

PowerFlex® 700L



TECHNICAL DATA

LIQUID-COOLED ADJUSTABLE FREQUENCY AC DRIVES



PowerFlex 700L Technical Data

Table of Contents

<u>Description</u>	<u>Page</u>
Product Overview	<u>3</u>
Key Features/Benefits	
Easy to Use Communication and Human Interface Options	4
Catalog Number Explanation	<u>6</u>
Standard Drive Product Selection	<u>8</u>
Factory Installed Options	9
User Installed Options	10
Product Dimensions	
Installation Considerations	14
Cable Recommendations	<u>20</u>
Power Ratings and Branch Circuit Protection	21
Maximum Motor Cable Lengths	23
DPI Connections	26
Control Connections	29
Control Highlights	32
Standard Drive Specifications	37
Derating Guidelines	40
Watts Loss (@ Rated Load, Speed, and PWM Carrier Frequency)	<u>40</u>
Cooling Loop Options	41

Reference Materials

For additional PowerFlex 700L data and general drive information, refer to the following publications:

Title	Publication	Available Online at
PowerFlex 700L Liquid-Cooled Adjustable Frequency AC Drive User Manual	20L-UM001	www.rockwellautomation.com
PowerFlex 700L Active Converter Power Module User Manual	PFLEX-UM002	/literature
PowerFlex 700 Adjustable Frequency AC Drive User Manual — Series B (for standard vector control information)	20B-UM002	
PowerFlex 700S High Performance AC Drive — Phase II Control User Manual (for Phase II control information)	20D-UM006	
PowerFlex 70/700 Reference Manual	PFLEX-RM001	
PowerFlex 700L Liquid-to-Liquid Heat Exchanger User Manual	20L-UM002	
Wiring and Grounding Guidelines for Pulse Width Modulated (PWM) AC Drives	DRIVES-IN001	
Preventive Maintenance of Industrial Control and Drive System Equipment	DRIVES-TD001	
Safety Guidelines for the Application, Installation and Maintenance of Solid State Control	SGI-1.1	

For other information, contact Allen-Bradley Drives Technical Support:

Title	Online at
Allen-Bradley Drives Technical Support	www.ab.com/support/abdrives

Product Overview

PowerFlex 700L Liquid-Cooled AC drives are responsive, high performance, regenerative industrial drives for installations requiring a compact footprint. The PowerFlex 700L drive offers two versions of control: either the PowerFlex 700 Vector Control or the PowerFlex 700S Phase II Control. This provides the PowerFlex 700L drive with exceptional and proven performance as well as the same interface, communications capabilities and programming tools of the air-cooled drives. The many features allow the user to easily configure the drive for most application needs. Ratings currently available include:

- 268 to 960 Hp (200 to 715 kW) at 400V AC
- 300 to 1150 Hp (224 to 860 kW) at 480V AC
- 465 to 870 Hp (345 to 650 kW) at 600V AC
- 475 to 881 Hp (355 to 657 kW) at 690V AC

Frame 2



Frame 3B shown (with cabinet doors open)



Key Features/Benefits

Space Saving Features

• The PowerFlex 700L AC drive features a patented liquid-cooled heatsink design to transfer over 80% of the drive heat loss to the liquid coolant, resulting in the best drive power-to-size ratio in the market. The integral active converter and line filter translate to a fully regenerative drive that's over 60% smaller than typical air-cooled units.

Integrated Line Regenerative Braking For Precise Control and Energy Savings

- The Liquid-Cooled AC drive features regenerative braking which is ideal for precise, high-response speed and position control, continuous holdback, rapid deceleration and stopping of high inertia loads. Instead of wasting energy with resistor braking technology, regenerative braking actually puts the energy back into the system to be used by other equipment.
- Regenerative braking eliminates the need for large resistor banks. These resistors banks can create a lot of heat and must frequently be cleaned.

Improved Power Quality with Regenerative Rectifier

- Compact and cost-effective means to achieve compliance with CE and IEEE 519 harmonic limits.
- Actively controls power factor regardless of motor speed which reduces input line currents and minimizes the size of upstream devices.

Input Voltage Boost

- Integrated active converter and line-side filter allow "input voltage boost" protect your system from power disturbances.
- Maintains consistent system performance in the event of power dips or other power quality issues.
- Provides full 480V AC to the motor even when operating on 380V AC power lines.

Flexible Control Platforms

- Designed for applications with requirements ranging from the simplest speed control to the most demanding torque control, the PowerFlex 700L drive is available with either PowerFlex 700 Vector Control or PowerFlex 700S Control.
- Outstanding open or closed loop speed regulation for applications ranging from fans and pumps to precise winder control.
- Excellent torque production and tight torque regulation for demanding applications like extruders, web process and test stands.
- Fast update times of torque inputs are suitable for high performance applications.
- All of this flexibility is possible through multiple control modes: V/Hz control, Sensorless Vector, Vector Control with FORCE™ Technology, and Permanent Magnet Control (700S control only).
- Safe Off Option (1), the first offering available within the DriveGuard™ series of safety solutions, prevents a drive from delivering rotational energy to motors by integrating a safety circuit with the drive's power switching signals. This solution meets EN 954-1, Category 3.
- (1) At time of publication, the Safe Off Option is available with the PowerFlex 700S Control Option in Frame 3A and 3B PowerFlex 700L drives.

Packaging Options

- The PowerFlex 700L Frame 2 is an IP00 (Open Style) panel mount drive that can be mounted in a variety of enclosures.
- The PowerFlex 700L Frame 3A and 3B are available in a IP20 (NEMA 1) Rittal enclosure that includes the input circuit breaker.
- The majority of heat lost from the drive is transferred to the liquid coolant. Therefore, other enclosure options such as IP54 (NEMA/UL Type 12) or IP66 (NEMA/UL Type 4X) can be utilized and placed directly into dusty, dirty and outdoor environments. Contact your local Rockwell Automation drive center for these packaging options.

Cooling Loop Options

- The PowerFlex 700L Liquid-to-Liquid Heat Exchanger provides customers a cost effective, standard cooling loop solution for use with the PowerFlex 700L drive. The liquid to liquid heat exchanger utilizes a heat transfer plate to transfer heat from one liquid to another and does require a stable water supply from the user.
- A chiller or liquid to air heat exchanger can also be used with the PowerFlex 700L drive. See page 41 for details.

Easy to Use Communication and Human Interface Options

Premier Integration with PowerFlex Drives and RSLogix 5000

For simplified AC drive start-up and reduced development time, we've integrated Allen-Bradley PowerFlex drive configuration with $RSLogix^{TM}$ 5000 software. This single-software approach simplifies parameter and tag programming while still allowing stand-alone drive software tool use on the factory floor.

Communication Modules

DPI communication modules provide fast and efficient control and/or data exchange over the following interfaces:

- DeviceNetTM
- ControlNetTM
- EtherNet/IPTM
- Remote I/OTM
- Serial Communications
- Other open control and communication networks

Unsurpassed Capability in Network Communications

PowerFlex drives are fully compatible with the wide variety of Allen-Bradley DPI^{TM} communication adapters, offering the following benefits:

BACnet [®]	DeviceNet™	ControlNet™	EtherNet/IP™	Remote I/O	RS485 DF1	PROFIBUS DP	Interbus™	LonWorks [™]	Modbus RTU	Modbus TCP	Metasys N2	Siemens P1 FLN	Bluetooth®	Description	
	~	>	~											Unconnected Messaging permits other network devices (e.g. PanelView™) to communicate directly to a drive without routing the communication through the network scanner.	
~	~	/	<		<				~				~	Adapter Routing – Plug PC into one drive and talk to all other Allen-Bradley drives on same network, without being routed through the network scanner.	
~	~	>	~	\	~	~	~	~	~	~	~	~	~	Access to 100% of all parameters over the network.	
~	~		<			<								AutoBaud capability makes initial connections less problematic.	
	~													Change of State significantly reduces network traffic by configuring control messages to be sent only upon customer defined states. Very flexible configuration for each node (Example: "reference must change by more than 5%").	
	~		<											Peer Control provides master-slave type control between drives, where one or more slave drives (consumers) can run based on the status of a master drive (producer), which can also significantly reduce network traffic.	
	~													Automatic Device Replacement (ADR) saves significant time and effort when replacing a drive, by allowing the scanner to be configured to automatically detect a new drive and download the required parameter settings.	
V	~	~	•	>	~	~	′	~	~	~	~	~	~	Flexible Fault Configuration – Adapters can be programmed to take fault based actions such as ramp to stop, coast-to-stop, and hold last state, as well as send user configurable logic control and speed reference values. In addition, different actions can be taken based on whether the network experienced a serious problem (broken cable, etc.) versus a network idle condition (PLC set to "Program").	

PowerFlex Architecture-Class LCD Human Interface Modules

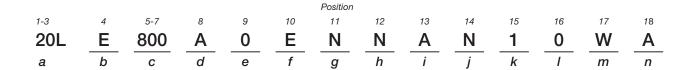
- An LCD Human Interface Module (also used with the PowerFlex 70, PowerFlex 700, PowerFlex 700S, and PowerFlex 700H) provides multilingual text for startup, metering, programming, and troubleshooting.
- Large and easy to read 7 line x 21 character backlit display
- Alternate function keys for shortcuts to common tasks
- "Calculator-like" number pad for fast and easy data entry (Full Numeric version only)
- Control keys for local start, stop, speed, and direction
- Remote versions for panel mount applications

PC-based Configuration Tools

- DriveExplorer[™] and DriveExplorer Lite. Simple and flexible "On-line" tools for monitoring and configuring while connected to a drive.
- DriveTools[™] SP. A suite of software tools which provide an intuitive means for programming, troubleshooting, and maintaining Allen-Bradley AC and DC drives.

Catalog Number Explanation

To interpret the meaning of a catalog number, match the values of the catalog number code in positions **a**, **b**, **c**, etc. with the tables labeled **a**, **b**, **c**, etc. below.



ć	3
Dr	ive
Code	Туре
20L	PowerFlex 700L

	D	
	Voltage Rating	
Code	Voltage	Ph.
С	400V AC	3
D	480V AC	3
Е	600V AC	3
F	690V AC	3

		CI					
	ND Rating						
	400	V, 60 Hz Ir	nput				
Code	Amps	kW	Нр	Frame			
360	360	200	268	2			
650	650	370	500	3A			
1K2	1250	715	960	3B			

		C2		
		ND Rating	ı	
	480	V, 60 Hz Ir	nput	
Code	Amps	kW	Нр	Frame
360	360	224	300	2
650	650	445	600	3A
1K2	1250	860	1150	3B

		c3				
	ND Rating					
	600V, 60 Hz Input					
Code	Amps	kW	Нр	Frame		
425	425	345	465	3A		
800	800	650	870	3B		

	C4						
	ND Rating						
	690V, 60 Hz Input						
Code	Amps	kW	Нр	Frame			
380	380	355	475	3A			
705	705	657	881	3B			
				-			

	d								
	Enclosure								
Code	Enclosure	Conformal Coating							
А	IP20, NEMA/UL Type 1 §	No							
N	IP00, Open Chassis *	No							
§ Frames 3A & 3B complete drive.									
# Frame 2 only.									

е					
HIM					
Code	Operator Interface				
0	No HIM/Blank Cover				
3	Full Numeric LCD (Frame 2 Only)				
С	Full Numeric LCD, Door Mount (Frames 3A & 3B Only)				

	f									
Documentation										
Code Documents Ship Carto										
Е	English Doc Set	Yes								
N	No Documentation	Yes								

	g
	Brake
Code	w/Brake IGBT
N	No

	h	
	Brake Resistor	
Code	w/Resistor	
N	No	

Equipment Type										
Code	Description	Frame								
Α	Complete Regenerative Drive	2, 3A & 3B								

	j	
	Comm Slot	
Code	Communication Option	DPI™ User Installed Kit Cat. No. ‡
N	None	N
С	DPI ControlNet (Coax) *	20-Comm-C
D	DPI DeviceNet *	20-Comm-D
Е	DPI EtherNet/IP *	20-Comm-E
R	DPI RIO *	20-Comm-R
S	DPI RS-485 DF1 *	20-Comm-S
1	DriveLogix™ ControlNet (Coax) ®	-
2	DriveLogix ControlNet Redundant (Coax) *	-
3	DriveLogix ControlNet (Fiber) *	-
4	DriveLogix ControlNet Redundant (Fiber) *	-
5	DriveLogix DeviceNet (Open Conn.) *	-
6	DriveLogix EtherNet/IP	-

- * 700 Vector Control uses DPI comm. slot options only.
- DriveLogix comm. slot options require 700S Phase II Control with DriveLogix5730.
- ‡ For 700S Phase II Control with DriveLogix5730, comm. slot option selections are mutually exclusive. For two communication adapters, (DPI and DriveLogix), select the DriveLogix comm. slot option and order the DPI user installed kit catalog number separately.

Code

W

Е

			k									
	Control Options											
Code	Code Control Cassette Logic Expansion Synch-L											
1	700VC 24V I/O	Base	N/A	N/A								
2	700VC 120V I/O	Base	N/A	N/A								
Α	700S Phase II	Expanded	No	No								
В	700S Phase II	Expanded	No	Yes								
С	700S Phase II	Expanded	Yes	No §								
D	700S Phase II	Expanded	Yes	Yes §								
§ Requir	es DriveLogix57	30.	•									

K	Phase II Control w/DriveLogix5730	No								
L	Phase II Control w/DriveLogix5730	EtherNet/IP								
	n									
Coolant Type										
Code	Coolant Frame									

Water

m
Additional Config.

Logix Option

None Phase II Control Embedded

Comm.

No

All

	I										
	Feedback										
Code Control Type											
0	All	None									
1	700VC	Encoder 5V/12V									
Α	700S Ph. II	Resolver *									
В	700S Ph. II	Stegmann Hi-Resolution Encoder *									
С	700S Ph. II	Multi-Device Interface ♣≻									
Е	700S Ph. II	2nd Encoder ♣									

^{*} Expanded cassette required.

Multi-Device Interface allows the connection of the Stegmann and Temposonics linear sensors. The Temposonics sensor cannot be used to close motor control or speed loops.

Standard Drive Product Selection

400V AC Three-Phase Drives

Out	Output Amps (with 400V AC Induction Motor) (1)						ominal Po	wer Rating	gs	IP20, NEMA/UL Type 1 (2)	Frame	PWM Freg.
1	Normal Duty		Heavy Duty			Normal Duty		Heavy Duty				
Cont.	110% 1 Min.	150% 3 sec.	Cont.	150% 1 Min.	200% 3 sec.	kW	НР	kW	НР	Catalog No.	Size	(kHz)
360	396	540	264	396	540	200	268	150	200	20LC360N0ENNAN10WA	2	4
650	715	975	475	715	975	370	500	270	365	20LC650A0ENNAN10WA	3A	4
1250	1375	1875	915	1375	1875	715	960	525	700	20LC1K2A0ENNAN10WA	3B	4

⁽¹⁾ Frame 2 ratings are based on 50°C ambient and 50°C coolant. Frame 3A and 3B ratings are based on 40°C ambient and 40°C coolant.

480V AC Three-Phase Drives

Out	Output Amps (with 480V AC Induction Motor) (1)						ominal Po	wer Rating	gs	IP20, NEMA/UL Type 1 (2)		DWM
Normal Duty		Heavy Duty			Norma	Normal Duty		y Duty		Frame	PWM Frea.	
Cont.	110% 1 Min.	150% 3 sec.	Cont.	150% 1 Min.	200% 3 sec.	kW	HP	kW	HP	Catalog No.	Size	(kHz)
360	396	540	264	396	540	224	300	175	235	20LD360N0ENNAN10WA	2	4
650	715	975	475	715	975	445	600	325	440	20LD650A0ENNAN10WA	3A	4
1250	1375	1875	915	1375	1875	860	1150	630	845	20LD1K2A0ENNAN10WA	3B	4

 $^{^{(1)} \}quad \text{Frame 2 ratings are based on } 50^{\circ}\text{C ambient and } 50^{\circ}\text{C coolant. Frame 3A and 3B ratings are based on } 40^{\circ}\text{C ambient and } 40^{\circ}\text{C coolant.}$

600V AC Three-Phase Drives

Out	Output Amps (with 600V AC Induction Motor) (1)							wer Ratin	gs	IP20, NEMA/UL Type 1		DWA
Normal Duty		Heavy Duty			Normal Duty Heavy Duty			y Duty		Frame	PWM Frea.	
Cont.	110% 1 Min.	150% 3 sec.	Cont.	150% 1 Min.	200% 3 sec.	kW	HP	kW	НР	Catalog No.	Size	(kHz)
425	470	640	315	470	640	345	465	255	345	20LE425A0ENNAN10WA	3A	4
800	885	1200	590	885	1200	650	870	480	640	20LE800A0ENNAN10WA	3B	4
1175	1295	1765	860	1295	1765	955	1275	695	935	20LE1K1A0ENNAN10WA	3B	2 (2)

⁽¹⁾ Frame 3A and 3B ratings are based on 40°C ambient and 40°C coolant.

690V AC Three-Phase Drives

Out	Output Amps (with 690V AC Induction Motor) (1)						ominal Po	ower Ratin	gs	IP20, NEMA/UL Type 1		DWA
Normal Duty		Heavy Duty			Normal Duty		Heavy Duty			Frame	PWM Frea.	
Cont.	110% 1 Min.	150% 3 sec.	Cont.	150% 1 Min.	200% 3 sec.	kW	HP	kW	HP	Catalog No.	Size	(kHz)
380	420	570	280	420	570	355	475	260	350	20LF380A0ENNAN10WA	3A	4
705	780	1060	520	780	1060	657	881	485	650	20LF705A0ENNAN10WA	3B	4
1050	1155	1575	770	1155	1575	980	1315	720	965	20LF1K0A0ENNAN10WA		2 (2)

⁽¹⁾ Frame 3A and 3B ratings are based on 40°C ambient and 40°C coolant.

⁽²⁾ Frames 3A and 3B only. Frame 2 drives are IP00, NEMA/UL Type Open.

⁽²⁾ Frames 3A and 3B only. Frame 2 drives are IP00, NEMA/UL Type Open.

⁽²⁾ Must operate at 2 kHz PWM only, and only as a stand-alone inverter module ("K" in catalog string position 13).

⁽²⁾ Must operate at 2 kHz PWM only, and only as a stand-alone inverter module ("K" in catalog string position 13).

Factory Installed Options

Human Interface and Wireless Interface Modules IP20, NEMA/UL Type 1 (Position e)







Cat. Code: 3 LCD Display, Full Numeric Keypad



Cat. Code: C Door Mounted Bezel LCD Display, Full Numeric Keypad NEMA/UL Type 1

Documentation

	Cat. Code
Description	(Position f)
English Documentation Set	Е
No Documentation	N

Internal Communication Adapters

	Cat. Code
Description	(Position j)
None	N
ControlNet™ Communication Adapter (Coax) ‡	С
DeviceNet™ Communication Adapter ‡	D
EtherNet/IP™ Communication Adapter ‡	Е
Remote I/O Communication Adapter ‡	R
RS485 DF1 Communication Adapter ‡	S
DriveLogix Comm Option, ControlNet (Coax) §	1
DriveLogix Comm Option, ControlNet Redundant (Coax) §	2
DriveLogix Comm Option, ControlNet (Fiber) §	3
DriveLogix Comm Option, ControlNet Redundant (Fiber) §	4
DriveLogix Comm Option, DeviceNet (Open Conn.) §	5
DriveLogix Comm Option, EtherNet/IP (Twisted Pair) §	6

- \ddagger 700 Vector Control uses DPI comm. slot options only.
- S DriveLogix comm. slot option requires 700S Phase II Control with DriveLogix5730.

Control Options

		Cat. Code
Control Option	Description	(Position k)
700VC - 24V I/O	Base Cassette	1
700VC - 115V I/O	Base Cassette	2
	Expanded Cassette Only	Α
Phase II Control	Expanded Cassette w/SynchLink	В
Phase II Control *	Expanded Cassette w/Logix Expansion Board	С
rnase ii Control *	Expanded Cassette w/Logix Expansion Board & SynchLink	D

^{*} Requires DriveLogix5730.

Feedback Options

Control		Cat. Code
Туре	Description	(Position I)
All	No Encoder	0
700VC	12V/5V Encoder	1
	Resolver, 1026V, 10 kHz, 1016 bit	А
	Stegmann - High Resolution Encoder Hyperface, 8.5V dc, 20 bit, 100k/r §	В
700S Phase II	Multi-Device Interface - for Stegmann or Linear Temposonics §	С
	2nd Encoder, 5V or 12V Configurable by the Drive §	E
	DriveGuard Safe-Off (w/2nd Encoder) §	S

[§] Requires Expanded Cassette.

Additional 700S Configurations

	Embedded	Cat. Code
Description	Communica tion	(Position m)
None	_	W
Phase II Control	No	Е
Phase II Control, with DriveLogix5730 Controller	No	K
Phase II Control, with DriveLogix5730 Controller & EtherNet/IP	EtherNet/IP	L

Coolant Options

		Cat. Code
Description	Frame	(Position n)
Water	All	А

User Installed Options

Human Interface and Wireless Interface Modules



No HIM (Blank Plate) 20-HIM-A0



LCD Display, Full Numeric Keypad 20-HIM-A3



LCD Display, Programmer Only 20-HIM-A5



Wireless Interface Module 20-WIM-N1



Remote (Panel Mount) LCD Display, Full Numeric Keypad 20-HIM-C3S



Remote (Panel Mount) LCD Display, Programmer Only 20-HIM-C5S



Remote (Panel Mount) Wireless Interface Module 20-WIM-N4S

	Handheld/Local (Drive Mount)	Remote (Panel Mount) IP66, NEMA/UL Type 4x/12 *
Description	Cat. No.	Cat. No.
No HIM (Blank Plate)	20-HIM-A0	-
LCD Display, Full Numeric Keypad	20-HIM-A3	20-HIM-C3S §
LCD Display, Programmer Only	20-HIM-A5	20-HIM-C5S §
Wireless Interface Module	20-WIM-N1	20-WIM-N4S

^{*} For indoor use only.

Human Interface Module Accessories

Description	Cat. No.
Bezel Kit for LCD HIMs, NEMA/UL Type 1 §	20-HIM-B1
PowerFlex HIM Interface Cable, 1 m (39 in) *	20-HIM-H10
Cable Kit (Male-Female) ➤	•
0.33 Meters (1.1 Feet)	1202-H03
1 Meter (3.3 Feet)	1202-H10
3 Meter (9.8 Feet)	1202-H30
9 Meter (29.5 Feet)	1202-H90
DPI/SCANport™ One to Two Port Splitter Cable	1203-S03

[§] Includes a 1202-C30 interface cable (3 meters) for connection to drive

- * Required only when HIM is used as handheld or remote.
- ➤ Required in addition to 20-HIM-H10 for distances up to a total maximum of 10 Meters (32.8 Feet).

[§] Includes a 1202-C30 interface cable (3 meters) for connection to drive.

Communication Option Kits

Description	Cat No
ControlNet™ Communication Adapter (Coax)	20-COMM-C
DeviceNet™ Communication Adapter	20-COMM-D
EtherNet/IP™ Communication Adapter	20-COMM-E
Interbus™ Communication Adapter	20-COMM-I
CANopen® Communication Adapter	20-COMM-K
Modbus/TCP Communication Adapter	20-COMM-M
PROFIBUS™ DP Communication Adapter	20-COMM-P
ControlNet™ Communication Adapter (Fiber)	20-COMM-Q
	20-COMM-R
Remote I/O Communication Adapter	20-COMM-S
RS485 DF1 Communication Adapter	
DriveLogix ControlNet Communication Adapter (Coax) ★❖	1788-CNC
DriveLogix Comm Option, ControlNet Redundant (Coax) ★❖	1788-CNCR
DriveLogix Comm Option, ControlNet (Fiber) ★❖	1788-CNF
DriveLogix Comm Option, ControlNet Redundant (Fiber) ★❖	1788-CNFR
DriveLogix Comm Option, DeviceNet (Open Conn.) ★❖	1788-DNBO
DriveLogix Comm Option, EtherNet/IP (Twisted Pair) ★❖	1788-ENBT
DriveLogix5730 Comm Option, Embedded EtherNet/IP	20D-DL2- ENET0
External Communications Kit Power Supply	20-XCOMM- AC-PS1
DPI External Communications Kit	20-XCOMM- DC-BASE
External DPI I/O Option Board +	20-XCOMM- IO-OPT1
Compact I/O Module (3 Channel)	1769-SM1

- * For use with DriveLogix option only.
- + For use only with External DPI Communications Kits 20-XCOMM-DC-BASE.
- ❖ Requires Logix Expansion Board (20D-DL2-LEB0).

Communication Accessories

Description	Cat. No.
Serial Null Modem Adapter	1203-SNM
Smart Self-powered Serial Converter (RS232) includes 1203- SFC and 1202-C10 Cables	1203-SSS
Universal Serial Bus™ (USB) Converter includes 2m USB, 20-HIM-H10 & 22-HIM-H10 Cables	1203-USB
ControlNet Ex Right-Angle T-Tap 1 Meter Coax Cable Assembly	1786-TPR

PC Programming Software

Description		
DriveTools™ SP Software +		
DriveExplorer™ Software (Lite/Full) + ❖	See publication PFLEX-SG002 for further information	
Pocket DriveExplorer™ Software		

- → Set-up wizards are available for use with DriveTools SP and DriveExplorer (Lite/Full) only.
- DriveExplorer Lite is available for free download at: http://www.ab.com/drives/driveexplorer/free_download.html.

Accessories

Note: Please refer to publication number <u>1756-TD008</u> for details on SynchLink.

Description	Cat. No.
SynchLink Board	20D-P2-SLB0
SynchLink Fiber Base Block	1751-SLBA
SynchLink 4-port Fiber Splitter Block	1751-SL4SP
SynchLink Fiber Bypass Switch Block	1751-SLBP
2x1 Meter Fiber Link for Power Monitor/SynchLink	1403-CF001
2x3 Meter Fiber Link for Power Monitor/SynchLink	1403-CF003
2x5 Meter Fiber Link for Power Monitor/SynchLink	1403-CF005
10 Meter Fiber Link for Power Monitor/SynchLink	1403-CF010
20 Meter Fiber Link for Power Monitor/SynchLink	1403-CF020
50 Meter Fiber Link for Power Monitor/SynchLink	1403-CF050
100 Meter Fiber Link for Power Monitor/SynchLink	1403-CF100
250 Meter Fiber Link for Power Monitor/SynchLink	1403-CF250

Feedback Option Kits

Description	Cat. No.
Multi-Device Interface ➤	20D-MDI-C2
DriveGuard Safe-Off (w/2nd Encoder) ➤	20D-P2-DG01
2nd Encoder, 5V/12V ➤	20D-P2-ENC0
Resolver >	20D-RES-A1
Stegmann High Resolution Hyperface Encoder ➤	20D-STEG-B1

➤ Requires Expanded Cassette.

DriveLogix Option Kits

Description	Cat. No.
Logix Expansion board for DriveLogix5730 ➤	20D-DL2-LEB0
Industrial Compact Flash 64K Memory Card	1784-CF64

➤ Requires Expanded Cassette.

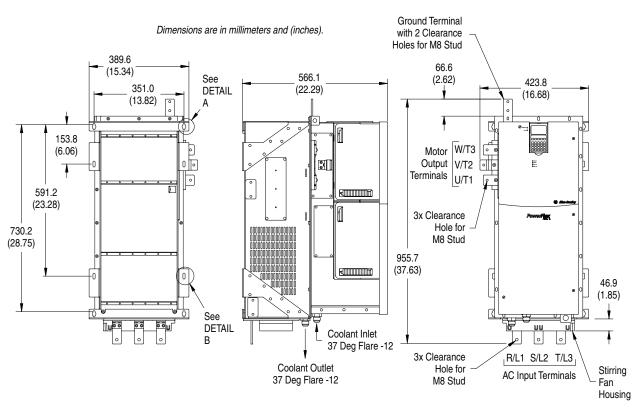
DriveLogix I/O Cables

Description	Cat. No.
DriveLogix5730 - Compact I/O cable, 3.28 ft. (1 meter), Left Bus Cap≻§	20D-DL2-CL3
DriveLogix5730 - Compact I/O cable, 3.28 ft. (1 meter), Right Bus Cap ≻§	20D-DL2-CR3
Logix5000 RS-232 Programming Cable	1756-CP3

- ➤ Requires Expanded Cassette.
- § Refer to Publication 1769-SG001 for details and selection of Compact I/O.

Product Dimensions

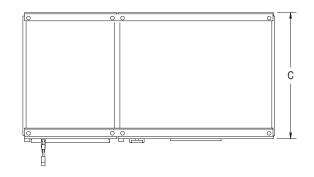
Frame 2 Drive



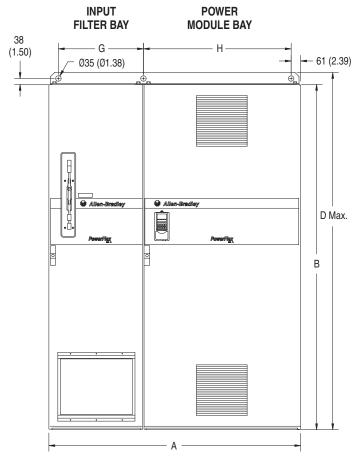
BACK VIEW SIDE VIEW FRONT VIEW 4x Ø 8.5 (0.33) 15.0 (0.59) DETAIL A DETAIL B

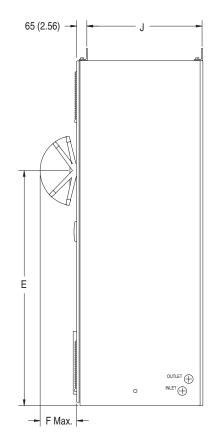
Weight: 186 kg (410 lbs.)

Frame 3A/3B Drive



Dimensions are in millimeters and (inches).





Frame	Dimensions									Weight kg (lbs.)		
Size	Α	В	С	D	E	F	G	Н	J	Complete Drive		
3A	1200 (47.2)	2000 (78.7)	600 (23.6)	2078 (81.9)	1500 (59.1)	233 (9.2)	542 (21.3)	542 (21.3)	535 (21.1)	950 (2090)		
3B	1600 (63.0)	2200 (86.6)	800 (31.5)	2278 (89.8)	1500 (59.1)	233 (9.2)	542 (21.3)	942 (37.1)	735 (28.9)	1361 (3000)		

Installation Considerations

Power Wiring

The PowerFlex 700L has the following built in protective features to help simplify installation:

- Ground fault protection during start up and running ensures reliable operation
- Electronic motor overload protection increases motor life

AC Supply Source Considerations

PowerFlex 700L Liquid-Cooled AC drives are suitable for use on a circuit capable of delivering up to a maximum of 200,000 rms symmetrical amperes.

PowerFlex 700L Liquid Cooled AC drives should not be used on undersized or high-impedance supply systems. The supply system kVA should be equal to or greater than the drive-rated kW, and the system impedance should be less than 10%. Operation outside these limits could cause instability resulting in drive shutdown.

PowerFlex 700L Liquid Cooled AC drives have a built-in LCL filter which includes a 3% input line reactor. Additional input line reactors are not recommended.

Unbalanced, Ungrounded or Resistive Grounded Distribution Systems

Removable MOV to ground and common mode capacitors to ground ensure compatibility with ungrounded systems. These devices must be disconnected if the drive is installed on a resistive grounded distribution system, an ungrounded distribution system, or a B phase grounded distribution system. These devices must also be disconnected if a regenerative unit is used as a bus supply or brake.

Input Power Conditioning

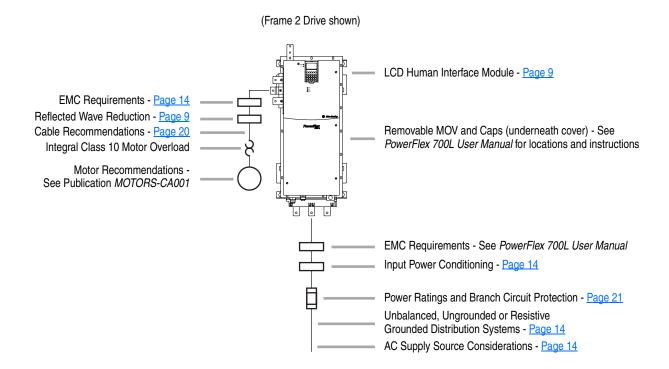
Certain events on the power system supplying a drive can cause component damage or shortened product life. They are:

- The power system has power factor correction capacitors switched in and out of the system, either by the user or by the power company.
- The power source has intermittent voltage spikes in excess of 6000 volts. These spikes could be caused by other equipment on the line or by events such as lightning strikes.
- The power source has frequent interruptions.

There are many other factors that must be considered for optimal performance in any given application. The block diagram below highlights the primary installation considerations. For detailed recommendations on input power conditioning, reflected wave protection, and motor cable types, refer to *Wiring and Grounding Guidelines for AC Drives* (publication DRIVES-IN001) available online at www.rockwellautomation.com/literature.

EMC Requirements

The 700VC control option for Frame 2 comes with two common mode chokes — one for input and one for output. The 700S control option for Frame 2 requires a field-installed kit SK-L1-CHK2-F2. See the *PowerFlex 700L User Manual* (publication 20L-UM001) for other CE requirements. PowerFlex 700L Frame 3A and 3B drives do not require common mode chokes for CE compliance.



Frame 2 Drive

Recommended Mounting Clearances

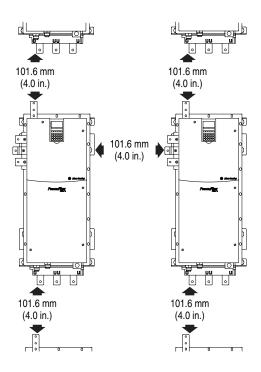
Specified vertical clearance requirements are intended to be from drive to drive. Other objects can occupy this space; however, reduced air flow may cause protection circuits to fault the drive. In addition, inlet air temperature must not exceed the product specification.

Mounting Requirements

The PowerFlex700L Frame 2 drive is a single integrated assembly consisting of a filter section and a power section. The filter section provides the mounting feet and represents greater than 50% of the approximately 186 kg (410 lb.) total weight.

- The Frame 2 drive should be mounted into an enclosure that is designed according to Electrical Equipment Pollution Degree 2 requirements.
- Any enclosure mounting panel needs to be sized and fastened appropriately to accommodate for the weight of the drive.
- The Frame 2 drive is designed to use eight M8 x 1.25 fasteners in mounting slots shown in Detail A and Detail B of the drawing on page 12.
- The M8 x 1.25 fasteners shall be class 5.8 or greater.
- The fasteners shall use a lock washer or similar mechanism to prevent loosening after mounting.

Frame 2 Drive Clearances



- All M8 x 1.25 fastener threads shall engage a steel panel with 6 to 7 full threads or a permanent backing nut such as a weld nut or a self-clinching PEM[®](1) nut with 4 full threads.
- M8 x 1.25 fasteners shall be tightened to 11.3 ± 2.8 N•m (100 ± 25 lb•in) unless the lock washer mechanism requires a different torque. If this is the case, the holding force shall be equivalent.

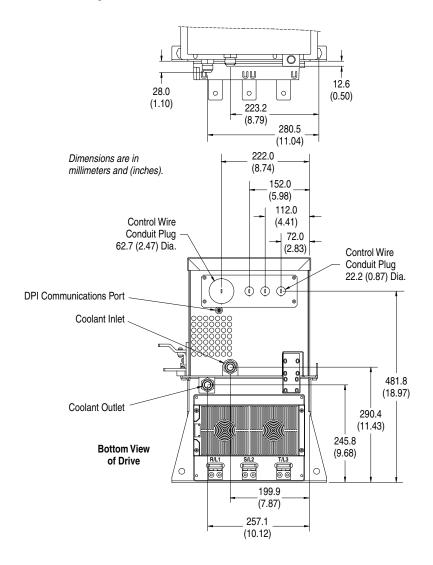
Determining Wire Routing for Control, Ground, Drive Input, and Motor Output

All wiring should be installed in conformance with the applicable local, national, and international codes (e.g., NEC/CEC). Signal wiring, control wiring, and power wiring must be routed in separate conduits to prevent interference with drive operation. Use grommets, when hubs are not provided, to guard against wire chafing.

Do not route signal and control wiring with power wiring in the same conduit. This can cause interference with drive operation. Failure to observe this precaution could result in damage to, or destruction of, the equipment.

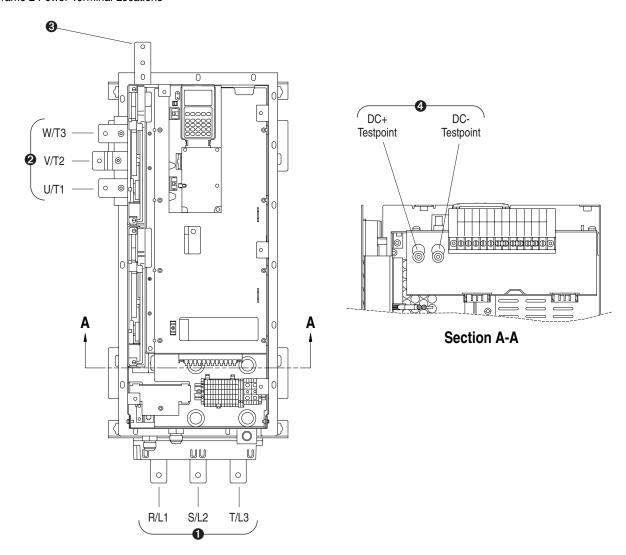
Do not route more than three sets of motor leads through a single conduit. This will minimize cross-talk that could reduce the effectiveness of noise reduction methods. If more than three drive/motor connections per conduit are required, shielded cable must be used. If possible, each conduit should contain only one set of motor leads.

Frame 2 Locations for Control Wire Routing, DPI Communications Port, and Coolant Connections.



(1) PEM is a registered trademark of PennEngineering.

Frame 2 Power Terminal Locations



Frame 2 Power Terminal Specifications

Item	Name	Description	Recommended Tightening Torque (±10%)	Terminal Bolt Size (1)		
0	Input Power Bus Bar (2) R/L1, S/L2, T/L3	Input power	40 N∙m (354 lb•in)	M8		
0	Output Power Bus Bar (2) U/T1, V/T2, W/T3	Motor connections	40 N∙m (354 lb•in)	M8		
0	PE, Motor Ground Bus Bar (2)	Terminating point for wiring shields and grounds	40 N∙m (354 lb•in)	M8		
4	DC Bus Test Point Socket (3) (2 Terminals; DC+, DC-)	4 mm socket for DC bus voltage measurement only	_	_		

⁽¹⁾ Apply counter torque to the nut on the other side of terminations when tightening or loosening the terminal bolt to avoid damage to the terminal.

 $^{^{(2)}}$ These connections are bus bar type terminations and require the use of lug connectors.

⁽³⁾ Use only to verify that DC bus capacitors are discharged before servicing the Power Module. No other external use is permitted.

Frame 3A/3B Drive

Recommended Mounting Clearances

Be sure there is adequate clearance for air circulation around the drive enclosures. A 15 cm (6-in.) minimum clearance is required wherever vents are located in the cabinet.

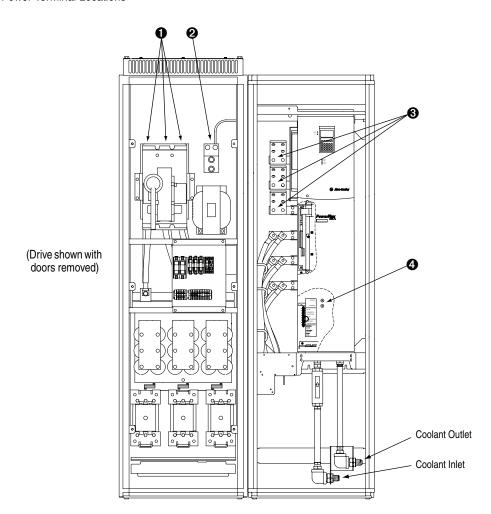
Determining Wire Routing for Control, Ground, Drive Input, and Motor Output

All wiring should be installed in conformance with the applicable local, national, and international codes (e.g., NEC/CEC). Signal wiring, control wiring, and power wiring must be routed in separate conduits to prevent interference with drive operation. Use grommets, when hubs are not provided, to guard against wire chafing.

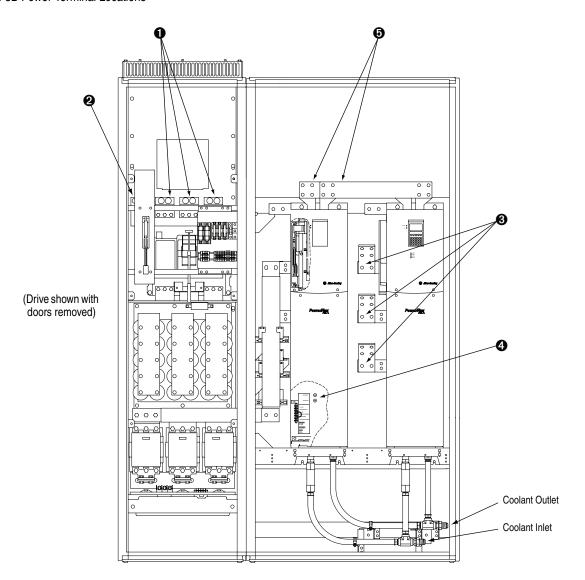
Do not route signal and control wiring with power wiring in the same conduit. This can cause interference with drive operation. Failure to observe this precaution could result in damage to, or destruction of, the equipment.

Do not route more than three sets of motor leads through a single conduit. This will minimize cross-talk that could reduce the effectiveness of noise reduction methods. If more than three drive/motor connections per conduit are required, shielded cable must be used. If possible, each conduit should contain only one set of motor leads.

Frame 3A Power Terminal Locations



Frame 3B Power Terminal Locations



Frame 3A/3B Power Terminal Specifications

			Frame	Wire Size Ra	ange (1)	Recommended Tightening Torque (±10%)		
Item	Name	Description	Size	Maximum	Minimum			
0	Input Power Wire Lugs	Input power connections on drive	3A	400 MCM	3/0	42 N•m (375 lb•in)		
	R/L1, S/L2, T/L3		3B	1000 MCM	500 MCM	62 N•m (550 lb•in)		
0	PE Wire Lug	Terminating point for ground wires	3A or 3B	600 MCM	# 2 AWG	34 N∙m (300 lb•in)		
0	Output Power Bus Bar (2) U/T1, V/T2, W/T3	Motor connections	3A or 3B			62 N∙m (550 lb•in)		
4	DC Bus Test Point Socket (3) (2 Terminals; DC+, DC-)	4 mm socket for DC bus voltage measurement only	3A or 3B	_	_	_		
•	DC Power Bus Bar (2) (4) (2 Terminals; DC+, DC-)	DC power from Converter Power Module to Inverter Power Module	3B			62 N∙m (550 lb•in)		

⁽¹⁾ Maximum/minimum sizes that the terminals will accept - these are not recommendations.

⁽²⁾ These connections are bus bar type terminations and require the use of lug connectors.

⁽³⁾ Use only to verify that DC bus capacitors are discharged before servicing the Power Module. No other external use is permitted.

 $^{^{(4)}}$ Size DC power conductors for current carrying capacity as follows: 400/480V, 1000 Amps; 600/690V, 800 Amps.

Cable Recommendations

Cable Types Acceptable for 200-600 Volt Installations

A variety of cable types are acceptable for drive installations. For many installations, unshielded cable is adequate, provided it can be separated from sensitive circuits. As an approximate guide, allow a spacing of 0.3 meters (1 foot) for every 10 meters (32.8 feet) of length. In all cases, long parallel runs must be avoided. Do not use cable with an insulation thickness less than or equal to 15 mils (0.4 mm/0.015 in.). Use Copper wire only. Wire gauge requirements and recommendations are based on 75°C (167°F). Do not reduce wire gauge when using higher temperature wire. See table below.

Unshielded Cable

THHN, THWN or similar wire is acceptable for drive installation in dry environments provided adequate free air space and/or conduit fill rates limits are provided. **Do not use THHN or similarly coated wire in wet areas**. Any wire chosen must have a minimum insulation thickness of 15 mils (0.4mm/0.015 in.) and should not have large variations in insulation concentricity.

Shielded Cable

Shielded cable contains all of the general benefits of multi-conductor cable with the added benefit of a copper braided shield that can contain much of the noise generated by a typical AC drive. Strong consideration for shielded cable should be given in installations with sensitive equipment such as weigh scales, capacitive proximity switches, and other devices that may be affected by electrical noise in the distribution system. Applications with large numbers of drives in a similar location, imposed EMC regulations or a high degree of communications/networking are also good candidates for shielded cable.

Shielded cable may also help reduce shaft voltage and induced bearing currents for some applications. In addition, the increased impedance of shielded cable may help extend the distance that the motor can be located from the drive without the addition of motor protective devices such as terminator networks. Refer to "Reflected Wave" in *Wiring and Grounding Guidelines for Pulse Width Modulated (PWM) AC Drives, publication DRIVES-IN001*.

Consideration should be given to all of the general specifications dictated by the environment of the installation, including temperature, flexibility, moisture characteristics, and chemical resistance. In addition, a braided shield should be included and be specified by the cable manufacturer as having coverage of at least 75%. An additional foil shield can greatly improve noise containment.

A good example of recommended cable is Belden® 29528-29532 (AWG-1 through AWG-410). This cable has 3 XLPE insulated conductors plus ground with a spiral copper shield surrounded by a PVC jacket.

Other types of shielded cable are available, but the selection of these types may limit the allowable cable length. Particularly, some of the newer cables twist 4 conductors of THHN wire and wrap them tightly with a foil shield. This construction can greatly increase the cable charging current required and reduce the overall drive performance. These cables are not recommended.

Armored Cable

Cable with continuous aluminum armor is often recommended in drive system applications or specific industries. It offers most of the advantages of standard shielded cable and also combines considerable mechanical strength and resistance to moisture. It can be installed in concealed and exposed manners and removes the requirement for conduit (EMT) in the installation. It can also be directly buried or embedded in concrete.

Because noise containment can be affected by incidental grounding of the armor to building steel (see "Wire Types" in Wiring and Grounding Guidelines for Pulse Width Modulated (PWM) AC Drives, publication DRIVES-IN001) when the cable is mounted, it is recommended the armor cable have an overall PVC jacket.

Interlocked armor is acceptable for shorter cable runs, but continuous welded armor is preferred.

Best performance is achieved with three spaced ground conductors, but acceptable performance below 200 HP is provided via a single ground conductor.

Location	Cable Rating/Type	Description
Standard (Option 1)	1000V, 90°C (194°F) XHHW2/RHW-2	Four tinned copper conductors with XLPE insulation.
	Anixter B29528-B29532, Belden 29528-29532, or	Copper braid/aluminum foil combination shield and tinned copper drain wire.
	equivalent	PVC jacket.
Standard (Option 2)	Tray rated 1000V, 90°C (194°F) RHH/RHW-2	Three tinned copper conductors with XLPE insulation.
	Anixter OLFLEX-76xxx03 or equivalent	Corrugated copper tape with three bare copper grounds in contact with shield.
		PVC jacket.
Class I & II; Division I & II	Tray rated 1000V, 90°C (194°F) RHH/RHW-2 Anixter 7VFD-xxxx or equivalent	 Three bare copper conductors with XLPE insulation and impervious corrugated continuously welded aluminum armor.
		Black sunlight resistant PVC jacket overall.
		Three copper grounds.

Cable Trays and Conduit

If cable trays or large conduits are to be used, refer to guidelines presented in the Wiring and Grounding Guidelines for Pulse Width Modulated (PWM) AC Drives, publication DRIVES-IN001.

Power Ratings and Branch Circuit Protection

Frame 2 Drive

Most codes require that upstream branch circuit protection be provided to protect input power wiring.

The Frame 2 drive does not provide input power short circuit protection. The tables below provide drive ratings and recommended AC line input fuse and circuit breaker information. Both types of short circuit protection are acceptable for UL and IEC requirements. Sizes listed are the recommended sizes <u>based on 40°C and the U.S. N.E.C.</u> Other country, state or local codes may require different ratings.

Fusing

If fuses are chosen as the desired protection method, refer to the recommended types listed below. If available amp ratings do not match the tables provided, the <u>closest</u> fuse rating that exceeds the drive rating should be chosen.

- IEC BS88 (British Standard) Parts 1 & 2 (1), EN60269-1, Parts 1 & 2, type gG or equivalent should be used.
- UL UL Class T, J or L must be used.

⁽¹⁾ Typical designations include, but may not be limited to the following; Parts 1 & 2: AC, AD, BC, BD, CD, DD, ED, EFS, EF, FF, FG, GF, GG, GH.

Circuit Breakers

The "non-fuse" listings in the tables below include both circuit breakers (inverse time or instantaneous trip). **If one of these is chosen as the desired protection method**, the following requirements apply.

• IEC and UL – Both types of devices are acceptable for IEC and UL installations.

400 Volt AC Input Protection Devices

Drive		HP (kW) Rat	\				Dual Elem Time Dela		Non-Time I	Delay Fuse	Circuit Breaker (3)	Motor Circuit Protector (5)		
Cat. No.	Frame	ND	HD	Amps	Min. ⁽¹⁾	Max. (2)	Min.	Max.	Max. (4)	Max.				
20LC360	2	268 (200)	_	360	500	750	500 900		900	600				
		_	200 (150)	264	400	650	450	900	900	400				

⁽¹⁾ Minimum protection device size is the lowest rated device that supplies maximum protection without nuisance tripping.

480 Volt AC Input Protection Devices

Drive		(,		Input Rating Dual Element Time Delay Fuse			Non-Time [Delay Fuse	Circuit Breaker (3)	Motor Circuit Protector (5)		
Cat. No.	Frame	ND	HD	Amps	Min. (1)	Max. (2)	Min.	Max.	Max. (4)	Max.		
20LD360	2	300 (224)	_	360	500	750	500	900	900	600		
		_	235 (175)	264	400	650	450	900	900	400		

⁽¹⁾ Minimum protection device size is the lowest rated device that supplies maximum protection without nuisance tripping.

Frame 3A/3B Drive

Frame 3A/3B Complete Drives include an input power circuit breaker. The value of the circuit breaker provided with the drive is listed in the table below.

Frame Size	Input Voltage	Circuit Breaker Provided	Shunt Trip Rating
3A	400-480V AC	800 A	65 kAIC
	575-690V AC	800 A	35 kAIC
3B	400-480V AC	1500 A	100 kAIC
	575-690V AC	1500 A	35 kAIC

⁽²⁾ Maximum protection device size is the highest rated device that supplies drive protection. For US NEC, minimum size is 125% of motor FLA. Ratings shown are maximum.

⁽³⁾ Circuit Breaker - inverse time breaker. For US NEC, minimum size is 125% of motor FLA. Ratings shown are maximum

⁽⁴⁾ Maximum allowable rating by US NEC. Exact size must be chosen for each installation.

⁽⁵⁾ Motor Circuit Protector - instantaneous trip circuit breaker. For US NEC minimum size is 125% of motor FLA. Ratings shown are maximum

⁽²⁾ Maximum protection device size is the highest rated device that supplies drive protection. For US NEC, minimum size is 125% of motor FLA. Ratings shown are maximum.

⁽³⁾ Circuit Breaker - inverse time breaker. For US NEC, minimum size is 125% of motor FLA. Ratings shown are maximum

⁽⁴⁾ Maximum allowable rating by US NEC. Exact size must be chosen for each installation.

⁽⁵⁾ Motor Circuit Protector - instantaneous trip circuit breaker. For US NEC minimum size is 125% of motor FLA. Ratings shown are maximum

Maximum Motor Cable Lengths

In the following tables, a "•" in any of the latter columns will indicate that this drive rating can be used with an Allen-Bradley Terminator (1204-TFA1/1204-TFB2) and/or Reflected Wave Reduction Device with Common Mode Choke (1204-RWC-17) or without choke (1204-RWR2).

For the Terminator, the maximum cable length is 182.9 meters (600 feet) for 400/480/600V drives (not 690V). The PWM frequency must be 2 kHz.

The 1321-RWR is a complete reflected wave reduction solution available for many of the PowerFlex drives. If available, a 1321-RWR catalog number will be indicated in the "Reactor/RWR" column. When not available, use the reactor and resistor information provided to build a solution.

For Further Information on	See Publication
1204-TFxx	1204-IN002

PowerFlex 700L with 700VC Control, 400V Shielded/Unshielded Cable - Meters (Feet)

Drive			No Sol	ution			Reactor Only			Reactor + Damping Resistor			Reactor	Resistor		Available Options					
Frame	HP (kW)	kHz	1000V	1200V	1488V	1600V	1000V	1200V	1488V	1600V	1000V	1200V	1488V	1600V	Cat. No.	Ohms	Watts	TFA1	TFB2	RWR2	RWC
2	268 (200)	2	24.4 (80)	91.4 (300)	152.4 (500)	213.4 (700)	30.5 (100)	76.2 (250)	228.6 (750)	365.8 (1200)	152.4 (500)	274.3 (900)	365.8 (1200)	365.8 (1200)	1321-3R400-B ⁽¹⁾	20	495		•		
		4	24.4 (80)	91.4 (300)	121.9 (400)	152.4 (500)	18.3 (60)	76.2 (250)	137.2 (450)	182.9 (600)	76.2 (250)	137.2 (450)	274.3 (900)	365.8 (1200)	1321-3R400-B(1)	20	990				
3A	500 (370)	2	24.4 (80)	91.4 (300)	152.4 (500)	213.4 (700)	30.5 (100)	76.2 (250)	228.6 (750)	365.8 (1200)	152.4 (500)	274.3 (900)	365.8 (1200)	365.8 (1200)	1321-3R750-B ⁽¹⁾	20	735		•		
		4	24.4 (80)	91.4 (300)	121.9 (400)	152.4 (500)	18.3 (60)	76.2 (250)	137.2 (450)	182.9 (600)	76.2 (250)	137.2 (450)	274.3 (900)	365.8 (1200)	1321-3R750-B ⁽¹⁾	20	1470				
3B	960 (715)	2	24.4 (80)	76.2 (250)	129.5 (425)	160.0 (525)	91.4 (80)	76.2 (250)	152.4 (500)	228.6 (750)	152.4 (500)	274.3 (900)	365.8 (1200)	365.8 (1200)	2 x 1321-3R600-B ⁽²⁾	20	525				
		4	18.3 (60)	76.2 (250)	121.9 (400)	152.4 (500)	18.3 (60)	76.2 (250)	121.9 (400)	152.4 (500)	76.2 (250)	137.2 (450)	274.3 (900)	365.8 (1200)	2 x 1321-3R600-B ⁽²⁾	20	1050				

⁽¹⁾ Requires two parallel cables.

PowerFlex 700L with 700VC Control, 480V Shielded/Unshielded Cable - Meters (Feet)

Drive			No Sol	ution			Reacto	or Only			Reacto	r + Dan	nping R	esistor	Reactor	Resist	or		ailab tion:		
Frame	HP (kW)	kHz	1000V	1200V	1488V	1600V	1000V	1200V	1488V	1600V	1000V	1200V	1488V	1600V	Cat. No.	Ohms	Watts	TFA1	TFB2	RWR2	RWC
2	300 (224)	2	12.2 (40)	30.5 (100)	91.4 (300)	121.9 (400)	12.2 (40)	36.6 (120)	99.1 (325)	137.2 (450)	61.0 (200)	137.2 (450)	274.3 (900)	365.8 (1200)	1321-3R400-B(1)	20	495		•		
		4	7.6 (25)	24.4 (80)	83.8 (275)	114.3 (375)	7.6 (25)	24.4 (80)	83.8 (275)	114.3 (375)	30.5 (100)	61.0 (200)	152.4 (500)	213.4 (700)	1321-3R400-B(1)	20	990				
3A	600 (445)	2	12.2 (40)	30.5 (100)	91.4 (300)	121.9 (400)	12.2 (40)	36.6 (120)	99.1 (325)	137.2 (450)	61.0 (200)	137.2 (450)	274.3 (900)	365.8 (1200)	1321-3R750-B ⁽¹⁾	20	735		•		
		4	7.6 (25)	24.4 (80)	83.8 (275)	114.3 (375)	7.6 (25)	24.4 (80)	83.8 (275)	114.3 (375)	30.5 (100)	61.0 (200)	152.4 (500)	213.4 (700)	1321-3R750-B(1)	20	1470				
3B	1150 (860)	2	12.2 (40)	24.4 (80)	83.8 (275)	114.3 (375)	12.2 (40)	30.5 (100)	91.4 (300)	121.9 (400)	61.0 (200)	137.2 (450)	274.3 (900)	365.8 (1200)	2 x 1321-3R600-B(2)	20	525				
		4	7.6 (25)	24.4 (80)	83.8 (275)	114.3 (375)	7.6 (25)	24.4 (80)	83.8 (275)	114.3 (375)	30.5 (100)	61.0 (200)	152.4 (500)	213.4 (700)	2 x 1321-3R600-B ⁽²⁾	20	1050				

⁽¹⁾ Requires two parallel cables.

⁽²⁾ Requires four parallel cables.

⁽²⁾ Requires four parallel cables.

PowerFlex 700L with 700VC Control, 600V Shielded/Unshielded Cable - Meters (Feet)

Drive			No Sol	ution	Reacto	or Only	Reacto Dampi Resiste	ng	Reactor	Resist	or		ilable ions	е	
Frame	HP (kW)	kHz	1488V	1850V	1488V	1850V	1488V	1850V	Cat. No.	Ohms	Watts	TFA1	TFB2	RWR2	RWC
3A	465 (345)	2	24.4 (80)	106.7 (350)	24.4 (80)	365.8 (350)	182.9 (600)	365.8 (1200)	1321-3R500-B ⁽¹⁾	20	585		•		
		4	18.3 (60)	61.0 (200)	18.3 (60)	61.0 (200)	76.2 (250)	190.5 (625)	1321-3R500-B(1)	20	1170				Ì
3B	870 (650)	2	18.3 (60)	91.4 (300)	18.3 (60)	91.4 (300)	152.4 (500)	274.3 (900)	1321-3R850-B ⁽²⁾	20	960				
		4	18.3 (60)	61.0 (200)	18.3 (60)	61.0 (200)	53.3 (175)	137.2 (450)	1321-3R850-B(2)	20	1920				
3B	1275 (955)	2	18.3 (60)	83.8 (275)	18.3 (60)	83.8 (275)	137.2 (450)	274.3 (900)	2 x 1321-3R600-B ⁽³⁾	20	720				

⁽¹⁾ Requires two parallel cables.

PowerFlex 700L with 700VC Control, 690V Shielded/Unshielded Cable - Meters (Feet)

Drive			No Sol	ution	Reacto	or Only	Reacto Dampi Resiste	ng	Reactor	Resist	or		ilable	;	
Frame	HP (kW)	kHz	1488V	1850V	1488V	1850V	1488V	1850V	Cat. No.	Ohms	Watts	TFA1	TFB2	RWR2	RWC
3A	475 (355)	2	24.4 (80)	45.7 (150)	24.4 (80)	45.7 (150)	228.6 (750)	304.8 (1000)	1321-3R500-C(1)	20	960				
		4	24.4 (80)	45.7 (150)	24.4 (80)	45.7 (150)	76.2 (250)	121.9 (400)	1321-3R500-C ⁽¹⁾	20	1920				
3B	881 (657)	2	24.4 (80)	45.7 (150)	24.4 (80)	45.7 (150)	182.9 (600)	228.6 (750)	1321-3R850-C(2)	20	1290		No	ne	
		4	24.4 (80)	45.7 (150)	24.4 (80)	45.7 (150)	76.2 (250)	121.9 (400)	1321-3R850-C(2)	20	2580				
3B	1315 (980)	2	24.4 (80)	45.7 (150)	24.4 (80)	45.7 (150)	182.9 (600)	228.6 (750)	2 x 1321-3R600-C ⁽³⁾	20	840				

⁽¹⁾ Requires two parallel cables.

PowerFlex 700L with 700S Control, 400V Shielded/Unshielded Cable - Meters (Feet)

Drive			No Sol	ution			Reacto	r Only			Reacto	or + Dan	nping Re	esistor	Reactor	Resist	or		ailat tion		
Frame	HP (kW)	kHz	1000V	1200V	1488V	1600V	1000V	1200V	1488V	1600V	1000V	1200V	1488V	1600V	Cat. No.	Ohms	Watts	TFA1	TFB2	RWR2	RWC
2	268 (200)	2	18.3 (60)	68.6 (225)	99.1 (325)	167.6 (550)	36.6 (120)	68.6 (225)	274.3 (900)	335.3 (1100)	152.4 (500)	274.3 (900)	365.8 (1200)	365.8 (1200)	1321-3R400-B ⁽¹⁾	20	495		•		
	, ,	4	18.3 (60)	68.6 (225)	99.1 (325)	167.6 (550)	36.6 (120)	68.6 (225)	274.3 (900)	335.3 (1100)	152.4 (500)	274.3 (900)	365.8 (1200)	365.8 (1200)	1321-3R400-B ⁽¹⁾	20	990				
3A	500 (370)	2	18.3 (60)	68.6 (225)	99.1 (325)	167.6 (550)	36.6 (120)	68.6 (225)	274.3 (900)	335.3 (1100)	152.4 (500)	274.3 (900)	365.8 (1200)	365.8 (1200)	1321-3R750-B ⁽¹⁾	20	735		•		
		4	18.3 (60)	68.6 (225)	99.1 (325)	167.6 (550)	36.6 (120)	68.6 (225)	274.3 (900)	335.3 (1100)	152.4 (500)	274.3 (900)	365.8 (1200)	365.8 (1200)	1321-3R750-B ⁽¹⁾	20	1470				
3B	960 (715)	2	12.2 (40)	68.6 (225)	99.1 (325)	167.6 (550)	36.6 (120)	68.6 (225)	274.3 (900)	335.3 (1100)	152.4 (500)	274.3 (900)	365.8 (1200)	365.8 (1200)	2 x 1321-3R600-B ⁽²⁾	20	525				
		4	12.2 (40)	68.6 (225)	99.1 (325)	167.6 (550)	36.6 (120)	68.6 (225)	274.3 (900)	335.3 (1100)	152.4 (500)	274.3 (900)	365.8 (1200)	365.8 (1200)	2 x 1321-3R600-B ⁽²⁾	20	1050				

⁽¹⁾ Requires two parallel cables.

⁽²⁾ Requires three parallel cables.

⁽³⁾ Requires four parallel cables.

⁽²⁾ Requires three parallel cables.

⁽³⁾ Requires four parallel cables.

⁽²⁾ Requires four parallel cables.

PowerFlex 700L with 700S Control, 480V Shielded/Unshielded Cable - Meters (Feet)

Drive			No Sol	ution			Reacto	r Only			Reacto	or + Dam	nping Re	esistor	Reactor	Resist	or		ailab tion:		
Frame	HP (kW)	kHz	1000V	1200V	1488V	1600V	1000V	1200V	1488V	1600V	1000V	1200V	1488V	1600V	Cat. No.	Ohms	Watts	TFA1	TFB2	RWR2	RWC
2	300 (224)	2	12.2 (40)	30.5 (100)	61.0 (200)	121.9 (400)	12.2 (40)	45.7 (150)	61.0 (200)	121.9 (400)	61.0 (200)	213.4 (700)	304.8 (1000)	365.8 (1200)	1321-3R400-B(1)	20	495		•		
		4	12.2 (40)	30.5 (100)	61.0 (200)	121.9 (400)	12.2 (40)	45.7 (150)	61.0 (200)	121.9 (400)	61.0 (200)	213.4 (700)	304.8 (1000)	365.8 (1200)	1321-3R400-B(1)	20	990				
3A	600 (445)	2	12.2 (40)	30.5 (100)	61.0 (200)	121.9 (400)	12.2 (40)	45.7 (150)	61.0 (200)	121.9 (400)	61.0 (200)	213.4 (700)	304.8 (1000)	365.8 (1200)	1321-3R750-B ⁽¹⁾	20	735		•		
		4	12.2 (40)	30.5 (100)	61.0 (200)	121.9 (400)	12.2 (40)	45.7 (150)	61.0 (200)	121.9 (400)	61.0 (200)	213.4 (700)	304.8 (1000)	365.8 (1200)	1321-3R750-B(1)	20	1470				
3B	1150 (860)	2	12.2 (40)	30.5 (100)	61.0 (200)	121.9 (400)	12.2 (40)	45.7 (150)	61.0 (200)	121.9 (400)	45.7 (150)	152.4 (500)	304.8 (1000)	365.8 (1200)	2 x 1321-3R600-B(2)	20	525				
		4	12.2 (40)	30.5 (100)	61.0 (200)	121.9 (400)	12.2 (40)	45.7 (150)	61.0 (200)	121.9 (400)	45.7 (150)	152.4 (500)	304.8 (1000)	365.8 (1200)	2 x 1321-3R600-B ⁽²⁾	20	1050				

⁽¹⁾ Requires two parallel cables.

PowerFlex 700L with 700S Control, 600V Shielded/Unshielded Cable - Meters (Feet)

Drive			No Sol	ution	Reacto	or Only	Reacto Dampi Resiste	ng	Reactor	Resist	or	Ava Opti	ilable ions	Э	
Frame	HP (kW)	kHz	1488V	1850V	1488V	1850V	1488V	1850V	Cat. No.	Ohms	Watts	TFA1	TFB2	RWR2	RWC
3A	465 (345)	2	18.3 (60)	76.2 (250)	18.3 (60)	76.2 (250)	182.9 (600)	304.8 (1000)	1321-3R500-B ⁽¹⁾	20	585		•		
		4	18.3 (60)	76.2 (250)	18.3 (60)	76.2 (250)	182.9 (600)	304.8 (1000)	1321-3R500-B(1)	20	1170				
3B	870 (650)	2	18.3 (60)	61.0 (200)	18.3 (60)	61.0 (200)	152.4 (500)	228.6 (750)	1321-3R850-B(2)	20	960				
		4	18.3 (60)	61.0 (200)	18.3 (60)	61.0 (200)	152.4 (500)	228.6 (750)	1321-3R850-B ⁽²⁾	20	1920				
3B	1275 (955)	2	12.2 (40)	45.7 (150)	12.2 (40)	45.7 (150)	121.9 (400)	228.6 (750)	2 x 1321-3R600-B ⁽³⁾	20	720				

⁽¹⁾ Requires two parallel cables.

PowerFlex 700L with 700S Control, 690V Shielded/Unshielded Cable - Meters (Feet)

Drive			No Sol	ution	Reacto	or Only	Reacto Dampi Resist	ng	Reactor	Resist	or	Avai Opti)	
Frame	HP (kW)	kHz	1488V	1850V	1488V	1850V	1488V	1850V	Cat. No.	Ohms	Watts	TFA1	TFB2	RWR2	RWC
3A	475 (355)	2	24.4 (80)	45.7 (150)	24.4 (80)	45.7 (150)	228.6 (750)	304.8 (1000)	1321-3R500-C(1)	20	960				
		4	24.4 (80)	45.7 (150)	24.4 (80)	45.7 (150)	182.9 (600)	228.6 (750)	1321-3R500-C(1)	20	1920				
3B	881 (657)	2	24.4 (80)	45.7 (150)	24.4 (80)	45.7 (150)	182.9 (600)	228.6 (750)	1321-3R850-C ⁽²⁾	20	1290		No	ne	
		4	24.4 (80)	45.7 (150)	24.4 (80)	45.7 (150)	182.9 (600)	228.6 (750)	1321-3R850-C(2)	20	2580				
3B	1315 (980)	2	24.4 (80)	45.7 (150)	24.4 (80)	45.7 (150)	182.9 (600)	228.6 (750)	2 x 1321-3R600-C ⁽³⁾	20	840				

⁽¹⁾ Requires two parallel cables.

⁽²⁾ Requires four parallel cables.

⁽²⁾ Requires three parallel cables.

⁽³⁾ Requires four parallel cables.

⁽²⁾ Requires three parallel cables.

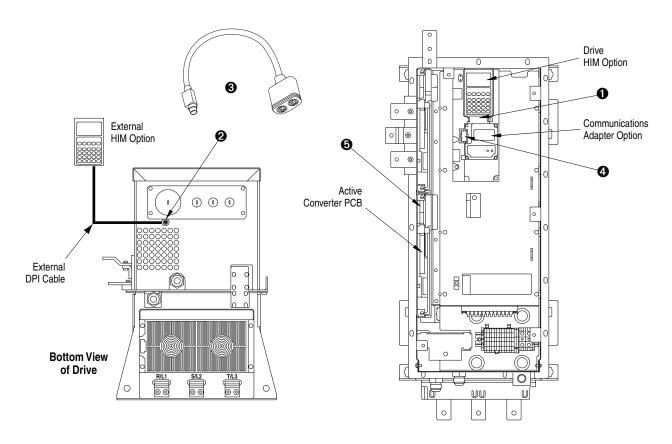
⁽³⁾ Requires four parallel cables.

DPI Connections

Frame 2

Drive Connection Points

The PowerFlex 700L Frame 2 drive provides a number of cable connection points as shown in the drawing below. If an additional external HIM is required for the application, the HIM can be connected to the DPI port on the bottom of the drive. Only one additional external HIM device may be connected. The use of two external HIM devices is not supported. If multiple external HIM devices are required, then install a user-supplied splitter cable or splitter box.



Item	Connector	Description
0	DPI Port 1	HIM connection when installed in the drive.
0	DPI Port 2	Cable connection for handheld and remote options.
8	DPI Port 3 or 2	Splitter cable connection to DPI Port 2 provides additional port.
4	DPI Port 5	Cable connection for communications adapter.
•	DPI Port 6	Internal DPI connection to Active Converter pcb.

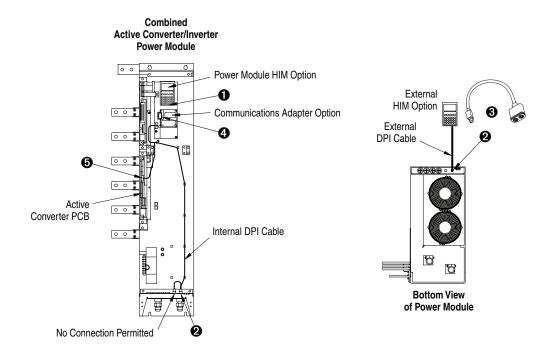
External Door-Mounted HIM Connection (optional)

For a Frame 2 drive installed in a user-supplied enclosure, an optional external door-mounted HIM may be connected as an alternative to the external HIM option. The cable supplied with the door-mount HIM option kit connects to the DPI port on the bottom of the drive (see drawing above). For additional installation information, refer to the instructions provided with the door-mount HIM option kit.

Frame 3A

Drive Connection Points

The PowerFlex 700L provides a number of cable connection points as shown in the drawings below. If an additional external HIM is required for the application, the HIM can be connected to the DPI port on the bottom of the Power Module. Only one additional external HIM device may be connected. The use of two external HIM devices is not supported. If multiple external HIM devices are required, then install a user-supplied splitter cable or splitter box.



Item	Connector	Description
0	DPI Port 1	HIM connection when installed in Power Module.
2	DPI Port 2	Cable connection for handheld and remote options.
8	DPI Port 3 or 2	Splitter cable connected to DPI Port 2 provides an additional port.
4	DPI Port 5	Cable connection for communications adapter.
0	DPI Port 6	Internal DPI connection to Active Converter PCB.

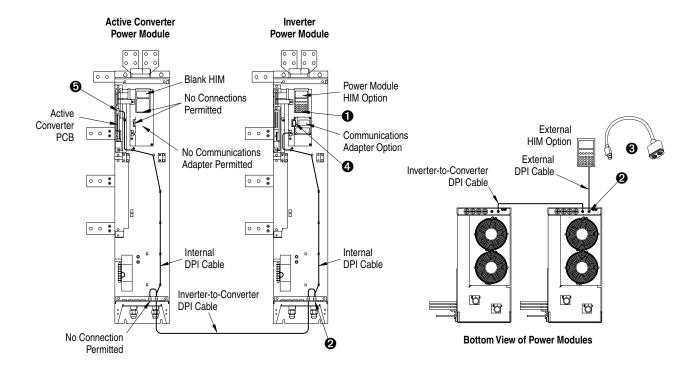
External Door-Mounted HIM Connection (optional)

For complete drives, the door-mounted HIM is standard equipment. It is located in the door mount bezel on the door of the Power Module Bay.

Frame 3B

Drive Connection Points

The PowerFlex 700L provides a number of cable connection points as shown in the drawings below. If an additional external HIM is required for the application, the HIM can be connected to the DPI port on the bottom of the Power Module. Only one additional external HIM device may be connected. The use of two external HIM devices is not supported. If multiple external HIM devices are required, then install a user-supplied splitter cable or splitter box.



Item	Connector	Description
0	DPI Port 1	HIM connection when installed in Power Module.
2	DPI Port 2	Cable connection for handheld and remote options.
8	DPI Port 3 or 2	Splitter cable connected to DPI Port 2 provides an additional port.
4	DPI Port 5	Cable connection for communications adapter.
0	DPI Port 6	Internal DPI connection to Active Converter PCB.

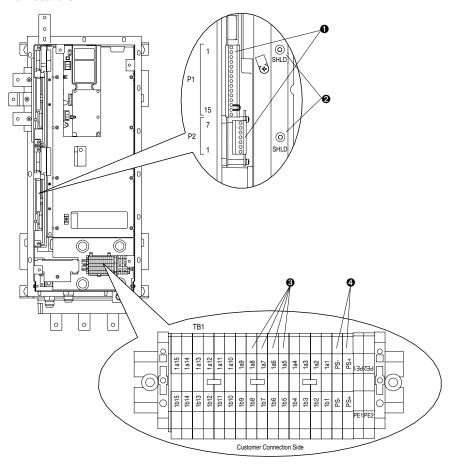
External Door-Mounted HIM Connection (optional)

For complete drives, the door-mounted HIM is standard equipment. It is located in the door mount bezel on the door of the Power Module Bay.

Control Connections

Frame 2

Frame 2 Control Terminal Locations



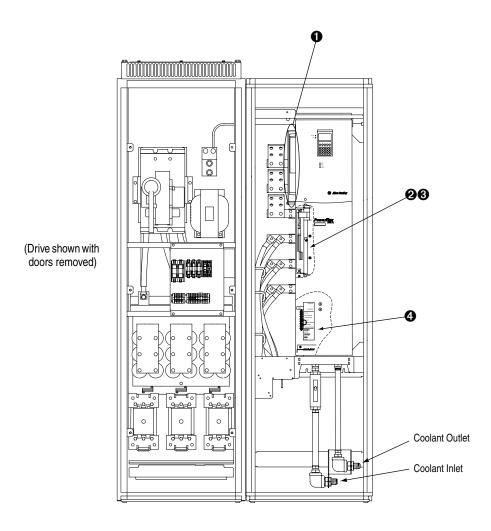
Frame 2 Control Terminal Specifications

			Wire Size R	ange ⁽¹⁾	Recommended Tightening	Wire Strip
Item	Name	Description	Maximum	Minimum	Torque (<u>+</u> 10%)	Length
0	PowerFlex 700 Vector Control or PowerFlex 700S Phase II Control Cassette Terminal Blocks	See PowerFlex 700 Series B Tech Data (publication PowerFlex 700S Tech Data (publication 20D-TD0				
0	Active Converter Cassette Terminal Blocks — P1 & P2	Active Converter AC power and control wiring	3.3 mm ² (#12 AWG)	0.3 mm ² (#22 AWG)	0.8 N•m (7 lb•in)	8 mm (0.31 in.)
8	SHLD Terminal	Terminating point for control wiring shields on the drive	2.1 mm ² (#14 AWG)	0.3 mm ² (#22 AWG)	1.4 N•m (12 lb•in)	10 mm (0.39 in.)
4	Terminal Block — TB1 1b 5: +12/+24V Cooling Loop 1b 6: Cooling Loop Return	Drive control wiring: Output dry contact (12V dc/24V dc, 2 Amps max.) indicating the drive is powered and has completed precharge.	4.0 mm ² (#10 AWG)	0.2 mm ² (#24 AWG)	0.9 N∙m (8 lb•in)	8 mm (0.31 in.)
	1b 7: +24V (digin)	Drive-supplied +24V dc				
	1b 8: Gate Enable	Enables the firing of the IGBTs. Factory- installed jumper from terminal 1b 7 to terminal 1b 8 allows firing of the IGBTs.				
6	PS- Terminal PS+ Terminal	300V dc Auxiliary Control voltage	4.0 mm ² (#12 AWG)	0.5 mm ² (#22 AWG)	0.6 N∙m (5.3 lb•in)	10 mm (0.39 in.)

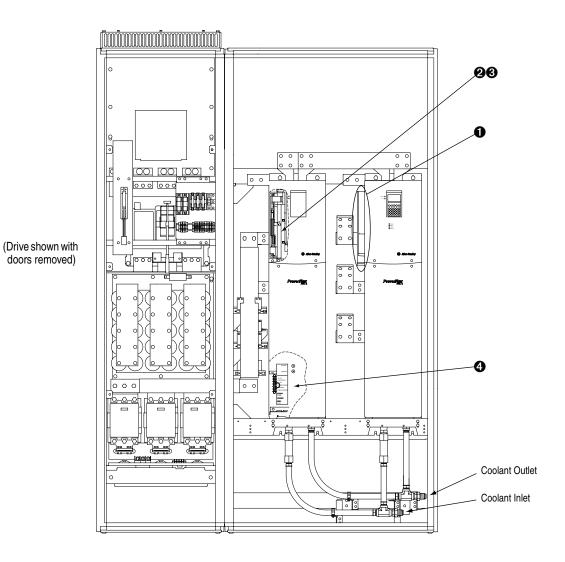
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Frame 3

Frame 3A Control Terminal Locations



Frame 3B Control Terminal Locations



Frame 3A/3B Control Terminal Specifications

			Wire Size Ra	ange (1)	Recommended Tightening	Wire Strip	Wire
Item	Name	Description	Maximum	Minimum	Torque (±10%)	Length	Terminal
0	PowerFlex 700 Vector Control or PowerFlex 700S Phase II Control Cassette Terminal Blocks	See PowerFlex 700 Series B Tecl PowerFlex 700S Tech Data (publi					
0	Active Converter Cassette Terminal Blocks — P1 & P2	Active Converter AC power and control wiring	3.3 mm ² (#12 AWG)	0.3 mm ² (#22 AWG)	0.8 N∙m (7 lb•in)	8 mm (0.31 in.)	not applicable
0	SHLD Terminal	Terminating point for control wiring shields on Power Module	2.1 mm ² (#14 AWG)	0.3 mm ² (#22 AWG)	1.4 N∙m (12 lb•in)	10 mm (0.39 in.)	not applicable
4	Terminal Blocks — TB5 and TB6	Power Module control wiring	4.0 mm ² (#10 AWG)	0.2 mm ² (#24 AWG)	1.4 N∙m (12 lb•in)	8 mm (0.31 in.)	not applicable

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Control Highlights

Active Converter Control

File	Group	Parameters							
Monitor	Current	Rated Amps Input Current R Input Current S	001 002 003	Input Current T Ground Current Active Current	004 005 006	Reactive Current I Imbalance IT Overload	007 008 009		
	Voltage	Rated Volts Input Voltage RS	010 011	Input Voltage ST Input Voltage TR	012 013	DcLink Voltage DcLink Ripple	014 015	V Imbalance	016
	Power & Time	Rated Power AC Line kW Motoring kWh	020 021 022	Regen kWh Lifetime kWh Elapsed Run Time	023 024 025	Life Run Time Life Power Time Life Pwr Cycles	026 027 028		
	Temperature	Ambient Temp	030	IGBT Base Temp	031	IGBT Junct Temp	032		
	Frequency	Line Frequency Min Line Freq	040 041	Max Line Freq Min Max Persist	042 043	Change Line Freq	044		
Command	Start/Stop	Start Config	050	Option Select	051	Manual Control	052	Turn Off Delay	053
Comans	Setpoints	DcLink Reference kVAR Reference	060 061	Extern Cml Ref Modulation Index	062 063	Modulation Freq	064		
	Data Exchange	Converter Control	070	Converter Status	071	Converter Min Vdc	072	Converter Fault	073
Limit Config	Current	Active I Lmt Active OL I Lmt	100 101	Reactive RateLmt I Imbalance Lmt	102 103	I Imbalance Time Regen I Lmt	104 105		
	AC Line Voltage	Ride Through Ena Ride Through Sec	110 111	Low Vac Lmt Low Vac Time	112 113	High Vac Lmt High Vac Time	114 115	V Imbalance Lmt V Imbalance Time	116 117
	Temperature	Ambnt Temp Alrm Ambnt Temp Trip	120 121	Base Temp Alrm Base Temp Trip	122 123	Junct Temp Alrm Junct Temp Trip	124 125	CldPlt Temp Alrm	126
	Frequency	PWM Frequency AC Low Freq Lmt	130 131	AC Low Freq Time AC High Freq Lmt	132 133	AC High Freq Time AC Maximum dF/dt	134 135		
Dynamic Control	Current Loop	Reduce IImt Sel Active I Cmd Inductance	150 151 152	CML Bandwidth CML Damping CML Ki	153 154 155	CML Kp PF Bandwidth Reactive I Lmt	156 157 158	Reactive I Cmd	159
	Voltage Loop	Voltage Loop Sel DcLink Command Capacitance	160 161 162	VML Bandwidth VML Damping VML Ki	163 164 165	VML Kp VML Kf VML Reset Level	166 167 168	Parallel Config Bus Capacitance	169 170
Utility	Drive Memory	Param Access Lvl Reset to Defaults	196 197	Reset Meters Language	200 201	Drive Checksum Control SW Ver	203 204	Password	205
	Diagnostics	Alarm Status Start Inhibit Fault Frequency Fault Amps R Fault Amps S	211 214 220 221 222	Fault Amps T Fault Amps Q Fault Amps D Fault Volts RS Fault Volts ST	223 224 225 226 227	Fault VoltsTR Fault Volts Vdc Fault Base Temp Testpoint 1 Sel Testpoint 1 Data	228 229 230 234 235	Testpoint 2 Sel Testpoint 2 Data	236 237
	Fault Queue	Fault Config Fault Clear Power Up Marker	238 239 242	Fault 1 Code Fault 1 Time Fault 2 Code	243 244 245	Fault 2 Time Fault 3 Code Fault 3 Time	246 247 248	Fault 4 Code Fault 4 Time Alarm Config	249 250 260
Communication	Datalinks	Data In A1 Data In A2 Data In B1 Data In B2	300 301 302 303	Data In C1 Data In C2 Data In D1 Data In D2	304 305 306 307	Data Out A1 Data Out A2 Data Out B1 Data Out B2	310 311 312 313	Data Out C1 Data Out C2 Data Out D1 Data Out D2	314 315 316 317
	DPI Status	Connect Status DPI Error Out CS Msg Rx Cnt	320 321 322	CS Msg Tx Cnt CS Timeout Cnt CS Msg Bad Cnt	323 324 325	PC Msg Rx Cnt PC Msg Tx Cnt PC Timeout Cnt	326 327 328	CAN Bus Off Cnt	329
	Masks & Owners	Logic Mask Start Mask	340 341	Fault Clr Mask Stop Owner	342 343	Start Owner Fault Clr Owner	344 345		
	Security	Port Mask Act	346	Write Mask Cfg	347	Write Mask Act	348	Logic Mask Act	349
Inputs & Outputs	Mux'ed Temps	IGBT NTC Temp1 IGBT NTC Temp2 IGBT NTC Temp3	330 331 332	IGBT NTC Temp4 Coldplate Temp1 IGBT NTC Temp5	333 334 335	IGBT NTC Temp6 IGBT NTC Temp7 IGBT NTC Temp8	336 337 338	Coldplate Temp2	339
	Digital Inputs	Dig In Status	350	Dig In Frc Mask	351	Dig In Frc Data	352		
	Digital Outputs	Dig Out Status	360	Dig Out Frc Mask	361	Dig Out Frc Data	362	·	

PowerFlex 700 Vector Control

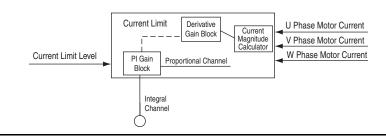
File	Group	Parameters							
Monitor	Metering	Output Freq Commanded Speed Ramped Speed Speed Reference Commanded Torque Speed Feedback	001 002 022 023 024 025	Output Current Torque Current Flux Current Output Voltage Output Power Output Powr Fctr	003 004 005 006 007 008	Elapsed MWh Elapsed Run Time MOP Reference DC Bus Voltage DC Bus Memory Analog In1 Value	009 010 011 012 013 016	Analog In2 Value Elapsed kWh PTC HW Value Spd Fdbk No Filt	017 014 018 021
	Drive Data	Rated kW	026	Rated Volts	027	Rated Amps	028	Control SW Ver	029
Motor Control	Motor Data	Motor Type Motor NP Volts Motor NP FLA	040 041 042	Motor NP Hertz Motor NP RPM Motor NP Power	043 044 045	Mtr NP Pwr Units Motor OL Hertz Motor OL Factor	046 047 048	Motor Poles	049
	Torq Attributes	Motor Cntl Sel Maximum Voltage Maximum Freq Compensation Flux Up Mode Flux Up Time SV Boost Filter Autotune	053 054 055 056 057 058 059 061	IR Voltage Drop Flux Current Ref IXo Voltage Drop Autotune Torque Inertia Autotune Torque Ref A Sel Torque Ref A Hi Torque Ref A Lo	062 063 064 066 067 427 428 429	Torq Ref A Div Torque Ref B Sel Torque Ref B Hi Torque Ref B Lo Torq Ref B Mult Torque Setpoint 1 Torque Setpoint 2 Pos Torque Limit	430 431 432 433 434 435 438 436	Neg Torque Limit Control Status Mtr Tor Cur Ref	437 440 441
	Volts per Hertz	Start/Acc Boost	069	Run Boost	070	Break Voltage	071	Break Frequency	072
	Speed Feedback	Motor Fdbk Type Encoder PPR Enc Position Fdbk	412 413 414	Encoder Speed Fdbk Filter Sel Notch Filter Freq	415 416 419	Notch Filter K Marker Pulse Pulse In Scale	420 421 422	Encoder Z Chan	423
Speed Command	Spd Mode & Limits	Speed Units Feedback Select Minimum Speed	079 080 081	Maximum Speed Overspeed Limit Skip Frequency 1	082 083 084	Skip Frequency 2 Skip Frequency 3 Skip Freq Band	085 086 087	Speed/Torque Mod Rev Speed Limit	088 454
	Speed References	Speed Ref A Sel Speed Ref A Hi Speed Ref A Lo	090 091 092	Speed Ref B Sel Speed Ref B Hi Speed Ref B Lo	093 094 095	TB Man Ref Sel TB Man Ref Hi TB Man Ref Lo	096 097 098	Pulse Input Ref	099
	Discrete Speeds	Jog Speed 1 Preset Speed 1 Preset Speed 2	100 101 102	Preset Speed 3 Preset Speed 4 Preset Speed 5	103 104 105	Preset Speed 6 Preset Speed 7 Jog Speed 2	106 107 108		
	Speed Trim	Trim In Select Trim Out Select	117 118	Trim Hi Trim Lo	119 120	Trim % Setpoint	116		
	Slip Comp	Slip RPM @ FLA	121	Slip Comp Gain	122	Slip RPM Meter	123		
	Process PI	PI Configuration PI Control PI Reference Sel PI Setpoint PI Feedback Sel PI Integral Time	124 125 126 127 128 129	PI Prop Gain PI Lower Limit PI Upper Limit PI Preload PI Status PI Ref Meter	130 131 132 133 134 135	PI Fdback Meter PI Error Meter PI Output Meter PI Reference Hi PI Reference Lo PI Feedback Hi	136 137 138 460 461 462	PI Feedback Lo PI BW Filter PI Deriv Time PI Output Gain	463 139 459 464
	Speed Regulator	Ki Speed Loop Kp Speed Loop	445 446	Kf Speed Loop Speed Desired BW	447 449	Total Inertia Speed Loop Meter	450 451		
Dynamic Control	Ramp Rates	Accel Time 1 Accel Time 2	140 141	Decel Time 1 Decel Time 2	142 143	S Curve %	146		
	Load Limits	Current Lmt Sel Current Lmt Val	147 148	Current Lmt Gain Drive OL Mode	149 150	PWM Frequency Droop RPM @ FLA	151 152	Regen Power Limit Current Rate Limit	153 154
	Stop/Brake Modes	Stop Mode A Stop Mode B DC Brk Lvl Sel DC Brake Level	155 156 157 158	DC Brake Time Bus Reg Ki Bus Reg Mode A Bus Reg Mode B	159 160 161 162	DB Resistor Type Bus Reg Kp Bus Reg Kd Flux Braking	163 164 165 166	DB While Stopped	145
	Restart Modes	Start At PowerUp Flying Start En Flying StartGain	168 169 170	Auto Rstrt Tries Auto Rstrt Delay Sleep-Wake Mode	174 175 178	Sleep-Wake Ref Wake Level Wake Time	179 180 181	Sleep Level Sleep Time Powerup Delay	182 183 167
	Power Loss	Power Loss Mode Power Loss Time	184 185	Power Loss Level Load Loss Level	186 187	Load Loss Time Shear Pin Time	188 189	Gnd Warn Level	177

PowerFlex 700L Technical Data

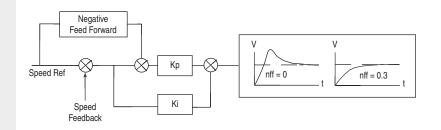
File	Group	Parameters							
Utility	Direction Config	Direction Mode	190						
	HIM Ref Config	Save HIM Ref	192	Man Ref Preload	193				
	MOP Config	Save MOP Ref	194	MOP Rate	195				
	Drive Memory	Param Access Lvl Reset To Defalts Load Frm Usr Set	196 197 198	Save To User Set Reset Meters Language	199 200 201	Voltage Class Drive Checksum Dyn UserSet Cnfg	202 203 204	Dyn UserSet Sel Dyn UserSet Actv	205 206
	Diagnostics	Drive Status 1 Drive Status 2 Drive Alarm 1 Drive Alarm 2 Speed Ref Source Start Inhibits	209 210 211 212 213 214	Last Stop Source Dig In Status Dig Out Status Drive Temp Drive OL Count Motor OL Count	215 216 217 218 219 220	Fault Speed Fault Amps Fault Bus Volts Status 1 @ Fault Status 2 @ Fault Alarm 1 @ Fault	224 225 226 227 228 229	Alarm 2 @ Fault Testpoint 1 Sel Testpoint 2 Sel Testpoint 1 Data Testpoint 2 Data Mtr OL Trip Time	230 234 236 235 237 221
	Faults	Fault Config 1 Fault Clear Fault Clear Mode Power Up Marker Fault 1 Code	238 240 241 242 243	Fault 1 Time Fault 2 Code Fault 2 Time Fault 3 Code Fault 3 Time	244 245 246 247 248	Fault 4 Code Fault 4 Time Fault 5 Code Fault 5 Time Fault 6 Code	249 250 251 252 253	Fault 6 Time Fault 7 Code Fault 7 Time Fault 8 Code Fault 8 Time	254 255 256 257 258
	Alarms	Alarm Config 1 Alarm Clear Alarm 1 Code	259 261 262	Alarm 2 Code Alarm 3 Code Alarm 4 Code	263 264 265	Alarm 5 Code Alarm 6 Code Alarm 7 Code	266 267 268	Alarm 8 Code	269
	Scaled Blocks	Scale1 In Value Scale1 In Hi Scale1 In Lo Scale1 Out Hi Scale1 Out Lo Scale1 Out Value	476 477 478 479 480 481	Scale2 In Value Scale2 In Hi Scale2 In Lo Scale2 Out Hi Scale2 Out Lo Scale2 Out Value	482 483 484 485 486 487	Scale3 In Value Scale3 In Hi Scale3 In Lo Scale3 Out Hi Scale3 Out Lo Scale3 Out Value	488 489 490 491 492 493	Scale4 In Value Scale4 In Hi Scale4 In Lo Scale4 Out Hi Scale4 Out Lo Scale4 Out Value	494 495 496 497 498 499
Communication	Comm Control	DPI Baud Rate Drive Logic RsIt	270 271	Drive Ref Rslt Drive Ramp Rslt	272 273	DPI Port Sel DPI Port Value	274 275	DPI Ref Select DPI Fdbk Select	298 299
	Masks & Owners	Logic Mask Start Mask Jog Mask Direction Mask Reference Mask	276 277 278 279 280	Accel Mask Decel Mask Fault Cir Mask MOP Mask Local Mask	281 282 283 284 285	Stop Owner Start Owner Jog Owner Direction Owner Reference Owner	288 289 290 291 292	Accel Owner Decel Owner Fault Cir Owner MOP Owner Local Owner	293 294 295 296 297
	Datalinks	Data In A1 Data In A2 Data In B1 Data In B2	300 301 302 303	Data In C1 Data In C2 Data In D1 Data In D2	304 305 306 307	Data Out A1 Data Out A2 Data Out B1 Data Out B2	310 311 312 313	Data Out C1 Data Out C2 Data Out D1 Data Out D2	314 315 316 317
	Security	Port Mask Act Write Mask Cfg	595 596	Write Mask Act Logic Mask	597 276	Logic Mask Act	598		
Inputs & Outputs	Analog Inputs	Anlg In Config Anlg In Sqr Root	320 321	Analog In1 Hi Analog In1 Lo	322 323	Analog In1 Loss Analog In2 Hi	324 325	Analog In2 Lo Analog In2 Loss	326 327
	Analog Outputs	Anlg Out Config Anlg Out Absolut Analog Out1 Sel	340 341 342	Analog Out1 Hi Analog Out1 Lo Analog Out2 Sel	343 344 345	Analog Out2 Hi Analog Out2 Lo Anlg Out1 Scale	346 347 354	Anlg Out2 Scale Anlg1 Out Setpt Anlg2 Out Setpt	355 377 378
	Digital Inputs	Digital In1 Sel Digital In2 Sel	361 362	Digital In3 Sel Digital In4 Sel	363 364	Digital In5 Sel Digital In6 Sel	365 366		
	Digital Outputs	Dig Out Setpt Digital Out1 Sel Dig Out1 Level Dig Out1 OnTime	379 380 381 382	Dig Out1 OffTime Digital Out2 Sel Dig Out2 Level Dig Out2 OnTime	383 384 385 386	Dig Out2 OffTime Digital Out3 Sel Dig Out3 Level Dig Out3 OnTime	387 388 389 390	Dig Out3 OffTime Dig Out Invert Dig Out Param Dig Out Mask	391 392 393 394

PowerFlex 700S Phase II Control

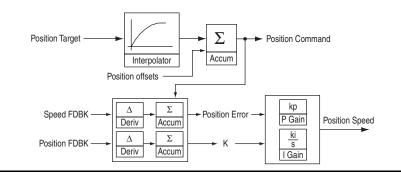
Digital Current Regulator outperforms older style analog regulators in speed, repeatability and drift.



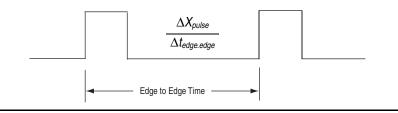
Negative Feed Forward reduces or eliminates overshoot during step speed changes. Helpful in preventing backup during stopping.



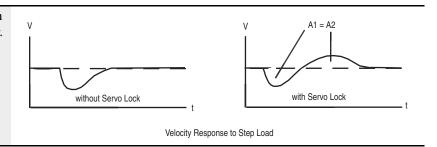
Coarse-to-Fine interpolation for **DriveLogix Motion**, direct positioning for precise control and point-to-point for indexing are all features of the **Integral Position Loop.** The loop easily handles applications such as simple indexing and electronic line shaft.



Advanced **Edge-to-Edge Algorithms** and pulse position averaging provides extremely accurate speed measurement and excellent performance at very low speed.

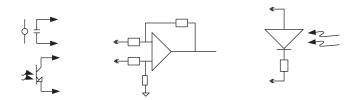


Servo Lock compensates for lost position during step loads to the velocity regulator. Offers optimum performance for draw applications and others.

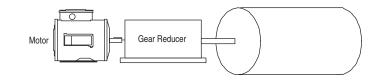


High Speed Analog & Digital I/O

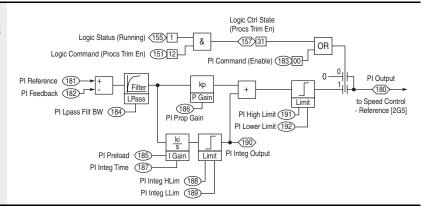
execute in 0.5 mSec or less to provide fast response and fast capture for registration information and position data. Output relays, optically isolated and differentially isolated I/O are supplied.



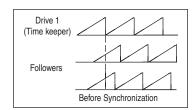
Inertia Adaptation stabilizes inertia disconnect due to gear boxes or flexible couplings. It also provides broadband resonance compensation, allowing up to 4 times improvement to speed regulator bandwidth.

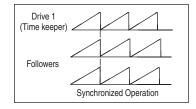


An **Enhanced Process Loop** executes six times faster than previous loops, providing greatly improved dynamic response in tension control applications.

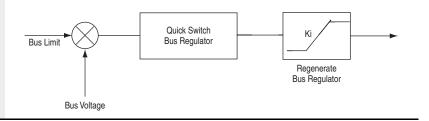


The **Control Loops** within each drive are **Synchronized**. In addition, the control loops for all drives on SynchLink are synchronized within micro-seconds. This provides exceptional link coordination and tracking for critical applications.





The **Enhanced Bus Regulator** reacts four times faster than previous products, providing quicker stops without overvoltage issues and outstanding performance in other regenerative applications.



Standard Drive Specifications

	Specificati	on	
Category		Frame 2	Frame 3A/3B
Agency Certification	c UL us	Listed to UL508C and CAN/CSA-C2.2 No. 14-05. UL Listing for Fran applicable up to 600V AC.	me 2 is applicable up to 480V AC. UL Listing for Frame 3A and 3B is
	CE	Marked for all applicable European Directives (1) EMC Directive (89/336/EEC) EN 61800-3 Adjustable Speed electrical power drive systems Low Voltage Directive (73/23/EEC) EN 50178 Electronic Equipment for use in Power Installations	
	C N223	Certified to AS/NZS, 1997 Group 1, Class A.	
	NFPA 70 NEMA IC IEC 146	s are also designed to meet the following specifications: - US National Electrical Code S 3.1 - Safety standards for Construction and Guide for Selection, In International Electrical Code. Decification #70 (Crane Manufacturers of America Association)	stallation and Operation of Adjustable Speed Drive Systems.

⁽¹⁾ Applied noise impulses may be counted in addition to the standard pulse train causing erroneously high [Pulse Freq] readings.

The following specifications, unless otherwise noted, pertain to PowerFlex 700L drives equipped with 700 Vector Control or 700S Phase II Control.

	Specification													
Category		Frame 2		Frame 3A/3	Frame 3A/3B									
Protection		400V	480V	400V	480V	600V	690V							
	AC Input Overvoltage Trip:	528V AC	528V AC	528V AC	528V AC	760V AC	760V AC							
	AC Input Undervoltage Trip:	340V AC	340V AC	340V AC	340V AC	340V AC	340V AC							
	Bus Overvoltage Trip:	815V DC	815V DC	815V DC	815V DC	1168V DC	1168V DC							
	Bus Undervoltage Shutoff/Fault:	300V DC	300V DC	300V DC	300V DC	300V DC	300V DC							
	Nominal Bus Voltage:	600V DC	700V DC	600V DC	700V DC	900V DC	1000V DC							
	Heat Sink Thermistor:	Monitored by microproc	essor overtemp trip											
	Drive Overcurrent Trip Software Overcurrent Trip: Hardware Overcurrent Trip:	200% of rated current (typical) 220-300% of rated current (dependent on drive rating)												
	Line Transients:	Up to 6000 volts peak per IEEE C62.41-1991												
	Control Logic Noise Immunity:	Showering arc transients up to 1500V peak												
	Logic Control Ride-Thru Vector Control:	0.5 seconds minimum, 2 seconds typical												
	700S Phase II Control:	0.25 seconds, drive not running												
	Ground Fault Trip:	Phase-to-ground on drive output												
	Short Circuit Trip:	Phase-to-phase on driv												
Environment	Altitude:	1000 m (3280 ft.) at rated current. See Derating Guidelines on page 40 for operation above 1000 m (3280 ft.).												
	Maximum Surrounding Air Temperature w/o Derating: IP20, NEMA/UL Type 1:	0 to 50°C (32 to 122°F) 0 to 40°C (32 to 104°F)												
	Storage Temperature (all constructions):	-40 to 85°C (-40 to 185°F)												
	Atmosphere:	Important: Drive <u>must not</u> be installed in an area where the ambient atmosphere contains volatile or corrosive gas, vapors or dust. If the drive is not going to be installed for a period of time, it must be stored in an area where it will not be exposed to a corrosive atmosphere.												
	Relative Humidity:	5 to 95% non-condensing												
	Shock:	10G peak for 11 milliseconds duration (±1.0 ms)												
	Vibration:	0.152 mm (0.006 in.) di	splacement, 1G peak, 5.5 Hz				0.152 mm (0.006 in.) displacement, 1G peak, 5.5 Hz							

	Specification							
Category		Frame 2	Frame 3A/3B					
Electrical	Voltage Tolerance Vector Control:	For full power and operating range, see the <i>PowerFlex 70</i> (publication 20B-UM002), Appendix C.	00 Adjustable Frequency AC Drive — Series B User Manual					
	700S Phase II Control:	For full power and operating range, see the <i>PowerFlex 70 Manual (publication 20D-UM006), Appendix C.</i>	00S High Performance AC Drive — Phase II Control User					
	Input Frequency Tolerance:	27-93 Hz.						
	Input Phases:	Three-phase input provides full rating for all drives.						
	Displacement Power Factor:	0.98 across entire speed range.						
	Efficiency:	96.2% at rated amps, nominal line volts.	97.5% at rated amps, nominal line volts.					
	Maximum Short Circuit Current Rating:	To match specified circuit breaker capability, ≤200,000 A						
	Actual Short Circuit Rating:	Determined by AIC rating of installed circuit breaker.	F					
	Motor Lead Lengths:	76 meters (250 feet) total						
Control	Method:	Sine coded PWM with programmable carrier frequency.						
Control	Carrier Frequency:	4, or 8 kHz. Drive rating based on 4 kHz. See <u>Derating Guidelines on page 40</u> for more information	2 or 4 kHz. Drive rating based on 4 kHz.					
	Output Voltage Range:	0 to rated motor voltage						
	Output Frequency Range Vector Control:	0 to 420 Hz						
	700S Phase II Control:	0 to 350 Hz						
		0 to 350 Hz						
	Frequency Accuracy (Vector Control only) Digital Input:	Within ± 0.01% of set output frequency.	Within ± 0.01% of set output frequency.					
	Analog Input:	Within ± 0.4% of maximum output frequency						
	Frequency Control (Vector Control only):	Speed Regulation - w/Slip Compensation (Volts per Hertz Mode) 0.5% of base speed across 40:1 speed range 40:1 operating range 10 rad/sec bandwidth Speed Regulation - w/Slip Compensation (Sensorless Vector Mode) 0.5% of base speed across 80:1 speed range 80:1 operating range 20 rad/sec bandwidth						
	Speed Control Vector Control:	Speed Regulation - without feedback (Vector Control Mod 0.1% of base speed across 120:1 speed range	de)					
		120:1 operating range 50 rad/sec bandwidth Speed Regulation - with feedback (Vector Control Mode) 0.001% of base speed across 120:1 speed range 1000:1 operating range 250 rad/sec bandwidth						
	700S Phase II Control:	Speed Regulation - without feedback 0.1% of base speed across 120:1 speed range 120:1 operating range 50 rad/sec bandwidth Speed Regulation - with feedback 0.001% of base speed across 120:1 speed range 1000:1 operating range 740 rad/sec bandwidth						
	Torque Regulation Vector Control:	Torque regulation without Feedback; ± 5%, 600 rad/sec language Torque regulation with Feedback; ± 2%, 2500 rad/sec back;						
	700S Phase II Control:	Torque regulation without Feedback; ± 10%, 600 rad/sec Torque regulation with Feedback; ± 5%, 4400 rad/sec ba						
	Selectable Motor Control Vector Control:	Sensorless Vector with full tuning. Standard V/Hz with full Technology (with and without feedback).	Il custom capability and Vector Control with Force					
	700S Phase II Control:	Vector Control with Force Technology (with and without feedback), V/Hz Control, and permanent magnet motor control.						

	Specification			
Category		Frame 2	Frame 3A/3B	
Control	Stop Modes		1.1	
(continued)	Vector Control:	Multiple programmable stop modes including Ramp, Coas	st, DC-Brake, Ramp-to-Hold, and S-curve.	
	700S Ph. II Control:	Multiple programmable stop modes including Ramp, Coas	st, and Current Limit.	
	Accel/Decel Vector Control:	Two independently programmable accel and decel times. Each time may be programmed from 0-3600 seconds in 0.1 second increments.		
	700S Phase II Control:	Independently programmable accel and decel times, adju-	stable from 0-6553.5 seconds in 0.01 second increments.	
	Intermittent Overload:	110% Overload capability for up to 1 minute 150% Overlo	pad capability for up to 3 seconds	
	Current Limit Capability Vector Control:	Proactive Current Limit programmable from 20 to 160% of proportional and integral gain.	f rated output current. Independently programmable	
	700S Phase II Control:	Independent Motoring and Regenerative Power Limits pro	ogrammable to 800% of rated output current.	
	Electronic Motor Overload Protection:	Class 10 protection with speed sensitive response. Invest E59272, volume 12.	·	
Encoder	Type:	Incremental, dual channel		
(Vector Control	Supply:	12V or 5V, 250 mA. 12V or 5V, 10 mA minimum inputs iso	plated with differential transmitter, 250 kHz maximum.	
only)	Quadrature:	90°, ± 27° at 25°C	,,	
	Duty Cycle:	50%, ± 10%		
	Requirements:		nel) or pulse (single channel), 8-15V DC output (3.5-6V DC	
	Tiequirements.	for 5V encoder), single-ended or differential, and capable input frequency is 250 kHz. The Encoder Interface Board high state of 7.0V DC (12 volt encoder) or 3.1V DC (5 volt	of supplying a minimum of 10 mA per channel. Maximum accepts 12V DC or 5V DC square-wave with a minimum	
Feedback (700S Phase II Control only)	Encoder Input: Encoder Voltage Supply: Maximum Input Freq:	Dual Channel Plus Marker, Isolated with differential transr Quadrature type 5V DC or 12V DC (5V DC requires an external power sup 400 kHz	mitter Output (Line Drive) Incremental, Dual Channel	
	Stegmann Hi-Resolution Option Encoder Voltage Supply: Hi-Resolution Feedback: Maximum Cable Length: RS-485 Interface:	11.5V DC @ 130 mA Sine/Cosine 1V P-P Offset 2.5 182 m (600 ft.)	information via the Hiperface RS-485 interface shortly after r of Turns, Number of Sine/Cos cycles, and Checksum.	
	Customer-I/O Plug (P1) - Hi Res:	Allen-Bradley PN: S94262912 Weidmuller PN: BL3.50/90/12BK		
	Resolver Option Excitation Frequency: Excitation Voltage: Operating Freq. Range: Resolver Fdbk. Voltage: Maximum Cable Length:	2400 Hz 4.25-26 Vrms 1-10 kHz 2V ±300mV 304.8 m (1000 ft.)		
DriveLogix	User Available Memory Base:	1.5 megabytes		
(700S Phase II	Battery:	1756-BA1 (Allen-Bradley P/N 94194801) 0.59g lithium		
Control only)	Serial Cable:	1761-CBLPM02 to 1761-NET-AIC 1761-CBLPA00 to 1761-NET-AIC 1756-CP3 directly to controller 1747-CP3 directly to controller Category 3 (2)		
	Compact I/O Connection:	Up to (30) modules		
	Cable:	20D-DL2-CL3 20D-DL2-CR3		

Derating Guidelines

Altitude

Above 1000 m (3280 ft.), derate the output current by 1% for every 100 additional meters (328 additional feet). This is applicable to filters and power modules. PowerFlex 700L 600/690V drives should not be used above 2000 m (6562 ft.) due to voltage spacing requirements.

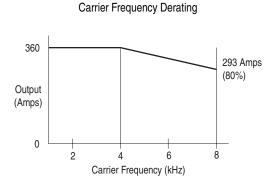
Ambient

Frame 2 drives have a maximum ambient of 50°C (122°F). Frame 3A and 3B drives have a maximum ambient of 40°C (104°F). PowerFlex 700L drives cannot be derated to operate at higher ambients.

Carrier Frequency

For Frame 2 drives, refer to the carrier frequency derating table below. PowerFlex 700L Frame 3A and 3B drives cannot be run above 4 kHz.

PowerFlex 700L Frame 2 Drive



Watts Loss (@ Rated Load, Speed, and PWM Carrier Frequency)

			Watts Loss					
Frame		PWM	Filter Section	Filter Section Power Section			Complete Drive	
Size	Voltage	Freq.	Into Air	Into Air	Into Liquid	Total	Total Air	Total Liquid
2	400V	4 kHz		Not App	olicable		1500	7900
	480V	4 kHz		Not App	olicable		1500	7900
3A	400V	4 kHz	4000	1000	10,500	11,500	5000	10,500
	480V	4 kHz	4000	1000	11,500	12,500	5000	11,500
	600V	4 kHz	4000	1200	10,500	11,700	5200	10,500
	690V	4 kHz	4000	1200	12,000	13,200	5200	12,000
3B (1)	400V	4 kHz	7800	2000	21,000	23,000	9800	21,000
	480V	4 kHz	7800	2000	23,000	25,000	9800	23,000
	600V	4 kHz	7800	2400	21,000	23,400	10,200	21,000
	690V	4 kHz	7800	2400	24,000	26,400	10,200	24,000

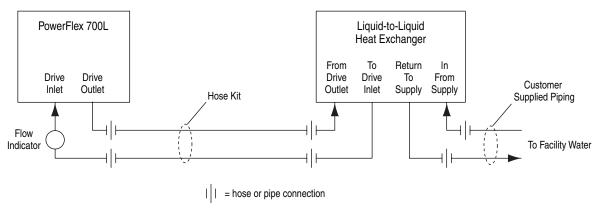
⁽¹⁾ Frame 3B power section consists of two (2) power modules. Each module dissipates half (½) of the watts shown in this table.

Cooling Loop Options

This section provides information about the various types of cooling loops.

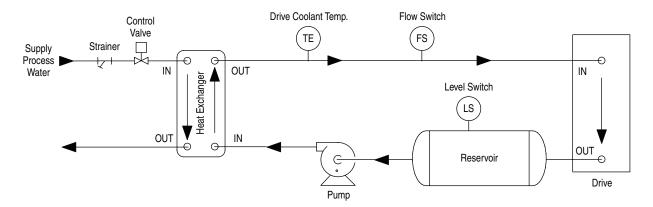
Liquid-to-Liquid Heat Exchanger

The liquid-to-liquid heat exchanger utilizes a heat transfer plate to transfer heat from one liquid to another. This method requires a stable water supply from the user.



The drawing below shows a cooling loop diagram for a typical liquid-to-liquid heat exchanger.



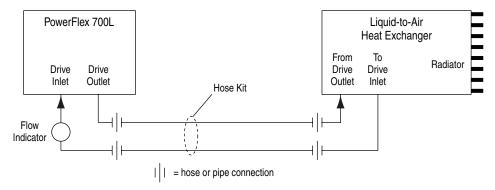


The main components of the liquid-to-liquid heat exchanger cooling loop include:

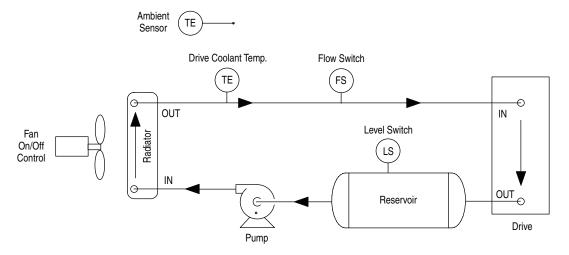
Part	Description
Strainer	Filters particles from the supply water.
Control Valve	Controls the supply loop water flow.
Heat Exchanger Plate	Transfers heat from the drive loop to the supply loop.
Ambient Sensor	Senses the ambient temperature used for the dew point control.
Drive Coolant Temperature Sensor	Senses the drive coolant temperature used for the dew point control.
Drive Coolant Flow Switch	Measures the drive coolant flow rate.
Level Switch	Senses the level of coolant in the reservoir.
Reservoir	Stores drive coolant.
Pump and Motor	Circulates drive coolant.

Liquid-to-Air Heat Exchanger

The liquid-to-air heat exchanger utilizes radiator technology to transfer heat from a liquid to surrounding air. This is a simple closed loop system — it does not require a water supply from the user. However, this system requires surrounding air 5 to 10° C below the maximum operating temperature of the drive.



The drawing below shows a cooling loop diagram for a typical liquid-to-air heat exchanger.

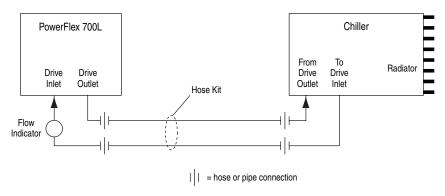


The main components of the liquid-to-air heat exchanger cooling loop include:

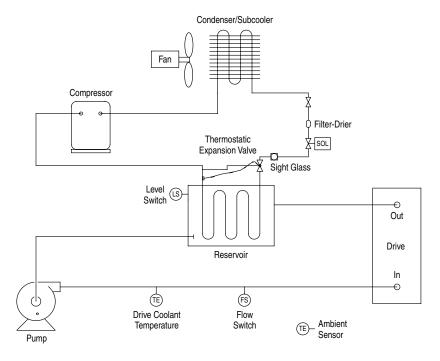
Part	Description
Fan	Blows air across the radiator.
Radiator	Transfers heat from liquid to air.
Ambient Sensor	Senses the ambient temperature used for the dew point control.
Drive Coolant Temperature Sensor	Senses the drive coolant temperature used for the dew point control.
Drive Coolant Flow Switch	Measures the drive coolant flow rate.
Level Switch	Senses the level of coolant in the reservoir.
Reservoir	Allows for expansion of coolant.
Pump and Motor	Circulates drive coolant.

Chiller

The chiller utilizes refrigerant to transfer heat from a liquid to air. This is a simple closed loop system — it does not require a water supply from the user. A chiller can achieve almost any coolant temperature required. Coolant temperature should be at or above ambient temperature to avoid condensation on drive components.



The drawing below shows a cooling loop diagram for a typical chiller.



The main components of the chiller cooling loop include:

Part	Description
Compressor	Forces the refrigerant into a smaller space.
Fan	Blows air across the condenser/subcooler.
Condenser/Subcooler	Cools the refrigerant.
Filter-Drier	Filters the refrigerant.
Sight Glass	Allows viewing of the level of drive coolant in the reservoir.
Thermostatic Expansion Valve	Allows for expansion of the refrigerant.
Level Switch	Senses the level of coolant in the reservoir.
Reservoir	Allows for expansion of coolant.
Pump and Motor	Circulates drive coolant.
Drive Coolant Temperature Sensor	Senses the drive coolant temperature used for the dew point control.
Drive Coolant Flow Switch	Measures the drive coolant flow rate.
Ambient Sensor	Senses the ambient temperature used for the dew point control.

Recommended Cooling Loops

Liquid-to-Liquid Heat Exchanger Selection

	Supply Loop Requirements (1)							
Drive Frame Size	Minimum Flow @ Pressure (2)	Maximum Pressure	Temperature Range	Exchanger Cat. No. (3)				
2	15.1 LPM @ 0.83 bar (4 GPM @ 12 PSI)	8.62 bar (125 PSI)	0-40°C (32-104°F)	20L-LL13K-P75A				
3A	22.7 LPM @ 0.83 bar (6 GPM @ 12 PSI)	8.62 bar (125 PSI)	0-35°C (32-95°F)	20L-LL13K-P75A				
3B	56.8 LPM @ 0.83 bar (15 GPM @ 12 PSI)	8.62 bar (125 PSi)	0-35°C (32-95°F)	20L-LL24K-1P0A				

⁽¹⁾ Supply loop requirements are for the input to the heat exchanger. These are not requirements for the drive. The output of the heat exchanger is designed to meet the flow and pressure requirements of the drive. For the flow and pressure requirements of the drive, see the table on page 46.

Estimated Amount of Coolant for the Drive Loop

Drive Frame Size	Estimated Amount of Coolant (1)
2	15.1 liters (4 gal.)
3A	19 liters (5 gal.)
3B	19 liters (5 gal.)

⁽¹⁾ The estimated amount of coolant is based on the heat exchanger using 1.2 m (4 ft.) hoses. Longer hoses require more coolant. The maximum hose length of 9.1 m (30 ft.) would require up to an additional 2.8 liters (3/4 gal.).

Hose Kits

Hose Length	Hoses per Kit	Drive Side(1) Coupling Size	Heat Exchanger Side Coupling Size	Used With	Hose Kit (2) Cat. No.
3 m (10 ft.)	2	0.75 inch	0.75 inch	Frame 2 and 13 kW heat exchanger	20L-GH10-B1
9.1 m (30 ft.)	2	0.75 inch	0.75 inch	Frame 2 and 13 kW heat exchanger	20L-GH30-B1
3 m (10 ft.)	2	1 inch	1 inch with 90° elbow	Frame 3A and 13 kW heat exchanger	20L-GH10-A2
9.1 m (30 ft.)	2	1 inch	1 inch with 90° elbow	Frame 3A and 13 kW heat exchanger	20L-GH30-A2
3 m (10 ft.)	2	1 inch	1 inch	Frame 3B and 24 kW heat exchanger	20L-GH10-A1
9.1 m (30 ft.)	2	1 inch	1 inch	Frame 3B and 24 kW heat exchanger	20L-GH30-A1

⁽¹⁾ All drive side hose kit fittings are 37 degree flare.

When a chiller or liquid-to-air heat exchanger is preferred, we recommend consulting with a cooling loop supplier such as Dimplex Thermal Solutions. The following are recommended chillers.

Recommended Chillers (from Dimplex Thermal Solutions)

Drive Frame Size	Capacity	Flow Rate	Pressure	Reservoir Size	Piping (Inlet and Outlet)	Chiller Model (1)
2 and 3A	16,983 watts	94.6 LPM (25 GPM)	3.44 bar (50 PSI)	117.3 L (31 gal)	1-1/4 in. NPT	KV5000
3B	28,110 watts	151.4 LPM (40 GPM)	3.44 bar (50 PSI)	181.7 L (48 gal)	1-1/4 in. NPT	KV7500

⁽¹⁾ Each chiller is designed for single drive cooling for indoor installation only. For applications requiring multiple drives using one chiller or outdoor use, contact Dimplex Thermal Solutions.

Chiller Specifications

Chiller Model	Electrical Line Input (1)	Rated Load	Dimensions	Weight
KV5000	230V, 3 phase, 60 Hz	29 Amp	1067 mm L x 711 mm W x 1676 mm H	249.5 kg
	460V, 3 phase, 60 Hz	17 Amp	(42 in. L x 28 in. W x 66 in. H)	(550 lbs.)
KV7500	230V, 3 phase, 60 Hz	40 Amp	1270 mm L x 914 mm W x 1676 mm H	340 kg
	460V, 3 phase, 60 Hz	22 Amp	(50 in. L x 36 in. W x 66 in. H)	(750 lbs.)

⁽¹⁾ Desired Line Voltage must be specified upon ordering.

For chiller pricing/ordering, contact Dimplex Thermal Solutions:

USA and Canada: 1-800-968-5665 Elsewhere: 1-269-349-6800

⁽²⁾ The minimum pressure applies to the pressure drop across the heat exchanger and does not take into account additional pressure drop in the system such as piping or hosing.

⁽³⁾ Recommended cooling loops shown are based on a single drive per cooling loop. Consult the factory for use of multiple drives on one cooling loop.

⁽²⁾ Each hose kit contains two (2) hoses and the appropriate connectors.

Drive Coolant Requirements

Recommended Coolants

The table below lists approved sources and recommended coolants with appropriate corrosion inhibitors for the drive loop:

Source	Coolant		
Interstate Chemical http://www.interstatechemical.com/contact.htm	NFP-50 (1); a 50/50 premix of propylene glycol and distilled water NFE-50 (1); a 50/50 premix of ethylene glycol and distilled water		
Koolant Koolers/Dimplex Thermal Solutions http://www.koolantkoolers.com/index.php/nic=contact	K-Kool-E (1); ethylene glycol (available premixed with distilled water) Propylene glycol (1) also available		
Dow Chemical http://www.dow.com	Dowtherm® SR-1 (2); ethylene glycol Dowfrost® (2); propylene glycol Dowtherm and Dowfrost are registered trademarks of the Dow Chemical Company		

⁽¹⁾ Available in 5 gallon pails.

Non-premixed coolants require a coolant-to-water mix ratio of 50% by volume.

Important: Since coolant performance slowly degrades over time, the drive loop coolant should be replaced every two years and/or whenever the loop is drained for servicing.

Corrosion Inhibitor

If an approved coolant is not used, the drive coolant must consist of clean water *with a corrosion inhibitor*. An approved corrosion inhibitor is Chemtool, Inc. (www.chemtool.com) part number Watertool 4435-C. The recommended concentration of the inhibitor is 8-10% by volume. Deionized water is prohibited. Use distilled water or water with less than 50 ppm concentrations of:

- · Sulfate and chloride
- Hard water ions such as Mg++ and Ca++

Ethylene and propylene glycols must be inhibited and silicate free. Use of common silicate-containing, automotive-type ethylene glycol solutions is prohibited as they may damage the heat exchanger and/or drive and cooling module equipment.

The drive coolant must be compatible with the following materials:

- Copper
- Brass
- Aluminum
- Arimid fiber gasket with nitrile binder (Garlock, Inc. Blue-Gard 3000®)
 Blue-Gard 3000 is a registered trademark of Garlock, Inc.
- Synthetic rubber hose (Parker Hannifan Corp 801 General Purpose Hose)
- Viton seal (Complete Drive only)

Biocide

A biocide may be needed to control biological growth. Use of a biocide is permitted. For specific recommendations, consult a reputable water treatment company.

⁽²⁾ Not premixed with distilled water, and may not be available in 5 gallon quantities.

Coolant Requirements for One Frame 2, 3A or 3B Drive

Drive Frame Size	Coolant Temperature Range		Pressure Drop (2) From Drive Inlet to Drive Outlet at Minimum Coolant Flow Rate	Coolant Type
2	0-50°C (32-122°F)	30.3 LPM (8 GPM)	1.58 bar (23 PSI)	MEOEO (2)
3A	0-40°C (32-104°F)	30.3 LPM (8 GPM)	0.35 bar (5 PSI)	WEG50 ⁽³⁾ or WPG50 ⁽⁴⁾
3B	0-40°C (32-104°F)	56.8 LPM (15 GPM) (1)	0.48 bar (7 PSI) (1)	WFG50 (1)

⁽¹⁾ Frame 3B includes separate converter and inverter power modules. A single inverter or converter power module requires a minimum flow rate of 30.3 LPM (8 GPM) at 0.35 bar (5 PSI).

Cooling Loop Application Guidelines

Do not use ferrous and plated-ferrous materials for pipe-treated water to the power modules and drive. Use of ferrous materials will degrade the performance of the power module chillplate.

Use the following guidelines for applying cooling loops other than those recommended.

• The allowable drive coolant temperature range is:

Frame 2 Drive: 0°C to 50°C (32°F to 122°F)
 Frame 3A/3B Drive: 0°C to 40°C (32°F to 105°F)

When using coolant at a temperature below the dew point of the surrounding air, condensation could accumulate on the drive heatsink and/or circuit boards and damage the drive. In this situation, install a coolant flow regulating device and tube/hose insulation. A flow regulating device modulates the coolant flow rate to a level that permits the drive heatsink temperature to rise above the dew point. Insulation for customer side tube or hose may be closed-cell foam insulation with minimum 12.7 mm (0.50 in.) wall thickness.

- The cooling loop should include a flow switch on the connection to the drive inlet to turn off the drive if coolant flow drops below the minimum flow required by the drive (see table above).
- Circulate coolant through the drive only when the drive is also powered. Failure to do this may result in condensation accumulating on the drive heatsink and/or circuit boards, which could damage the drive.
- An interlock from the cooling loop should be used to stop the drive when the cooling loop is faulted.
- For applications requiring a closed loop coolant system, ensure the system is vented to remove air that would otherwise degrade the performance of the drive heatsink.
- Install a flow measuring device at the inlet of each Converter and each Inverter Power Module. Note that flow measuring devices are included in the PF700L Frame 3A/3B Complete Drive cabinets (13th position in catalog number = A). The coolant flow rate (GPM) must meet the requirements in the table above.
- The following types of pipe are recommended for cooling loop connections:
 - Copper tubing, type L
 - Brass pipe
 - Stainless steel, 300 series

Important: Do not use galvanized pipe.

• The cooling loop should have a method for draining and replacing the coolant.

⁽²⁾ Pressure drop does not include any system connections such as hoses or piping. Cooling systems must be sized to provide minimum flow considering entire system pressure drop.

⁽³⁾ WEG50 equals good quality or distilled water with approved inhibited* ethylene glycol, 50% glycol by volume.

⁽⁴⁾ WPG50 equals good quality or distilled water with approved *inhibited** propylene glycol, 50% glycol by volume.

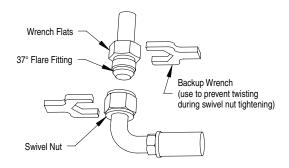
^{*} Inhibited ethylene glycol or propylene glycol must contain a corrosion inhibitor. See Corrosion Inhibitor on page 45 for an approved source.

Drive Coolant Connections

Frame 2 Drive

Coolant connections for a Frame 2 drive are made using 37 degree flare fittings which have a:

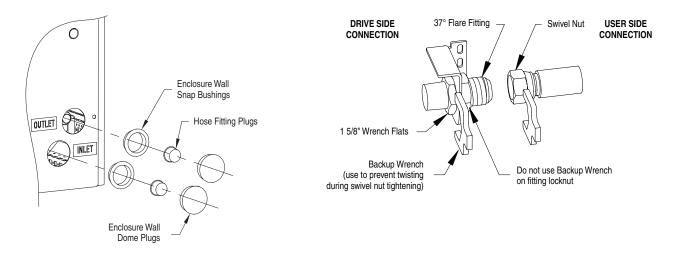
- 3/4-inch nominal size
- "-12" SAE dash size
- 1 1/16-12 UN/UNF-2B external thread size



Frame 3A/3B Complete Drive

Frame 3A/3B Complete Drive coolant connections are made using 37 degree flare fittings which have a:

- 1-inch nominal size
- "-16" SAE dash size
- 1 5/16-12 UN/UNF-2B external thread size



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