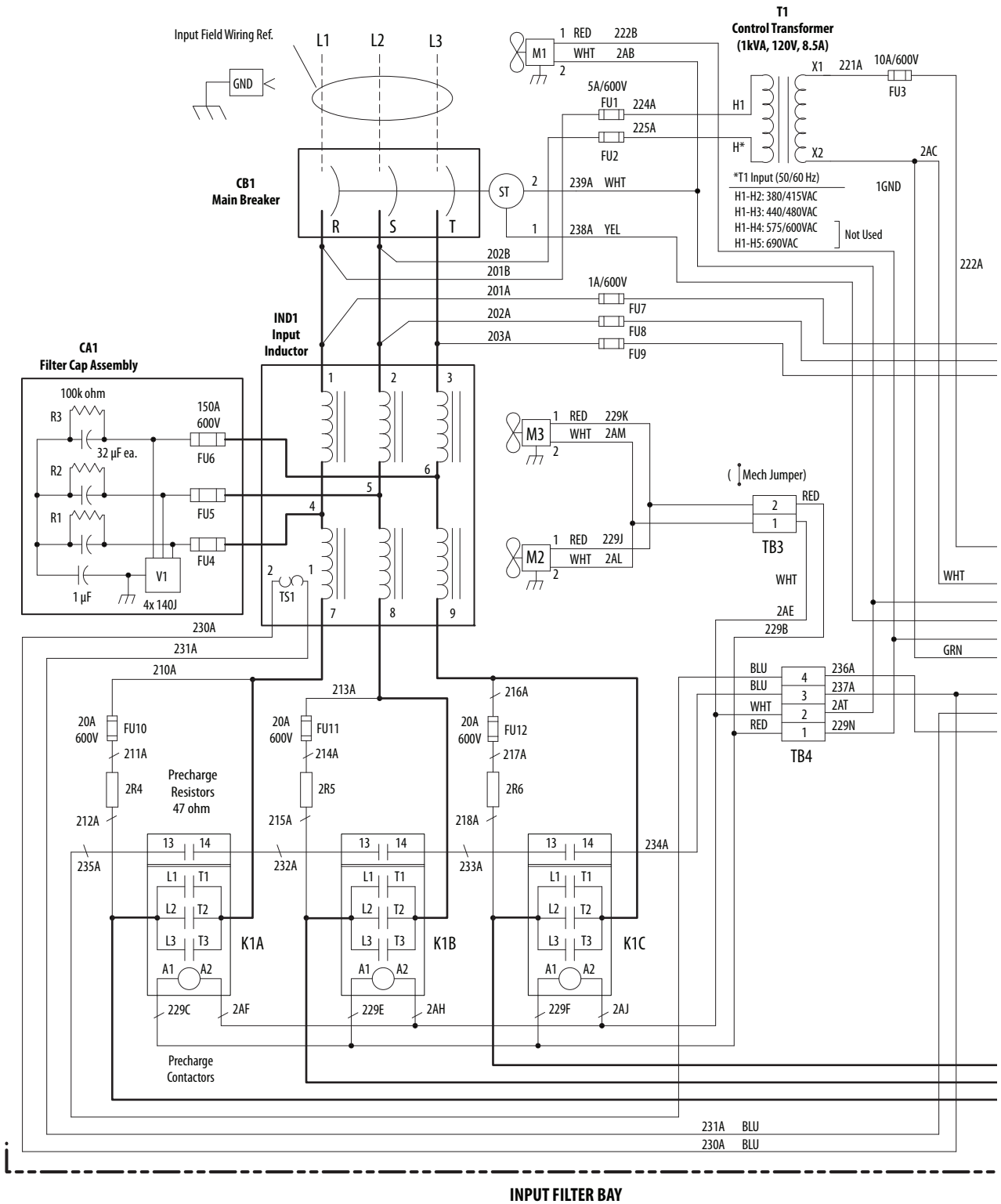
**Notes:**

## Frame 3A and 3B Schematics

Schematics on the following pages illustrate the PowerFlex® 700L Frame 3A and Frame 3B Liquid-Cooled drives and power modules.

<b>Topic</b>	<b>Page</b>
Frame 3A Regenerative Drive Wiring Diagram - 400/480V, 3 Phase	136
Frame 3A Regenerative Drive Wiring Diagram - 600/690V, 3 Phase	138
Frame 3A Converter/Inverter Power Module Wiring Diagram - 400/690V, 3 Phase	140
Frame 3A Dual Inverter Power Module Wiring Diagram - 400/690V, 3 Phase	142
Frame 3B Regenerative Drive Wiring Diagram - 400/480V, 3 Phase	144
Frame 3B Regenerative Drive Wiring Diagram - 600/690V, 3 Phase	146
Frame 3B Active Converter Power Module Schematic - 400/690V, 3 Phase	148
Frame 3B Inverter Power Module Schematic - 400/690V, 3 Phase	150

# Frame 3A Regenerative Drive Wiring Diagram - 400/480V, 3 Phase

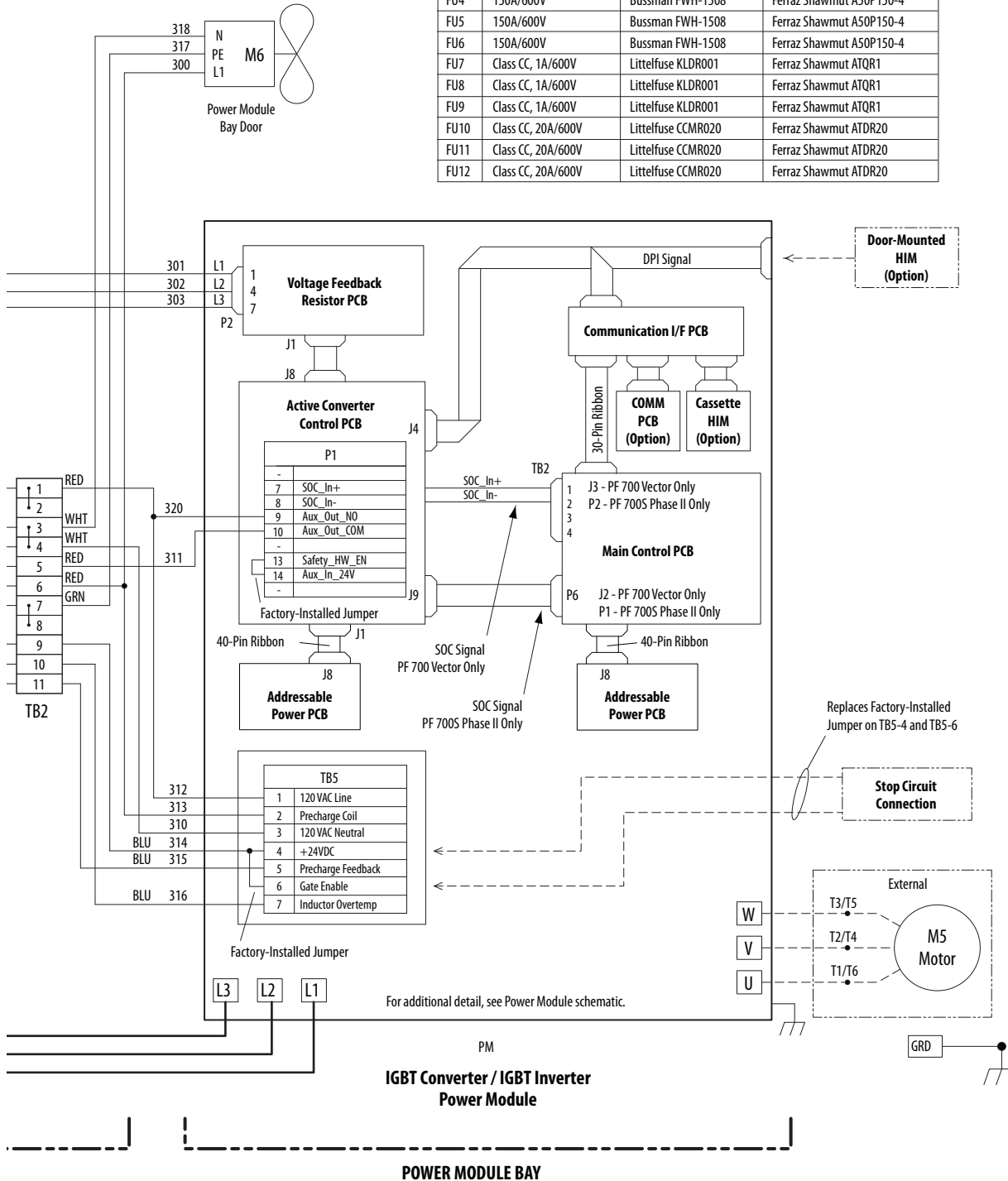




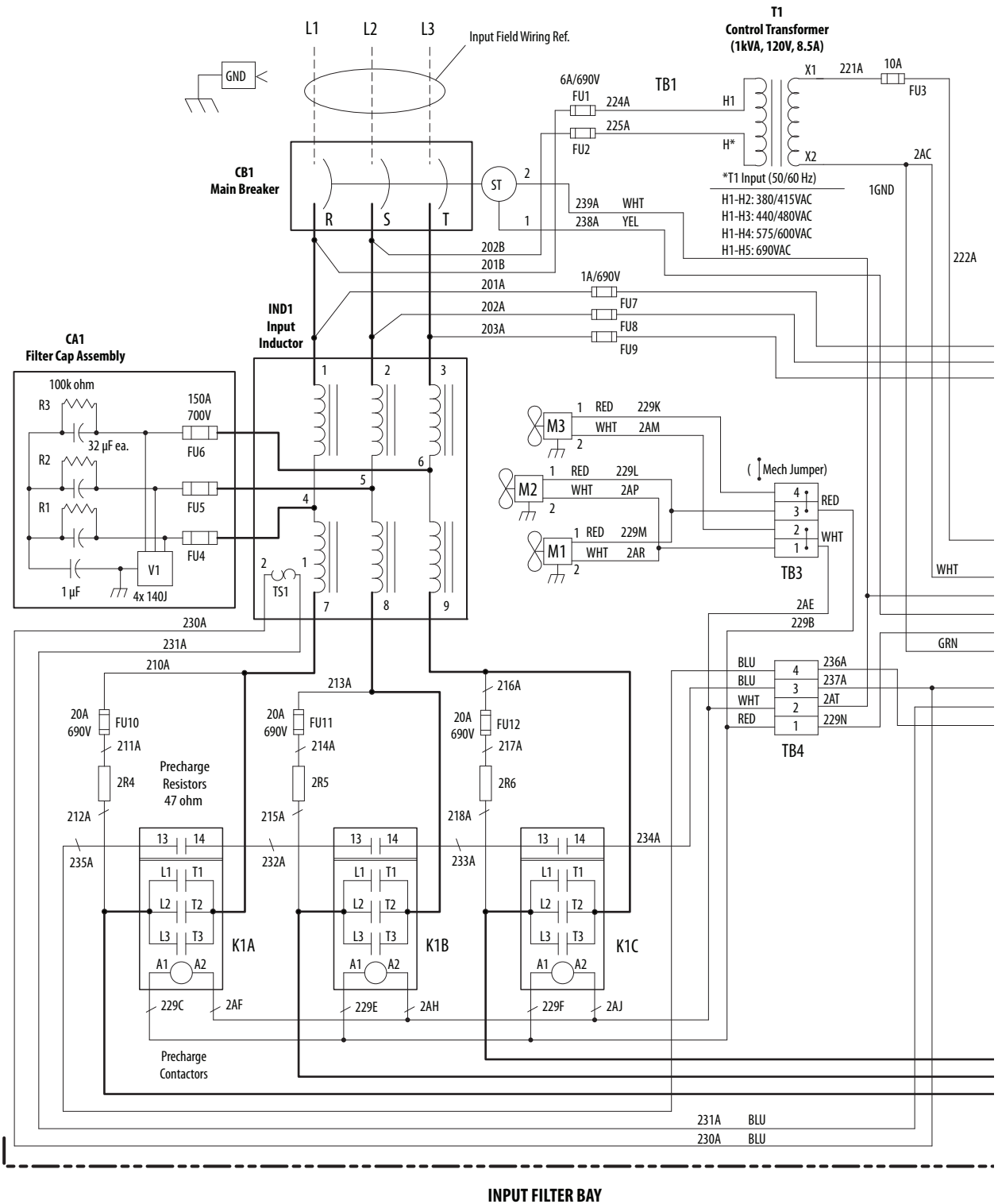
FUSE TABLE - DRIVE INPUT			
Ref.	Fuse Description	Supplier "A" and P/N	Supplier "B" and P/N
FU1	Class RK-5, 5A/600V	Bussman FRS-R-5	Ferraz Shawmut TR55R
FU2	Class RK-5, 5A/600V	Bussman FRS-R-5	Ferraz Shawmut TR55R
FU3	Class CC, 10A/600V	Littelfuse KLDRO10	Ferraz Shawmut ATQR10
FU4	150A/600V	Bussman FWH-1508	Ferraz Shawmut A50P150-4
FU5	150A/600V	Bussman FWH-1508	Ferraz Shawmut A50P150-4
FU6	150A/600V	Bussman FWH-1508	Ferraz Shawmut A50P150-4
FU7	Class CC, 1A/600V	Littelfuse KLDRO01	Ferraz Shawmut ATQR1
FU8	Class CC, 1A/600V	Littelfuse KLDRO01	Ferraz Shawmut ATQR1
FU9	Class CC, 1A/600V	Littelfuse KLDRO01	Ferraz Shawmut ATQR1
FU10	Class CC, 20A/600V	Littelfuse CCMR020	Ferraz Shawmut ATDR20
FU11	Class CC, 20A/600V	Littelfuse CCMR020	Ferraz Shawmut ATDR20
FU12	Class CC, 20A/600V	Littelfuse CCMR020	Ferraz Shawmut ATDR20

**NOTES:**

1.) Dashed lines indicate external components and wiring by others.



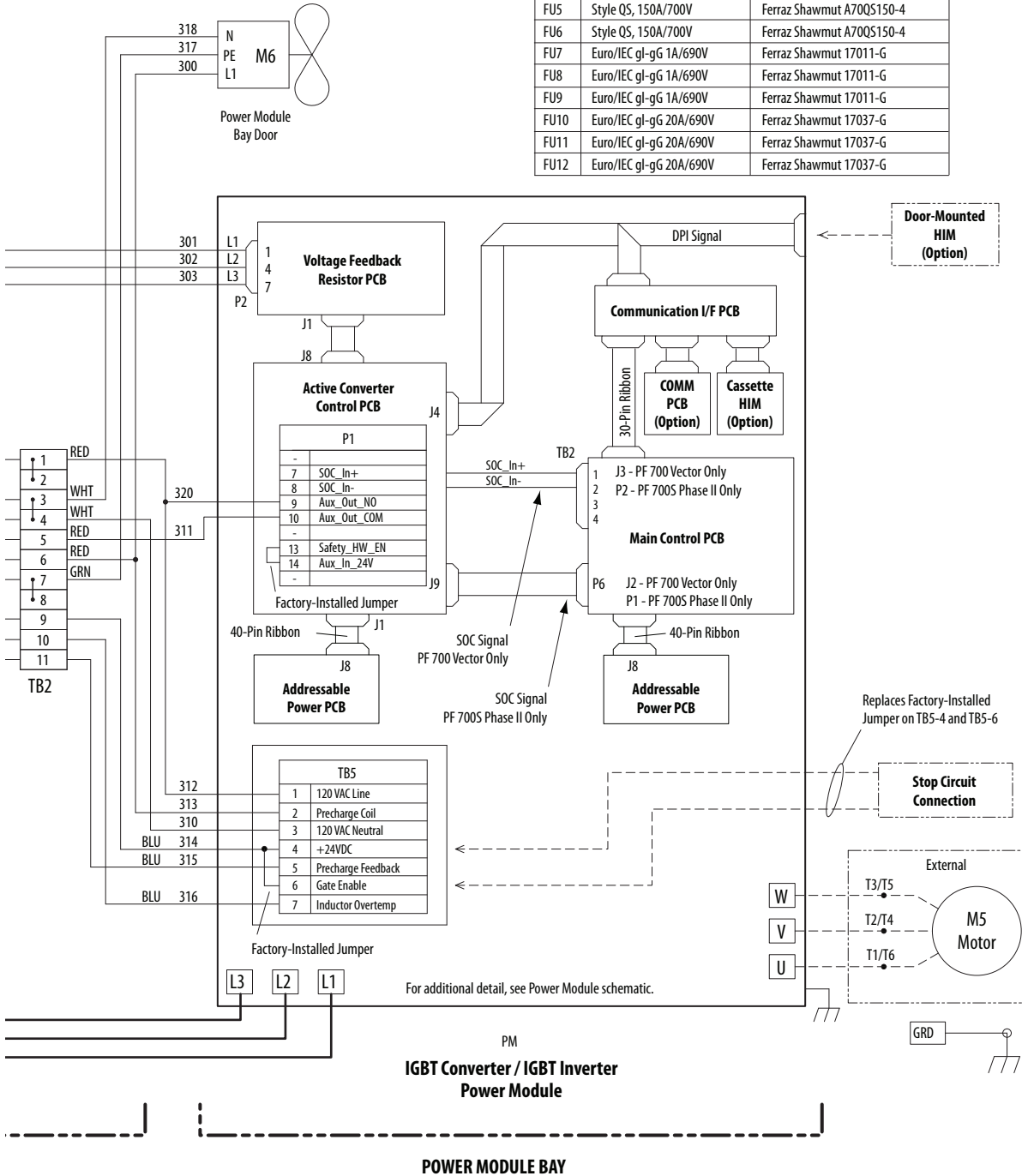
# Frame 3A Regenerative Drive Wiring Diagram - 600/690V, 3 Phase



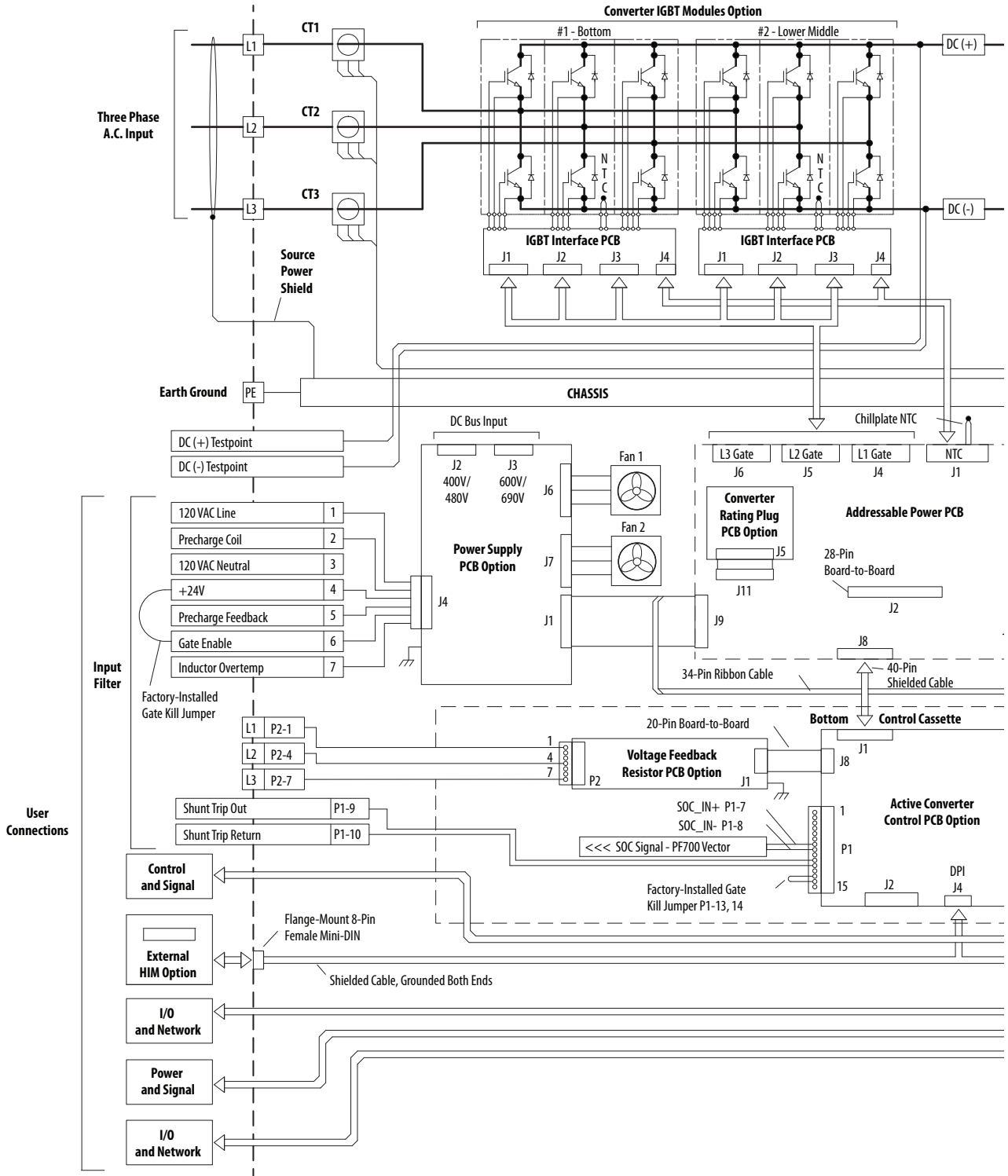
**NOTES:**

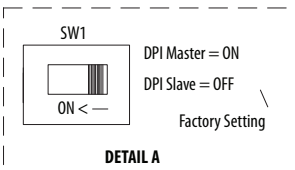
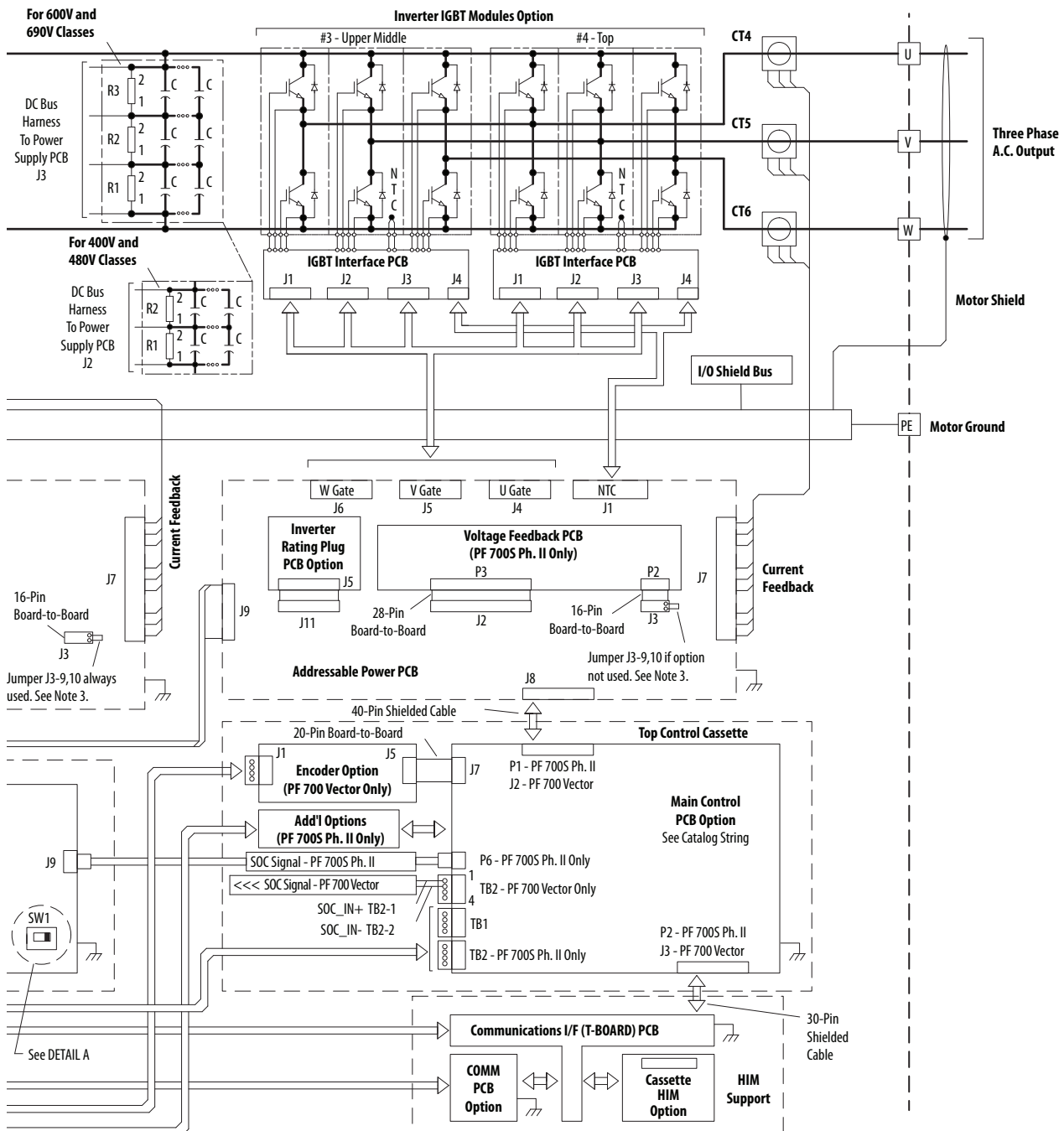
1.) Dashed lines indicate external components and wiring by others.

FUSE TABLE - INPUT FILTER BAY		
Ref.	Fuse Description	Supplier and P/N
FU1	Euro/IEC gl-gG 6A/690V	Ferraz Shawmut 18023-G
FU2	Euro/IEC gl-gG 6A/690V	Ferraz Shawmut 18023-G
FU3	Class CC, 10A/600V	Ferraz Shawmut ATQR10
FU4	Style QS, 150A/700V	Ferraz Shawmut A70QS150-4
FU5	Style QS, 150A/700V	Ferraz Shawmut A70QS150-4
FU6	Style QS, 150A/700V	Ferraz Shawmut A70QS150-4
FU7	Euro/IEC gl-gG 1A/690V	Ferraz Shawmut 17011-G
FU8	Euro/IEC gl-gG 1A/690V	Ferraz Shawmut 17011-G
FU9	Euro/IEC gl-gG 1A/690V	Ferraz Shawmut 17011-G
FU10	Euro/IEC gl-gG 20A/690V	Ferraz Shawmut 17037-G
FU11	Euro/IEC gl-gG 20A/690V	Ferraz Shawmut 17037-G
FU12	Euro/IEC gl-gG 20A/690V	Ferraz Shawmut 17037-G



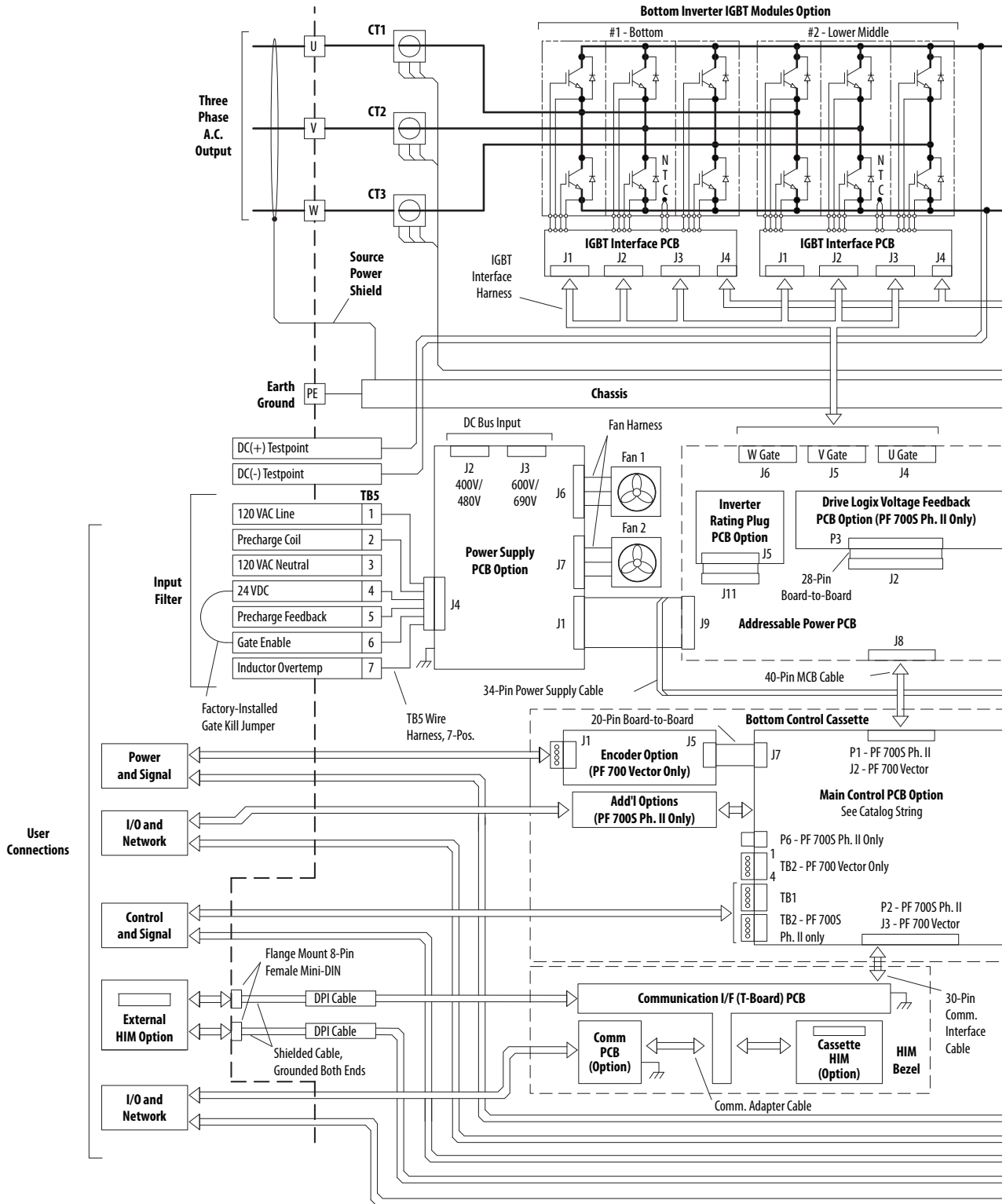
# Frame 3A Converter/Inverter Power Module Wiring Diagram - 400/690V, 3 Phase

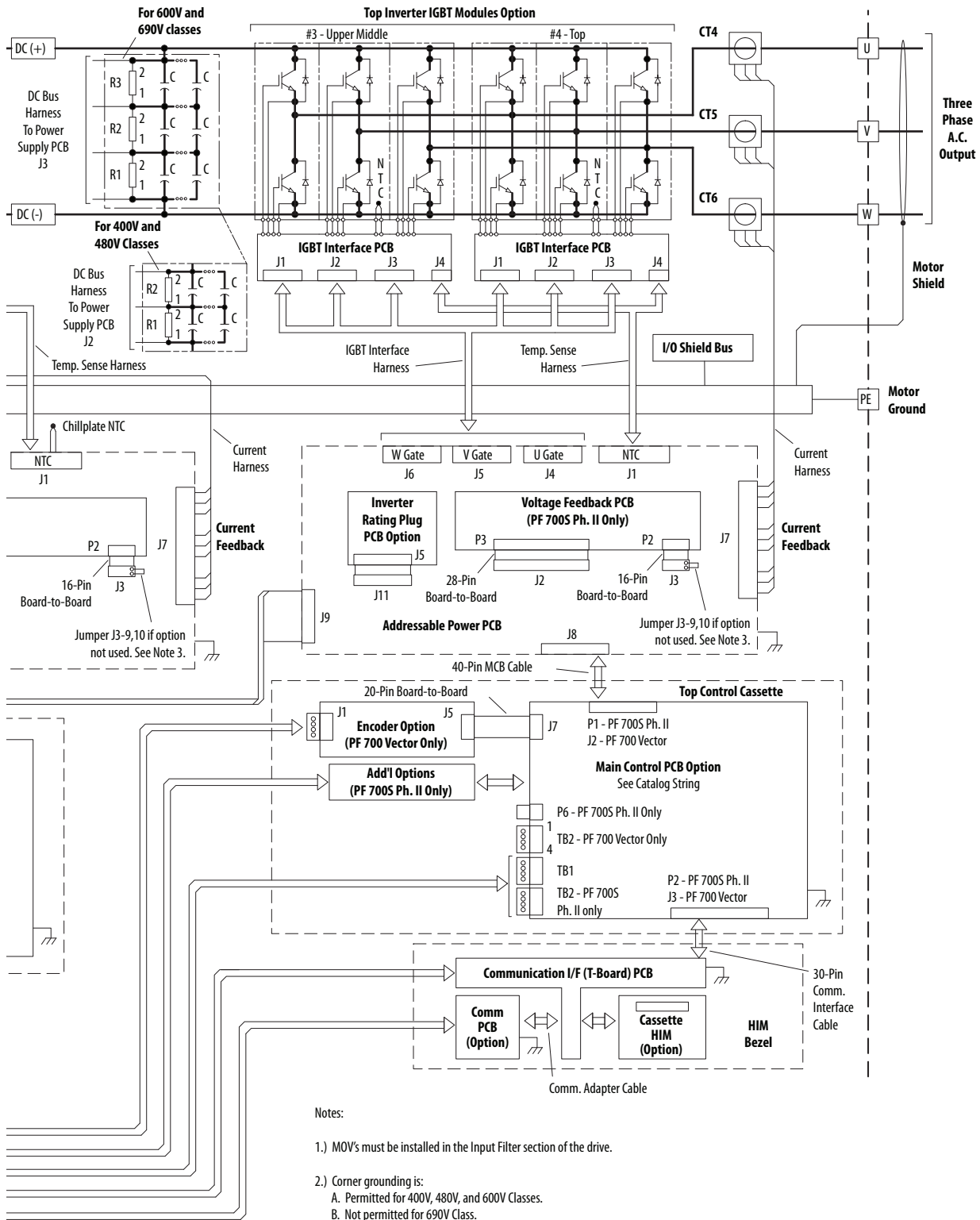




- NOTES:**
- 1.) MOV's must be installed in the input filter section of the drive.
  - 2.) Corner grounding is:  
 A. Permitted for 400V, 480V, and 600V Classes.  
 B. Not permitted for 690V Class.
  - 3.) Jumper J3-9, 10 is provided with the Addressable Power PCB.
  - 4.) Product software supports only one external HIM.  
 A splitter box is required for multiple external HIM devices.

# Frame 3A Dual Inverter Power Module Wiring Diagram - 400/690V, 3 Phase

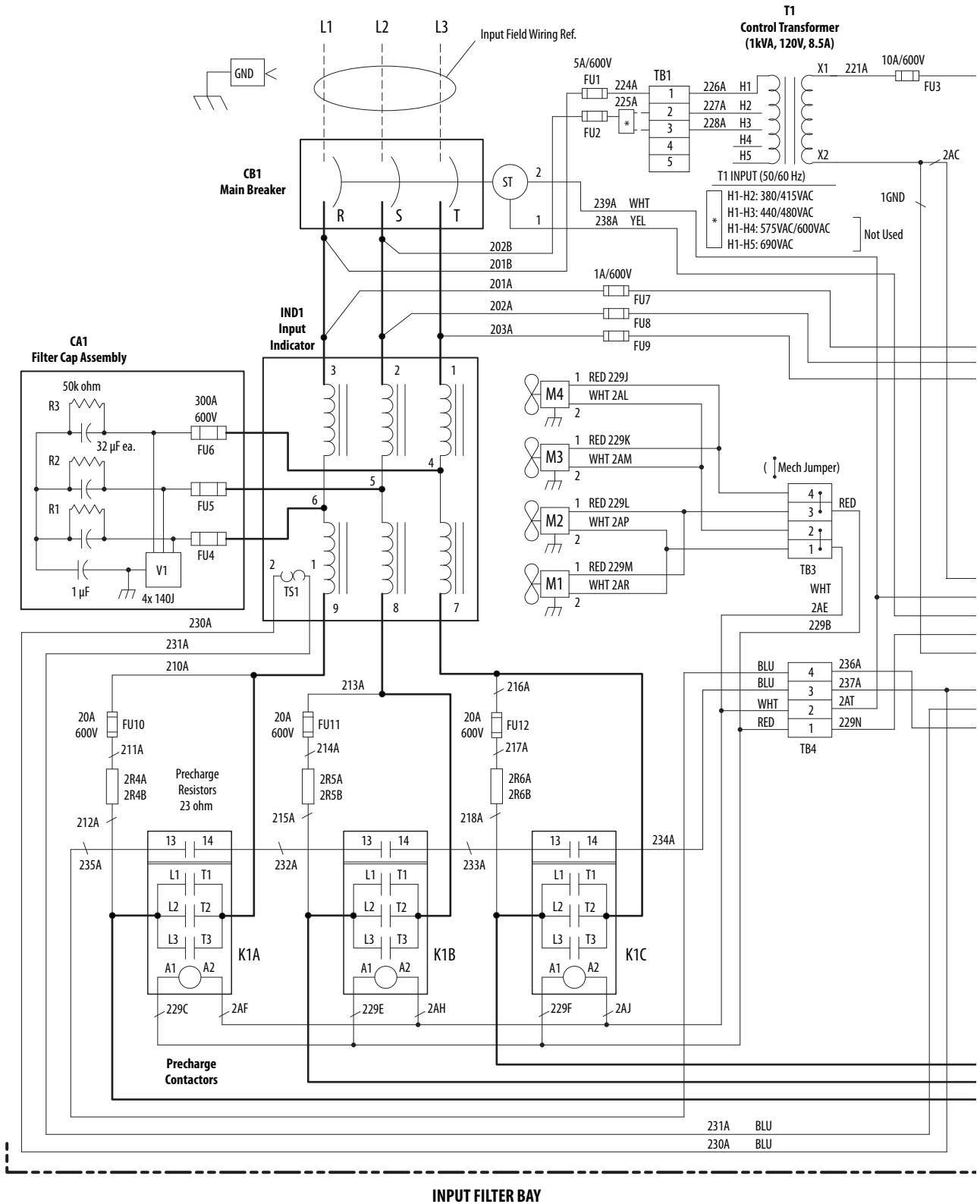




**Notes:**

- 1.) MOV's must be installed in the Input Filter section of the drive.
- 2.) Corner grounding is:
  - A. Permitted for 400V, 480V, and 600V Classes.
  - B. Not permitted for 690V Class.
- 3.) Jumper J3-9, 10 is provided with the Addressable Power PCB.

# Frame 3B Regenerative Drive Wiring Diagram - 400/480V, 3 Phase

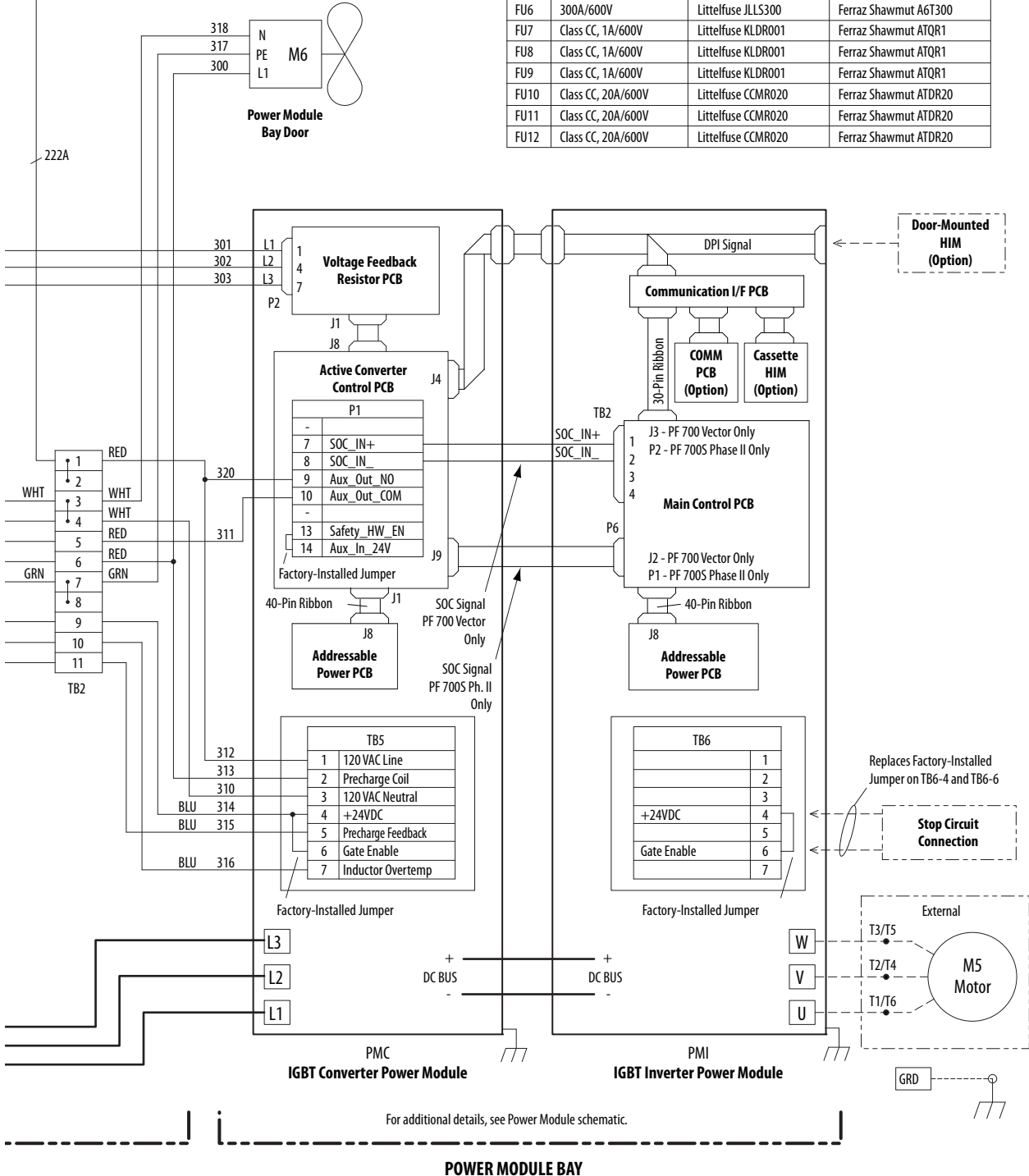




FUSE TABLE - DRIVE INPUT			
Ref.	Fuse Description	Supplier "A" and P/N	Supplier "B" and P/N
FU1	Class RK-5, 5A/600V	Bussman FRS-R-5	Ferraz Shawmut TR5SR
FU2	Class RK-5, 5A/600V	Bussman FRS-R-5	Ferraz Shawmut TR5SR
FU3	Class CC, 10A/600V	Littelfuse KLDRO10	Ferraz Shawmut ATQR10
FU4	300A/600V	Littelfuse JLS300	Ferraz Shawmut A6T300
FU5	300A/600V	Littelfuse JLS300	Ferraz Shawmut A6T300
FU6	300A/600V	Littelfuse JLS300	Ferraz Shawmut A6T300
FU7	Class CC, 1A/600V	Littelfuse KLDRO01	Ferraz Shawmut ATQR1
FU8	Class CC, 1A/600V	Littelfuse KLDRO01	Ferraz Shawmut ATQR1
FU9	Class CC, 1A/600V	Littelfuse KLDRO01	Ferraz Shawmut ATQR1
FU10	Class CC, 20A/600V	Littelfuse CCMR020	Ferraz Shawmut ATDR20
FU11	Class CC, 20A/600V	Littelfuse CCMR020	Ferraz Shawmut ATDR20
FU12	Class CC, 20A/600V	Littelfuse CCMR020	Ferraz Shawmut ATDR20

**NOTES:**

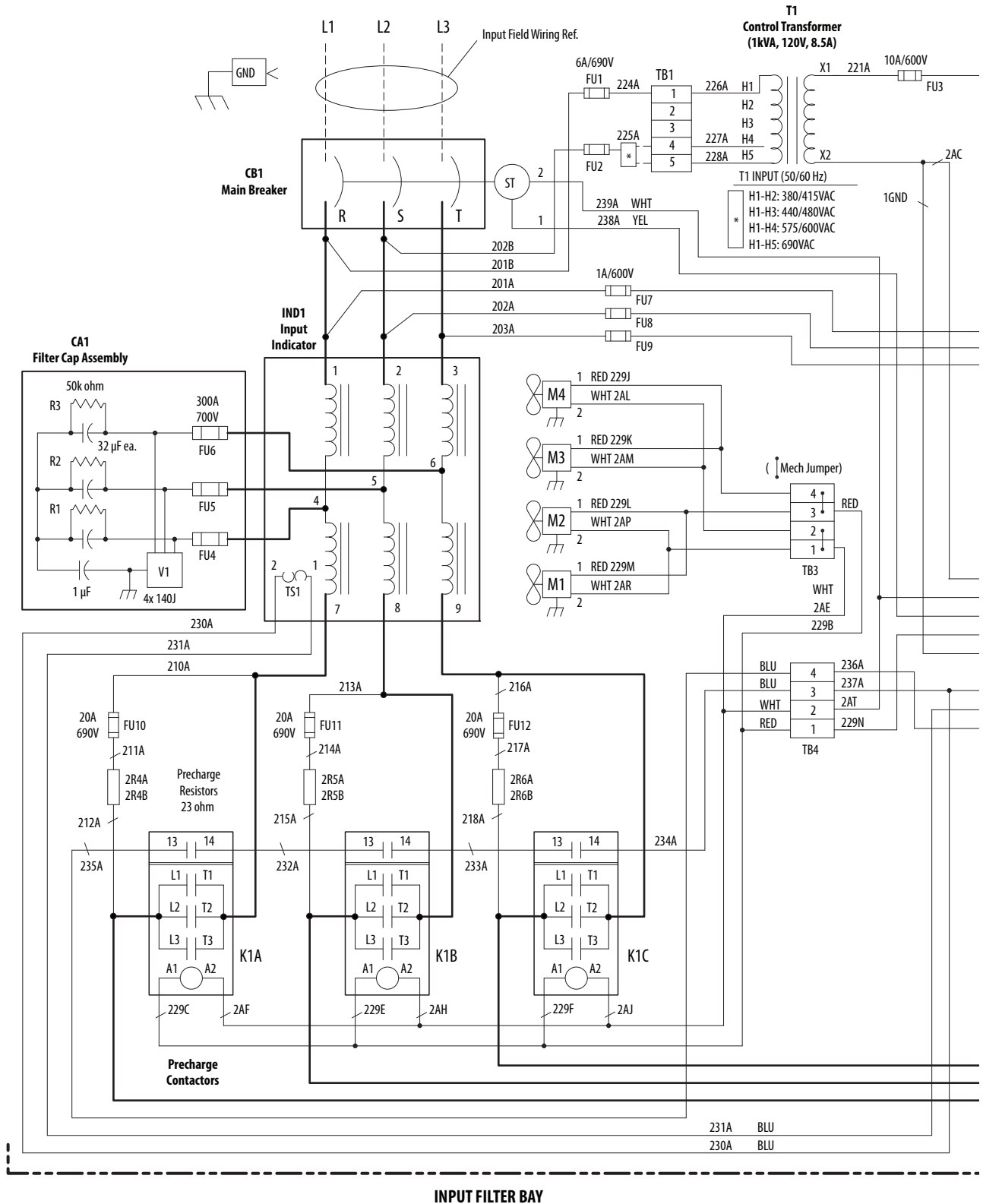
1.) Dashed lines indicate external components and wiring by others.



For additional details, see Power Module schematic.

**POWER MODULE BAY**

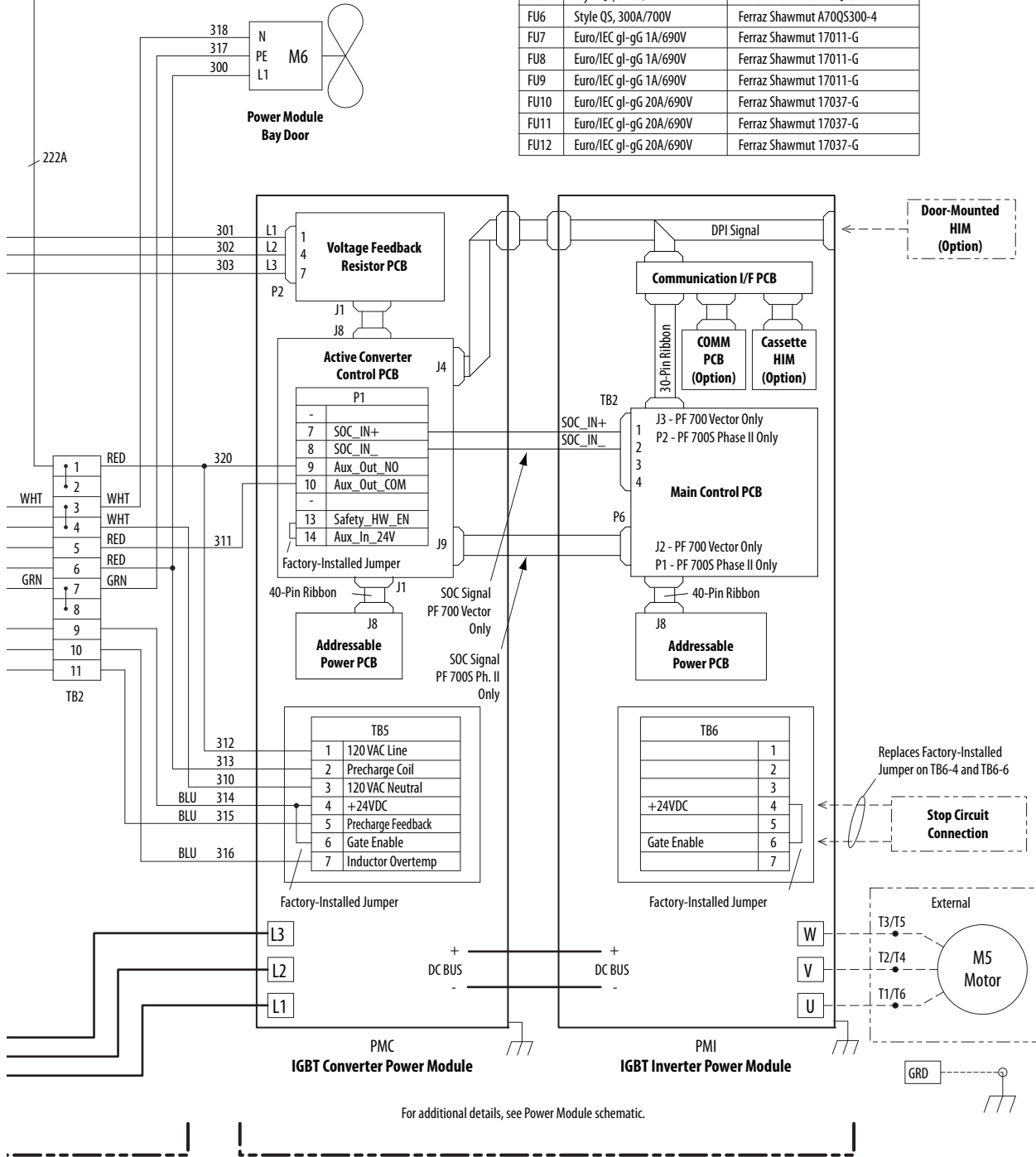
# Frame 3B Regenerative Drive Wiring Diagram - 600/690V, 3 Phase



FUSE TABLE - INPUT FILTER BAY		
Ref.	Fuse Description	Supplier and P/N
FU1	Euro/IEC gl-gG 6A/690V	Ferraz Shawmut 18023-G
FU2	Euro/IEC gl-gG 6A/690V	Ferraz Shawmut 18023-G
FU3	Class CC, 10A/600V	Ferraz Shawmut ATQR10
FU4	Style QS, 300A/700V	Ferraz Shawmut A70QS300-4
FU5	Style QS, 300A/700V	Ferraz Shawmut A70QS300-4
FU6	Style QS, 300A/700V	Ferraz Shawmut A70QS300-4
FU7	Euro/IEC gl-gG 1A/690V	Ferraz Shawmut 17011-G
FU8	Euro/IEC gl-gG 1A/690V	Ferraz Shawmut 17011-G
FU9	Euro/IEC gl-gG 1A/690V	Ferraz Shawmut 17011-G
FU10	Euro/IEC gl-gG 20A/690V	Ferraz Shawmut 17037-G
FU11	Euro/IEC gl-gG 20A/690V	Ferraz Shawmut 17037-G
FU12	Euro/IEC gl-gG 20A/690V	Ferraz Shawmut 17037-G

**NOTES:**

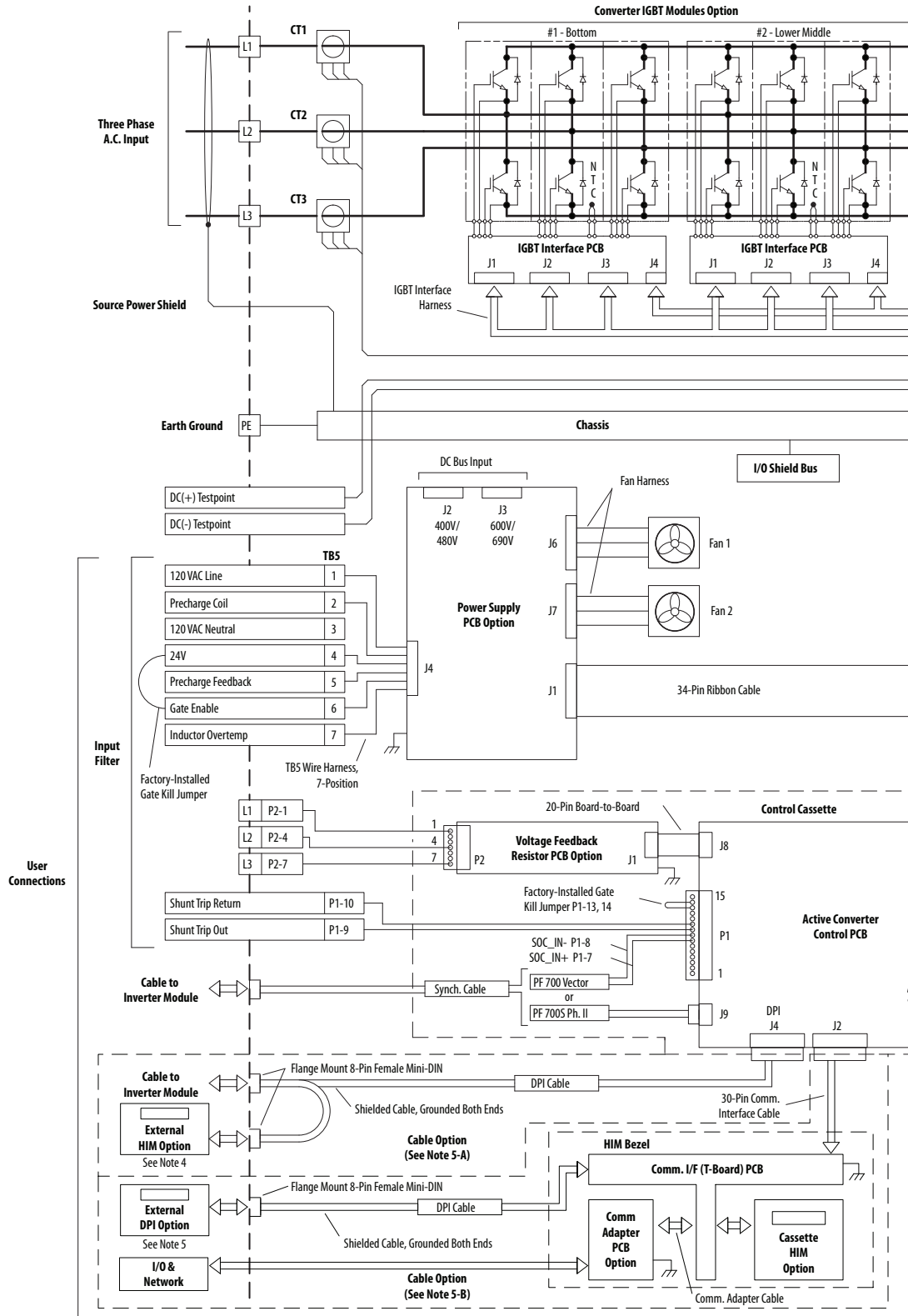
1.) Dashed lines indicate external components and wiring by others.

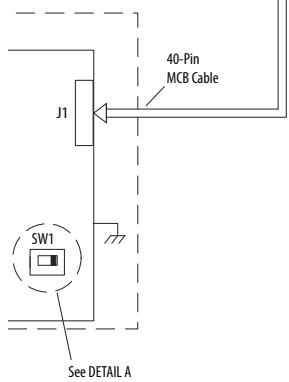
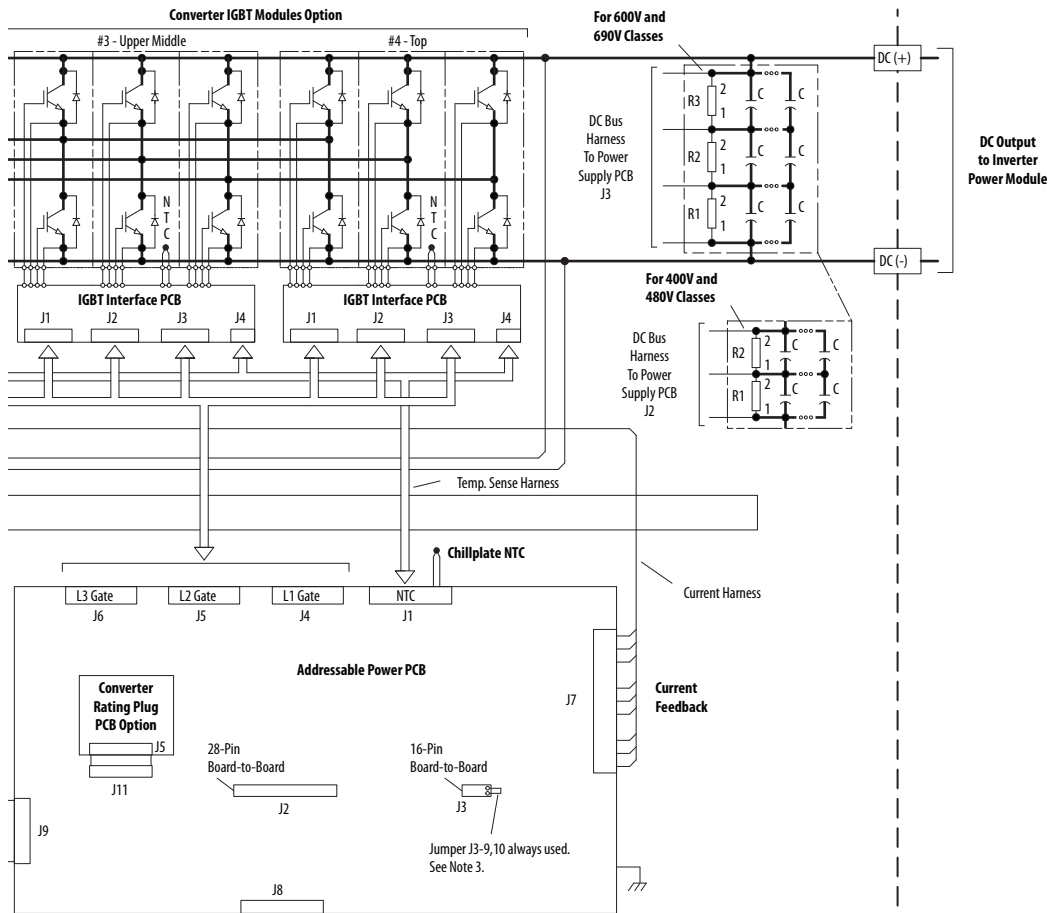


For additional details, see Power Module schematic.

**POWER MODULE BAY**

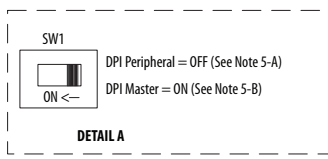
# Frame 3B Active Converter Power Module Schematic - 400/690V, 3 Phase



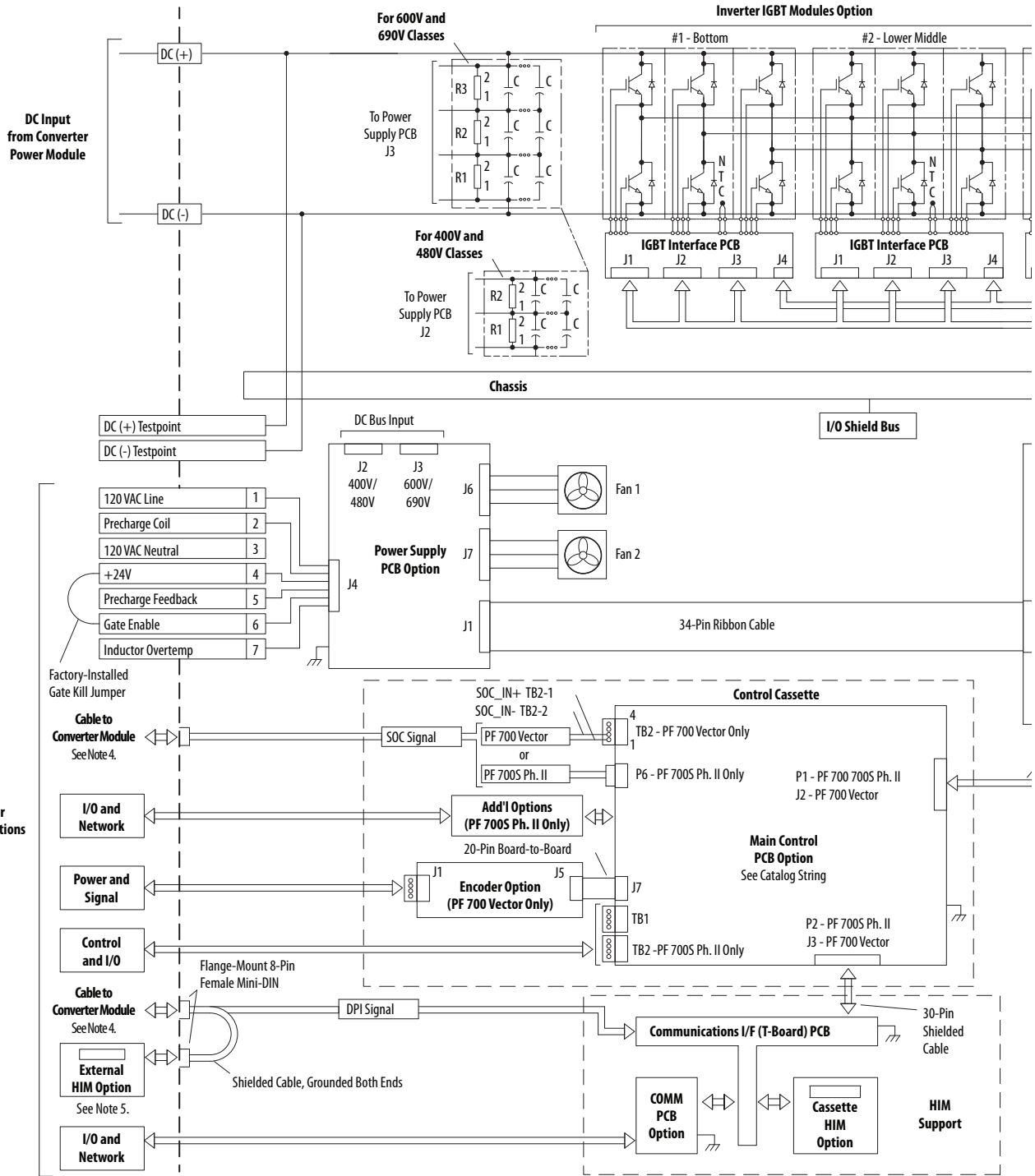


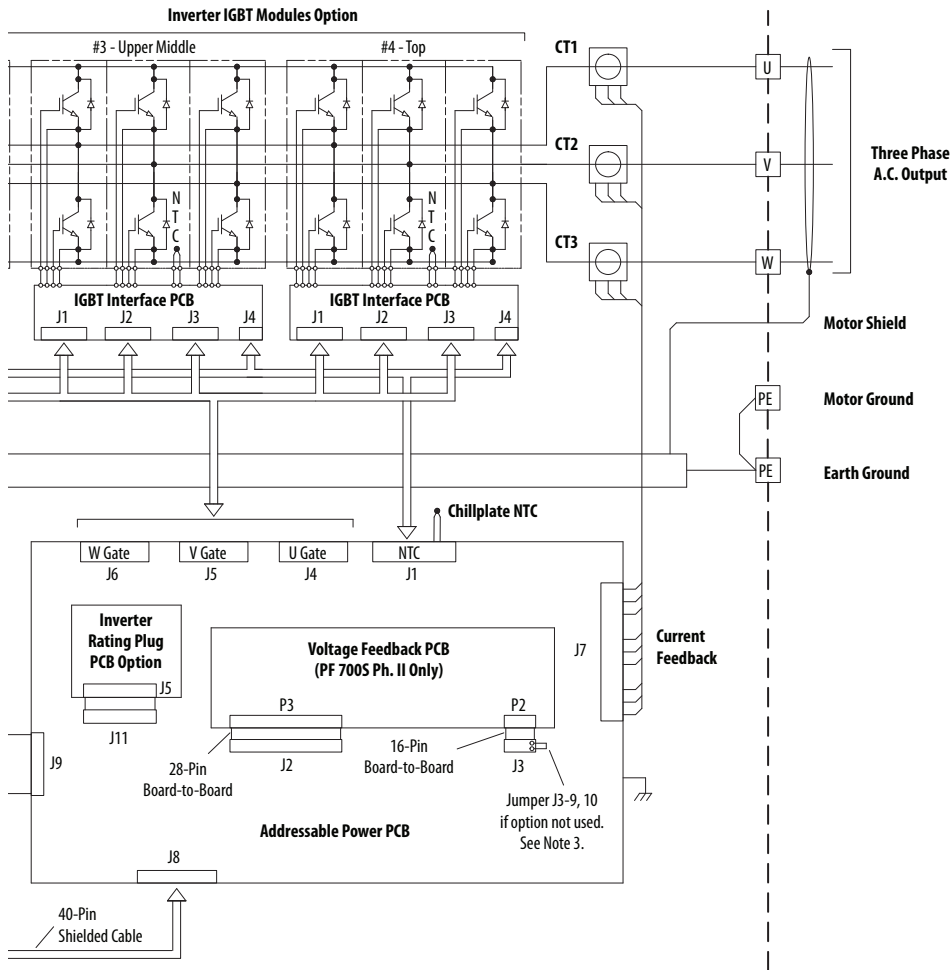
**NOTES:**

- 1.) MOV's must be installed in the input filter section of the drive.
- 2.) Corner grounding is:
  - A. Permitted for 400V, 480V, and 600V Classes.
  - B. Not permitted for 690V Class.
- 3.) Jumper J3-9, 10 is provided with Addressable Power PCB.
- 4.) Product software supports only one external HIM. Do not connect external HIM if one is also connected to the Inverter Power Module. A splitter box is required for multiple external HIM devices.
- 5.) DPI Cable and SW1 Options:
  - A. Use with Active Converter Power Module (Catalog String position 13 = G).
  - B. Use with Active Converter Power Module - Stand Alone (Catalog String position 13 = P).



# Frame 3B Inverter Power Module Schematic - 400/690V, 3 Phase





**NOTES:**

- 1.) MOV's must be installed in the input filter section of the drive.
- 2.) Corner grounding is:
  - A. Permitted for 400V, 480V, and 600V Classes.
  - B. Not permitted for 690V Class.
- 3.) Jumper J3-9, 10 is provided with the Addressable Power PCB.
- 4.) SOC cable and DPI cable are used only with Inverter Power Modules coupled to Converter Power Modules. These cables are not used with stand-alone Inverter Modules.
- 5.) Product software supports only one external HIM. Do not connect external HIM if one is also connected to the Converter Power Module. A splitter box is required for multiple external HIM devices.

**Notes:**



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